

# Cumulative Summation Control Charts

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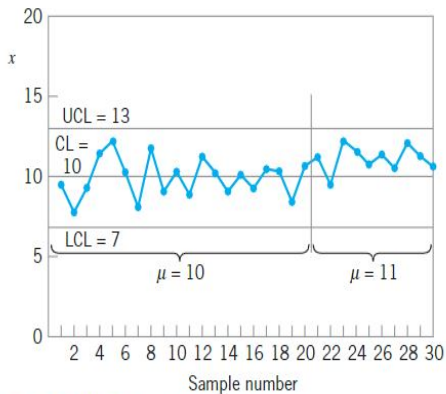
# Introduction

- ▶ To this point, we have primarily been discussing Shewhart-style charts
- ▶ The  $\bar{x}$ ,  $R$ ,  $s$ ,  $s^2$ ,  $p$ ,  $C$ , and  $U$  charts are all Shewhart-style which means we have:
  1. A sample plotting statistic
  2. An upper and possibly lower control limit based on the in-control sampling distribution of the plotting statistic
  3. An assumption of independence between observations

# Introduction

- ▶ Shewhart-style charts are useful for (1) efficiently detecting large shifts ( $> 2\sigma$ ) and (2) ease of interpretation and set up.
- ▶ However, it also has limitations:
  1. Since we assume independence, the only information Shewhart-style charts take into consideration is contained in the most recently observed point (the whole sequence is not considered).
  2. It is inefficient at detecting smaller shifts ( $< 1.5\sigma$ ).
  3. Use of runs rules/warning limits etc., impede the interpretability of the charts
  4. Not effective when  $n = 1$
- ▶ This leads to the need for new types of control charts which address these two limitations, one of which is called the “Cumulative Summation (CUSUM)” control chart.

# CUSUM Chart



■ **FIGURE 9.1** A Shewhart control chart for the data in Table 9.1.

# CUSUM Chart

- ▶ As we can see in this prior example, the first 20 observations come from a normal distribution with mean 10 and standard deviation 1. The following 10 come from a normal distribution with mean 11 and standard deviation 1.
- ▶ If we only rely upon the control limits, we would not stop the process to search for an assignable cause despite a shift having taken place.
- ▶ So how does the CUSUM chart solve this problem?

# CUSUM Chart

- ▶ The CUSUM chart was proposed by Page (1954). Here's the concept:
- ▶ Let's say we want to monitor the mean of a process and this process has a target value, say  $\mu_0$ . To monitor the process, we still take random samples and obtain an estimate of the sample mean, say  $\bar{x}_i$ .
- ▶ Instead of plotting the individual value of  $\bar{x}_i$  itself, we take the deviance between the target value and the sample mean,  $\bar{x}_i - \mu_0$ .

# CUSUM Chart

- ▶ Then, the cumulative summation component is that the plotting statistic is a function of the cumulative sum of the deviances.

$$C_i = \sum_{j=1}^i (\bar{x}_j - \mu_0)$$

- ▶ Here, the idea is that if the process starts to drift upwards or downwards, those cumulative differences will eventually signal to us that a shift has occurred. Notice that we are taking all  $\bar{x}_j$ 's into consideration instead of just the latest one!

# CUSUM Chart

- ▶ What you'll likely notice from the previous  $C_i$  is that its distribution is non-stationary. If you've taken time series, you'll know that this means that either the mean or the variance change with time.
- ▶ If we assume  $\bar{x}_i$  is normally distributed with mean  $\mu_0$  and variance  $\sigma^2/n$ , then:

$$C_i = \sum_{j=1}^i (\bar{x}_j - \mu_0) \sim N\left(0, \frac{i\sigma^2}{n}\right)$$



# CUSUM Chart

- ▶ This may serve as a limitation if we were to construct control limits in a Shewhart-style manner as the limits will change over time and also won't approach an asymptote.
- ▶ Consequently, there have been two proposed variants to the CUSUM chart to help solve this problem, but we will only focus on the one that's mostly used in practice: the **Tabular CUSUM**.

# CUSUM Chart

- ▶ The plotting statistic for the Tabular CUSUM is actually two statistics, an upper and a lower CUSUM:

$$C^+ = \max[0, \bar{x}_i - (\mu_0 + K) + C_{i-1}^+]$$

$$C^- = \max[0, (\mu_0 - K) - \bar{x}_i + C_{i-1}^-]$$

where,  $C_0^+ = C_0^- = 0$  and  $K$  is referred to as the “slack” or “allowance” value.

