

Assignment 2:

Aim : To implement a Wiener filter to remove additive gaussian noise and defocus blur from an image.

Methodology:

Training:

1. We consider the noise free image , in the training set. We then apply defocus blur by convolving it with a 3*3 gaussian filter. The variance of the gaussian is a random number between 0 and 1.
2. To model noise we add to it an additive Gaussian noise of variance as a random integer between 0 and 1.
3. Now we design the Wiener filter as follows,

$$W(u,v) = E(|XD^*|)/E(|X|^2)$$

Testing:

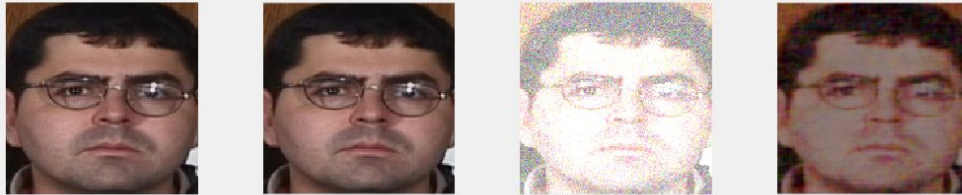
1. Now we test the Wiener filter by computing the fourier transform of the incoming image. Let $X(u,v)$ be the fourier transform.

$$Y(u,v) = W(u,v)X(u,v)$$

2. Now we obtain the final image by taking the ifft of $Y(u,v)$.

Results: (Original - Blurred - Noised - Filtered)

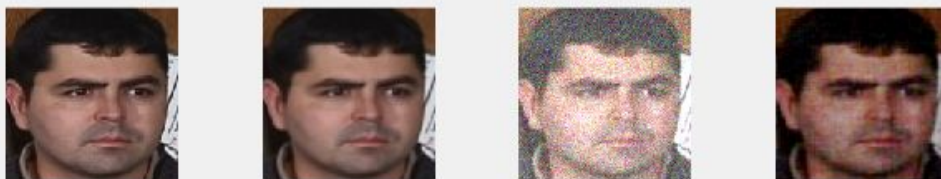
1. Noise Variance = 0.6, Blurring variance = 0.1



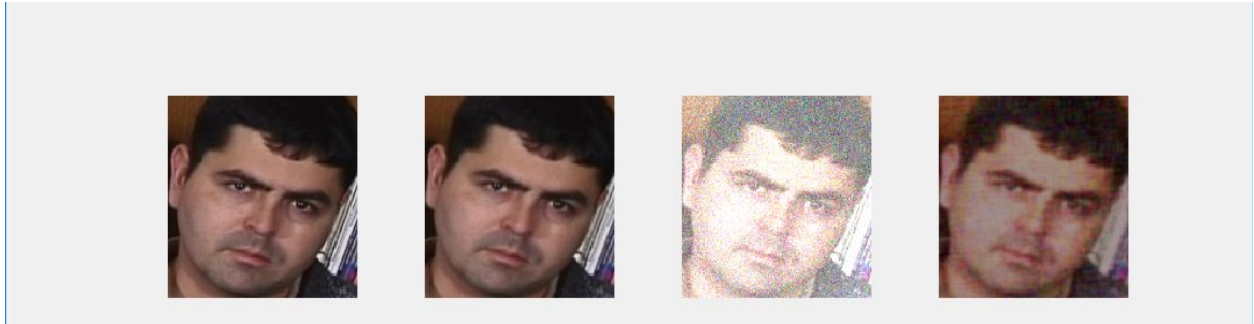
2. Noise variance = 0.3, Blurring variance = 0.1



3. Noise variance = 0.3, Blurring variance = 0.8



4. Noise Variance = 0.5, Blurring Variance = 0.5



Output Metrics:

I obtained the PSNR and MSE on the output image. They were averaged for all the testing images. The values of the noise variance was chosen randomly.

Average PSNR of output $\approx 19\text{dB}$

Average PSNR of Noisy Image $\approx 9\text{dB}$

Average value = MSE $\approx 1.6\%$

The average PSNR and MSE may vary every execution of the code.

Conclusion:

The global method for Wiener filtering produces a decent value of PSNR and MSE after filtering. It is suitable for removing Gaussian Noise and Defocus blur.