

1. Define the following terms :
  - (i) System
  - (ii) Control system
  - (iii) Input
  - (iv) Output
  - (v) Disturbance
2. Define open-loop and closed-loop control systems. Mention their merits and demerits.
3. Draw the block diagram of a closed-loop system and indicate the following on it :
  - (i) Plant
  - (ii) Command input
  - (iii) Controlled output
  - (iv) Actuating signal
  - (v) Feedback element and control element.
4. What is Feedback ? Explain the effects of feedback.
5. How are feedback control systems classified ?
6. Differentiate between
  - (i) Linear and nonlinear systems
  - (ii) Time-invariant and time-varying systems
  - (iii) Continuous and discrete-data systems
7. What are the limitations of open-loop systems over closed-loop systems ? List the advantages of closed-loop system over open-loop system.
8. Explain the following terms giving suitable examples :
  - (i) Servomechanism
  - (ii) Regulator

1. What do you mean by transfer function ?
2. Find the transfer function of the network shown in Fig. P2.1

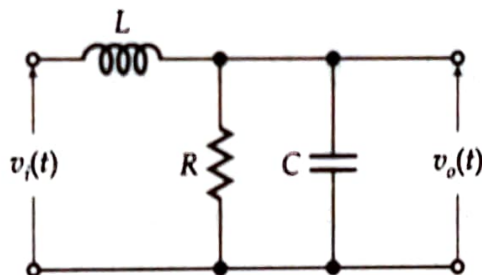


Fig. P2.1

[Ans.  $\frac{V_o(s)}{V_i(s)} = \frac{1}{LCs^2 + \frac{L}{R}s + 1}$ ]

3. Derive the transfer function of the network shown in Fig. P2.2

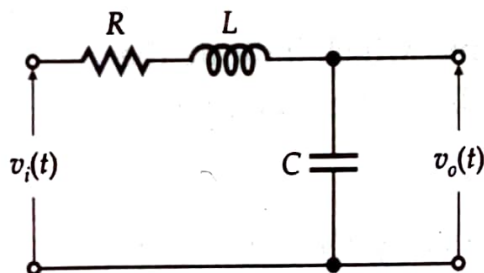


Fig. P2.1

[Ans.  $\frac{V_o(s)}{V_i(s)} = \frac{1}{LCs^2 + RCs + 1}$ ]

1. Determine the transfer function  $\frac{C(s)}{R(s)}$  for the block diagram as shown in Fig. P3.1.

Ans.

$$\left[ \frac{C(s)}{R(s)} = \frac{G_1(G_2 + G_3)}{1 + G_2 + G_3 + H_1 G_1 G_2} \right]$$

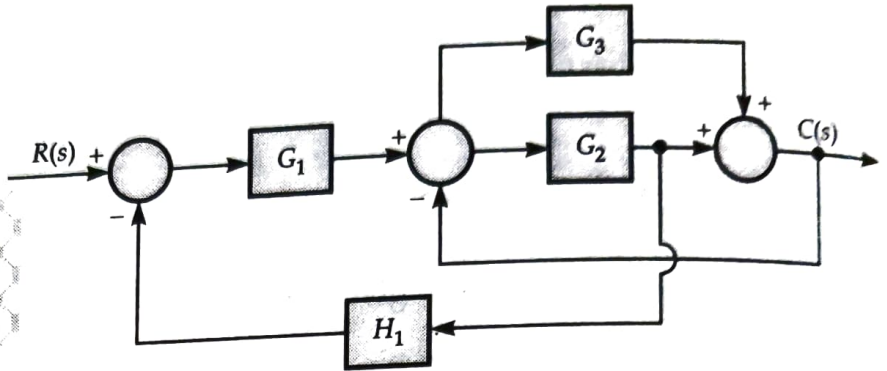


Fig. P3.1

2. What do you mean by a block diagram? What is meant by summing point and takeoff point? State the advantages of block diagram representation.
3. Reduce the block diagram shown in Fig. P3.2 and find the input-output relationship ratio  $\frac{C}{R}$ .

