

Overview of mixed-effects models

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Grouped datasets

- Empirical datasets are often grouped e.g.
 - Repeated voice samples from the same person,
 - Trees within sample plots or aerial images,
 - repeated observations of trees (e.g., in successive years or on different images)
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These groups often constitute a sample from a population of groups, and are therefore naturally modeled using mixed-effect models.

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(2) and (3) are especially interesting in prediction and classification problems, which are considered in machine learning.

Linear mixed-effect model with random constant

$$y_{ij} = \boldsymbol{\beta}' \mathbf{x}_{ij} + b_i + \epsilon_{ij},$$

where

- y_{ij} is the observed response for individual j , $j = 1, \dots, n_i$ in group i , $i = 1, \dots, M$.
- \mathbf{x}_{ij} is a vector of fixed predictors,
- $\boldsymbol{\beta}$ includes the fixed parameters,
- b_i are random group effects for groups i ,
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- Model parameters are $\boldsymbol{\beta}$, σ_b^2 , and σ^2 . Also group effects b_i can be predicted.
- Can be seen as a marginal model $y_{ij} = \boldsymbol{\beta}' \mathbf{x}_{ij} + e_{ij}$, where $\text{var}(y_{ij}) = \sigma_b^2 + \sigma^2$ and $\text{cov}(y_{ij}, y_{ij'}) = \sigma_b^2$.

Parameter estimation

- The (restricted) likelihood for the marginal model $y_{ij} = \beta' \mathbf{x}_{ij} + e_{ij}$ is easy to write to get (RE)ML estimates of parameters σ_b^2 and σ^2 , and GLS/REML/ML estimates of β . The REML is based on multivariate normality of $\mathbf{y} = (y_1, y_2, \dots, y_n)'$ but the resulting estimators have nice properties in non-normal data as well.

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- The random group effects can be predicted using Best Linear Unbiased Predictor (BLUP)

$$\tilde{b}_i = \frac{\sigma_b^2}{\frac{1}{n_i}\sigma^2 + \sigma_b^2}(\bar{y}_i - \beta' \bar{\mathbf{x}}_{ij})$$

where \bar{y}_i and $\beta' \bar{\mathbf{x}}_{ij}$ are the means of the n_i observed values and fixed-part predictions for the group in question.

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- The prediction variance is

$$\text{var}(\tilde{b}_i - b_i) = \left(\frac{\sigma_b^2}{\frac{1}{n_i}\sigma^2 + \sigma_b^2} \right) \frac{\sigma^2}{n_i}$$

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- In practice, we use Empirical BLUP where the unknown β , σ_b^2 and σ^2 are replaced by their numerical estimates.

Some notes on prediction

- Mixed-effects allows *group-level prediction* where the predicted random effect is used.

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- Group-level predictions utilize the observed values of the response from the group in question. For groups not present in the modeling data, the typical-group prediction is the best one can get, unless local calibration data from the group in question are available for prediction of the random effects.

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- Group-level predictions utilize the observed values of the response from the group in question. For groups not present in the modeling data, the typical-group prediction is the best one can get, unless local calibration data from the group in question are available for prediction of the random effects.
- Prediction of random-effect for an previously fitted model provides a highly useful application, which has a Bayesian flavour.¹

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Example 1: Stemwood volume of eucalyptus trees

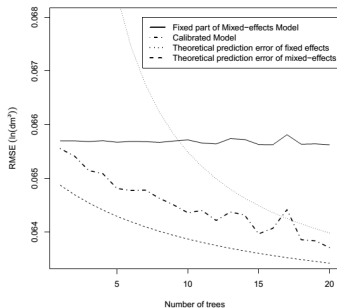
Model

$$\ln(v_{ij}) = \beta_0 + \beta_1 \ln(dbh_{ij}) + \beta_2 \ln(h_{ij}) + b_i + \epsilon_{ij}$$

was fitted for the volume of Eucalyptus trees j on farms i , using a stem analysis data of 1434 stems from 15 farms (de Souza Vismara et al. 2016).

The parameter estimates for random part were $\hat{\sigma}_b^2 = 0.18^2$ and $\hat{\sigma}^2 = 0.62^2$.

Therefore, some benefit may be obtained by prediction of random effects, as shown below.



More advanced mixed-effects models

- One may have other random effects than just constant:

$$y_{ij} = \beta' \mathbf{x}_{ij} + \mathbf{b}_i' \mathbf{z}_{ij} + \epsilon_{ij}$$

where \mathbf{z}_{ij} includes \mathbf{x}_{ij} or part of it, and $\mathbf{b}_i \sim N(0, \mathbf{D})$ (i.i.d).

