ITERATIVE REFINEMENT GRAPH NEURAL NETWORK FOR ANTIBODY SEQUENCE-STRUCTURE CO-DESIGN

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Abstract

♦ Abstract

- Antibody → bind to pathogens like viruses and stimulate the adaptive immune system
- The specificity of antibody binding → complementarity-determining regions (CDRs) at the tips of these Y-shaped proteins.
- In this paper,
 - 1. Propose a generative model to **automatically design the CDRs of antibodies** with enhanced binding specificity or neutralization capabilities
 - 2. Propose to co-design the sequence and 3D structure of CDRs as graphs



Abstract

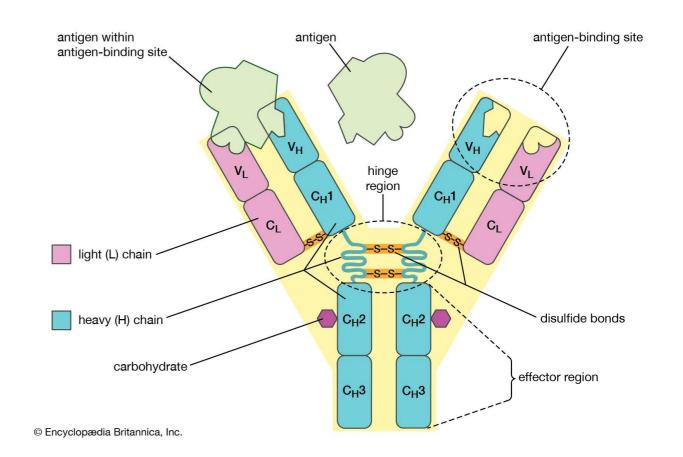
♦ Abstract

- The model unravels a sequence autoregressively while iteratively refining its predicted global structure (Structure 를 계속해서 수정해 나간다는 뜻)
- The inferred structure in turn guides subsequent residue choices
- We model the conditional dependence between residues inside and outside of a CDR in a coarse-grained manner (뭉뚱그려서 한다는 뜻, Figure 2 참조)
- Our method achieves superior log-likelihood on the test set
- Outperforms previous baselines in designing antibodies capable of neutralizing the SARS-CoV-2 virus1



Antibodies

- Monoclonal antibodies are increasingly adopted as therapeutics targeting a wide range of pathogens such as SARS-CoV-2
- Binding specificity
 - → Determined by their complementaritydetermining regions (CDRs)
- Main Goal
 - → To automate the creation of CDR subsequences with desired properties



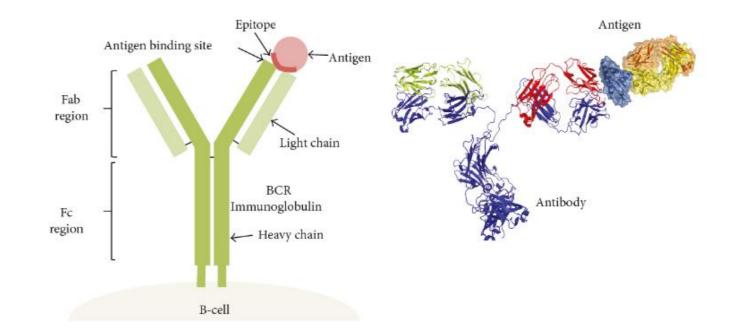


◆ CDR (Antibody) Epitope (Antigen)

- 1. Complementarity-determining region
 - '항체' 에 존재하는 것
 - '항원' 과 상보적인 결합을 하는 부위
 - Hypervariable region (HV) 라고도 부름
 - 아미노산들의 서열 변화가 집중되어 있음

2. Epitope

- '항원' 에 존재하는 것
- CDR 혹은 HV와 결합하는 부위



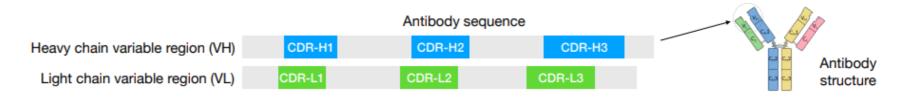
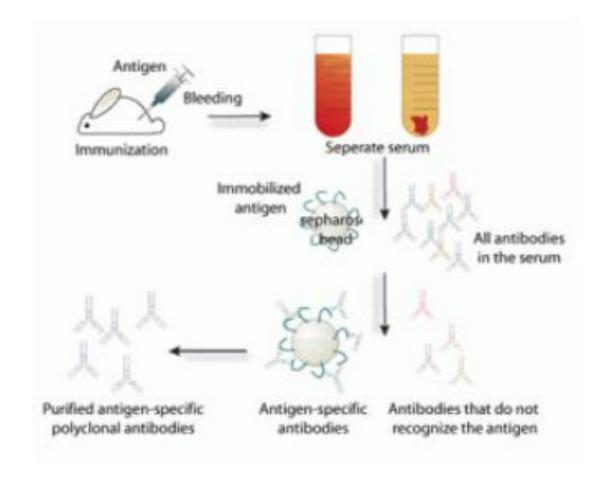


Figure 1: Schematic structure of an antibody (figure modified from Wikipedia).



