Komework 5 Arthur Braziuskas 11138904 J(a, R, &, L, V) = R2 + C \(\xi \xi_i - \xi \Li \xi_i (-11x; -a112 R2;) - \xi \xi_i \xi_i \xi_i (constraint) N2 1) 2: 7,0 2) gi 7/0 => -11 x; - a11 - R + &; 7/0 5) &i 7/0 For i = 1... N 3) Lig; =0 6) Hi&i=0 In addition we seach for $\nabla f = \lambda \nabla g$ so $\forall \nabla_a J = 0 \Rightarrow -\frac{\chi}{2} - 2 \cdot \lambda_i (x_i - g) (-1) = 0 \Rightarrow \frac{\chi}{2} \lambda_i \chi_i = \frac{\chi}{2} \lambda_i g$ $\Rightarrow a = \underbrace{\stackrel{\vee}{\neq}}_{i=1}^{\vee} \underbrace{\lambda_i \times i}_{i=1} \left(a = \underbrace{\stackrel{\vee}{\neq}}_{i=1}^{\vee} \underbrace{\lambda_i \times i}_{i=1}^{\vee} \left(a = \underbrace{\stackrel{\vee}{\neq}}_{i=1}^{\vee} \underbrace{\lambda_i \times i}_{i=1}^{\vee} \right) \right)$ 8) VRJ = 0 => 1- = Li = 0 => (= Li = 1) 9) 76; 1=0 => C-21-11: => (21=C-N) (1012) Complete slackness conditions are: 3) and @: Ligi = 0 and pi &i = 0 for i=1. N 1) if d: >0 then g; must be O, so: +11x; -all+R+&; =0 => => 11x:-all= R+Eqi, so the point x; is either outside of the circle or on the border, depending on &. -2) if pi70 then &i =0, so x; is inside of the circle or on the Bordor (SV) g= R2+C= 8; - 2; (-1/x; - 2, d) x) + R2+ 6;)- 2 p; 6; = = P3+ C = &; + \(\frac{1}{2} \) \(\frac{1}{2} = C \(\frac{\times}{\xi}\) + \(\frac{\times}{\xi}\) \(\frac{\times}{\xi}\) + \(\frac{\times}{\xi

Ny (continue é) | N | 2 | N | 0; 0; 0; $= \sum_{i=1}^{N} d_i ||x_i - \sum_{j=1}^{N} d_j x_j||^2 = \sum_{i=1}^{N} d_i (x_i - \sum_{j=1}^{N} d_j x_j)^{\mathsf{T}} (x_i - \sum_{j=1}^{N} d_j x_j) =$ $= \sum_{i=1}^{N} \lambda_i \left(x_i^T x_i - 2 x_i^T \sum_{j=1}^{N} \lambda_j x_j + \sum_{j=1}^{N} \lambda_j x_j^T \sum_{m=1}^{N} \lambda_m x_m \right) = \int_{1 \text{ denoted}}^{1 \text{ hose Become}} \frac{1}{1 \text{ denoted}}$ $= \underbrace{\times}_{1} \underbrace{\lambda_{i}}_{1} \underbrace{\times_{1}}_{1} \underbrace{\times_{1}}_{2} \underbrace{\times_{1}}_{2} \underbrace{\lambda_{i}}_{1} \underbrace{\lambda_{j}}_{2} \underbrace{\times_{1}}_{3} \underbrace{\times_{1}}_{4} \underbrace{\times_{1}}_{4} \underbrace{\times_{1}}_{3} \underbrace{\times_{1}}_{4} \underbrace{\times_{$ = (\frac{\xi}{1} \lambda k(\xi, \xi) + \frac{\xi}{2} \frac{\xi}{2} d \gamma d \gamma m k(\xi, \xm) \in dual hernalized problem objective funce) N5 1) Li=C-Vi = Li-C=-Vi = (Pi=C-Li) 2) $(a = \underbrace{\xi}_{i} \lambda_{i}, \chi_{i})$ 3) if g; = 0: $Ei = ||x_i - a||^2 - R^2$, and Ei > 0 for outliers: (we shall replace a and R^2 in (5)) 4) Our Radius depends on the support vectors, so we can continue the Van of the eq. in 3 and get (R= 1 = 11x; = 11x; = 11x) Notice that our R is computed by taking an averaged sum over Manpport vectors, and we know that for S.V. E: gor i= 1...M 5) Now we rewrite 3 and soy that E = 0 of X; is the s. V. or or &; = ||x; - \frac{1}{2} \(\lambda_i \times | \) \(\lambda_i \times | \lambda_i \time The latter case of Ep; is for Xi that are outliers.

y(x;) = 11x; -a112 R270 for outliers, now we dualize and hernalize $||x_i - \underbrace{\xi}_{j=1} d_j x_j||^2 - \underbrace{1 \underbrace{\xi}_{j=1} ||x_j - \underbrace{\xi}_{m=1} d_m x_m||^2}_{\mathcal{L}_m \times_m ||x_j||^2} > 0 \Rightarrow (\text{we apply the same Andle})$ $\Rightarrow (x_i - \underbrace{\xi}_{J=1}^{\mathcal{X}} \lambda_J x_J)^{\mathsf{T}} (x_i - \underbrace{\xi}_{J=1}^{\mathcal{X}} \lambda_J) \geq \underbrace{1}_{\mathcal{U}_{J=1}^{\mathcal{X}}} \underbrace{1}_{\mathcal{U}_{J}} \underbrace{1}_{\mathcal{$ $\Rightarrow x \cdot x_{i} - 2 \xrightarrow{V} d_{ij} x_{i} x_{j} + \underbrace{Z}_{j=1}^{N} d_{jm} x_{j} x_{m} \cdot 1 \xrightarrow{X_{j}^{N}} \underbrace{Z}_{j=1}^{N} \underbrace{Z}_{m=1}^{N} d_{im} x_{j} x_{m} + \underbrace{Z}_{m=1}^{N} \underbrace{Z}_{m} d_{im} x_{j} x_{m} + \underbrace{Z}_{m=1}^{N} d_{im} x_{j} x_{m} + \underbrace{Z}_{m=1}^{N$ 13. I's not obvious, then we could phink that if the equation is satisfied, then x: is an outlier. 1) if C=O, the cost for outliers 150 zero, so we will end up having small R > 0 and a lot of outliers. 2) if C=00, the radius will cover nevely every point, so that we will not have any outliers. k(xi, xy) = exp(-1/xi-xy112), so this hernal measuring the similarity of two vectors will durn into a binary identicities function Junction of 500 of the problem it will mean the following the problem is 3. (egrdoon sketales) small o Thus if & is too small it will lead to a lot of outliers.
during the test unless dest points similarity is are identical to the training data points. Dolf Xi 1-1. Norain points) small 8 aver. S

N8 (consinued) The difference between linear hernal and gaussian & based solutions is that
for X and X' pair with increase of X' the linear hernal quelpteds
will increase linearly while the gaussian thernals with very small &
will return values close to OGS X and X' start to differ. We rewrite our objective function sightly and introduce a hingle $J(a,R) = R^2 + C \stackrel{\sim}{\geq} \max(0, -+; y(x,))$ $y(xi) = 1|x_i - a|^2 - R^2$ Induition is the pallowing. 1) if y;=y(x;)= O, we have a support vector X; and the cost is O 2) if y; <0-x; is infor. 3) if y; 70 - Xi is outlier. E.g. += -1 and y = 1000 , then the cost is C-1000 as x; should have been on inlier but was classified as an outlier.