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- For two nested groups, we specify

$$y_{ijk} = \beta' \mathbf{x}_{ijk} + \mathbf{a}_i' \mathbf{z}_{ijk}^{(a)} + \mathbf{c}_{ij}' \mathbf{z}_{ijk}^{(c)} + \epsilon_{ijk}$$

where $\mathbf{z}_{ijk}^{(a)}$ includes \mathbf{x}_{ijk} or part of it, and $\mathbf{z}_{ijk}^{(c)}$ includes $\mathbf{z}_{ijk}^{(a)}$ or part of it, and $\mathbf{a}_i \sim N(0, \mathbf{D}_a)$ (i.i.d) and $\mathbf{c}_{ij} \sim N(0, \mathbf{D}_c)$ (i.i.d).

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- For two crossed groups², we specify

$$y_{ijk} = \beta' \mathbf{x}_{ijk} + \mathbf{a}'_i \mathbf{z}_{ijk}^{(a)} + \mathbf{c}'_j \mathbf{z}_{ijk}^{(c)} + \epsilon_{ijk}$$

where $\mathbf{z}_{ijk}^{(a)}$ and $\mathbf{z}_{ijk}^{(c)}$ includes \mathbf{x}_{ijk} or part of it and $\mathbf{a}_i \sim N(0, \mathbf{D}_a)$ (i.i.d) and $\mathbf{c}_j \sim N(0, \mathbf{D}_c)$ (i.i.d).

²e.g. Mehtätalo et al 2014, Korpela et al. 2014

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- A bivariate LMM (with single level of grouping) may be specified by ³

$$y1_{ij} = \beta' \mathbf{x}1_{ij} + \mathbf{b}1'_i \mathbf{z}1_{ij} + \epsilon1_{ij}$$

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- The assumption of constant error variance can also be relaxed using variance functions/ correlation structures.
- Parameter estimation can be based on (RE)ML/GLS.
- Prediction of random effect is based on the general formulation of BLUP.

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BLUP - the general case

- Consider random vector \mathbf{h} which is partitioned as follows:

$$\mathbf{h} = \begin{pmatrix} \mathbf{h}_1 \\ \mathbf{h}_2 \end{pmatrix}$$

and has the following mean and variance:

$$\begin{pmatrix} \mathbf{h}_1 \\ \mathbf{h}_2 \end{pmatrix} \sim \left[\begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \begin{pmatrix} \mathbf{V}_1 & \mathbf{V}_{12} \\ \mathbf{V}'_{12} & \mathbf{V}_2 \end{pmatrix} \right]$$

- Consider a situation where the value of \mathbf{h}_2 has been observed and one wants to predict the value of unobserved vector \mathbf{h}_1 .
- The Best Linear Unbiased Predictor (BLUP) of \mathbf{h}_1 is

$$BLUP(\mathbf{h}_1) = \tilde{\mathbf{h}}_1 = \mu_1 + \mathbf{V}_{12}\mathbf{V}_2^{-1}(\mathbf{h}_2 - \mu_2) \quad (1)$$

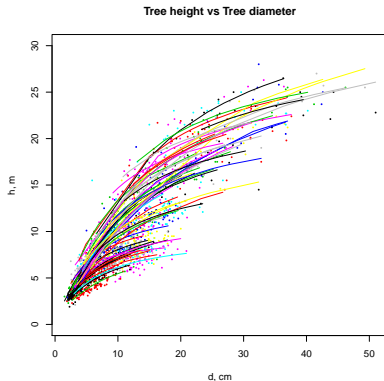
- The prediction variance is

$$\text{var}(\tilde{\mathbf{h}}_1 - \mathbf{h}_1) = \mathbf{V}_1 - \mathbf{V}_{12}\mathbf{V}_2^{-1}\mathbf{V}'_{12} \quad (2)$$

- If \mathbf{h} has multivariate normal distribution, BLUP is BP.
- If the mean and variances are estimates, the resulting estimator is called Estimated or empirical BLUP (EBLUP).

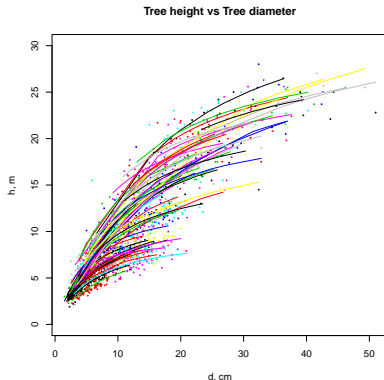
Example 2: A longitudinal H-D model

- H-D relationship varies much among groups (sample plots), but height measurement is time-consuming.