Monoclonal Antibody

- Monoclonal antibodies (mAbs) are generated by identical B cells which are clones from a single parent cell
- This means that the monoclonal antibodies have monovalent affinity and only recognize the same epitope of an antigen.

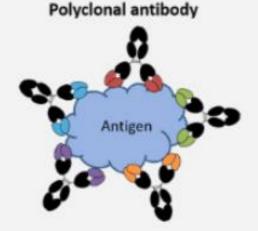




Monoclonal vs Polyclonal

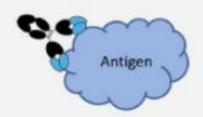
Polyclonal Antibody

- Cheap to produce
- · Mixed population of antibodies
- · May bind to different areas of the target molecule
- Tolerant of small changes in protein structure



Monoclonal Antibody

- Expensive to produce
- Single antibody species
- · Will only bind single specific site
- May recognise a particular protein form
 Monoclonal antibody









♦ Three Key modeling questions

- 1. How to model the relation between a sequence and its underlying 3D structure
 - Structure 을 고려 안하면? → lead to sub-optimal performance (안 좋은 것)
 - Predefined 된 3D structure 를 고려하면 되지 않나? → 이상적으로 알려진 priori 는 지극히 적다
- 2. How to model the conditional distribution of CDRs given the remainder of a sequence (context)
 - 여기서 context 란 우리가 고려하는 CDR 의 sequence 를 말하는 듯
 - 이 sequence 를 이용해 CDR 의 조건부 분포를 만드는 것이 중요하다는 의미
 - Attention-based 방법은 sequence 단에서만 conditional dependence 를 고려하지만 Context 와 CDR region 의 구조적인 관계는 generation 에 있어서 매우 중요
- 3. Model's ability to optimize for various properties
 - 전통적인 물리적 방법은 binding E 를 최소화 시키는 것에만 집중했으나
 - 저자는 binding E 보다 더 중요한, 또 다른 objective 에 집중했음



♦ In this paper,

- Represent a sequence-structure pair as a graph
- Formulate the co-design task as a graph generation problem
- CDR 과 그에 해당하는 context 사이의 조건부 의존성을 Sequence 와 Structure level 둘 다 에서 고려하여 모델링 함
 - Sequence level Residue amino acid
 - 3D structure Pairwise residue distance



◆ Solve,

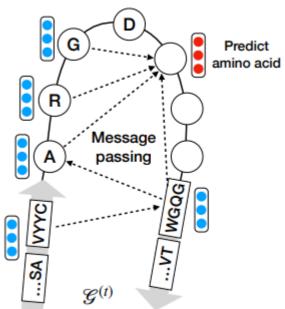
- Antibody graph generation poses unique challenges because the global structure is expected to change when new nodes are inserted
- Previous autoregressive cannot modify a generated structure because they are trained under teacher forcing
 - → 이미 이 다음 structure 가 주어진 상태에서 그 structure 에 맞춰 훈련을 하는 방식이기 때문에 robust 한 model 이 될 수가 없음
 - → Cascade of errors 를 가져오는 문제가 생김



