# Proposal Towards a Framework for DHT Distributed Computing

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Proposed Work



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Objective

Our objective is to create a generalized framework for distributed computing using Distributed Hash Tables.





# Objective

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Or





#### Our objective is to create a generalized framework for distributed computing using Distributed Hash Tables.

Or

We want to build a completely decentralized distributed computing framework.





Distributed Computing and Challenges

## What do I Mean by Distributed Computing?

A system where we can take a task and break it down into multiple parts, where each part is worked upon individually.





# Challenges of Distributed Computing

Distributed Computing platforms experience these challenges:

Scalability As the network grows, more resources are spent on maintaining and organizing the network.





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Scalability As the network grows, more resources are spent on maintaining and organizing the network.

Fault-Tolerance As more machines join the network, there is an increased risk of failure.

Load-Balancing Tasks need to be evenly distributed among all the workers.





**Distributed Hash Tables** are mechanisms for storing values associated with certain keys.

- Values, such as filenames, data, or IP/port combinations are associated with keys.
- These keys are generated by taking the hash of the value.
- We can get the value for a certain key by asking any node in the network.





# **Current Applications**

#### Applications that use or incorporate DHTs:

- P2P File Sharing applications, such as BitTorrent.
- Distributed File Storage.
- Distributed Machine Learning.
- Name resolution in a large distributed database.





## How Does It Work?

We'll explain in greater detail later, but briefly:

- DHTs organize a set of nodes, each identified by an ID.
- Nodes are responsible for the keys that are closest to their IDs.
- Nodes maintain a list of other peers in the network.
  - Typically a size log(n) subset of all nodes in the network.
- Each node uses a very simple routing algorithm to find a node responsible for any given key.





# Strengths of DHTs

DHTs are designed for large P2P applications, which means they need to be (and are):

- Scalable
- Fault-Tolerant
- Load-Balancing





## DHTs Address the Specified Challenges

The big issues in distributed computing can be solved by the mechanisms provided by Distributed Hash Tables.





# Uses For DHT Distributed Computing

The generic framework we are proposing would be ideal for:

- Embarrassingly Parallel Computations
  - Any problem that can be framed using Map and Reduce.
  - Brute force cryptography.
  - Genetic algorithms.
  - Markov chain Monte Carlo methods.
- Use in either a P2P context or a more traditional deployment.





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Proposed Work

The Components and Terminology

Introduction

## Required Attributes of DHT

- A distance and midpoint function.
- A closeness or ownership definition.
- A Peer management strategy.

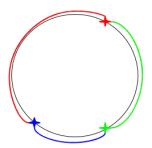




The Components and Terminology

#### Chord's Closest Metric.

Figure: A Voronoi diagram for a Chord network, using Chord's definition of closest.

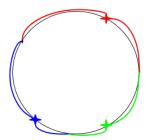






## Chord Using A Different Closest Metric

Figure: A Voronoi diagram for a Chord network, where closest is defined by the node being the closest in either direction.







#### Terms and Variables

- Network size is n nodes.
- Keys and IDs are *m* bit hashes, usually SHA1.
- Peerlists are made up of:
  - Short Peers The neighboring nodes that define the network's topology.
  - Long Peers Routing shortcuts.
- We'll call the node responsible for a key the root of the key.





#### **Functions**

lookup(key) Finds the node responsible for a given key. put(key, value) Stores value at the node responsible for key, where key = hash(value). get(key) Returns the value associated with key.



#### Chord

- Ring Topology
- Short Peers: predecessor and successor in the ring.
- Responsible for keys between their predecessor and themselves.
- Long Peers: log n nodes, where the node at index i in the peerlist is

$$root(r+2^{i-1} \mod m), 1 < i < m$$





## A Chord Network

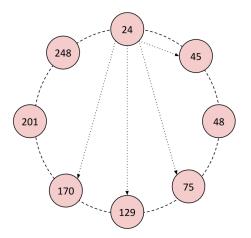


Figure: An 8-node Chord ring where m=8. Node 24's long peers are shown.