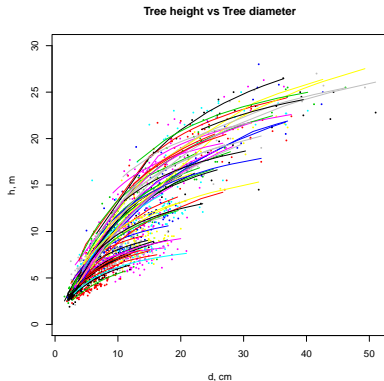
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If a previously fitted H-D model is available, it can be localized, or calibrated, for the new plot by predicting the random effects using the sampled tree heights.

The Height-Diameter model

The logarithmic height H_{ijk} for tree k in stand i at time j with transformed diameter D_{ijk} at the breast height is expressed by ⁴

$$\begin{aligned}\ln(H_{ijk}) &= \beta_0(DGM_{ij}) + a_i^{(1)} + c_{ij}^{(1)} + (\beta_1(DGM_{kt}) + a_i^{(2)} + c_{ij}^{(2)})D_{ijk} + \epsilon_{ijk} \\ &= \beta_0(DGM_{ij}) + \beta_1(DGM_{kt})D_{ijk} + a_i^{(1)} + a_i^{(2)}D_{ijk} + c_{ij}^{(1)} + c_{ij}^{(2)}D_{ijk} + \epsilon_{ijk},\end{aligned}$$

where

- $\beta_0(DGM_{ij})$ and $\beta_1(DGM_{ij})$ are known fixed functions of plot-specific mean diameter DGM_{ij} ,
- $\mathbf{a} = (a_i^{(1)}, a_i^{(2)})'$ are plot-level random effects
- $\mathbf{c} = (c_{ij}^{(1)}, c_{ij}^{(2)})'$ are measurement occasion -level random effects

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- The variances (correlations) were estimated to be

$$\text{var}(\mathbf{a}_i) = \begin{bmatrix} 0.108^2 & (0.269) \\ 0.0028 & 0.0958^2 \end{bmatrix} \quad \text{var}(\mathbf{c}_{ij}) = \begin{bmatrix} 0.0168^2 & (-0.681) \\ -0.0003 & 0.0223^2 \end{bmatrix}$$

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- ϵ_{ijk} are independent normal residuals with

$$\text{var}(\epsilon_{ijk}) = 0.401^2 (\max(D_{ijk}, 7.5))^{-1.068}$$

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The stand level mixed-effects model

The sample tree heights of a new stand i can be described by model

$$\mathbf{y}_i = \mathbf{X}_i \boldsymbol{\beta} + \mathbf{Z}_i \mathbf{b}_i + \boldsymbol{\epsilon}_i,$$

where

\mathbf{y}_i includes the observed sample tree heights,

$\mathbf{X}_i \boldsymbol{\beta}$ is the fixed part,

$\mathbf{b}_i = (a_i^{(1)} \ a_i^{(2)} \ c_{i1}^{(1)} \ c_{i1}^{(2)} \ c_{i2}^{(1)} \ c_{i2}^{(2)} \ \dots)'$ includes the random effects,

\mathbf{Z}_i is the random part design matrix of the group, and

$\boldsymbol{\epsilon}_i$ includes the residuals.

We denote $\text{var}(\mathbf{b}_i) = \mathbf{D}$ and $\text{var}(\boldsymbol{\epsilon}_i) = \mathbf{R}_i$.

Prediction of random effects

The variances and covariances between random effects and observed heights can be written as

$$\begin{bmatrix} \mathbf{b}_i \\ \mathbf{y}_i \end{bmatrix} \sim \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{X}_i \boldsymbol{\beta} \end{bmatrix}, \begin{bmatrix} \mathbf{D} & \mathbf{DZ}_i' \\ \mathbf{Z}_i \mathbf{D} & \mathbf{Z}_i \mathbf{DZ}_i' + \mathbf{R}_i \end{bmatrix} \right)$$

The Empirical Best Linear Unbiased Predictor (EBLUP) of random effects is

$$\tilde{\mathbf{b}}_i = \mathbf{DZ}_i'(\mathbf{Z}_i \mathbf{DZ}_i' + \mathbf{R}_i)^{-1}(\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta}).$$

and the variance of prediction errors is

$$\text{var}(\tilde{\mathbf{b}}_i - \mathbf{b}_i) = \mathbf{D} - \mathbf{DZ}_i'(\mathbf{Z}_i \mathbf{DZ}_i' + \mathbf{R}_i)^{-1} \mathbf{Z}_i \mathbf{D}$$

