

# Reservoir Computing on Non-Linear Schrödinger Equation

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# Outline

## 1 Theory

## 2 Result

- Verification with Lorenz-96
- Non-Linear Schrödinger

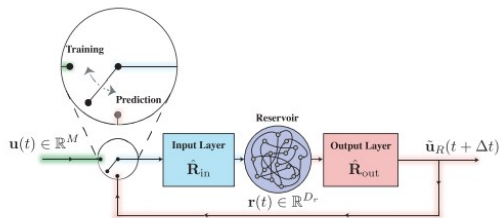
# Data Driven Method for Partial Differential Equation

Frame subtitles are optional. Use upper- or lowercase letters.

- First Principle Methods: Discretize PDEs using Numerical Schemes: Finite Difference, Finite Element, Finite Volume, Spectral Methods, etc
- Data Driven Method: Incorporate Observation/Data to simulate PDEs: Physics Informed Neural Network,
- Pros/Reasoning Using DDM:
  - Learning Hidden Physics from Data (Turbulence, Wall Model)
  - Reducing Computational Cost (Reduced Order Method, )
  - Data Assimilation with observation data[4]

# Reservoir Computing

- Recurrent Neural Network but only train the output layer [2]
- Fast training as only output parameters need to be optimized [1, 2]
- Does not suffer from vanishing gradient problem



# Reservoir Computing for Spatiotemporal Problem

- By locality of interaction between grids, we can split the spatial domain into several reservoirs and train them independently
- internal states updates:

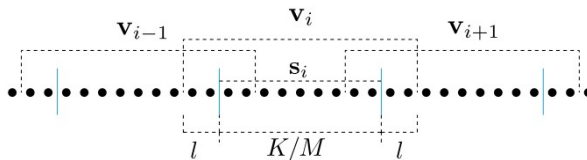
$$r_{i+1}^{(k)} = \tanh \left( W^{(k)} r_i^{(k)} + W_{in}^{(k)} v_i^{(k)} \right)$$

- output readout

$$y_i^{(k)} = W_{out}^{(k)} \hat{r}_i^{(k)} \quad \hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ \left( r_{ij}^{(k)} \right)^2 & j \text{ is even} \end{cases}$$

- Training Objectives

$$E^{(k)} = \min_{W_{out}^{(k)}} \sum_{i=1}^{N_{train}} \left\| W_{out}^{(k)} \hat{r}_i^{(k)} - s_i^{(k)} \right\|_2^2 + \beta \left\| W_{out}^{(k)} \right\|^2$$



# Prediction Steps

- 1 Compute  $y_i^{(k)} = W_{out}^k \hat{r}_i^{(k)}$
- 2 Construct  $\tilde{v}_i^{(k)}$  based on  $y_i^{(k-1)}, y_i^{(k)}, y_i^{(k+1)}$
- 3 Update the reservoir states:  $r_{i+1}^{(k)} = \tanh \left( W^{(k)} r_i^{(k)} + W_{in}^{(k)} \tilde{v}_i^{(k)} \right)$

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# Lorenz 96

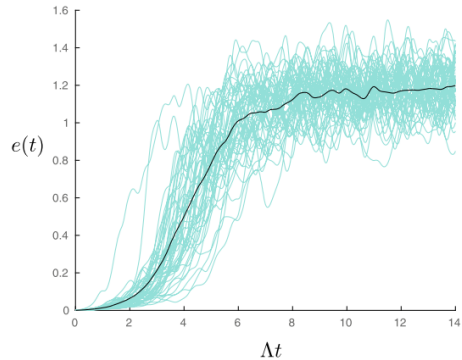
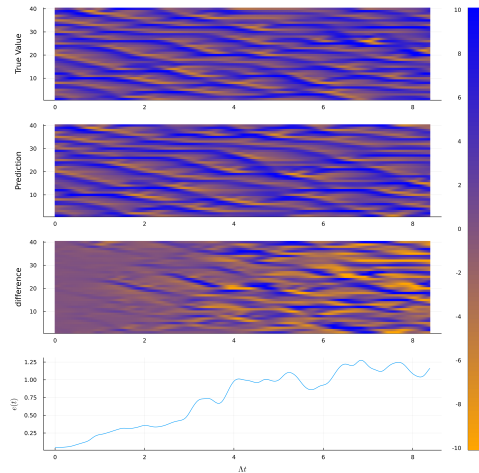
- Periodic and Chaotic ODE
- Dummy equation for atmospheric model
- Equations given by:

