

Machine Learning 1

Home Work 2

Arthur Bražiškas
University of Amsterdam

September 18, 2015

1 Posterior predictive distributions (3.2)

1.1

First of all it's important to note that t_* is scalar and therefore the likelihood is a univariate Gaussian density function, and there is no need for t_* transpose.

1.2

$$p(t_*|\underline{\phi}_*, w, \beta)p(\underline{w}|\underline{m}_N, \underline{S}_N) = \mathcal{N}(t_*|\underline{\phi}_*^T \underline{w}, \frac{1}{\beta})\mathcal{N}(\underline{w}|\underline{m}_N, \underline{S}_N) =$$

$$= \sqrt{\frac{\beta}{2\pi}} \exp(-\frac{\beta}{2}(t_* - \underline{\phi}_*^T \underline{w})^T (t_* - \underline{\phi}_*^T \underline{w})) \frac{|\underline{S}_N|^{-\frac{1}{2}}}{(2\pi)^{\frac{D}{2}}} \exp(-\frac{1}{2}(\underline{w} - \underline{m}_N)^T \underline{S}_N^{-1}(\underline{w} - \underline{m}_N))$$

Now we set $C_L = \sqrt{\frac{\beta}{2\pi}}$ to be the constant of the likelihood, and $C_P = \frac{|\underline{S}_N|^{-\frac{1}{2}}}{(2\pi)^{\frac{D}{2}}}$ to be our posterior constant.

$$= C_L C_P \exp(-\frac{\beta}{2}(t_* - \underline{\phi}_*^T \underline{w})^T (t_* - \underline{\phi}_*^T \underline{w})) \exp(-\frac{1}{2}(\underline{w} - \underline{m}_N)^T \underline{S}_N^{-1}(\underline{w} - \underline{m}_N)) =$$

Next we expand our exponent terms.

$$= C_L C_P \exp(-\frac{1}{2}(\beta t_* t_* - \beta t_* \underline{\phi}_*^T \underline{w} - \beta t_* \underline{\phi}_*^T \underline{w} + \beta \underline{\phi}_*^T \underline{w} \underline{\phi}_*^T \underline{w} + \underline{w}^T \underline{S}_N^{-1} \underline{w} - \underline{w}^T \underline{S}_N^{-1} \underline{m}_N - \underline{m}_N^T \underline{S}_N^{-1} \underline{w} + \underline{m}_N^T \underline{S}_N^{-1} \underline{m}_N))$$

Now we are going to collect all the terms that depend on w in one exponent, and the rest in another one. And we simplify our clauses.

$$= C_L C_P \exp(-\frac{1}{2}(\underline{w}^T (\beta \underline{\phi}_*^T \underline{\phi}_* + \underline{S}_N^{-1}) \underline{w} - 2 \underline{w}^T (\beta \underline{\phi}_*^T t_* + \underline{S}_N^{-1} \underline{m}_N))) \exp(-\frac{1}{2}(\beta t_* t_* + \underline{m}_N^T \underline{S}_N^{-1} \underline{m}_N))$$

In the next step we set $S_{N+1}^{-1} = \beta \underline{\phi}_{*}^T \underline{\phi}_{*} + S_N^{-1}$ and $\underline{S}_{N+1}^{-1} m_{N+1} = \beta \underline{\phi}_{*}^T t_{*} + S_N^{-1} m_N$ and rewrite our expression accordingly.

$$= C_L C_p \exp(-\frac{1}{2}(\underline{w}^T S_{N+1}^{-1} \underline{w} - 2 \underline{w}^T S_{N+1}^{-1} m_{N+1})) \exp(-\frac{1}{2}(\beta t_{*}^T t_{*} + m_N^T S_N^{-1} m_N))$$

1.3

Next we complete the square for \underline{w} by adding $m_{N+1}^T S_{N+1}^{-1} m_{N+1}$ to the exponent with \underline{w} terms and subtract from the second exponent.

$$= C_L C_p \exp(-\frac{1}{2}(\underline{w}^T S_{N+1}^{-1} \underline{w} - 2 \underline{w}^T S_{N+1}^{-1} m_{N+1} + m_{N+1}^T S_{N+1}^{-1} m_{N+1})) \exp(-\frac{1}{2}(\beta t_{*}^T t_{*} + m_N^T S_N^{-1} m_N - m_{N+1}^T S_{N+1}^{-1} m_{N+1}))$$