Example

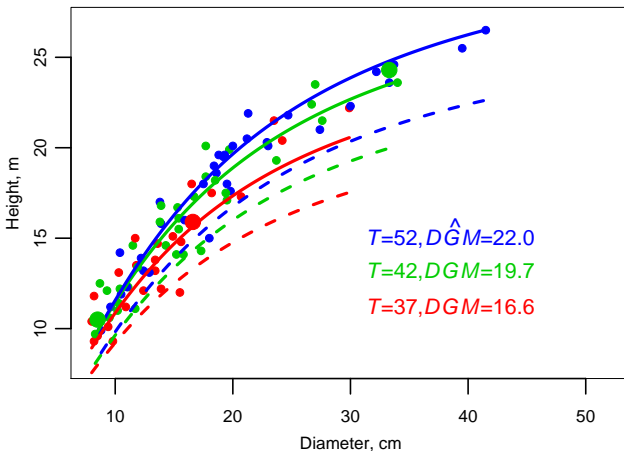
Height of one tree was measured 5 years ago and 2 trees at the current year for plot i . The matrices and vectors are

$$\mu_i = \mathbf{X}_i \boldsymbol{\beta} = \begin{bmatrix} 2.59 \\ 2.11 \\ 2.99 \end{bmatrix} \quad \mathbf{y}_i = \begin{bmatrix} 2.77 \\ 2.35 \\ 3.19 \end{bmatrix}$$

$$\mathbf{Z}_i = \begin{bmatrix} 1 & -0.36 & 1 & -0.36 & 0 & 0 \\ 1 & -1.22 & 0 & 0 & 1 & -1.22 \\ 1 & 0.058 & 0 & 0 & 1 & 0.058 \end{bmatrix} \quad \mathbf{R}_i = \begin{bmatrix} 0.008 & 0 & 0 \\ 0 & 0.016 & 0 \\ 0 & 0 & 0.004 \end{bmatrix}$$

$$\boldsymbol{\beta} = \begin{bmatrix} \alpha_i \\ \beta_i \\ \alpha_{i1} \\ \beta_{i1} \\ \alpha_{i2} \\ \beta_{i2} \end{bmatrix} \quad \mathbf{D} = \begin{bmatrix} 0.0118 & 0.0028 & 0 & 0 & 0 & 0 \\ 0.0028 & 0.0092 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.0003 & 0.0004 & 0 & 0 \\ 0 & 0 & 0.0004 & 0.0005 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.0003 & 0.0004 \\ 0 & 0 & 0 & 0 & 0.0004 & 0.0005 \end{bmatrix}$$

Uncalibrated and calibrated predictions



Dashed shows prediction based on fixed part. Three trees (large symbols) were used to predict the random effects to get plot-level predictions (solid).

Example 3: Modelling tree-level reflectance on aerial images

- A multivariate linear mixed-effects model with crossed grouping structure was used to analyze the reflectance of forest trees on overlapping aerial images.⁵
- The reflectance (color) of a tree on an image can be used to classify tree species

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- However, the viewing direction with respect to sunlight affects the spectral characteristics of a tree.
- This effect is species-specific
- Therefore, observing a certain tree from multiple directions (=images) may provide more accurate species classification than an observation on one aerial image only.

⁵Korpela et al. 2014

Study material

- 20 partially overlapping aerial images of a forest area were taken.

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- Trees of different images were automatically matched.
- The individual pixels within tree crowns were divided to sunlit and self-shaded pixels. The mean reflectances in these parts were analyzed separately -> a system of 8 models (4 channels, shaded and sunlit) for each of the three tree species.

Structure of aerial image data on a forest

- Observations from a given image are similar due to e.g. the properties of the atmosphere at the time of imaging and the atmospheric correction.

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- The model for each response and tree species has the following (crossed) structure

$$y_{ij} = \beta' \mathbf{x}_{ij} + b_i + c_j + \epsilon_{ij},$$

where i and j refer to image and tree effects, respectively. σ_i^2 and σ_j^2 are the corresponding variances. The predictors \mathbf{x}_{ij} are trigonometric transformations of the horizontal and vertical viewing and Sun angles.

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- The random effects at different levels of grouping are independent, therefore

$$\begin{aligned} \text{var}(y_{ij}) &= \sigma_i^2 + \sigma_j^2 + \sigma^2 \\ \text{cov}(y_{ij}, y_{i'j'}) &= 0 \\ \text{cov}(y_{ij}, y_{ij'}) &= \sigma_i^2 \\ \text{cov}(y_{ij}, y_{i'j}) &= \sigma_j^2 \end{aligned}$$

The multivariate model

The multivariate model for a tree species is

$$\begin{aligned} y_{1ij} &= \beta_1' x_{1ij} + b_{1i} + c_{1j} + \epsilon_{1ij} \\ &\vdots \\ y_{8ij} &= \beta_8' x_{8ij} + b_{8i} + c_{8j} + \epsilon_{8ij} \end{aligned}$$

or simply

$$\mathbf{y}_{ij} = \beta \mathbf{x}_{ij} + \mathbf{b}_i + \mathbf{c}_j + \epsilon_{ij}$$

where the responses 1-8 refer to the sunlit and self-shaded pixels of the four channels and