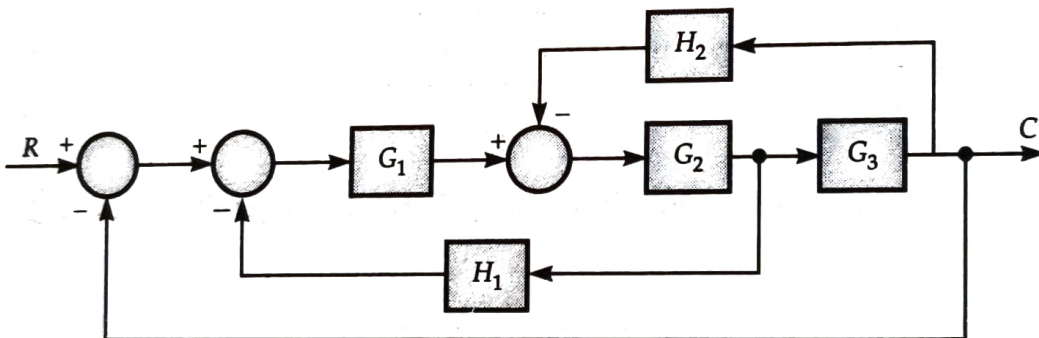


Fig. P3.2

$$\text{Ans. } \left[ \frac{C}{R} = \frac{G_1 G_2 G_3}{1 - G_1 G_2 H_1 + G_1 G_3 H_2 + G_1 G_2 G_3} \right]$$

4. Find the equivalent transfer function  $G(s) = \frac{C(s)}{R(s)}$  for the system shown in Fig. P3.3.

Ans.

$$\left[ G(s) = \frac{s^3 + 1}{2s^4 + s^2 + 2s} \right]$$

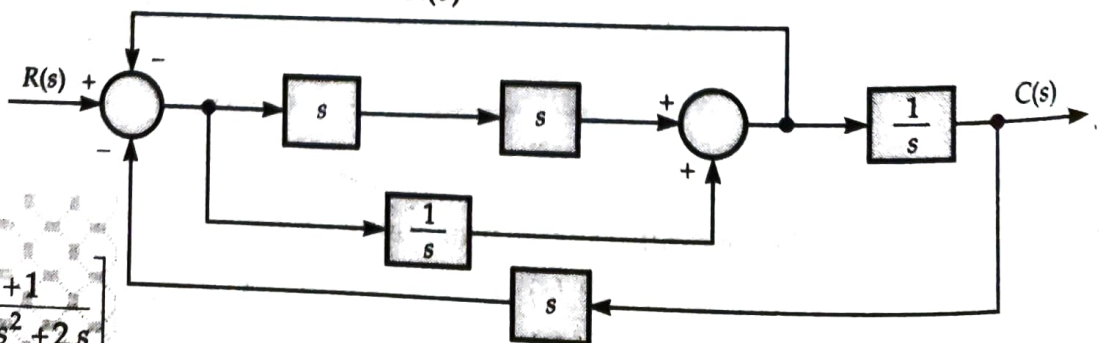


Fig. P3.3

5. A closed-loop control system is subjected to a disturbance  $D(s)$  as shown in Fig. 3.4. Determine the value of  $C(s)$ .

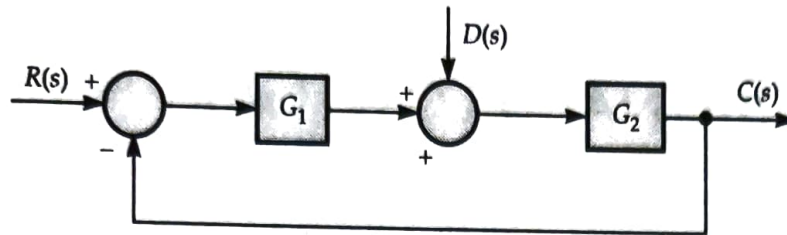


Fig. P3.4

Ans. 
$$C(s) = \left( \frac{G_2}{1 + G_1 + G_2} \right) [G_1 R(s) + D(s)]$$

6. A closed-loop control system is subjected to a disturbance  $D(s)$  as shown in Fig. P3.5. Determine the output of the system.

