

Reservoir Computing on Non-Linear Schrödinger Equation

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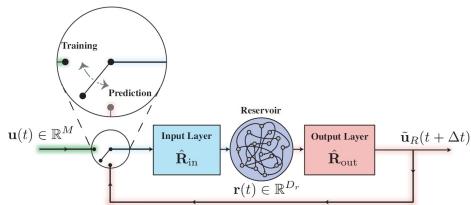
Data Driven Method for Partial Differential Equation

Frame subtitles are optional. Use upper- or lowercase letters.

- First Principle Methods: Discretize PDEs using Numerical Schemes: Finite Difference, Finite Element, Finite Volume, Spectral Methods, etc
- Data Driven Method: Incorporate Observation/Data to simulate PDEs: Physics Informed Neural Network,
- Pros/Reasoning Using DDM:
 - Learning Hidden Physics from Data (Turbulence, Wall Model)
 - Reducing Computational Cost (Reduced Order Method,)
 - Data Assimilation with observation data[5]

Reservoir Computing

- Recurrent Neural Network but only train the output layer [4]
- Fast training as only output parameters need to be optimized [1, 4]
- Does not suffer from vanishing gradient problem



Reservoir Computing for Spatiotemporal Problem

- By locality of interaction between grids, we can split the spatial domain into several reservoirs and train them independently
- internal states updates:

$$r_{i+1}^{(k)} = \tanh \left(W^{(k)} r_i^{(k)} + W_{in}^{(k)} v_i^{(k)} \right)$$

- output readout

$$y_i^{(k)} = W_{out}^{(k)} \hat{r}_i^{(k)} \quad \hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ \left(r_{ij}^{(k)} \right)^2 & j \text{ is even} \end{cases}$$

- Training Objectives

$$E^{(k)} = \min_{W_{out}^{(k)}} \sum_{i=1}^{N_{train}} \left\| W_{out}^{(k)} \hat{r}_i^{(k)} - s_i^{(k)} \right\|_2^2 + \beta \left\| W_{out}^{(k)} \right\|^2$$

Prediction Steps

- 1 Compute $y_i^{(k)} = W_{out}^k \hat{r}_i^{(k)}$
- 2 Construct $\tilde{v}_i^{(k)}$ based on $y_i^{(k-1)}, y_i^{(k)}, y_i^{(k+1)}$
- 3 Update the reservoir states: $r_{i+1}^{(k)} = \tanh \left(W^{(k)} r_i^{(k)} + W_{in}^{(k)} \tilde{v}_i^{(k)} \right)$

Outline

1 Theory

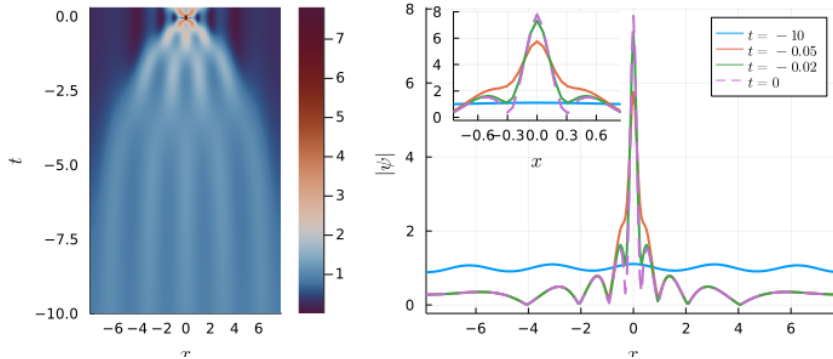
2 Result

- Non-Linear Schrödinger

Training Data

- 5th order maximum intensity breather governed by NLS equation [2]

