

# Proposal Defense

## Towards a Framework for DHT Distributed Computing

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- ChordReduce
- VHash
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- UrDHT
- DHT Distributed Computing

# Objective

Our objective is to create a generalized framework for distributed computing using Distributed Hash Tables.

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Or

We want to build a completely decentralized distributed computing framework.

# What do I Mean by Distributed Computing?

A system where we can take a task and break it down into multiple parts, where each part is worked upon individually.

# Challenges of Distributed Computing

Distributed Computing platforms should be:

**Scalable** The larger the network, the more resources need to be spent on maintaining and organizing the network.

# DHT Distributed Computing

## └ Introduction

## └ Distributed Computing and Challenges

## └ Challenges of Distributed Computing

Distributed Computing platforms should be:

[Scalable](#) The larger the network, the more resources need to be spent on maintaining and organizing the network.

Remember, computers aren't telepathic. There's always an overhead cost. It will grow. The challenge of scalability is designing a protocol that grows this organizational cost at an extremely slow rate. For example, a single node keeping track of all members of the system might be a tenable situation up to a certain point, but eventually, the cost becomes too high for a single node.



# Challenges of Distributed Computing

Distributed Computing platforms should be:

**Scalable** The larger the network, the more resources need to be spent on maintaining and organizing the network.

**Fault-Tolerant** As we add more machines, we need to be able to handle the increased risk of hardware failure.

# DHT Distributed Computing

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  - └ Distributed Computing and Challenges
    - └ Challenges of Distributed Computing

Distributed Computing platforms should be:

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**Fault-Tolerant** As we add more machines, we need to be able to handle the increased risk of hardware failure.

Hardware failure is a thing that can happen. Individually the chances are low, but this becomes high when we're talking about millions of machines. Also, what happens in a P2P environment.

# Challenges of Distributed Computing

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**Load-Balancing** Tasks need to be evenly distributed among all the workers.

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**Fault-Tolerant** As we add more machines, we need to be able to handle the increased risk of hardware failure.

**Load-Balancing** Tasks need to be evenly distributed among all the workers.

If we are splitting the task into multiple parts, we need some mechanism to ensure that each worker gets an even (or close enough) amount of work.

# Distributed Key/Value Stores

**Distributed Hash Tables** are mechanisms for storing values associated with certain keys.

- Values, such as filenames, data, or IP/port combinations are associated with keys.
- These keys are generated by taking the hash of the value.
- We can get the value for a certain key by asking any node in the network.

# Current Applications

Applications that use or incorporate DHTs:

- P2P File Sharing applications, such as Bittorrent [1] [4].
- Distributed File Storage [2].
- Distributed Machine Learning [3].
- Name resolution in a large distributed database [5].

# How Does It Work?

We'll explain in greater detail later, but briefly:

- DHTs organize a set of nodes, each identified by an **ID** (their key).
- Nodes are responsible for the keys that are closest to their IDs.
- Nodes maintain a list of other peers in the network.
  - Typically a size  $\log(n)$  subset of all nodes in the network.
- Each node uses a very simple routing algorithm to find a node responsible for any given key.

# DHT Distributed Computing

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We use ID for nodes and keys for data so we always know our context.



# Strengths of DHTs

DHTs are designed for large P2P applications, which means they need to be (and are):

## Scalable

- Each node knows a *small* subset of the entire network.
- Join/leave operations impact very few nodes.

## Fault-Tolerant

- The network is decentralized.
- DHTs are designed to handle **churn**.

## Load-Balancing

- Consistent hashing ensures that nodes and data are close to evenly distributed.
- Nodes are responsible for the data closest to it.

## DHT Distributed Computing

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## What Are Distributed Hash Tables?

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- Fault-Tolerant**
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- Load-Balancing**
  - Consistent hashing ensures that nodes and data are close to evenly distributed.
  - Nodes are responsible for the data closest to it.

- Remember to mention Napster.
- Distributed Hash Tables were designed to be used for completely decentralized P2P applications involving millions of nodes.
- As a result of the P2P focus, DHTs have the following qualities.
- Scalability
  - The subset each node knows is such that we have expected  $\lg(n)$  lookup
- Fault-Tolerance
  - Because Joins and node failures affect only nodes in the immediate vicinity, very few nodes are impacted by an individual operation.
- Load Balancing
  - The space is large enough to avoid Hash collisions

# DHTs Address the Specified Challenges

The big issues in distributed computing can be solved by the mechanisms provided by Distributed Hash Tables.