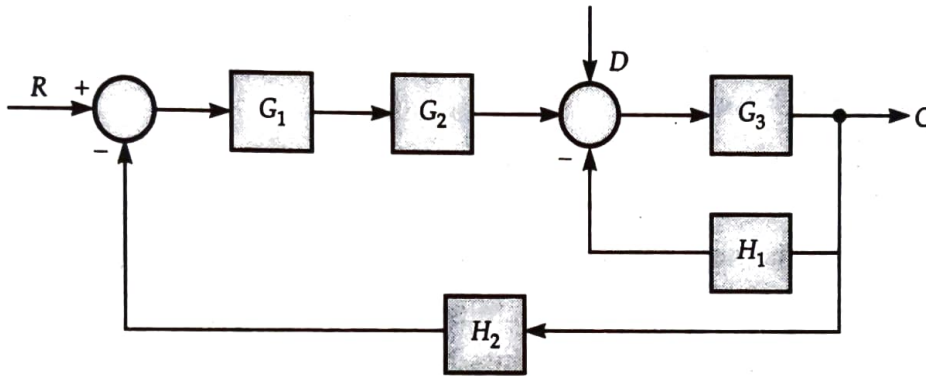


Fig. P3.5

Ans. 
$$C = \frac{G_1 G_2 G_3 R}{1 + G_3 H_1 + G_1 G_2 G_3 H_2} + \frac{G_3 D}{1 + G_3 H_1 + G_1 G_2 G_3 H_2}$$

7. Determine the output  $\theta_o$  for the system shown in Fig. 3.6.

Ans. 
$$\theta_o = \left[ \frac{Ks}{(s+2) - 2K(s+1)} \right] \theta_i + \left[ \frac{s(s+2)}{(s+2) - 2K(s+1)} \right] D_1 + \left[ \frac{2K}{(s+2) - 2K(s+1)} \right] D_2$$