As we will need m_{N+1} and $m_{N+1}^T S_{N+1}^{-1} m_{N+1}$ in the future, we going to solve for it now.

$$\underline{S}_{N+1}^{-1} m_{N+1} = \beta \underline{\phi}_{*}^T t_{*} + S_N^{-1} m_N$$

$$m_{N+1} = S_{N+1}(\beta \underline{\phi}_{*}^T t_{*} + S_N^{-1} m_N) = (S_{N+1}^{-1} = \beta \underline{\phi}_{*}^T \underline{\phi}_{*} + S_N^{-1})^{-1}(\beta \underline{\phi}_{*}^T t_{*} + S_N^{-1} m_N)$$

$$m_{N+1}^T S_{N+1}^{-1} m_{N+1} = (\beta \underline{\phi}_{*}^T t_{*} + S_N^{-1} m_N)^T S_{N+1}(\beta \underline{\phi}_{*}^T t_{*} + S_N^{-1} m_N)$$

1.4

After a bit of simplifications we obtain the \underline{w} exponential in a Gaussian form:

$$p(t_{*} | \underline{\phi}_{*}, \underline{w}, \beta) p(\underline{w} | \underline{m}_N, \underline{S}_N) =$$

$$= C_L C_p \exp(-\frac{1}{2}[(\underline{w} - m_{N+1})^T S_{N+1}^{-1} (\underline{w} - m_{N+1})]) \exp(-\frac{1}{2}(m_N^T S_N^{-1} m_N + \beta t_{*}^T t_{*} - m_{N+1}^T S_{N+1}^{-1} m_{N+1}))$$

So now as we have a joint of likelihood and posterior we can integrate over \underline{w} .

$$p(t_{*} | \underline{\phi}_{*}, \underline{\phi}, t, \alpha, \beta) = \int p(t_{*} | \underline{\phi}_{*}, \underline{w}, \beta) p(\underline{w} | \underline{m}_N, \underline{S}_N) d\underline{w} =$$

Now we set $\frac{1}{C_w} = \int \exp(-\frac{1}{2}[(\underline{w} - m_{N+1})^T S_{N+1}^{-1} (\underline{w} - m_{N+1})]) d\underline{w}$, and as the second exponent does not depend on \underline{w} it remains present the equation outside of the integral.

$$= \frac{C_L C_p}{C_w} \exp(-\frac{1}{2}(m_N^T S_N^{-1} m_N + \beta t_{*}^T t_{*} - m_{N+1}^T S_{N+1}^{-1} m_{N+1}))$$

1.5

What we obtain in the exponent is not in a Gaussian form, so we will expand the $m_{N+1}^T S_{N+1}^{-1} m_{N+1}$ term see sub-section 1.3, and will collect linear and squared terms of t_* as a first step of obtaining the form we want.

$$\begin{aligned}
& m_N^T S_N^{-1} m_N + \beta t_* t_* - m_{N+1}^T S_{N+1}^{-1} m_{N+1} = \\
& m_N^T S_N^{-1} m_N + \beta t_* t_* - (\beta \underline{\phi}_{\underline{*}}^T t_* + S_N^{-1} m_N)^T S_{N+1} (\beta \underline{\phi}_{\underline{*}}^T t_* + S_N^{-1} m_N) = \\
& = m_N^T S_N^{-1} m_N + \beta t_* t_* - m_{N+1}^T S_{N+1}^{-1} m_{N+1} = \\
& = m_N^T S_N^{-1} m_N + \beta t_* t_* - \beta \beta t_* t_* \underline{\phi}_{\underline{*}}^T S_{N+1} \underline{\phi}_{\underline{*}} - \beta t_* \underline{\phi}_{\underline{*}}^T S_{N+1} S_N^{-1} m_N - \beta t_* \underline{\phi}_{\underline{*}}^T S_{N+1} S_N^{-1} m_N - S_N^{-1} m_N S_{N+1} S_N^{-1} m_N =
\end{aligned}$$

Now we collect the terms of t_* . Remember that t_* is scalar and not a vector.