# Uses For DHT Distributed Computing

- Embarrassingly Parallel Computations
  - Brute force cryptography.
  - Genetic algorithms.
  - Markov chain Monte Carlo methods.
  - Any problem that can be framed using Map and Reduce.
- Can be used in either a P2P context or a more traditional deployment.

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## └ Introduction

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## └ Uses For DHT Distributed Computing

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- Need notes here
- Define Monte-Carlo Markov Chain

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# Attributes of DHT

- A distance and midpoint function.
- A closeness definition.
- A Peer management strategy.

└ Background

└ The Components and Terminology

└ Attributes of DHT

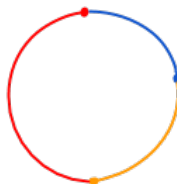
- A distance and midpoint function.
- A closeness definition.
- A Peer management strategy.

- There needs to be a way to establish how far things are from one another. Once we have a distance metric, we define what we mean when we say a node is responsible for all data *close* to it.
- We'll go into more detail about the difference between Distance and Closeness in Chord



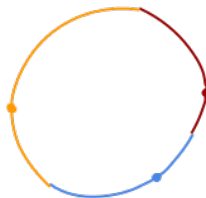
# Chord's Closest Metric.

**Figure :** A Voronoi diagram for a Chord network, using Chord's definition of closest.



# Chord Using A Different Closest Metric

**Figure :** A Voronoi diagram for a Chord network, where closest is defined by the node being the closest in either direction.



# Terms and Variables

- Network size is  $n$  nodes.
- Keys and IDs are generated  $m$  bit hash, usually SHA1.
- Peerlists are made up of:
  - **Short Peers** The neighboring nodes that define the network's topology.
  - **Long Peers** Routing shortcuts.
- We'll call the node responsible for a key the *root* of the key.

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- SHA1 is being depreciated.
- Short peers are actively maintained, long peers replaced gradually and are not actively pinged.
- We use root as it's is a topology agnostic term.

# Functions

`lookup(key)` Finds the node responsible for a given key.

`put(key, value)` Stores *value* at the node responsible for *key*,  
where  $key = hash(value)$ .

`get(key)` Returns the *value* associated with *key*.

└ Background

└ The Components and Terminology

└ Functions

`lookup(key)` Finds the node responsible for a given key.  
`put(key, value)` Stores value at the node responsible for `key`,  
where  $key \leftarrow \text{hash}(\text{value})$ .  
`get(key)` Returns the value associated with `key`.

- There is usually a delete function as well, but it's not important.
- All nodes use the same general lookup: Forward the message to the node closest to *key*

# Chord

- Ring Topology
- Short Peers: predecessor and successor in the ring.
- Responsible for keys between their predecessor and their own.
- Long Peers:  $\log n$  nodes, where the node at index  $i$  in the peerlist is

$$\text{root}(r + 2^{i-1}) \mod m, 1 < i < m$$

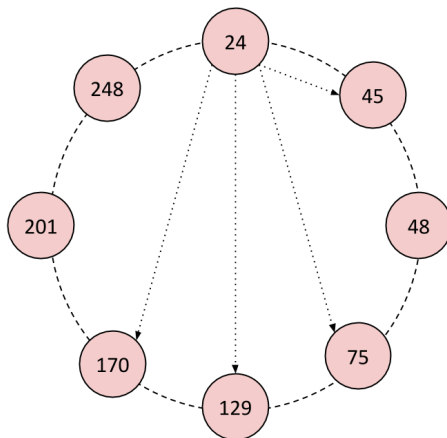
- ✓ Ring Topology
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- Chord is a favorite because we can draw it.
- Draw a Chord network on the wall?
- node  $r$  is our root node.
- $i$  is the index on the list
- English for the equation, the long peers double in distance from the root node, allowing us to cover at least half the distance to our target in a step
- In this way, we can achieve an expected  $\lg n$  hops.



# A Chord Network



**Figure :** An 8-node Chord ring where  $m = 8$ . Node 24's fingers are shown.

# Fault Tolerance in Chord

- Local maintenance thread gradually fixes the network topology.
  - Each node “notifies” its successor.
  - The successor replies with a better successor if one exists.
- The long peers are gradually updated by performing a lookup on each entry.
- Some implementations use predecessor and successor lists.