#### Fault Tolerence in Chord

- Local maintenance thread gradually fixes the network topology.
  - Each node "notifies" its successor.
  - The successor replies with a better successor if one exists.
- The long peers are gradually updated by performing a lookup on each entry.





- Short peers, the neighbors, are periodically queried to:
  - See of the node is still alive.
  - See if the neighbor knows about better nodes.
- Long peer failures are replaced by regular maintenance.





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# Overarching Goal

My research has been focused on:

- Abstracting out DHTs.
- Distributed computation using DHTs.





VHash sprung from two related ideas:

• We wanted a way be able optimize latency by embedding in into the routing overlay.



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## Goals

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- We wanted to create a DHT based off of Voronoi tessellation. Unfortunately:





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# Goals

#### VHash sprung from two related ideas:

- We wanted a way be able optimize latency by embedding in into the routing overlay.
- We wanted to create a DHT based off of Voronoi tessellation. Unfortunately:
  - Distributed algorithms for this problem don't really exist.
  - Existing approximation algorithms were unsuitable.





#### Voronoi Tesselation

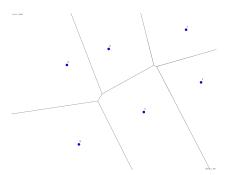


Figure: A set of points and the generated Voronoi regions



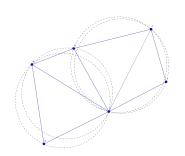


Figure: The same set of nodes with their corresponding Delaunay Triangulation.





# DHT and Voronoi Relationship

- We can view DHTs in terms of Voronoi tessellation and Delaunay triangulation.
  - The set of keys the node is responsible for is its Voronoi region.
  - The nodes neighbors are it's Delaunay neighbors.





#### **VHash**

- Voronoi-based Distributed Hash Table based on this relationship.
- Uses our approximation to solve for Delaunay neighbors, called DGVH.
- Topology updates occur via gossip-based protocol.
- Routing speed is  $O(\sqrt[d]{n})$
- Memory Cost
  - Worst case: O(n)
  - Expected maximum size:  $\Theta(\frac{\log n}{\log \log n})$





# Distributed Greedy Voronoi Heuristic

VHash

- Assumption: The majority of Delaunay links cross the corresponding Voronoi edges.
- We can test if the midpoint between two potentially connecting nodes is on the edge of the Voronoi region.
- This intuition fails if the midpoint between two nodes does not fall on their Voronoi edge.





### DGVH Heuristic

- 1: Given node n and its list of candidates.
- 2:  $peers \leftarrow \text{empty set that will contain } n's \text{ one-hop peers}$
- 3: Sort *candidates* in ascending order by each node's distance to *n*
- 4: Remove the first member of *candidates* and add it to *peers*
- 5. for all c in candidates do
- m is the midpoint between n and c 6.
- 7: **if** Any node in *peers* is closer to m than n **then**
- 8: Reject c as a peer
- 9. else
- Remove c from candidates 10:
- 11: Add c to peers
- end if 12:
- 13: end for





#### Results

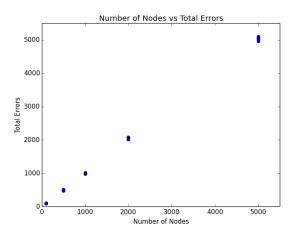


Figure: As the size of the graph increases, we see approximately 1 error GeorgiaState per node.



#### Results

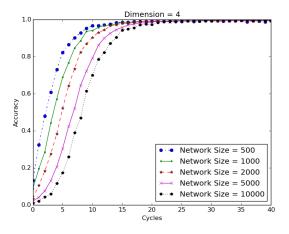


Figure: These figures show, starting from a randomized network, VHash forms a stable and consistent network topology.