Proposed Model

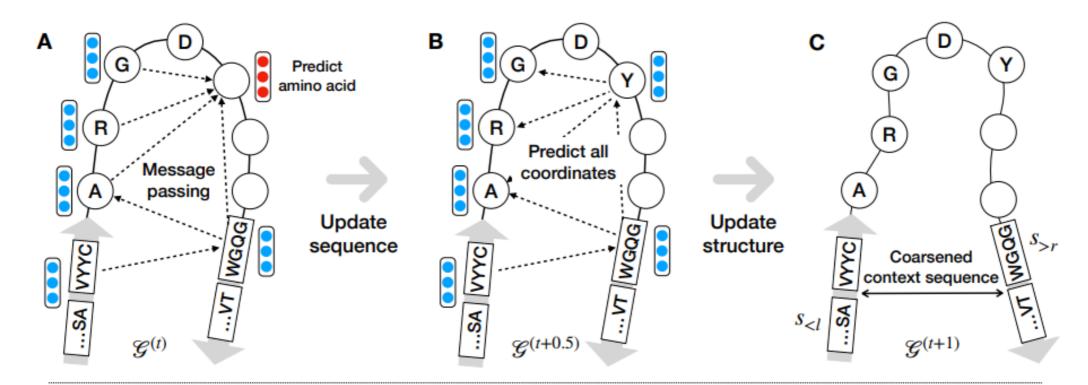
♦ Solve,

- To address these problems, we propose a novel architecture
 - → Interleaves the generation of amino acid nodes with the prediction of 3D structures
 - → Structure generation is based on an **iterative refinement of a global graph** rather than a sequential expansion of a partial graph with teacher forcing (단순히 sequence 를 늘려가는 방식이 아닌, global graph 자체를 계속해서 다듬는 과정을 말함)
- Since the context sequence is long, we further introduce a coarsened graph representation by grouping nodes into blocks



Antibody Sequence & Structure Co-design

Overview,



Original sequence s: ...TIYPGDGDTGYAQKFQGKATLTADKSSKTVYMHLSSLASEDSAVYYCARGDYYGSNSLDYWGQGTSVT.

Context sequence $b_{l,r}(s)$: ... AQKF QGKA TLTA DKSS KTVY MHLS SLAS EDSA VYYC \\ \text{ | QGKA TLTA DKSS KTVY MHLS SLAS EDSA VYYC \\ \text{ | QGKA TSVT | WGQG TSVT | } \\ \text{ | WGQG TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | CDR-H3 | \text{ | QGKA | TSVT | } \\ \text{ | QGKA | TSVT | \\ \text{ | QGKA | TSVT | } \\ \text{ | QGKA | TSVT | } \\ \text{ | QGKA | TSVT | \\ \text{ | QGKA | TSV



Current Methods,

- Computational antibody design roughly fall into two categories
 - · Based on energy function optimization
 - Based on generative models
- 1. Based on energy function optimization
 - Use Monte Carlo simulation to iteratively modify a sequence & its structure
 - → Until reaching a local energy minimum
 - Similar approaches are used in protein design
 - Weak point
 - → computationally expensive (Ingraham et al., 2019) and
 - → Our desired objective can be much more complicated than low binding energy (웬공진씨가 만든 모델은 이것 보다 더 복잡하다는 뜻 → Resource 의 한계가 뚜렷하다)



Current Methods,

- Computational antibody design roughly fall into two categories
 - Based on energy function optimization
 - Based on generative models
- 2. Based on generative models
 - Mostly sequence-based
 - Developed models conditioned on a backbone structure or protein fold
 - Weak point
 - → Not consider both structure and sequence
 - → Our model also seeks to incorporate 3D structure information for antibody generation
 - → Since the best CDR structures are often unknown for new pathogens, we **co-design sequences**

and structures for specific properties



Generative models for graphs

- Very related to autoregressive models for graph generation
 - Weak point
 - → Generate edges sequentially and cannot modify a previously generated subgraph when new nodes arrive
 - → (Even iterative model) Assumes all the node labels are given and **predicts edges only**
 - Our work combines autoregressive models with iterative refinement to generate a full graph with node and edge labels, including node labels and coordinates



♦ 3D structure prediction

- Closely related to protein folding
 - Weak point
 - → AlphaFold : Require a complete protein sequence, its multi-sequence alignment (MSA), and its template features
 - → (Even iterative model) Assumes all the node labels are given and **predicts edges only**
 - Our work : Models are **not directly applicable** because **we need to predict the structure of an incomplete sequence** and the MSA is not specified in advance



♦ 3D structure prediction

- Our iterative refinement model is also related to score matching methods for molecular conformation prediction and diffusion-based methods for point clouds
 - Iteratively refine a predicted 3D structure
 - Weak point
 - → Only for a complete molecule or point cloud (완전한 분자에만 적용)
 - Our work : Learns to predict the 3D structure for incomplete graphs and interleaves 3D structure refinement with graph generation (Incomplete graph 에도 적용이 가능하다)



♦ 3D structure prediction

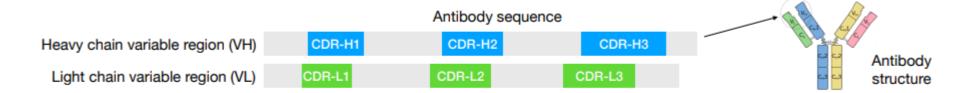


Figure 1: Schematic structure of an antibody (figure modified from Wikipedia).

