DVALOG



Workshop: Magnets Problem

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Workshop Overview

- Day 1: TotalEnergy
 - a. Algorithms
 - b. Writing general code
 - c. Exercises
- Day 2: Simulate
 - a. Code Review
 - b. Performance Tuning
 - c. Exercises



TotalEnergy

$$E = -J \sum_{\langle ij \rangle} S_i S_j$$

$$\mathbf{s}_E = -J \times \mathbf{s} \times (N + E + S + W)$$



TotalEnergy using Stencil

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \times \begin{bmatrix} -1 & -1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$



TotalEnergy using Stencil

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} -1 & -1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$











$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ -1 & -1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix} \begin{array}{c} 0 & 0 & 0 \\ -1 & 1 \\ -1 & 1 \\ 1 & 1 \end{bmatrix}$$

















Break



Maintainability

Others (and our future selves) can easily understand our code
 Code is read much more often than it is written, so plan accordingly

It is easy to make changes to the behaviour



Changing the Rules

- Change "constants"
 - Interaction constant
 - Temperature

Add an external magnetic field



Changing the Rules

- Which neighbours
 - Nearest neighbours
 - Anisotropic influence
 - Distant neighbours



Changing the Rules

- World shape
 - Plane
 - Cylinder
 - Torus



Interaction Constant

$$E = -J \sum_{ij} s_i s_j$$



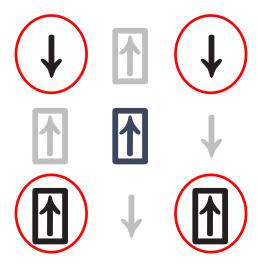
External Field

$$E = -J\sum_{ij} s_i s_j - h\sum_j s_j$$



Change contribution from neighbours

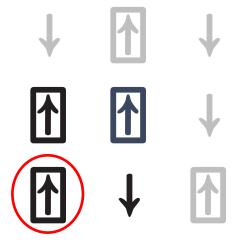
Corners also contribute





Change contribution from neighbours

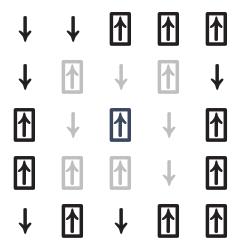
Anisotropic: southwest neighbours contribute more





Change contribution from neighbours

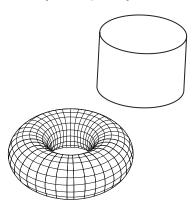
 More distant neighbours contribute more than nearby neighbours





Change the World Shape

- Bounded plane
 From the problem description, we do not flip edge spins
- Cylinder: one edge wraps around
- Torus: all edges wrap around
- BONUS: Consider
 - Non-rectangular lattice
 - 3D (or higher?)





Exercise

For each of the approaches we have looked at, modify your code to allow the system to be changed:

- Interaction constant
- Constant external field
- Modifiable neighbourhood

Which approaches do you find easy to understand? Which are easiest to change?



Exercise: Neighbourhood

Consider:

- A static neighbourhood (similar to the problem description, Boolean)
- A function of position and/or distance relative the "this spin"
- How will you represent the neighbourhood influence?

Try to write:

- Production quality code
- Sensible variable names
- Comments

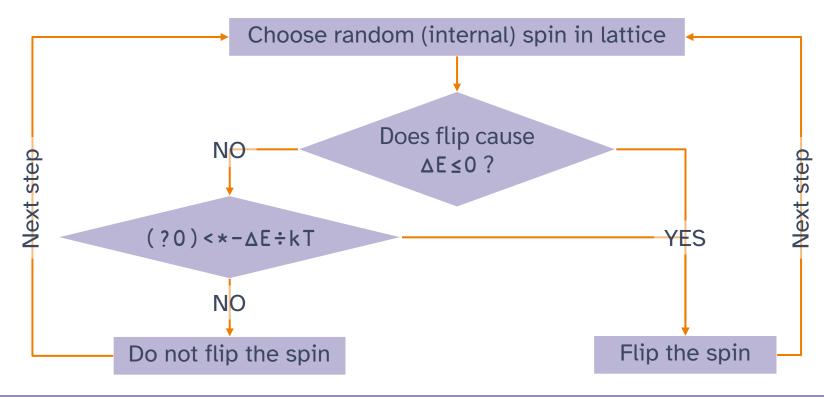


See you next week!

• Questions?



Simulate: The Metropolis Algorithm



Code Review

This code supposedly chooses a random spin to flip.

```
shape ← plat
random ← ?shape
random -← random=shape
random +← random=1
```



Code Review

This code supposedly chooses a random spin to flip.

random ← 1+2?⁻2+*≢*lat



Code Review

This code supposedly chooses a random spin to flip, then does it or not, depending on DoFlip ΔE .



Code Review: Bonus

This code supposedly chooses all random spins to flip, for the entire simulation, at once.

```
shape←plat
all_random ← 1+shape⊥♥?n 2pshape-2
```



How to detect / prevent errors?

- Simple visualisation
- Logging
- Plotting