- $(b_{1i}, \dots, b_{8i})' = \mathbf{b}_i \sim N(0, \mathbf{A}_{8 \times 8})$ include the random image-effects
- $(c_{1j}, \dots, c_{8j})' = \mathbf{c}_j \sim N(0, \mathbf{B}_{8 \times 8})$ include the random tree-effects
- $(\epsilon_{1ij}, \dots, \epsilon_{8ij})' = \epsilon_{ij} \sim N(0, \mathbf{E}_{8 \times 8})$ include the residual errors

The multivariate model (continued)

■ Now

$$\begin{aligned} \text{var}(\mathbf{y}_{ij}) &= \mathbf{A} + \mathbf{B} + \mathbf{E} \\ \text{cov}(\mathbf{y}_{ij}, \mathbf{y}_{i'j'}) &= \mathbf{0} \\ \text{cov}(\mathbf{y}_{ij}, \mathbf{y}_{ij'}) &= \mathbf{A} \\ \text{cov}(\mathbf{y}_{ij}, \mathbf{y}_{i'j}) &= \mathbf{B} \end{aligned}$$

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 \text{cov}(\mathbf{y}_{ij}, \mathbf{y}_{i'j}) &= \mathbf{B}
 \end{aligned}$$

■ Model fitting (based on REML/ML/GLS) yields $\hat{\beta}$, $\hat{\mathbf{A}}$, $\hat{\mathbf{B}}$ and $\hat{\mathbf{E}}$

Estimated variance components (covariances not shown)

Variance components, real data, 200 000 observations (%)

	sunlit shade		sunlit shade		sunlit shade		sunlit shade	
Fixed ($X\beta$)-%	33	11	32	13	45	29	7	-0
Tree-%	42	42	43	41	18	13	62	64
Image-%	4	12	5	14	27	46	6	2
Residual-%	21	35	20	32	10	13	25	34
Total	100	100	100	100	100	100	100	100

* Fixed part: The anisotropy trends explained SL >> SS,
BLU > GRN > RED > NIR. In NIR, anisotropy is low.

* Tree-effect: The correlations are strong, both for SL and SS. A bright tree is bright
across views and bands. In NIR > 60% of variance explained!!

* Image-effect: Substantial in BLU, SS > SL. Includes effects from solar
elevation changes (07-09 GMT), atmospheric correction errors.

The use in classification

- Let \mathbf{y}_{ij} be an observed vector (length=8) of the reflectances of one tree j on the 8 channels on one image i . The squared Mahalanobis distance between \mathbf{y}_{ij} and $\boldsymbol{\mu}_{ij}$ is

$$d_{ij}^2 = (\mathbf{y}_{ij} - \boldsymbol{\mu}_{ij})' (\mathbf{A} + \mathbf{B} + \mathbf{E})^{-1} (\mathbf{y}_{ij} - \boldsymbol{\mu}_{ij})$$

This distance takes into account the correlation of reflectance among different channels, and is (at least under multivariate normality of the reflectance data) in a way optimal for single tree on single image.

The use in classification (continued)

- For multiple images, the squared Mahalanobis distance between $\mathbf{y}_{\cdot j}$ and $\boldsymbol{\mu}_{\cdot j}$ is

$$d_{\cdot j}^2 = (\mathbf{y}_{\cdot j} - \boldsymbol{\mu}_{\cdot j})' \mathbf{D}_{\cdot j}^{-1} (\mathbf{y}_{\cdot j} - \boldsymbol{\mu}_{\cdot j}),$$

where $\mathbf{y}_{\cdot j} = (\mathbf{y}'_{1j}, \dots, \mathbf{y}'_{mj})$ is an observed vector (with length of $8m$) of the reflectances of tree j on the 8 channels of m images. The $8m \times 8m$ variance-covariance matrix is

$$\mathbf{D}_{\cdot j} = \begin{bmatrix} \mathbf{A} + \mathbf{B} + \mathbf{E} & \mathbf{B} & \dots & \mathbf{B} \\ \mathbf{B} & \mathbf{A} + \mathbf{B} + \mathbf{E} & & \mathbf{B} \\ \vdots & & \ddots & \vdots \\ \mathbf{B} & \mathbf{B} & \dots & \mathbf{A} + \mathbf{B} + \mathbf{E} \end{bmatrix}$$

This distance takes into account the correlation arising from the common tree effects

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This distance takes into account the correlation arising from the common tree effects

- Extension to many trees and images would be possible as well.