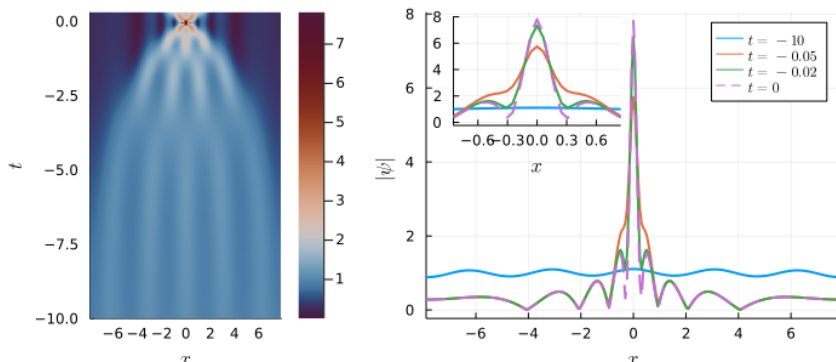
$$i \frac{\partial \psi}{\partial \tau} + \frac{1}{2} \frac{\partial^2 \psi}{\partial \xi^2} + |\psi|^2 \psi = 0$$



Training Data

- 5th order maximum intensity breather governed by NLS equation [2]

$$i \frac{\partial \psi}{\partial \tau} + \frac{1}{2} \frac{\partial^2 \psi}{\partial \xi^2} + |\psi|^2 \psi = 0$$



Simulation Hyperparameter

Parameter	Explanation	Value
ρ	Spectral Radius of W	0.6
σ	maximum elementwise magnitude of W_{in}	0.1
β	Regularization Parameter	10^{-4}
M	Number of reservoirs	32
l	Number of overlap grid	6

NLT1

$$\hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ \left(r_{ij}^{(k)}\right)^2 & j \text{ is even} \end{cases}$$

NLT2

$$\hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ |r_{ij}^{(k)}|^2 r_{ij}^{(k)} & j \text{ is even} \end{cases}$$

NLT3

$$\hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ |r_{ij}^{(k)}| r_{ij}^{(k)} & j \text{ is even} \end{cases}$$

Assessing the Result

To measure the performance, we use H^1 norm (Sobolev space norm). Let $u \in H^1$, then the norm is defined as:

$$\|u\|_{H^1} = \left[\int |u|^2 dx \right]^{\frac{1}{2}} + \left[\int |du|^2 dx \right]^{\frac{1}{2}}$$

the error is calculated at $t = 10$ (the expected peak), with error defined as:

$$e = \frac{\|\hat{\psi} - \psi\|_{H^1}}{\|\psi\|_{H^1}}$$

Hyperparameter Optimization

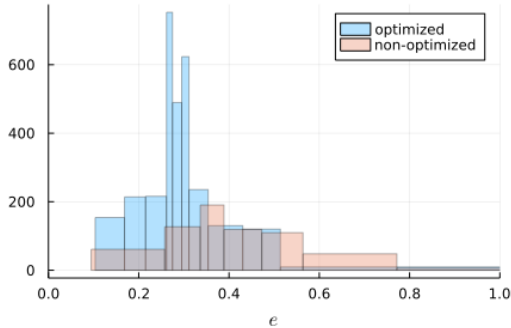
For each realization we train ESN with training data $(\psi)_{t=-10}^{t=-0.05}$, then calculate cross validation error:

$$e_{CV}(\hat{\psi}; \rho) = \int_{-0.05}^{-0.02} \frac{\|\hat{\psi} - \psi\|_{H^1}}{\|\psi\|_{H^1}} dt$$

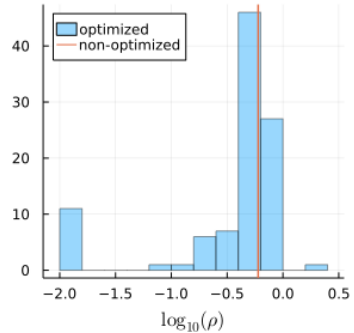
with $\log_{10} \rho \in [-2, 0.4]$. Define $\tilde{\rho} = \operatorname{argmax}_{\rho} e_{CV}$. Then train based on $(\psi)_{t=-10}^{t=-0.02}$ and $\tilde{\rho}$ and calculate e at $t = 0$