$$\frac{dX_j}{dt} = -X_j + X_{j-1}X_{j+1} - X_{j-1}X_{j-2} + F$$

- Training data generated by solving equation using RK orde 4 method



# Result



**Figure:** (Left) Simulation result: True Value based RK4 solution, Prediction based on Reservoir Computing, Difference (True Value - Prediction), and Root Mean Square (Right) Reference RMS based on Reservoir Computing on Non-Linear Schrödinger Equation

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## 2 Result

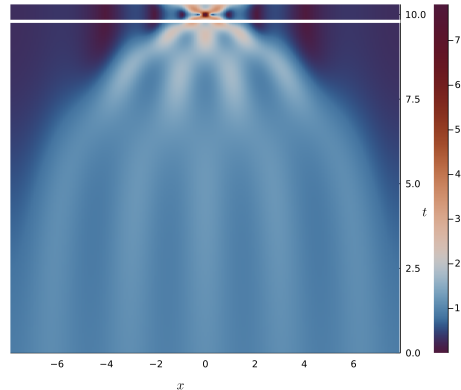
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# Non-Linear Schrödinger

- Equation given by:

$$i \frac{\partial \psi}{\partial \tau} + \frac{1}{2} \frac{\partial^2 \psi}{\partial \xi^2} + |\psi|^2 \psi = 0$$

- Can be used to modeled rogue wave
- The figure shows training and testing data for NLS. The limit of training data is given by whiteline



# Simulation Hyperparameter

Parameter	Explanation	Value
$\rho$	Spectral Radius of $W$	0.6
$\sigma$	maximum elementwise magnitude of $W_{in}$	0.1
$\beta$	Regularization Parameter	$10^{-4}$
$M$	Number of reservoirs	32
$l$	Number of overlap grid	6

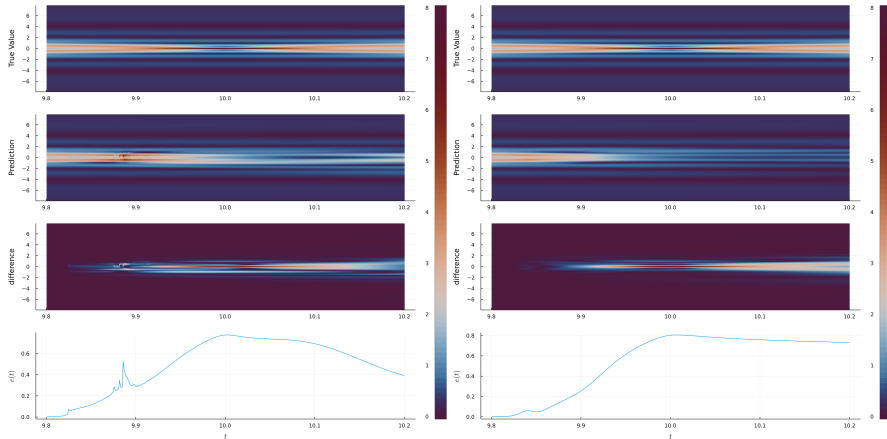
NLT1

$$\hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ \left(r_{ij}^{(k)}\right)^2 & j \text{ is even} \end{cases}$$

NLT2

$$\hat{r}_{ij}^{(k)} = \begin{cases} r_{ij}^{(k)} & j \text{ is odd} \\ \left|r_{ij}^{(k)}\right|^2 r_{ij}^{(k)} & j \text{ is even} \end{cases}$$

# Result: NLT1



**Figure:** Simulation using two different time discretization in training data: 0.01 (9800 Nt) in the left figure, 0.005 (19600 Nt) in the right figure. Both of using 4000 reservoir nodes