# CUSUM Chart

- ▶ Typically,  $K$  is chosen to be the midpoint between our target value,  $\mu_0$  and an out-of-control value,  $\mu_1$ , that we're interested in quickly detecting:

$$K = \frac{|\mu_1 - \mu_0|}{2}$$

- ▶  $C^+$  is for detecting upward shifts ( $\mu_1 > \mu_0$ ) and  $C^-$  is for detecting downward shifts ( $\mu_1 < \mu_0$ ).
- ▶ If either  $C_i^+$  or  $C_i^-$  exceed some control limit, say  $H$ , this signals to us that the process may be OOC.

# CUSUM Chart

- ▶ Let's look at an example using the data used in the example where the process mean shifted from 10 to 11.

## CUSUM Chart

- ▶ If a shift has taken place, it is often useful information to see what the new mean (or other characteristic that you're monitoring) has shifted to.
- ▶ To do this, your text recommends using:

$$\hat{\mu} = \mu_0 + K + \frac{C_i^+}{N^+}, \quad C_i^+ > H$$

$$\hat{\mu} = \mu_0 - K - \frac{C_i^-}{N^-}, \quad C_i^- > H$$

- ▶  $C_i^+$  and  $C_i^-$  denote the upper and lower CUSUM values associated with the first OOC point, and  $N^+$  and  $N^-$  denote the number of non-zero  $C_i^+$  and  $C_i^-$  values in the sequence which eventually lead to the OOC point. Let's go ahead and estimate the new mean in our example.

# CUSUM Chart Design

- ▶ In the last example, we used a CUSUM control chart where  $H = 5$  and  $K = 0.50$ . How do we choose those values?
- ▶ Generally, the rule of thumb is to define  $H = h\sigma$  and  $K = k\sigma$ , where  $h = 4$  or  $5$  and  $k = 0.50$ . So for a given known or estimated value of  $\sigma$ , we can obtain  $H$  and  $K$ .

# CUSUM Chart Design

■ TABLE 9.3

ARL Performance of the Tabular CUSUM with  $k = \frac{1}{2}$  and  $h = 4$  or  $h = 5$

Shift in Mean (multiple of $\sigma$ )	$h = 4$	$h = 5$
0	168	465
0.25	74.2	139
0.50	26.6	38.0
0.75	13.3	17.0
1.00	8.38	10.4
1.50	4.75	5.75
2.00	3.34	4.01
2.50	2.62	3.11
3.00	2.19	2.57
4.00	1.71	2.01

■ TABLE 9.4

Values of  $k$  and the Corresponding Values of  $h$  That Give  $ARL_0 = 370$  for the Two-Sided Tabular CUSUM [from Hawkins (1993a)]

$k$	0.25	0.5	0.75	1.0	1.25	1.5
$h$	8.01	4.77	3.34	2.52	1.99	1.61

## CUSUM Chart Usage

- ▶ So far we have seen that CUSUM can be used for monitoring sample means when  $n \geq 1$ .
- ▶ However, CUSUM can be used for other statistics as well, including the sample standard deviation, sample proportions, number of nonconforming items, etc.
- ▶ It can also be used for variable sample sizes by standardizing observations.



## CUSUM ARL Estimation

- ▶ Unlike the Shewhart-style charts, the plotting statistics for the CUSUM chart are not independent of each other. Thus, the typical  $ARL_0 = 1/\alpha$  and  $ARL_1 = 1/(1 - \beta)$  calculations aren't valid.
- ▶ Estimating ARL for CUSUM charts can be quite complicated. However, we do have some rough estimates that we can use in Phase I when making decisions about chart construction.
- ▶ For a one-sided CUSUM, Siegmund (1985) provided an approximation:

## CUSUM ARL Estimation

$$ARL = \frac{\exp(-2\Delta b) + 2\Delta b - 1}{2\Delta^2}$$

- ▶ where  $\Delta = \delta^* - k$  for the upper CUSUM,  $\Delta = -\delta^* - k$  for the lower CUSUM,  $b = h + 1.166$  and  $\delta^* = (\mu_1 - \mu_0)/\sigma$ .
- ▶ Then, if we're using a two-sided CUSUM, we can estimate the overall ARL by:

$$\frac{1}{ARL} = \frac{1}{ARL^+} + \frac{1}{ARL^-}$$

## CUSUM ARL Estimation

- ▶ Let's use the piston rings Phase I data to estimate the  $ARL_1$  where we want to protect against shifts of  $1.5\sigma$  in either the positive or negative direction.