- Antibody 의 구조 → Variable region 이 있는데 VR 은 2가지 부분으로 나뉨
 - Framework region
 - Three complementarity determining regions (CDRs)
- This work
 - → formulate antibody design as a CDR generation task, **conditioned on** the framework region



3D structure prediction

- 1. Represent an antibody as a graph, which encodes both its sequence and 3D structure
- 2. Propose a new graph generation approach called RefineGNN and extend it to handle **conditional generation given a fixed framework region**
- 3. Describe how to apply RefineGNN to property-guided optimization to design new antibodies with better neutralization properties
 - → For simplicity, we **focus on the generation of heavy chain CDRs**, though our method can be easily extended to model light chains CDRs

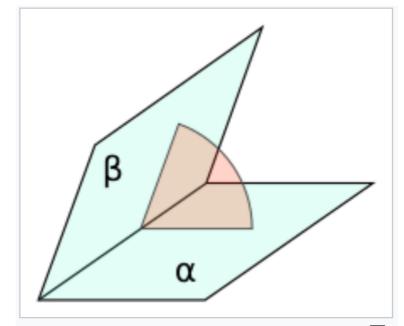


GRAPH REPRESENTATION

• Each node (Residue) → Has three dihedral angle (이면각? 이거 나만 몰랐나?)

$$(\phi_i, \psi_i, \omega_i)$$

Related to three backbone coordinates of residue i



Angle between two half-planes (α , β , pale blue) in a third plane (red) which cuts the line of intersection at right angles

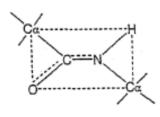
GRAPH REPRESENTATION

- For each residue, → The coordinate of alpha-carbon
 - \rightarrow The other side chain atoms \rightarrow Nitrogen, Carbon
- (참고 감소된 면역원성을 갖는 개질 에리트로포이에틴)

'알파 탄소 (Cα)' 는 펩티드 사슬 내에 있는 탄소-수소 (CH) 성분의 탄소 원자이다. '측쇄' 는 펩티드의 크기에 비해 상당히 다양할 수 있는 물리적 크기를 갖는, 단순하거나 복잡한 기 또는 부분을 구성할 수 있는 Cα에 대한 펜던트 기 이다.

단백질 또는 폴리펩티드의 전체 구조를 결정하는 데 중요한 역할을 하는 여러 요인들이 있다. 첫 번째로, 펩티드 결합, 즉 사슬 내의 아미노산을 함께 연결하는 결합은 공유 결합이다. 상기 결합은 평면 구조이며, 본질적으로 치환 아미드 이다. '아미드' 는 -CONH- 그룹을 함유하는 유기 화합물의 임의 기이다.

인접한 아미노산의 Ca를 연결하는 평면 펩티드 결합은 하기 도시한 바와 같이 나타낼 수 있다:



 \rightarrow Compute orientation matrix O_i (Local coordinate frame 을 나타냄)

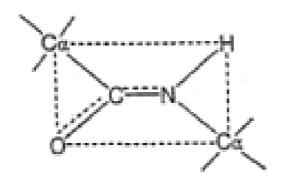


GRAPH REPRESENTATION

• Edge Feature : Contains four parts

$$e_{ij} = (E_{pos}(i-j), RBF(\|\boldsymbol{x}_{i,\alpha} - \boldsymbol{x}_{j,\alpha}\|), O_i^{\top} \frac{\boldsymbol{x}_{j,\alpha} - \boldsymbol{x}_{i,\alpha}}{\|\boldsymbol{x}_{i,\alpha} - \boldsymbol{x}_{j,\alpha}\|}, Q_i^{\top} O_j)$$

- e_{ij} = Distance of sequence level
- RBF = Distance encoding lifted into radial basis (방사형, 아래 그림)
 - = Distance between the alpha carbon of two residues
 - = 1. Take the distance, 2. Lift it to the radial basis form (RBF kernel 이라 생각)





GRAPH REPRESENTATION

• Edge Feature : Contains four parts

$$e_{ij} = (E_{pos}(i-j), RBF(\|\boldsymbol{x}_{i,\alpha} - \boldsymbol{x}_{j,\alpha}\|), O_i^{\top} \frac{\boldsymbol{x}_{j,\alpha} - \boldsymbol{x}_{i,\alpha}}{\|\boldsymbol{x}_{i,\alpha} - \boldsymbol{x}_{j,\alpha}\|}, Q(O_i^{\top}O_j))$$

- $O_i^{\top} \frac{x_{j,\alpha} x_{i,\alpha}}{\|x_{i,\alpha} x_{j,\alpha}\|}$ = Orientation matrix of between residue i and j = Local coordinate frame
- $q(O_i^{\top}O_j)$ = Orientation encoding of the quaternion representation of the spatial rotation matrix $(O_i^{\top}O_j)$
- These four parts → **Input** to the graph neural network