Result: Optimized vs Non-Optimized Cases

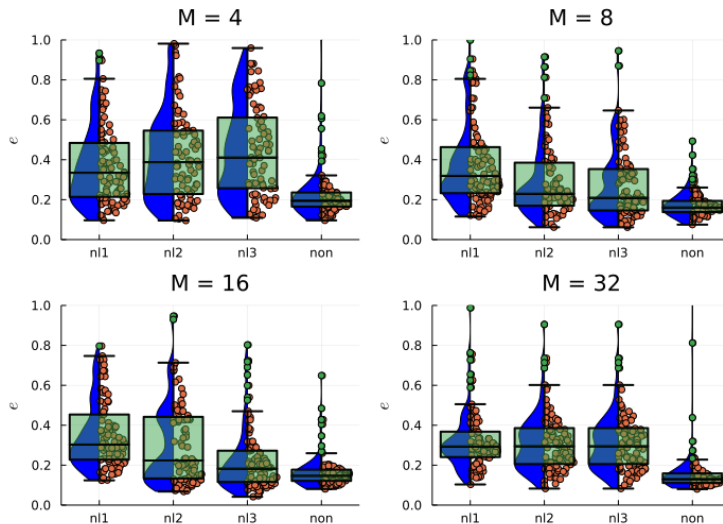
equal area histogram of error (10%)



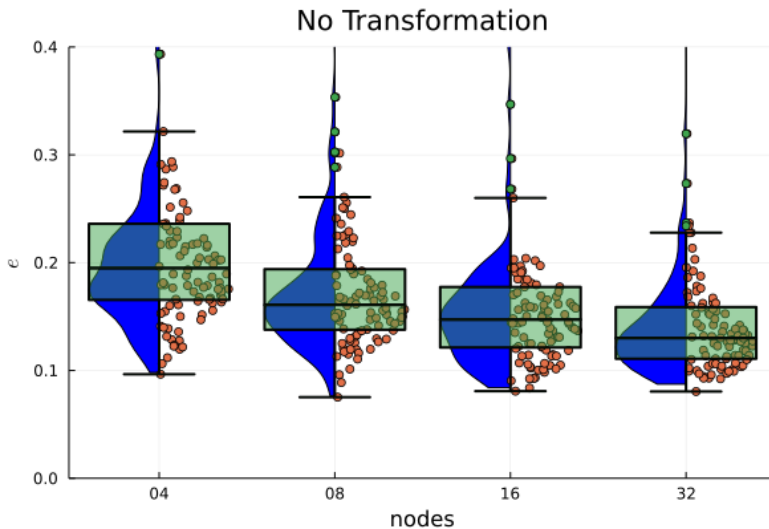
histogram of ρ



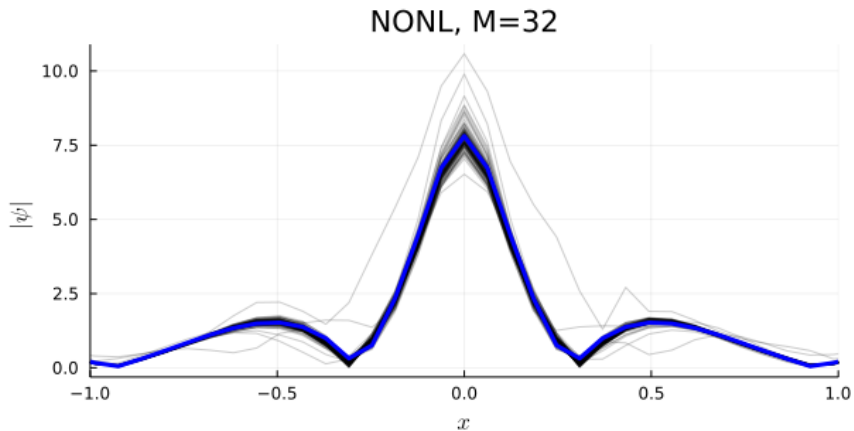
Result: Effect of Reservoir Number and NLT



Result: No Transformation



Result: NoNLT, M=32



Summary

- Spectral Radius Optimization significantly improve RC performances
- Increasing M improves RC result given optimized hyperparameter
- no non-linear transformation gives best result for NLS prediction
- Outlook
 - Can we improve optimization algorithm ? Bayesian Optimization ? [3, 6]
 - Further sensitivity studies: redo for reservoir nodes, training data length

For Further Reading I

- [1] Ashesh Chattopadhyay, Pedram Hassanzadeh, and Devika Subramanian.
Data-driven predictions of a multiscale Lorenz 96 chaotic system using machine-learning methods: Reservoir computing, artificial neural network, and long short-term memory network.
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- [3] Francisco Huhn and Luca Magri.
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For Further Reading II

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