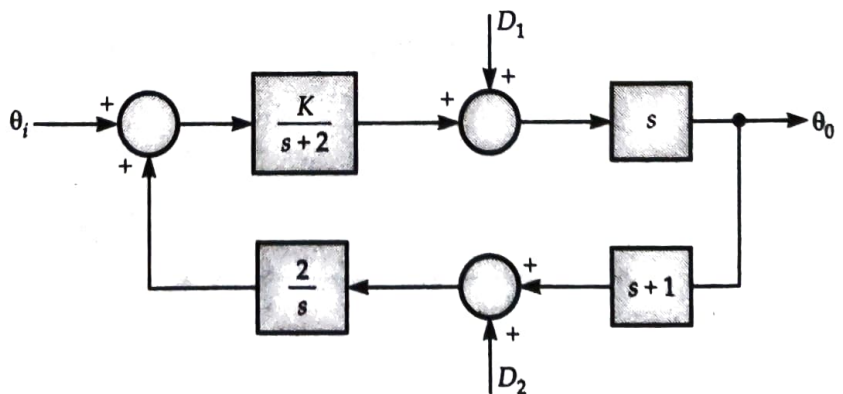


Fig. P3.61



## EXERCISES

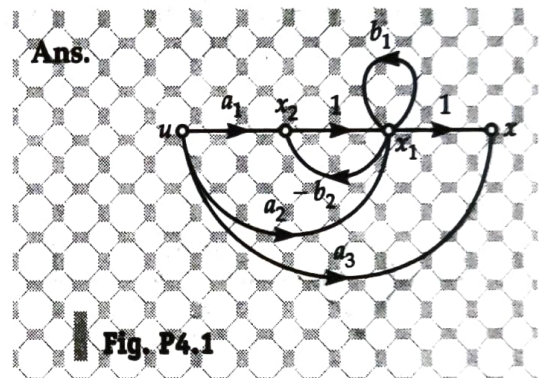
1. What is a node ? Name different types of nodes.
2. Define loop. Name different types of loops. What is meant by the term loop gain ?
3. Explain the following terms :
  - (a) Path
  - (b) Forward path
  - (c) Forward path gain
  - (d) Feedback path
  - (e) Loop gain
4. What do you mean by a signal flow graph ? State the properties of signal flow graphs.
5. State the Mason's gain formula.
6. Compare block diagram and signal flow graph methods.
7. A system having input and output represented by  $u$  and  $x$  is described by the following equations :

$$x = x_1 + a_3 u$$

$$x_1 = b_1 x_1 + x_2 + a_2 u$$

$$x_2 = -b_2 x_1 + a_1 u$$

Draw the signal flow diagram.



8. Obtain the transfer function  $\frac{C}{R}$  of signal flow graph shown in Fig. P4.2 using Mason's gain formula..

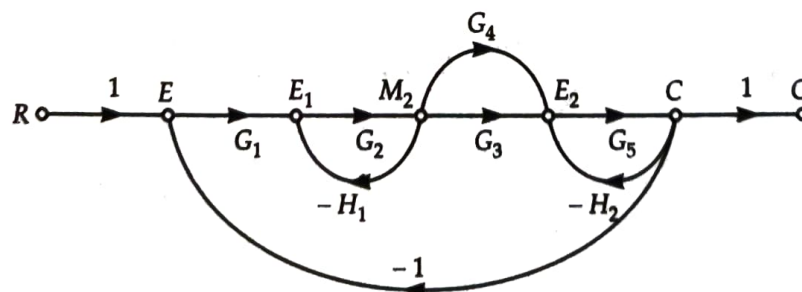


Fig. P4.2

Ans.  $\left[ \frac{C}{R} = \frac{G_1 G_2 G_3 G_5 + G_1 G_2 G_4 G_5}{1 + G_2 H_1 + G_5 H_2 + G_1 G_2 G_3 G_5 + G_1 G_2 G_4 G_5 + G_2 G_5 H_1 H_2} \right]$

9. Obtain the transfer function  $\frac{C}{R}$  of the signal flow graph shown in Fig. P4.3 using Mason's gain formula..

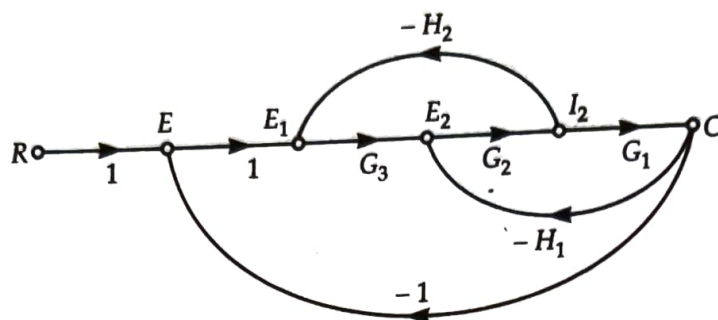
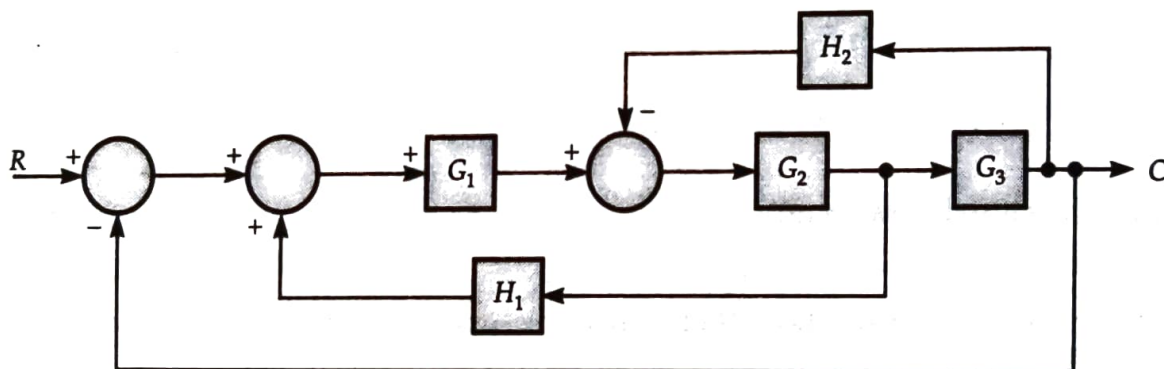