♦ ITERATIVE REFINEMENT GRAPH NEURAL NETWORK (REFINEGNN)

- $\mathcal{G}^{(0)}$: initial guess of the true antibody graph
- Each residue → initialized as a special token <MASK>
- Each edge $(i,j) \rightarrow$ initialized to be of distance 3|i-j| (Consecutive residues \rightarrow three?)
- Direction and orientation features are set to 0
- Each generation step
 - Model learns to revise a current antibody graph (그래프를 수정하는 법을 배움)
 - Predict the label of the next residue t+1 (노드 하나를 추가 하는게 하나의 step 임!!! 중요)

$$\{\boldsymbol{h}_1^{(t)},\cdots,\boldsymbol{h}_n^{(t)}\}=\mathrm{MPN}_{\theta}(\mathcal{G}^{(t)})$$

Given the current graph structure → Use message passing, encode to get the hidden state of each residue

♦ ITERATIVE REFINEMENT GRAPH NEURAL NETWORK (REFINEGNN)

$$\{\boldsymbol{h}_1^{(t)}, \cdots, \boldsymbol{h}_n^{(t)}\} = \mathrm{MPN}_{\theta}(\mathcal{G}^{(t)})$$

Any message passing network is adopted

$$\boldsymbol{h}_{i}^{(t,l+1)} = \text{LayerNorm}\left(\sum_{j} \text{FFN}\left(\boldsymbol{h}_{i}^{(t,l)}, \boldsymbol{h}_{j}^{(t,l)}, E(\boldsymbol{s}_{j}), \boldsymbol{e}_{i,j}\right)\right), \quad 0 \leq l \leq L-1$$

- 여기서는 단순하게 Feedforward network 를 사용
 - Residue $i \supseteq learned representation$
 - Residue *j* □ learned representation
 - Learned embedding of amino acid type S_i
 - Residue i 와 Residue j 의 distance Residue i



♦ ITERATIVE REFINEMENT GRAPH NEURAL NETWORK (REFINEGNN)

$$\{\boldsymbol{h}_1^{(t)}, \cdots, \boldsymbol{h}_n^{(t)}\} = \mathrm{MPN}_{\theta}(\mathcal{G}^{(t)})$$

Any message passing network is adopted

$$\boldsymbol{h}_{i}^{(t,l+1)} = \text{LayerNorm}\left(\sum_{j} \text{FFN}\left(\boldsymbol{h}_{i}^{(t,l)}, \boldsymbol{h}_{j}^{(t,l)}, E(\boldsymbol{s}_{j}), \boldsymbol{e}_{i,j}\right)\right), \quad 0 \leq l \leq L-1$$

• Based on the learned residue representations, we predict the **amino acid type** of the next residue $t + 1 = h_i^{(t,l+1)}$ 을 이용해서 그 다음 residue 를 예측

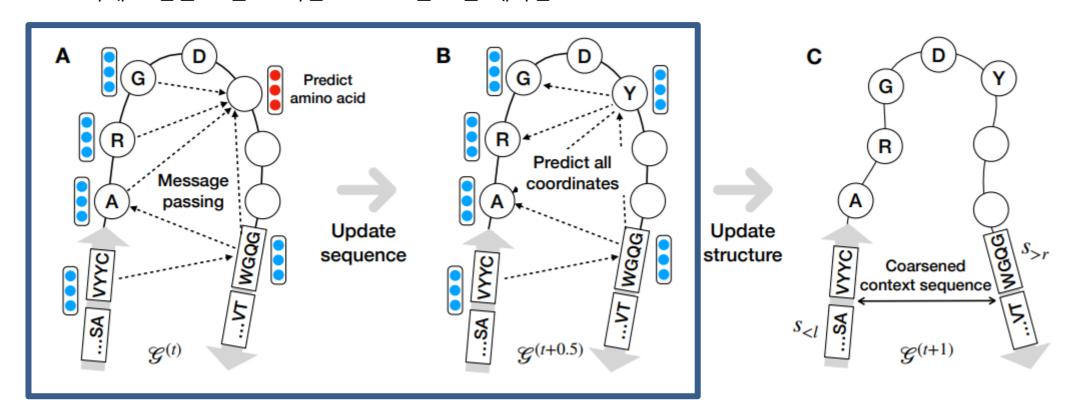
$$\boldsymbol{p}_{t+1} = \operatorname{softmax}(\boldsymbol{W}_a \boldsymbol{h}_{t+1}^{(t)})$$