# Result: NLT2

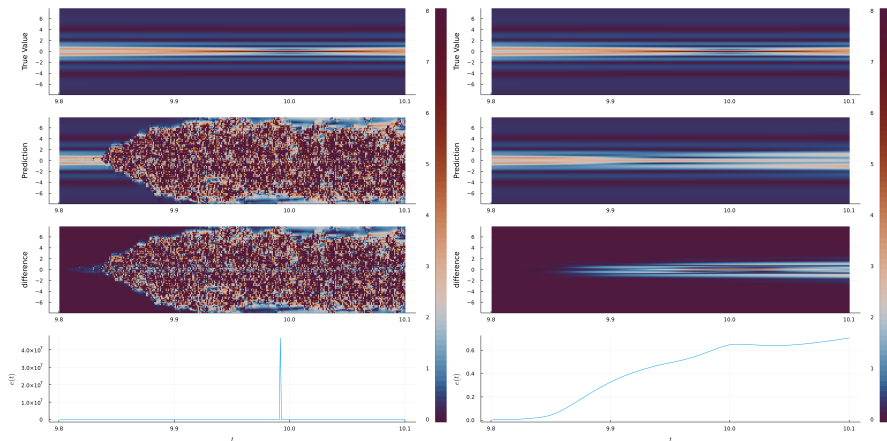


Figure: Result using different number of node in reservoir  $\Delta t = 0.01$ : left (4000), right (800)

# Result: NLT2

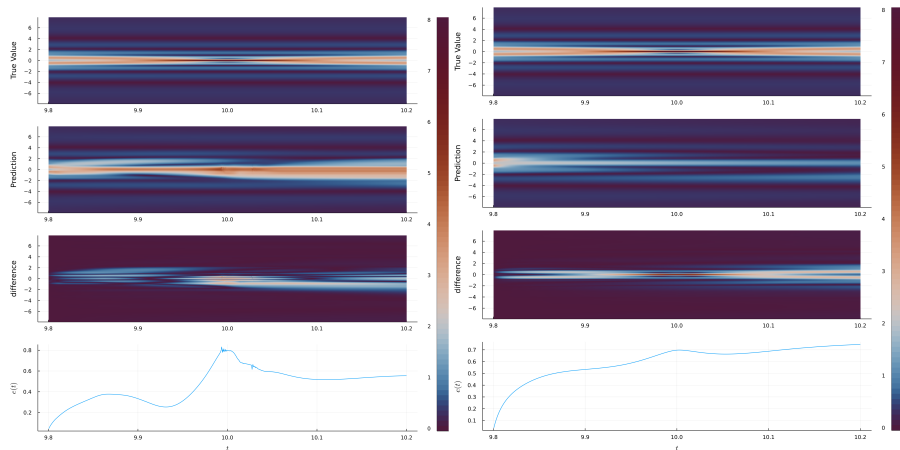





Figure: Result using different number of node in reservoir using  $\Delta t = 0.005$ : left (800), right (1600)

# Summary


- Enhancing the RC with NLT promote the expressibility of the RC
- Too much node reservoir can lead to completely wrong prediction (overfitting? )
- Finding the suitable hyperparameter for RC is not trivial
- Outlook
  - Experiment with different hyperparameter?
  - ??



# For Further Reading I

-  Ashesh Chattopadhyay, Pedram Hassanzadeh, and Devika Subramanian.  
Data-driven predictions of a multiscale Lorenz 96 chaotic system using machine-learning methods: Reservoir computing, artificial neural network, and long short-term memory network.  
*Nonlinear Processes in Geophysics*, 27(3):373–389, 2020.
-  Mantas Lukoševičius and Herbert Jaeger.  
Reservoir computing approaches to recurrent neural network training.  
*Computer Science Review*, 3(3):127–149, 2009.
-  Jaideep Pathak and Edward Ott.  
Reservoir Computing for Forecasting Large Spatiotemporal Dynamical Systems.  
In *Reservoir Computing*, pages 117–138. Springer Nature Singapore, 2021.

# For Further Reading II

-  Jaideep Pathak, Alexander Wikner, Rebeckah Fussell, Sarthak Chandra, Brian R. Hunt, Michelle Girvan, and Edward Ott.  
Hybrid forecasting of chaotic processes: Using machine learning in conjunction with a knowledge-based model.  
*Chaos*, 28(4), 2018.