Proposed Work

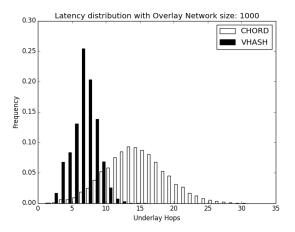


Figure: Comparing the routing effectiveness of Chord and VHash.





#### Conclusions

- DGVH is simple approximation for Delaunay Triangulation that guarantees a fully connected graph.
- VHash can optimize over a metric such as latency and achieve superior routing speeds as a result.





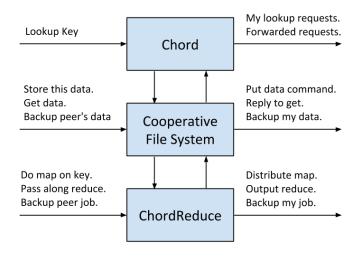
#### Goals

- We wanted build a more abstract system for MapReduce.
- We remove core assumptions:
  - The system is centralized.
  - Processing occurs in a static network.
- The resulting system must be:
  - Completely decentralized.
  - Scalable.
  - Fault tolerant.
  - Load Balancing.





# System Architecture







# Mapping Data

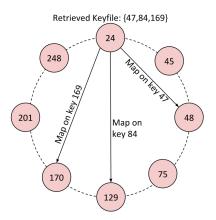


Figure: The stager sends a map task for each key in the keyfile. In larger networks, this process is streamlined by recursively bundling keys and sending them to the best finger.



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# Reducing Results of Data

Introduction

ChordReduce

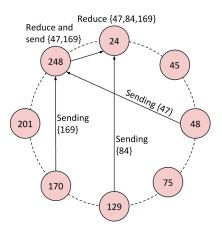


Figure: Results are sent back via the overlay. If a node receives multiple results, they are reduced before being sent on.



# Experiment Details

Our test was a Monte Carlo approximation of  $\pi$ .

Completed Work



Figure: The node chooses random xand y between 0 and 1. If  $x^2 + y^2 < 1^2$ , the "dart" landed inside the circle.

- Map jobs were sent to randomly generated hash addresses.
- The ratio of hits to generated results approximates  $\frac{\pi}{4}$ .
- Reducing the results was a matter of combining the two fields.





# **Experimental Results**

ChordReduce

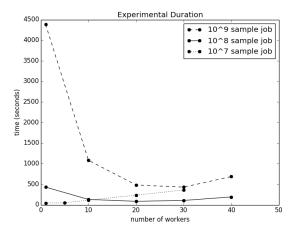


Figure: For a sufficiently large job, it was almost always preferable to distribute it.



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#### Churn Results

Churn rate per second	Average runtime (s)	Speedup vs 0% churn
0.8%	191.25	2.15
0.4%	329.20	1.25
0.025%	431.86	0.95
0.00775%	445.47	0.92
0.00250%	331.80	1.24
0%	441.57	1.00

Table: The results of calculating  $\pi$  by generating 10<sup>8</sup> samples under churn. Churn is the chance for each node to join or leave the network. The large speedup is from joining nodes acquiring work during experimental runtime.





#### Conclusions

#### Our experiments established:

- ChordReduce can operate under high rates of churn.
- Execution follows the desired speedup.
- Speedup occurs on sufficiently large problem sizes.

This makes ChordReduce an excellent platform for distributed and concurrent programming in cloud and loosely coupled environments.





# The Sybil Attack

- The Sybil attack is a type of attack against a distributed system such as a DHT.
- The adversary pretends to be more than one identity in the network.
  - Each of these false identities, called a Sybil is treated as a full member of the network.
- The overall goal is to occlude healthy nodes from one another.
- The Sybil attack is extremely well known, but there is little literature written from the attacker's perspective.





# The Sybil Attack in A P2P network

#### See Whiteboard

Introduction

- We want to inject a Sybil into as many of the regions between nodes as we can.
- The question we wanted to answer is what is the probability that a region can have a Sybil injected into it, given:
  - The network size n
  - The number of IDs available to the attacker (the number of identities they can fake).