→ Classification task



♦ ITERATIVE REFINEMENT GRAPH NEURAL NETWORK (REFINEGNN)

- Based on the learned residue representations, we predict the amino acid type of the next residue $t+1=h_i^{(t,l+1)}$ 을 이용해서 그 다음 residue 를 예측
- 아래 그림을 보면 그 다음 residue 인 Y 를 예측함





◆ ITERATIVE REFINEMENT GRAPH NEURAL NETWORK (REFINEGNN)

- Next, we need to update the structure to accommodate the new residue t+ 1
- Encode graph $\mathcal{G}^{(t+0.5)}$ by another MPN with a different parameter $\tilde{\theta}$, predict the coordinate of all residues

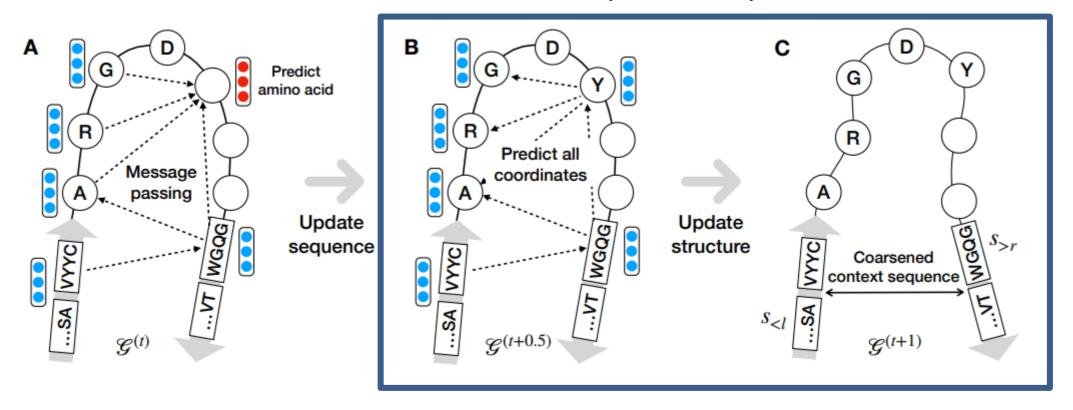
$$\{\boldsymbol{h}_{1}^{(t+0.5)}, \cdots, \boldsymbol{h}_{n}^{(t+0.5)}\} = \text{MPN}_{\tilde{\theta}}(\mathcal{G}^{(t+0.5)})$$

$$\boldsymbol{x}_{i,e}^{(t+1)} = \boldsymbol{W}_{x}^{e}\boldsymbol{h}_{i}^{(t+0.5)}, \quad 1 \leq i \leq n, e \in \{\alpha, c, n\}$$

• $x_{i,e}^{(t+1)}$ = new coordinate of each residue $\rightarrow \mathcal{G}^{(t+1)}$ 을 예측



◆ ITERATIVE REFINEMENT GRAPH NEURAL NETWORK (REFINEGNN)



- The structure prediction (coordinates x_i) and sequence prediction (amino acid types p_{t+1}) are carried out by two different MPNs, namely the structure network $\tilde{\theta}$ and sequence network θ
- This disentanglement allows the two networks to focus on two distinct tasks



Training

- 1. Apply teacher forcing to the discrete amino acid type prediction
- 2. In each generation step t, residues 1 to t are set to their ground truth amino acid types $s_1, ..., s_t$ while all future residues t + 1, ..., n are set to a padding token
- 3. In contrast, the continuous structure prediction is carried out without teacher forcing
- 4. In each iteration, the model refines the entire structure predicted in the previous step and constructs a new K-nearest neighbors graph $\mathcal{G}^{(t+1)}$ of all residues based on the predicted coordinates $\left\{x_{i,e}^{(t+1)} \mid 1 \leq x_{i,e}^{(t+1)} \right\}$

$$i \le n, e \in \{\alpha, c, n\}$$



Loss function

- **◆** Loss function = Structure prediction loss + Sequence prediction loss
- The loss function for antibody structure prediction consists of three parts
 - 1. Distance Loss
 - 2. Dihedral Loss
 - 3. C_{α} angle loss (Backbone angle)
- The loss function for sequence prediction is Cross-entropy loss
 - 1. Between predicted and true residue



♦ Loss function

- **◆** Loss function = Structure prediction loss + Sequence prediction loss
- The loss function for antibody structure prediction consists of three parts
 - 1. Distance Loss (Pairwise distances)

$$\mathcal{L}_d^{(t)} = \sum_{i,j} \ell_{ ext{huber}} (\|m{x}_{i,lpha}^{(t)} - m{x}_{j,lpha}^{(t)}\|^2, \|m{x}_{i,lpha} - m{x}_{j,lpha}\|^2)$$