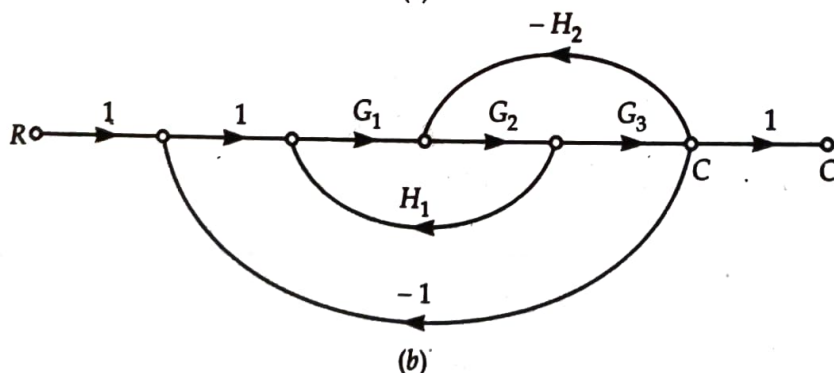
Fig. P4.3

Ans.  $\left[ \frac{C}{R} = \frac{G_1 G_2 G_3}{1 + G_2 G_3 H_2 + G_1 G_2 H_1 + G_1 G_2 G_3} \right]$

10. Convert the block diagram of Fig. P4.4(a) to a signal flow graph and determine the closed loop transfer function  $\frac{C(s)}{R(s)}$  by use of Mason's gain formula.



(a)



(b)

Fig. P4.4

Ans.  $\left[ \frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3}{1 - G_1 G_2 H_1 + G_2 G_3 H_2 + G_1 G_2 G_3} \right]$

11. Determine the closed loop transfer function  $\frac{C(s)}{R(s)}$  in the system shown in Fig. P4.5.

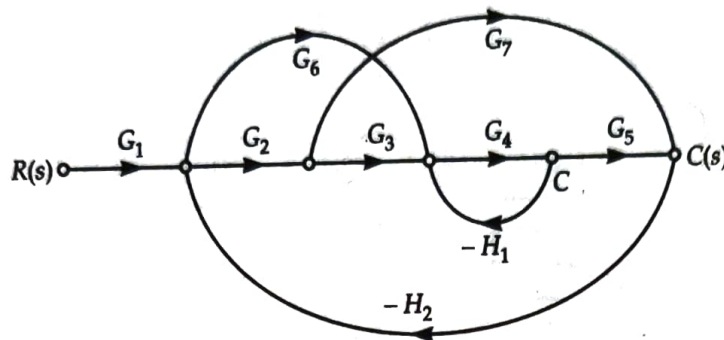


Fig. P4.5

Ans. 
$$\left[ \frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4 G_5 + G_1 G_6 G_4 G_5 + G_1 G_2 G_7 (1 + G_4 H_1)}{1 + G_4 H_1 + G_2 G_7 H_2 + G_4 G_5 G_6 H_2 + G_2 G_3 G_4 G_5 H_2 + G_4 H_1 G_2 G_7 H_2} \right]$$