# Assumptions

- The attacker is limited in the number of identities they can fake.
  - To fake an identity, the attacker must be able to generate a valid IP/port combo he owns.
  - The attacker therefore has num\_IP · num\_ports IDs.
  - We'll set *num\_ports* = 16383, the number of ephemeral ports.
  - Storage cost is 320 KiB.
- We call the act of finding an ID by modulating your IP and port so you can inject a node mashing.
- In Mainline DHT, used by BitTorrent, you can choose your own ID at "random." The implications should be apparent.





## Analysis

The probability you can mash a region between two adjacent nodes in a size *n* network is:

$$P \approx \frac{1}{n} \cdot num\_ips \cdot num\_ports \tag{1}$$

An attacker can compromise a portion  $P_{bad\_neighbor}$  of the network given by:

$$P_{bad\_neighbor} = \frac{num\_ips \cdot num\_ports}{num\_ips \cdot num\_ports + n - 1}$$
 (2)





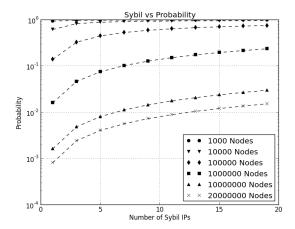


Figure: Our simulation results.

The dotted line traces the line corresponding to the Equation 2:

$$P_{bad\_neighbor} = \frac{num\_ips \cdot 16383}{num\_ips \cdot 16383 + n - 1}$$





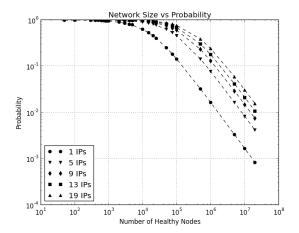


Figure: These are the same as results shown in Figure 13, but our *x*-axis is the network size *n* in this case. Here, each line corresponds to a different number of unique IP addresses the adversary has at their disposal.



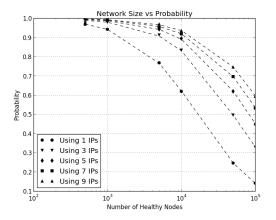


Figure: This graph shows the relationship between the network size and the probability a particular link, adjacent or not, can be mashed.



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#### Conclusion

- Our analysis showed an adversary with limited resources can occlude the majority of the paths between nodes.
- An attack of this sort on Mainline DHT would cost about \$43.26 USD per hour.
- Moreover, we demonstrated that creating virtual nodes is cheap and easy.





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#### **UrDHT**

- UrDHT is a completely abstracted DHT that will serve as a framework for creating DHTs.
- The goal is **not only** to create a DHT, but to create an easily extensible abstract framework for DHTs.
- Continuation of the work in VHash.





#### **UrDHT**

- We will be creating a mathematical description of what a DHT is.
- We will implement various DHTs using UrDHT and compare their performance.





# **DHT** Distributed Computing

- We will use UrDHT to implement a few of the more popular DHTs.
  - See if there is a difference for distributed computing.
  - Using UrDHT for all the implementations will minimize the differences between each DHT.





# **DHT** Distributed Computing

- Implement distributed computing on each of the implemented DHTs.
  - The emphasis is robustness and fault-tolerance.
- Test each framework using a variety of embarrassingly parallel problems, such as:
  - Brute-force cryptanalysis.
  - MapReduce problems.
  - Monte-Carlo computations.





# Autonomous Load-Balancing

- We will confirm that the effect from the high rate of Churn exists.
- We must create a scoring mechanism for nodes.
- The last step is to implement load-balancing strategies.





# Autonomous Load-Balancing Strategies

A few strategies we've thought up.

- Passive load-balancing: Nodes create virtual nodes based on their score.
- Traffic analysis: Create replicas where there is a high level of traffic.
- Invitation: Nodes with large areas of responsibility can invite other nodes to help.



