

# Swelling and Popping Model

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# Biophysics Background

- Water gain by osmosis causes the hydra to 'swell'
- Hydra maintain their water balance by periodically 'popping' removing excess water from the enteron through the mouth by contraction of their body
- A functioning nervous system is necessary for this process - supported by epithelial Hydra studies (Marcum '78)

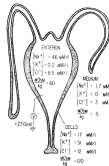


Fig. 8. Schematic diagram summarizing the data of Na, K, Cl, and osmolarity in the external medium, lumen, and interior of *Hydra* (Benos). The data are from Benos and Prusch (1973). The vertical line indicates the mean osmolarity. The horizontal line indicates the range of osmolarity.

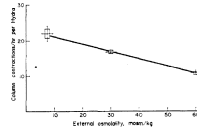


Fig. 1. Rate of column contraction of *H. littoralis* as a function of external osmolarity. Horizontal line: mean; vertical line: range; rectangle on either side of mean: two standard errors of the mean. Number of determinations: Versene medium, 7; 30 mOsmole/kg, 3; 60 mOsmole/kg, 4. The osmolarity of the Versene medium was increased by the addition of sucrose. The total number of column contractions of thirteen *Hydra* were counted in 1-hr intervals, and the results expressed in terms of contraction rate per individual *Hydra*.

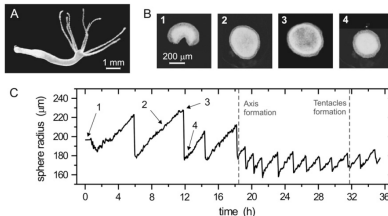
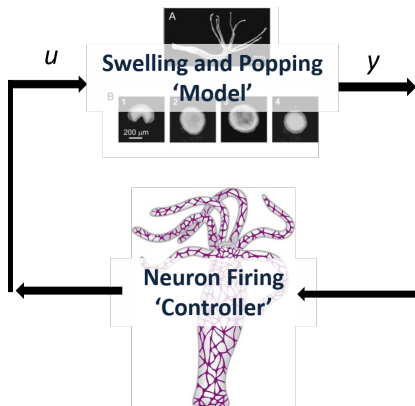


FIGURE 1 (A) Adult *Hydra vulgaris*. (B and C) Example of the swelling-collapse oscillations during regeneration at  $T = 20^{\circ}\text{C}$ . The snapshots in panel B show: 1), the initial fragment of tissue folding to form a sphere; 2), inflation stage; 3), critical inflation and rupture of the *Hydra* shell; and 4), collapse, healing, and beginning of a new inflation cycle.

References: Kucken, Soriano et al. '08; Benos and Prusch '73; Benos, Kirk et al. '77

# Volume Model and Neuron Network as Feedback

- Swelling and popping model described by the biophysics is 'controlled' by the neuron network



- Control  $u$ : Neuron firing induces contractions and mouth opening which regulates the volume
- Output  $y$ : Volume is measured and 'feeds back' to the neuron network

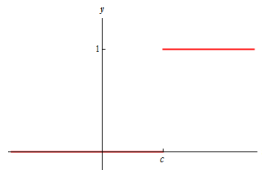
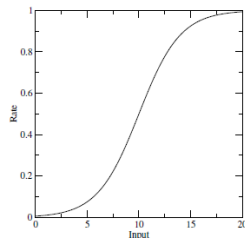
# Volume Model

The Hydra swells at the rate of  $v_0$  until sufficient neuron firing  $r(t)$  occurs inducing a 'pop'

$$\tau_v \frac{dv}{dt} = v_0 - \Phi_v(u)$$

where

- $v$  is the volume
- $v_0$  is the swelling rate ("the sphere inflates almost linearly in time" Kucken '08)
- $\tau_v$  is the time constant for the volume model
- $u$  is the control signal from the neuron network e.g., an accumulative firing rate
- $\Phi_v(\cdot)$  is the transfer function associated with the 'pop', e.g., sigmoidal or step function



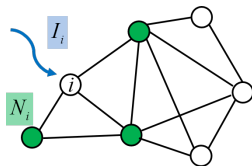
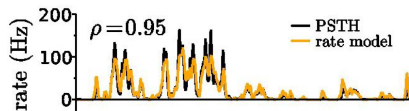
# Neuron Firing Rate Model

The average firing rate  $r_i(t)$  dynamics for neuron  $i$  (or subpopulation) is of the form

$$\frac{dr_i}{dt} = f(r_i, \{r_j\}_{N_i}, I_i)$$

where

- $\{r_j\}_{N_i}$  are the firing rates of neurons adjacent to  $i$
- $I_i$  is an external input to  $i$



## Rate equation

$$\tau_i \dot{r}_i = -r_i + \Phi_r \left( \sum_{j \in N_i} J_{ij} r_j + I_i \right), \text{ for } i = 1, 2, \dots, n$$