- $\|\boldsymbol{x}_{i,\alpha}^{(t)} \boldsymbol{x}_{i,\alpha}^{(t)}\|^2$ = Predicted
- $\|\boldsymbol{x}_{i,\alpha} \boldsymbol{x}_{j,\alpha}\|^2$ = Ground truth



♦ Loss function

- **◆** Loss function = Structure prediction loss + Sequence prediction loss
- The loss function for antibody structure prediction consists of three parts
 - 2. Dihedral Loss (Angle)

$$\mathcal{L}_{a}^{(t)} = \sum_{i} \sum_{a \in \{\phi, \psi, \omega\}} (\cos a_i^{(t)} - \cos a_i)^2 + (\sin a_i^{(t)} - \sin a_i)^2$$

•
$$(\phi_i^{(t)}, \psi_i^{(t)}, \omega_i^{(t)})$$
 = Dihedral angle based on predicted atom coordinates

$$m{x}_{i,lpha}^{(t)}, m{x}_{i,c}^{(t)}, m{x}_{i,n}^{(t)}$$
 and $m{x}_{i+1,lpha}^{(t)}, m{x}_{i+1,c}^{(t)}, m{x}_{i+1,n}^{(t)}$



♦ Loss function

- **◆** Loss function = Structure prediction loss + Sequence prediction loss
- The loss function for antibody structure prediction consists of three parts
 - 3. C_{α} angle loss : Calculate angle

$$\mathcal{L}_c^{(t)} = \sum_{i} (\cos \gamma_i^{(t)} - \cos \gamma_i)^2 + (\cos \beta_i^{(t)} - \cos \beta_i)^2$$

- Calculate angles $\gamma_i^{(t)}$ between two vectors $~m{x}_{i-1,lpha}^{(t)}-m{x}_{i,lpha}^{(t)}$ and $~m{x}_{i,lpha}^{(t)}-m{x}_{i+1,lpha}^{(t)}$
- Calculate angles $eta_i^{(t)}$ between two planes $m{x}_{i-2,lpha}^{(t)}, m{x}_{i-1,lpha}^{(t)}, m{x}_{i,lpha}^{(t)}, m{x}_{i+1,lpha}^{(t)}$
- Structure Loss = $\mathcal{L}_{\mathrm{struct}} = \sum_t \mathcal{L}_d^{(t)} + \mathcal{L}_a^{(t)} + \mathcal{L}_c^{(t)}$
- Sequence Loss = $\mathcal{L}_{ ext{seq}} = \sum_{t} \mathcal{L}_{ce}(m{p}_t, m{s}_t)$
- Total Loss = $\mathcal{L} = \mathcal{L}_{ ext{seq}} + \mathcal{L}_{ ext{struct}}$



Given framework condition

- The model architecture described so far is designed for unconditional generation
- It generates an entire antibody graph without any constraints

$$s_{< l} = s_1 \cdots s_{l-1}$$

- However, in practice,
 - · Usually fix the framework region of an antibody and
 - Design the CDR sequence only
- Therefore,
 - We need to extend the model architecture to learn the conditional distribution $P(s'|s_{< l},s_{> r})$ where $s_{< l} = s_1 \cdots s_{l-1}$ and $s_{> r} = s_{r+1} \cdots s_n$ are residues outside of the CDR s_l, \ldots, s_r



♦ Conditioning via attention

- A simple extension of RefineGNN is to encode the non-CDR sequence using a recurrent neural network and propagate information to the CDR through an attention layer.
- Leverage the information from the framework residues
- Apply attention over all the framework residues

$$\begin{aligned} \{ \boldsymbol{c}_1, \cdots, \boldsymbol{c}_n \} &= \boldsymbol{c}_{1:n} = \mathrm{GRU}(\tilde{\boldsymbol{s}}) \\ \boldsymbol{p}_{t+1} &= \mathrm{softmax} \big(\boldsymbol{W}_a \boldsymbol{h}_{t+1}^{(t)} + \boldsymbol{U}_a^{\top} \mathrm{attention}(\boldsymbol{c}_{1:n}, \boldsymbol{h}_{t+1}^{(t)}) \big) \\ \boldsymbol{x}_{i,e}^{(t+1)} &= \boldsymbol{W}_x^e \boldsymbol{h}_i^{(t+0.5)} + \boldsymbol{U}_x^{e^{\top}} \mathrm{attention}(\boldsymbol{c}_{1:n}, \boldsymbol{h}_i^{(t+0.5)}) \end{aligned}$$