# Handling Churn in General

- Short peers, the neighbors, are periodically queried to:
  - See if the node is still alive.
  - See if the neighbor knows about better nodes.
- Long peer failures are replaced by regular maintenance.

# Other DHTs

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# ChordReduce

content

# Churn Results

Churn rate per second	Average runtime (s)	Speedup vs 0% churn
0.8%	191.25	2.15
0.4%	329.20	1.25
0.025%	431.86	0.95
0.00775%	445.47	0.92
0.00250%	331.80	1.24
0%	441.57	1.00

**Table :** The results of calculating  $\pi$  by generating  $10^8$  samples under churn. Churn is the chance for each node to join or leave the network. The large speedup is from joining nodes acquiring work during experimental runtime.

# DHT and Voronoi Relationship

- Most DHTs optimize routing for the number of hops, rather than latency.
- We discovered a mapping between Distributed Hash Tables and Voronoi/Delaunay Triangulations.



# Voronoi Tessellation

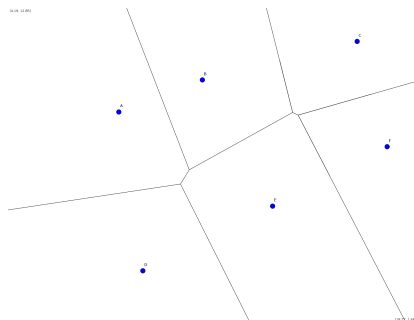


Figure : A set of points and the generated Voronoi regions

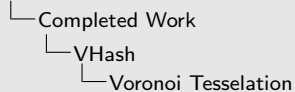


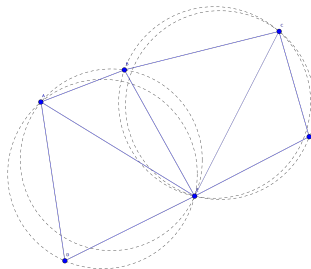
Figure : A set of points and the generated Voronoi regions

## Define

- Voronoi generators
- Voronoi Region
- Voronoi Tessellation/ Diagram

# Delaunay Triangulation

04.04.12.001



08.07.1.001

**Figure :** The same set of nodes with their corresponding Delaunay Triangulation.

# DHT and Voronoi Relationship

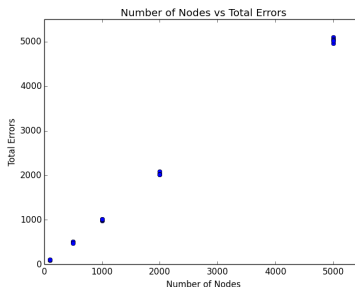
- Coprime
- We can view DHTs in terms of Voronoi and Delaunay
  - The set of keys the node is responsible for is its Voronoi region.
  - The nodes neighbors are it's Delaunay neighbors.

# VHash

- Voronoi-based Distributed Hash Table

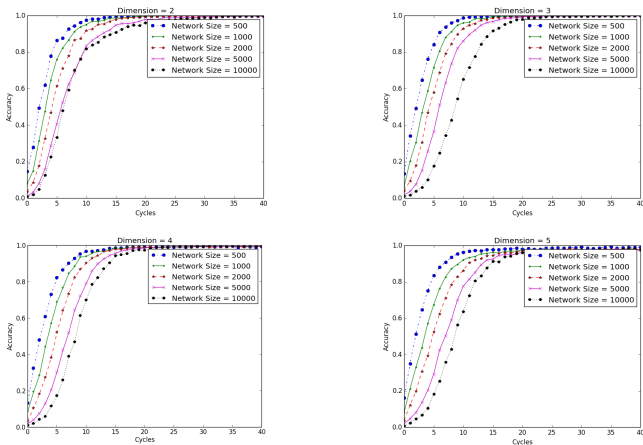
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# Results



**Figure :** As the size of the graph increases, we see approximately 1 error per node. We can also see that the error rate and number of nodes has a linear relationship.

# Results



**Figure :** These figures show, starting from a randomized network, VHash forms a stable and consistent network topology.



# The Sybil Attack

- The

# The goal of the Sybil Attack in A P2P network

See Whiteboard

- We want to inject a Sybil into as many of the regions between nodes as we can.
- The question I wanted to answer is what is the probability that a region can have a Sybil injected into it, given:
  - The network size  $n$
  - The number of keys (IDs) available to the attacker (the number of identities they can fake).