Example 4: Eucalyptus volumes on two rotations

A bivariate volume model

$$\ln(v_{1ij}) = \beta_1' \mathbf{x}_{1ij} + b_i^{(1)} + \epsilon_{1ij}$$

$$\ln(v_{2ij}) = \beta_2' \mathbf{x}_{2ij} + b_i^{(2)} + \epsilon_{2ij}$$

was used for rotations 1 and 2 of Eucalyptus plantations⁶.

The parameter estimates for random part were

$$\widehat{\text{var}} \begin{pmatrix} b_i^{(1)} \\ b_i^{(2)} \end{pmatrix} = \begin{pmatrix} 0.0192^2 & 0.0005170176 \\ 0.0005170176 & 0.0272^2 \end{pmatrix} = (\mathbf{C} \quad \mathbf{H})$$

and

$$\widehat{\text{var}} \begin{pmatrix} \epsilon_{1ij} \\ \epsilon_{2ij} \end{pmatrix} = \begin{pmatrix} 0.0624 & 0 \\ 0 & 0.0596^2 \end{pmatrix}$$

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The error variance is high compared to that of random effects, → calibration effects will be only modest.

⁶de Souza Vismara, Mehtatalo and Batista 2016

BLUP in this case

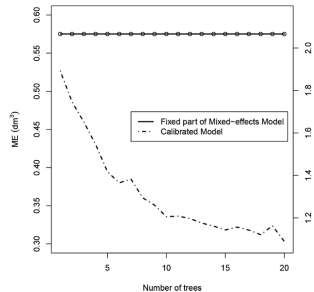
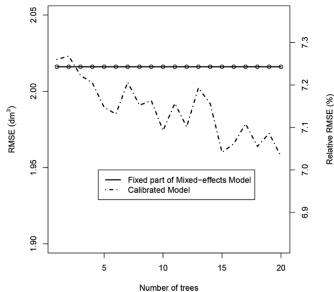
We have now

$$\begin{bmatrix} \mathbf{b}_i \\ \ln \mathbf{v}_{1i} \end{bmatrix} \sim \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{X}_{1i}\beta_1 \end{bmatrix}, \begin{bmatrix} \mathbf{D} & \mathbf{C}\mathbf{Z}'_{1i} \\ \mathbf{Z}_{1i}\mathbf{C}' & \mathbf{Z}_{1i}\text{var}(\mathbf{b}_i^{(1)})\mathbf{Z}'_{1i} + \mathbf{R}_{1i} \end{bmatrix} \right)$$

Leading to EBLUP:

$$\tilde{\mathbf{b}}_i = \mathbf{C}\mathbf{Z}'_{1i} \left(\mathbf{Z}_{1i}\text{var}(\mathbf{b}_i^{(1)})\mathbf{Z}'_{1i} + \mathbf{R}_{1i} \right)^{-1} (\ln \mathbf{v}_{1i} - \mathbf{X}_{1i}\beta_1) .$$

etc..



Example 5: System of mixed-effects model for aerial forest inventory

- Airborne Laser Scanners (ALS) provide information on the 3D- structure of forest
- Majority of large individual trees can be detected from an ALS point cloud
- Point cloud characteristics can be assigned to field-measured tree characteristics to estimate a system of predictive models for tree characteristics, such as stem volume, height, diameter, crown base height, dead crown height.
- These tree-specific characteristics are correlated within a forest stand
- Also the stand effects are correlated across models
- These correlations can be utilized to predict the random effects of a mixed-effects model for a given stand for all 5 models using even one observation of one characteristics only
- Enables improved predictions of hard-to-measure characteristics by using easy-to-measure characteristics. ⁷

The model

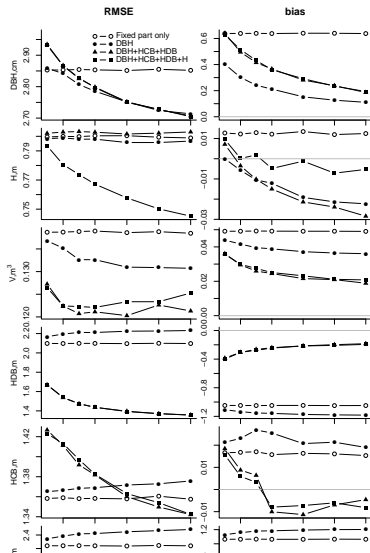
The model includes a system of 5 mixed-effects models of form for tree i in stand k :

$$\begin{aligned} y1_{ki} &= a1 + b1x1_{ki} + \dots + \alpha1_k + \beta1_k x1_{ki} + \epsilon1_{ki} \\ y2_{ki} &= a2 + b1x2_{ki} + \dots + \alpha2_k + \beta2_k x2_{ki} + \epsilon2_{ki} \\ &\vdots \\ y5_{ki} &= a5 + b5x5_{ki} + \dots + \alpha5_k + \beta5_k x5_{ki} + \epsilon5_{ki} \end{aligned}$$

where the fixed parts are as with the previous mixed-effects models and include the ALS-based predictors.

