Lecture 30 (section 5.2)

Section 5.2 — continued

■ From example (2) earlier:

$$A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$$

is a 3×3 matrix. Is A diagonalizable?

 \implies characteristic equation:

$$0 = \det(A - \lambda \cdot I_3) = \det \begin{bmatrix} -\lambda & 0 & -2 \\ 1 & 2 - \lambda & 1 \\ 1 & 0 & 3 - \lambda \end{bmatrix} \implies \text{second column expansion for det} \implies$$

$$0 = (2 - \lambda) \cdot \det \begin{bmatrix} -\lambda & -2 \\ 1 & 3 - \lambda \end{bmatrix} = (2 - \lambda) \cdot (-\lambda \cdot (3 - \lambda) - (-2) \cdot 1)$$

$$0 = (2 - \lambda) \cdot (\lambda^2 - 3\lambda + 2) = (2 - \lambda) \cdot (\lambda - 2) \cdot (\lambda - 1) = (1 - \lambda) \cdot (2 - \lambda)^2$$

 \implies eigenvalues:

$$\{\lambda_1 = 1, (m_1 = 1); \quad \lambda_2 = 2, (m_2 = 2)\}$$

where m denotes the multiplicity of the corresponding eigenvalue.

 \implies eigenvectors:

$$\vec{V}_{1} = \begin{bmatrix} -2\\1\\1 \end{bmatrix} \qquad \qquad \underbrace{\{\vec{V}_{2,1}, \vec{V}_{2,2}\} = \left\{ \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\0\\1 \end{bmatrix} \right\}}_{\lambda = \lambda_{2}}$$

 \implies Question: are vectors

$$\vec{V}_1$$
, $\vec{V}_{2,1}$, $\vec{V}_{2,2}$

linearly independent?

$$c_1 \cdot \vec{V}_1 + c_2 \cdot \vec{V}_{2,1} + c_3 \cdot \vec{V}_{2,2} = 0$$

$$\begin{bmatrix}
-2 & 0 & -1 \\
1 & 1 & 0 \\
1 & 0 & 1
\end{bmatrix} \cdot \begin{bmatrix}
c_1 \\
c_2 \\
c_3
\end{bmatrix} = \begin{bmatrix}
0 \\
0 \\
0
\end{bmatrix}$$

 \implies use det test to check the singularity of M:

$$\underbrace{\det(M)}_{\text{ord solumn expansion}} = 1 \cdot \det \begin{bmatrix} -2 & -1 \\ 1 & 1 \end{bmatrix} = 1 \cdot (-2 \cdot 1 - (-1) \cdot 1) = -1 \neq 0$$

 \Longrightarrow

$$\{\vec{V}_1, \vec{V}_{2,1}, \vec{V}_{2,2}\}$$

are linearly independent.

How do we find the P matrix?

 \Longrightarrow

$$P = \begin{bmatrix} \vec{V}_1 & \vec{V}_{2,1} & \vec{V}_{2,2} \end{bmatrix} = \begin{bmatrix} -2 & 0 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

 \implies Next step: compute P^{-1} :

$$\begin{bmatrix} P & | & I_3 \end{bmatrix} = \begin{bmatrix} -2 & 0 & -1 & & 1 & 0 & 0 \\ 1 & 1 & 0 & & 0 & 1 & 0 \\ 1 & 0 & 1 & & 0 & 0 & 1 \end{bmatrix} \rightarrow \qquad \begin{matrix} r_3 \leftrightarrow r_1 \\ r_2 \rightarrow r_2 - r_1 \end{matrix} \qquad \rightarrow \begin{bmatrix} 1 & 0 & 1 & & 0 & 0 & 1 \\ 0 & 1 & -1 & & 0 & 1 & -1 \\ -2 & 0 & -1 & & 1 & 0 & 0 \end{bmatrix}$$

$$\rightarrow \qquad r_{3} \rightarrow r_{3} + 2r_{1} \qquad \rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & 0 & 2 \end{bmatrix} \rightarrow \qquad \begin{matrix} r_{1} \rightarrow r_{1} - r_{3} \\ r_{2} \rightarrow r_{2} + r_{3} \end{matrix} \rightarrow$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 \\ 1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix} = \begin{bmatrix} I_{3} & | P^{-1} \end{bmatrix}$$

 \Longrightarrow

$$P^{-1} = \begin{bmatrix} -1 & 0 & -1 \\ 1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix}$$

 \implies We can now compute matrix transform of A due to P:

$$A \to P^{-1} \cdot A \cdot P = \underbrace{\begin{bmatrix} -1 & 0 & -1 \\ 1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix}}_{\text{compute first}} \cdot \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix} \cdot \begin{bmatrix} -2 & 0 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} -1 & 0 & -1 \\ 2 & 2 & 2 \\ 2 & 0 & 4 \end{bmatrix} \cdot \begin{bmatrix} -2 & 0 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \equiv \underbrace{D}_{\text{diagonal form of } A}$$

$$\{1, 2, 2\} \implies \text{eigenvalues of } A \text{ with multiplicities}$$

 \implies D is not unique. It depends on the order of the eigenvectors used to generate the matrix P