# Assumptions

- The attacker is limited in the number of identities they can fake.
  - To fake an identity, the attacker must be able to generate a valid IP/port combo he owns.
  - The attacker therefore has  $num\_IP \cdot num\_ports$  IDs.
  - We'll set  $num\_ports = 16383$ , the number of ephemeral ports.
  - Storage cost is 320 KiB.
- We call the act of finding an ID by modulating your IP and port so you can inject a node *mashing*.
- In Mainline DHT, used by BitTorrent, you can choose your own ID at “random.” The implications should be apparent.

# Analysis

The probability you can mash a region between two adjacent nodes in a size  $n$  network is:

$$P \approx \frac{1}{n} \cdot \text{num\_ips} \cdot \text{num\_ports} \quad (1)$$

An attacker can compromise a portion  $P_{bad\_neighbor}$  of the network given by:

$$P_{bad\_neighbor} = \frac{\text{num\_ips} \cdot \text{num\_ports}}{\text{num\_ips} \cdot \text{num\_ports} + n - 1} \quad (2)$$

## DHT Distributed Computing

└ Completed Work

└ Sybil Attack Analysis

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- Have proofs!

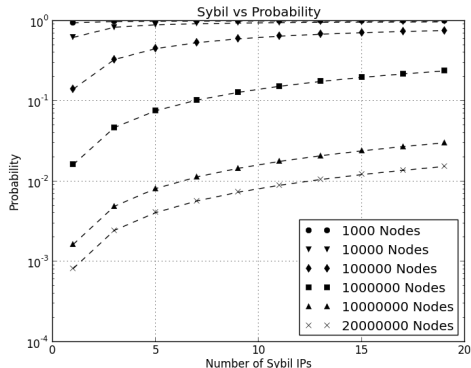
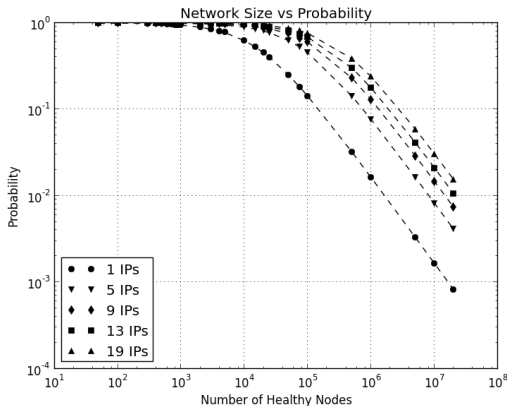
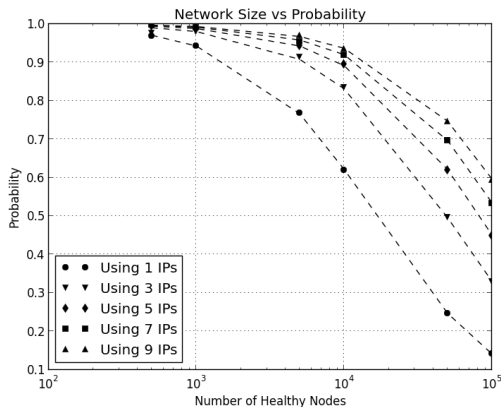


Figure : Our simulation results. The x-axis corresponds to the number of IP addresses the adversary can bring to bear. The y-axis is the probability that a random region between two adjacent normal members of the network can be mashed. Each line maps to a different network size of  $n$ . The dotted line traces the line corresponding to the Equation 2:

$$P_{bad\_neighbor} = \frac{num\_ips \cdot 16383}{num\_ips \cdot 16383 + n - 1}$$



**Figure :** These are the same as results shown in Figure 8, but our  $x$ -axis is the network size  $n$  in this case. Here, each line corresponds to a different number of unique IP addresses the adversary has at their disposal.



**Figure :** This graph shows the relationship between the network size and the probability a particular link, adjacent or not, can be mashed.



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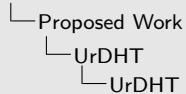
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# UrDHT

This kind of framework does not exist.  
VHash is a precursor to this work.

2015-07-06

## DHT Distributed Computing



UrDHT

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VHash is a precursor to this work.

At Brendan's suggestion We plan on extending the functionality of DHTs, post poll

# DHT Distributed Computing

content

# Autonomous Load-Balancing

content



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