- $\tau_i$  is a time constant for neuron  $i$
- $J_{ij}$  is the coupling effect of neuron  $j$  on neuron  $i$
- $\Phi_r(\cdot)$  is a transfer function e.g., linear, threshold linear, sigmoidal

# Combined Dynamics

Now to connect the two models...

$$\tau_v \dot{v} = v_0 - \Phi_v(u)$$

$$\tau_i \dot{r}_i = -r_i + \Phi_r(J_i r + I), \text{ for } i = 1, 2, \dots, n$$

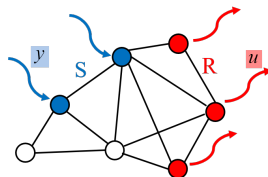
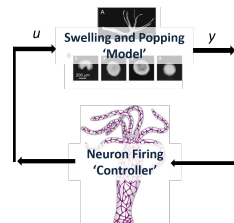
Sensing:  $y = I = b(S)$

- $S$  is the set of neurons that can 'sense' volume
- $b(S)$  encodes  $S$  as a binary vector, i.e.,

$$b_i(S) = \begin{cases} 1 & i \in S \\ 0 & \text{otherwise} \end{cases}$$

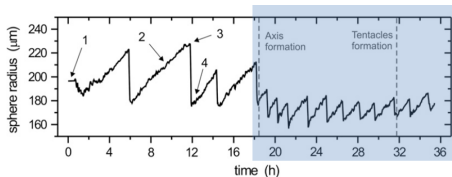
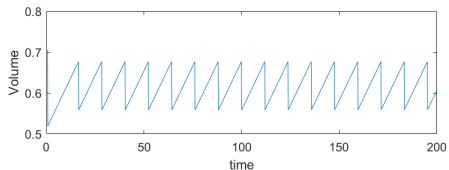
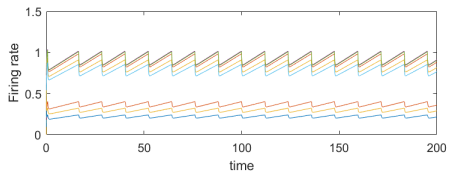
Control:  $u = c(R)^T r(t - t_d)$

- $R$  is the set of neurons associated with mouth opening ('actuators')
- $t_d$  is the time delay associated with the 'pop'
- $c(R)$  encodes  $R$  as a binary vector

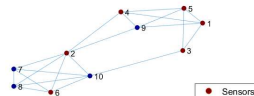


# Sample Performance

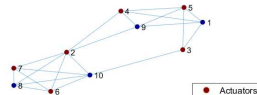
$\Phi_v(\cdot)$  is a step and  $\Phi_r(\cdot)$  is linear



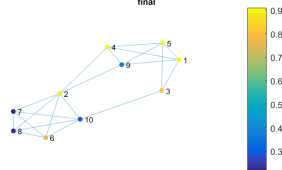
Topology and Sensor Locations



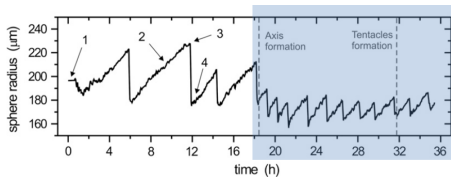
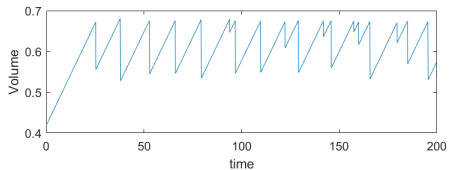
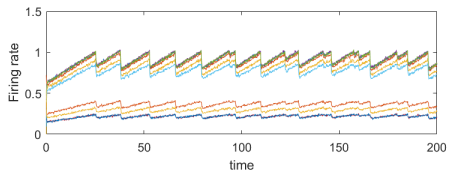
Topology and Actuator Locations



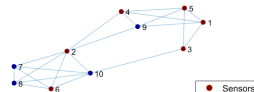
Rate Distribution at  $t_{\text{final}}$



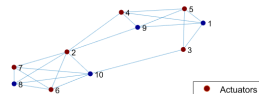
# Sample Performance with Noise



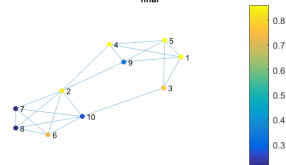
Topology and Sensor Locations



Topology and Actuator Locations



Rate Distribution at  $t_{\text{final}}$





# Next steps and directions...

## Refining the model

- Is there evidence that supports the proposed connection between the firing rate and mouth opening?
- Apply realistic swelling rates, time constants, scaling factors...
- Apply realistic network topologies, and sensor/actuator locations

## Control theory

- What is the role of the network? What characterized favorable network topologies?
- Where are the optimal sensor and actuator locations?
- Are certain configurations more robust to noise in sensors and actuator signals, and model uncertainty?
- What features make the system more amenable for control?
- If we were to perturb/control (or probe/observe) the topologies where are the best attachment (observation) points