12. Determine the transfer function  $\frac{Y(s)}{R(s)}$  from the signal flow graph shown in Fig. P4.6.

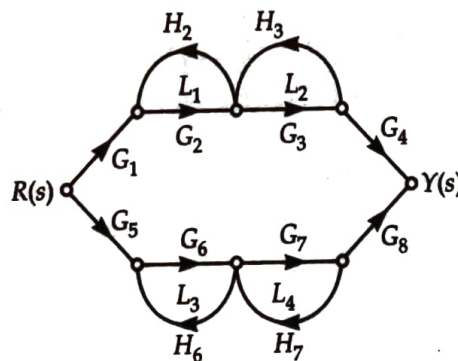
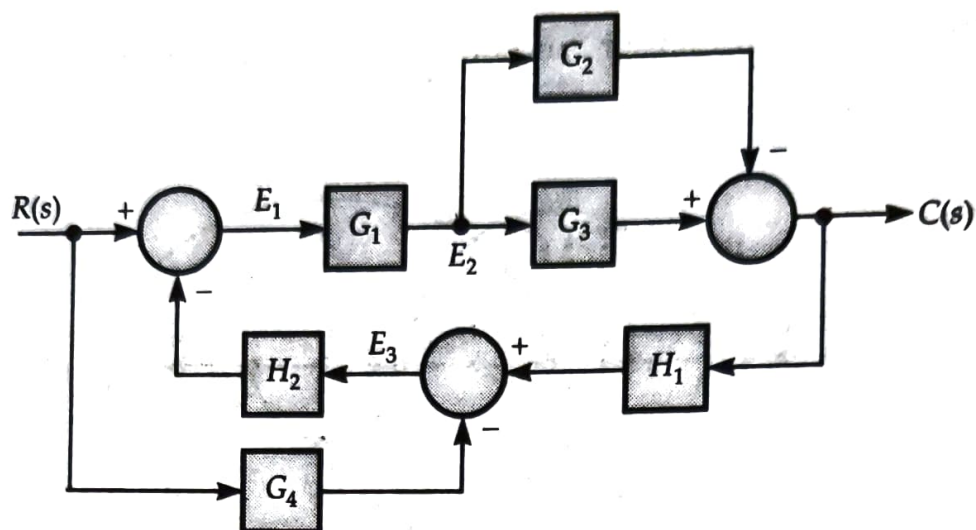


Fig. P4.6

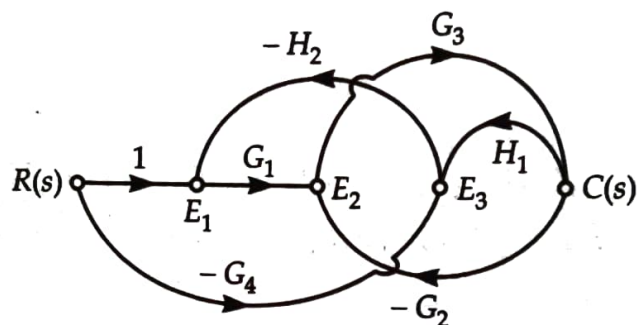
Ans.

$$\left[ \frac{Y(s)}{R(s)} = \frac{\{G_1 G_2 G_3 G_4 (1 - G_6 H_6 - G_7 H_7) + G_5 G_6 G_7 G_8 (1 - G_2 H_2 - G_3 H_3)\}}{[1 - G_2 H_2 - H_3 G_3 - G_6 H_6 - G_7 H_7 + G_2 H_2 G_6 H_6 + G_2 H_2 G_7 H_7 + G_3 H_3 G_6 H_6 + G_3 H_3 G_7 H_7]} \right]$$

13. Draw the signal flow graph and evaluate the closed-loop transfer function of a system whose block diagram is shown in Fig. P4.7(a).



(a)



(b)

Fig. P4.7

$$\text{Ans. } \left[ \frac{C(s)}{R(s)} = \frac{-G_1 G_2 + G_1 G_3 - G_1 G_2 G_4 H_2 + G_1 G_3 G_4 H_2}{1 + G_1 G_3 H_1 H_2 - G_1 G_2 H_1 H_2} \right]$$