- 'Weak Point!'
 - → Only modeling the structure of CDR (not entire antibody)



Multi-resolution modeling

- The attention-based approach alone is not sufficient
 - Because it does not model the structure of the context sequence, thus ignoring how its residues structurally interact with the CDR's
 - 앞서 말한 것과 같이 CDR 부분의 structure 만 신경씀, CDR 의 앞뒤로 있는 framework 부분과의 interaction (structure) 는 신경쓰지 않음



Multi-resolution modeling

- So, during training step, we use the known structure to predict the interaction
- However,
 - Computationally expensive because we need to recompute the MPN (message passing network)
 encoding for all residues in each generation step
 - Cannot predict the context residue coordinates at the outset and fix them
 - → Not adjusted accordingly when the coordinates of CDR residues are updated in each generation step



Multi-resolution modeling

- Solution
 - Propose a coarse-grained model that reduces the context sequence length by clustering it into residue blocks (Coarse-grained → 거칠고 큼직큼직 하나는 뜻 → Context sequence 를 만들어 줌)
 - 각 residue 의 coordinate 의 mean 값을 residue block 의 coordinate 로 사용

$$E(\boldsymbol{b}_i) = \sum_{\boldsymbol{s}_j \in \boldsymbol{b}_i} E(\boldsymbol{s}_j)/b, \qquad \boldsymbol{x}_{\boldsymbol{b}_i,e} = \sum_{\boldsymbol{s}_j \in \boldsymbol{b}_i} \boldsymbol{x}_{j,e}/b, \qquad e \in \{\alpha, c, n\}$$



Property-guided sequence optimization

Ultimate goal

- Generate new antibodies with desired properties such as neutralizing a particular virus
 - → Cen be formulated as an optimization problem
 - \rightarrow Conditional generative model $P_{\Theta}(s'|b_{l,r}(s))$
 - \rightarrow Maximizes the probability of neutralization for a training set of antibodies \mathcal{D}

$$\sum_{s \in \mathcal{D}} \log P(Y = 1 | \boldsymbol{b}_{l,r}(s)) = \sum_{s \in \mathcal{D}} \log \sum_{s'} f(s') P_{\Theta}(s' | \boldsymbol{b}_{l|r}(s))$$

 $f(s') \rightarrow \text{Predictor for } P_{\Theta}(s'|b_{l,r}(s))$

- Context sequence 가 주어졌을 때 desire property 를 가질 수 있도록 모든 amino acid (s') 에 대해 loglikelihood 값을 최대화 시켜 줌
 - $\rightarrow f$ 가 주어졌을 때, 위의 식은 iterative target augmentation 으로 풀이 될 수 있다 (오 이거 내가 발표했던 논문임!!!)
 - → 반복적으로 추가적인 target molecule 을 붙여나갈 수 있게 작업



Property-guided sequence optimization

◆ Ultimate goal

Algorithm 1 RefineGNN decoding

Require: Context sequence $s_{< l}, s_{> r}$

- 1: Predict the CDR length n
- 2: Coarsen the context sequence into $b_{l,r}(s)$
- 3: Construct the initial graph $\mathcal{G}^{(0)}$
- 4: **for** t = 0 to n 1 **do**
- 5: Encode $\mathcal{G}^{(t)}$ using the sequence MPN
- 6: Predict distribution of the next residue p_{t+1}
- 7: Sample $s_{t+1} \sim \text{categorical}(p_{t+1})$
- 8: Encode $\mathcal{G}^{(t+0.5)}$ with the structure MPN
- 9: Predict all residue coordinates $x_{i,e}^{(t+1)}$
- 10: Update $\mathcal{G}^{(t+1)}$ using the new coordinates

Algorithm 2 ITA-based sequence optimization

Require: A set of antibodies \mathcal{D} to be optimized

Require: A neutralization predictor f.

Require: A set of neutralizing antibodies Q

- 1: **for** each iteration **do**
- 2: Sample an antibody s from \mathcal{D} , remove its CDR and get a context sequence $b_{l,r}(s)$
- 3: **for** i = 1 to M **do**
- 4: Sample $s_i' \sim P_{\Theta}(s'|b_{l,r}(s))$
- 5: **if** $f(s_i') > \max(f(s), 0.5)$ **then**
- 6: $Q \leftarrow Q \cup \{s_i'\}$
- 7: Sample a batch of new antibodies from Q
- 8: Update model parameter Θ by minimizing the sequence prediction loss \mathcal{L}_{seq} .



Q & A

Thank You!