- The assumptions on the random effects and residuals are $(\alpha1_k, \beta1_k, \alpha2_k, \beta2_k, \dots, \alpha5_k, \beta5_k)' \sim MVN(0, \mathbf{D}_{10 \times 10})$, and $(\epsilon1_{k1}, \epsilon2_{ki}, \dots, \epsilon5_{ki}) \sim MVN(0, \mathbf{R}_{5 \times 5})$
- The intended use of the model is prediction applying the random effects.
- The previously presented principles were used to predict the random effects of the model system by using 1-10 sample trees per stand and 3 different measurement strategies

Results



Summary

- Random-effect prediction is a widely applicable tool for modeling grouped data where groups constitute a sample from a population of groups.
- Random effects may be justified for many different purposes, and modeling procedures should be adopted for the purpose of modeling.
 - local predictions through random effects.
 - statistical inference in grouped datasets
 - variance partitioning
 - estimation of variance-covariance structure for classification

Questions

- 1 Compute $\tilde{\mathbf{b}}_i$ and $\text{var}(\tilde{\mathbf{b}}_i - \mathbf{b}_i)$ using the matrices of example 2. Use the computed value of $\tilde{\mathbf{b}}_i$ to recover the relationship between Diameter and Height for the two points in time of the example. Compare to the figure shown in the notes.
- 2 Consider your own area of interest and describe such a problem where mixed-effect models could be used for group-specific prediction or classification.

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Case 2: Extracting effects of silvicultural thinnings

Utilizing a prediction from a linear mixed-effects model with crossed tree and calendar year effects

Mehtätalo, L., Peltola, H., Kilpeläinen, A. and Ikonen, V.-P. 2013. The effect of thinning on the basal area growth of Scots Pine: a longitudinal analysis using nonlinear mixed-effects model. Submitted manuscript.

Why thinning effects?

- Forest managers use silvicultural thinnings to decrease the competition of neighboring trees and, consequently, to increase the growth rate of the remaining trees for faster production of sawtimber.

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- To understand the dynamics of thinning, one may wish to analyse the effect of thinnings on tree growth.
- However, the growth is affected also by other factors, especially by the site productivity, tree age, and annual weather.
- Mixed-effects models can be used to model out these nuisance effects.

Study material

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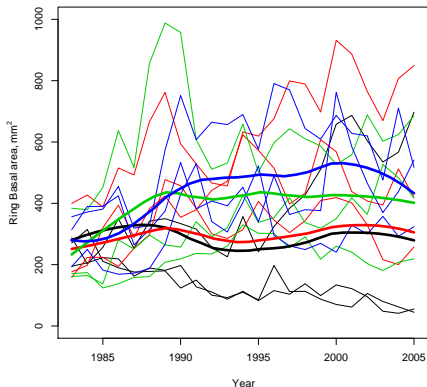
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- 88 trees were felled in 2006, and the complete time series of diameter increments between 1983 and 2006 was measured for each tree using an X-ray densiometer.

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- 88 trees were felled in 2006, and the complete time series of diameter increments between 1983 and 2006 was measured for each tree using an X-ray densiometer.
- The diameter growths were transformed to basal area growths, because $Volume \sim Diameter^2 Height$

The raw data



I (control) - black; II (light) - red
 III (moderate) - green; IV (heavy) - blue

- THICK: treatment-specific trends
- THIN: 12 randomly selected trees
- One can see
 - (Age trend)
 - climate-related year effects
 - tree effects

Modeling the non-thinned response

- A dataset without thinning treatments was produced by including from the original data
 - The control treatment for whole follow-up period
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 - The control treatment for whole follow-up period
 - The thinned treatments until the year of thinning (1986)
- A linear mixed effect model with random year and tree effects was fitted to the unthinned data

$$y_{kt} = f(T_{kt}; \mathbf{b}) + \alpha_k + \alpha_t + \epsilon_{kt} \quad (3)$$

where y_{kt} is the basal area growth of tree k at year t ,

$f(T_{kt}; \mathbf{b})$ is the age trend (modeled using a spline),

α_k is a NID tree effect,

α_t is a NID year effect and

ϵ_{kt} is a NID residual.

Extracting the thinning effects

- Using the estimated age trend and BLUP's of year and tree effects, the growth without thinning, \tilde{y}_{kt} was predicted for treatments II -IV after the thinning year.