$$\begin{aligned}
& t_*^2 (\beta \underline{I} - \beta^2 \underline{\phi}_{\underline{*}}^T S_{N+1} \underline{\phi}_{\underline{*}}) - 2 t_* (\beta \underline{\phi}_{\underline{*}}^T S_{N+1} S_N^{-1} m_N) + m_N^T S_N^{-1} m_N - S_N^{-1} m_N S_{N+1} S_N^{-1} m_N = \\
& = t_*^2 \beta_* - 2 t_* \beta_* y_* + y_*^T \beta_* y_*
\end{aligned}$$

Where

$$\begin{aligned}
\beta_* &= \beta \underline{I} - \beta^2 \underline{\phi}_{\underline{*}}^T S_{N+1} \underline{\phi}_{\underline{*}} \\
\beta_* y_* &= \beta \underline{\phi}_{\underline{*}}^T S_{N+1} S_N^{-1} m_N \\
y_*^T \beta_* y_* &= m_N^T S_N^{-1} m_N - S_N^{-1} m_N S_{N+1} S_N^{-1} m_N
\end{aligned}$$

1.6

Now we are going to solve for β_* by expanding S_{N+1} and by using Woodbury identity.

$$\begin{aligned}
\beta_* &= \beta \underline{I} - \beta^2 \underline{\phi}_{\underline{*}}^T S_{N+1} \underline{\phi}_{\underline{*}} = \beta \underline{I} - \beta \underline{I} \underline{\phi}_{\underline{*}} (\beta \underline{\phi}_{\underline{*}}^T \underline{\phi}_{\underline{*}} + S_N^{-1})^{-1} \underline{\phi}_{\underline{*}}^T \beta \underline{I} \\
&= \beta \underline{I} - \beta \underline{I} \underline{\phi}_{\underline{*}} (S_N^{-1} + \underline{\phi}_{\underline{*}}^T \beta \underline{I} \underline{\phi}_{\underline{*}})^{-1} \underline{\phi}_{\underline{*}}^T (\beta \underline{I}) = \left(\frac{1}{\beta} + \underline{\phi}_{\underline{*}}^T S_N \underline{\phi}_{\underline{*}} \right)^{-1}
\end{aligned}$$

1.7

Now we are going to solve for y_* by expanding S_{N+1} and β_* , and by doing some simplifications .

$$\begin{aligned}
\beta_* y_* &= \beta \underline{\phi}_* S_{N+1} S_N^{-1} m_N \\
y_* &= \beta_*^{-1} \beta \underline{\phi}_* (\beta \underline{\phi}_*^T \underline{\phi}_* + S_N^{-1})^{-1} S_N^{-1} m_N = \\
&= \left(\frac{1}{\beta} + \underline{\phi}_*^T S_N \underline{\phi}_* \right) \beta \underline{\phi}_* (S_N^{-1} + \beta \underline{\phi}_*^T \underline{\phi}_*)^{-1} S_N^{-1} m_N \\
&= \underline{\phi}_* [(\underline{I} + \beta S_N \underline{\phi}_*^T \underline{\phi}_*) (S_N^{-1} + \beta \underline{\phi}_*^T \underline{\phi}_*)^{-1} S_N^{-1}] m_N = \\
&= \underline{\phi}_* [S_N S_N^{-1} (\underline{I} + \beta S_N \underline{\phi}_*^T \underline{\phi}_*) (S_N^{-1} + \beta \underline{\phi}_*^T \underline{\phi}_*)^{-1} S_N^{-1}] m_N = \\
&= \underline{\phi}_* [S_N (S_N^{-1} + \beta \underline{\phi}_*^T \underline{\phi}_*) (S_N^{-1} + \beta \underline{\phi}_*^T \underline{\phi}_*)^{-1} S_N^{-1}] m_N =
\end{aligned}$$

Now using the rule of matrix multiplication by it's inverse we simplify everything an obtain:

$$= \underline{\phi}_* m_N$$

1.8

Since we obtained solutions for y_* and β_* we can plug them into the Gaussian form of the posterior predictive distribution.

$$p(t_* | \underline{\phi}_*, t, \underline{\Phi}, \alpha, \beta) = \mathcal{N}(t_* | y_*, \frac{1}{\beta_*}) = \mathcal{N}(t_* | \underline{\phi}_* m_N, \frac{1}{\beta} + \underline{\phi}_*^T S_N \underline{\phi}_*)$$