Neural network model for popping

Single neuron dynamics

$$C\frac{dV_k}{dt} = -g_L(V_k - V_L) - w_k + g_L \Delta_T \exp\left(\frac{V_k - V^T}{\Delta_T}\right) + I_{in}^k + \overline{w_{Vol}} Vol$$
 (1)

$$\tau_w \frac{dw_k}{dt} = \alpha(V_k - V_L) - w_k \tag{2}$$

if
$$V_k^{ac} \ge V_{sp} \rightarrow V_k = V_{reset}$$
 and $w_k = w_k + b$

Synaptic current

$$\tau_s \frac{dI_{in}^k}{dt} = -I_{in}^k + \sum_{i=1}^N \sum_{j=1}^{sp} \delta_i(t - t_j)$$
(3)

Actuator dynamics (muscle)

$$\tau_A \frac{dr_A}{dt} = -r_A + \overline{w_A} \sum_{i=1}^A \sum_{j=1}^{sp} \delta_i(t - t_j)$$
(4)

Volume dynamics (plant)

$$\tau_V \frac{dVol}{dt} = Vol - V_o - \Phi_V(r_A)$$

$$\Phi_V(r_A) = 0 \text{ if } r_A <= \text{Thr, else } \Phi_V(r_A) = Step$$
(5)

Connectivity

N - number of neurons

S – number of sensors

A - number of actuators

sp - spikes in the spike train

 $\overline{w_A}$ – vector of actuators weights

 $\overline{w_{Vol}}$ – vector of sensory weights

Indexes

k – index over neurons

i – index over synapses

j – index over spikes

Summation over synaptic connections is organised by sparse connectivity matrix **A**