Extracting the thinning effects

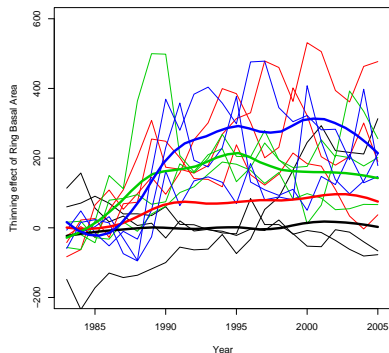
- Using the estimated age trend and BLUP's of year and tree effects, the growth without thinning, \tilde{y}_{kt} was predicted for treatments II -IV after the thinning year.
- The pure thinning effects were estimated by subtracting the prediction from the observed growth

$$d_{kt} = y_{kt} - \tilde{y}_{kt} \quad (4)$$

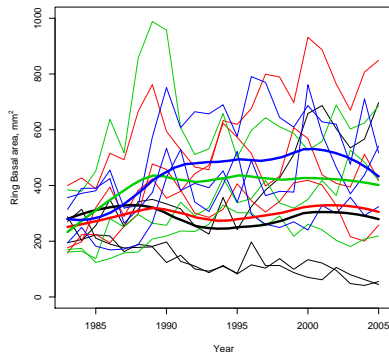
Extracting thinning effects

The estimated thinning effects

Extracted thinning effects



Raw data



Line color specifies treatment (I: black, II: red, III: green IV: blue). Thick lines show the treatment-specific mean trends; thin lines show 12 randomly selected trees.

Case 3: Modelling thinning effects using NLME's

A nonlinear model to analyze the effect of thinning intensity and tree size on the dynamics of tree-level thinning effect.

Mehtätalo, L., Peltola, H., Kilpeläinen, A. and Ikonen, V.-P. 2013. The effect of thinning on the basal area growth of Scots Pine: a longitudinal analysis using nonlinear mixed-effects model. Submitted manuscript.

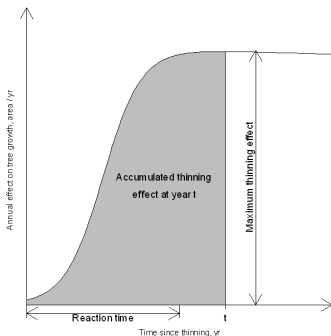
Modeling the thinning effects

- The thinning effects seem to switch on during a short time called **Reaction time** and stabilize thereafter at a level of **Maximum thinning effect**.
- To explore what predictors control these two parameters, the thinning effects of the thinnend treatments 2-4 were modeled using a nonlinear mixed-effects model.
- The random effects were used to take into account the data hierarchy for more reliable inference.

Nonlinear mixed-effects model for thinning effect

The thinning effect of tree k at time t was modeled using a logistic curve

$$d_{kt} = \frac{M_k}{1 + \exp\left(4 - 8 \frac{x_{kt}}{R_k}\right)} + e_{kt}$$



- d_{kt} - thinning effect
- x_{kt} - time since thinning
- $M_k = \mu_0 + \mu_1 T_2 + \mu_2 T_3 + \mu_4 x_{kt} + m_k$
- maximum thinning effect
- T_2, \dots, T_3 - treatments
- $R_k = \rho_0 + \rho_1 z_k + r_k$ - reaction time
- z_k - standardized diameter
- $\begin{bmatrix} m_k \\ r_k \end{bmatrix} \sim MVN(\mathbf{0}, \mathbf{D}_{2 \times 2})$
- e_{kt} - normal heteroscedastic residual with AR(1) structure within a tree.

The fitted model

- The reaction time was **6 years**. It did not significantly vary among treatments but was **shorter for large trees**.

Fixed parameters	Estimate	s.e.	p-value
μ_0	112.8	23.29	0.0000
μ_1	91.91	30.45	0.0026
μ_2	169.2	32.14	0.0000
μ_3	-3.214	1.006	0.0014
ρ_0	5.749	0.4458	0.0000
ρ_1	-1.461	0.4568	0.0014
Random parameters			
$\text{var}(r_k)$	93.012		
$\text{var}(m_k)$	2.0852		
$\text{cor}(r_k, m_k)$	0.203		
Residual			
σ^2	8.157*10-4		
δ_1	8.746*104		
δ_2	1.886		
δ_3	0.5888		

The fitted model

- The reaction time was **6 years**. It did not significantly vary among treatments but was **shorter for large trees**.
- The maximum thinning effect **increased with thinning intensity**, being 282 *mm/yr* for treatment IV, which indicates a 87% increase in the basal area growth compared to the control.

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