• we used:

$$P = \begin{bmatrix} \vec{V}_1 & \vec{V}_{2,1} & \vec{V}_{2,2} \end{bmatrix} \implies D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

corresponding to a sequence of eigenvalues:



■ if instead we used

$$\tilde{P} = \begin{bmatrix} \vec{V}_{2,1} & \vec{V}_1 & \vec{V}_{2,2} \end{bmatrix} \qquad \Longrightarrow \qquad \tilde{D} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

■ Problem:

Given

$$A = \begin{bmatrix} 0 & 3 \\ 2 & -1 \end{bmatrix}$$

calculate A^{2018}

Too long and painful to do directly. So let's be sneaky, assume that A is diagonalizable:

$$A \to P^{-1} \cdot A \cdot P = D \implies A = P \cdot D \cdot P^{-1}$$

 \Longrightarrow

$$A^{2} = A \cdot A = P \cdot D \cdot \underbrace{P^{-1} \cdot P}_{=I_{P}} \cdot D \cdot P^{-1} = P \cdot D^{2} \cdot P^{-1}$$

 \Longrightarrow

$$A^{2018} = P \cdot D^{2018} \cdot P^{-1}$$

and it is much easier to compute D^{2018} !

• Find eigenvalues:

$$0 = \det(A - \lambda I_2) = \det\begin{bmatrix} -\lambda & 3\\ 2 & -1 - \lambda \end{bmatrix} = (-\lambda \cdot (-1 - \lambda) - 3 \cdot 2) = \lambda^2 + \lambda - 6 = (\lambda + 3)(\lambda - 2)$$

$$\implies \lambda_1 = -3, \quad \lambda_2 = 2$$

• eigenvector \vec{V}_1 , corresponding to $\lambda = \lambda_1$:

$$\begin{bmatrix} -\lambda_1 & 3 \\ 2 & -1 - \lambda_1 \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \qquad \Longrightarrow \qquad \begin{bmatrix} 3 & 3 \\ 2 & 2 \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

 \implies augmented matrix approach

$$\begin{bmatrix} 3 & 3 & 0 \\ 2 & 2 & 0 \end{bmatrix} \rightarrow \begin{matrix} r_1 \to \frac{1}{3}r_1 \\ r_2 \to \frac{1}{2}r_2 \\ r_2 \to r_2 - r_1 \end{matrix} \to \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

 \Longrightarrow

$$\vec{V}_1 = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

• eigenvector \vec{V}_2 , corresponding to $\lambda = \lambda_2$:

$$\begin{bmatrix} -\lambda_2 & 3 \\ 2 & -1 - \lambda_2 \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \qquad \Longrightarrow \qquad \begin{bmatrix} -2 & 3 \\ 2 & -3 \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

 \implies augmented matrix approach

$$\begin{bmatrix} -2 & 3 & 0 \\ 2 & -3 & 0 \end{bmatrix} \rightarrow \begin{matrix} r_2 \to r_2 + r_1 \\ r_1 \to -\frac{1}{2}r_1 \end{matrix} \to \begin{bmatrix} \boxed{1} & -\frac{3}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

 \Longrightarrow

$$\vec{V}_2 = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

• compute P, P^{-1}, D :

$$P = \begin{bmatrix} \vec{V}_1 & \vec{V}_2 \end{bmatrix} = \begin{bmatrix} -1 & 3 \\ 1 & 2 \end{bmatrix}$$

$$P^{-1} = \frac{1}{\det P} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \frac{1}{-2-3} \begin{bmatrix} 2 & -3 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} -\frac{2}{5} & \frac{3}{5} \\ \frac{1}{5} & \frac{1}{5} \end{bmatrix}$$

$$D = P^{-1} \cdot A \cdot P = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} -3 & 0 \\ 0 & 2 \end{bmatrix}$$

• compute D^{2018} :

$$D^{2018} = \begin{bmatrix} (-3)^{2018} & 0\\ 0 & 2^{2018} \end{bmatrix} = \begin{bmatrix} 3^{2018} & 0\\ 0 & 2^{2018} \end{bmatrix}$$

• compute A^{2018} :

$$A^{2018} = \begin{bmatrix} -1 & 3 \\ 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 3^{2018} & 0 \\ 0 & 2^{2018} \end{bmatrix} \cdot \begin{bmatrix} -\frac{2}{5} & \frac{3}{5} \\ \frac{1}{5} & \frac{1}{5} \end{bmatrix} =$$

$$= \begin{bmatrix} \frac{3}{5} \cdot 2^{2018} + \frac{2}{5} \cdot 3^{2018} & \frac{3}{5} \cdot 2^{2018} - \frac{3}{5} \cdot 3^{2018} \\ \frac{2}{5} \cdot 2^{2018} - \frac{2}{5} \cdot 3^{2018} & \frac{2}{5} \cdot 2^{2018} + \frac{3}{5} \cdot 3^{2018} \end{bmatrix}$$