

#### SCUOLA DI INGEGNERIA INDUSTRIALE E DELL'INFORMAZIONE

# Quality Data Analysis - Project Work [FULL PROJECT]

PROJECT REPORT OF QUALITY DATA ANALYSIS - MATHEMATICAL ENGINEERING

Team number: 1

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### Phase 1

### 1.1. Introduction

Ensuring product quality and operational efficiency is critical in modern manufacturing processes as the ability to detect defects in real-time during production, known as in-line detection, is essential for maintaining high standards and minimizing waste and costs. In-line defect detection allows in fact for immediate identification and correction of production errors, preventing defective products from progressing through the manufacturing process. This real-time monitoring enhances operational efficiency by reducing idle time and the need for rework. Furthermore, it helps in maintaining a high level of product quality, which is essential for customer satisfaction and competitiveness in the market.

The purpose of the project was to create a robust statistical process monitoring (SPC) method, specifically for the in-line detection of defects on Voronoi filters printed with an HP Jet Fusion 580 Color 3D printer. As our samples, we had filters organized on ten trays, each containing four filters, and their top-view gray-scale images were captured at the MADE Competence Center.

Our project was structured into two phases. In the first one we were given objects without any defects to develop our statistical process control method, while the second phase involved testing our proposed method to identify objects with various defects. We used the Shewhart univariate control chart and multivariate control chart to design our SPC methods, as they provide a visual and statistical method for monitoring process stability and detecting anomalous variations, helping the organization to maintain consistent quality and identify opportunities for process improvement.

In the following sections, we will detail the project's methodology, results, and implications, offering insights into how our SPC method could be adopted to drive quality improvements and operational capabilities.

# 1.2. Assumptions and preliminary data analysis

# Data manipulation

Once completed the image acquisition we ran the python script provided on webeep to generate the images' statistics, obtaining the first dataset, which we will refer to as df\_old.

At that initial stage the unique "key" which identified each of the four objects inside each image was the combination of the Image Name and Position variables, so we opted to combine them into a single identifier, Part\_ID, using a simple function. This way we could more easily refer to single objects in the subsequent analysis.

The python script also included a segmentation part, which automatically isolated the objects by cropping a region around them. However, the crop was quite large and the objects inside were tilted, so we decided to implement our own code to do the segmentation. We deemed this step necessary since we thought that to compare more fairly the statistics of the images we needed a "common ground" (that is, perfect framing) on which they should be computed.

To perform this correction we binarized the images using Otsu treshold, detected the borders using a Canny filter, selected the main outer edge, and from that we derived the parameters for the proper rotation matrix and crop region (see Figure 1). After this refinement we re-computed their statistics obtaining the dataset df\_new.

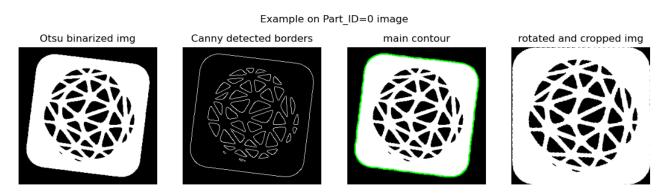


Figure 1: Visualization of the steps of our segmentation algorithm.

Before continuing with the analysis, we also deemed appropriate to split both old and new datasets into a *part* subset and a *void* subset, since they are constitutionally different features (the full object versus the small holes inside it), and we also saw a clear separation in the distribution of the variables, as depicted in Figure 2 and confirmed by ANOVA tests about the difference of the variables in the void and part groups, of which we report the pvalues of the tests in Table 1.

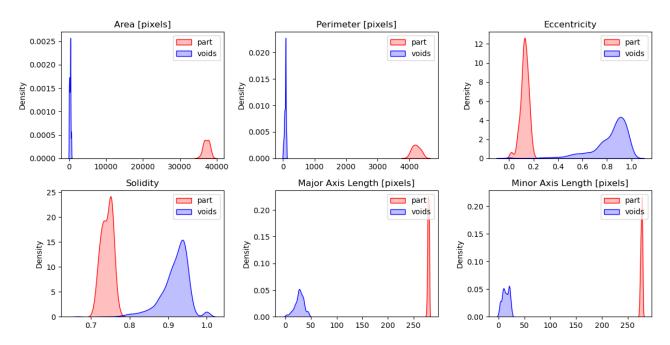


Figure 2: Visual comparison of the approximated distributions between parts and voids, for some variables of the df\_new dataset. Similar results were also present for the df\_old one.

Variable Name	Pvalue of ANOVA test
Area	0.0
Perimeter	0.0
Eccentricity	$4.3781482 \cdot 10^{-146}$
Orientation	$4.6979078 \cdot 10^{-8}$
Solidity	$2.8502201 \cdot 10^{-157}$
Extent	$2.4072606 \cdot 10^{-23}$
Major Axis Length	0.0
Minor Axis Length	0.0
Equivalent Diameter	0.0

Table 1: Pvalues of the ANOVA test, on each variable generated from the original python script, using the  $df_{new}$  dataset. The null hypothesis is that, for a certain variable i, the two groups have the same population mean.

# Dataset comparison

The two datasets, the old and the new one, seemed to provide different values, so we investigated this difference through nonparametric intervals (Boostrap t-intervals) and the respective tests. In this preliminary phase of our analysis we did not assume normality: that's why we chose to use a nonparametric approach to perform the comparison. We studied the parts separately from the voids.

About the parts we tested, for each variable i,

$$H_0: \mathbb{E}(\texttt{df\_old\_parts}[i]) = \mathbb{E}(\texttt{df\_new\_parts}[i]) \quad ext{vs} \quad H_1: H_0^c$$

and we obtained the following confidence intervals (where Voids number is a new variable that we quickly created to store how many voids each object had):

Variable name	Lower CI	Point Estimate	Upper CI	$0 \in CI$ ?
Area	-1539.53	-1452.3	-1362.32	no
Perimeter	87.112	96.9639	105.541	no
Eccentricity	-0.0022843	0.0025	0.00738961	yes
Orientation	-0.456515	-0.057225	0.0647833	yes
Solidity	-0.0227009	-0.02125	-0.0197547	no
Extent	0.00990142	0.017275	0.029109	no
Major Axis Length	1.02045	1.1686	1.3052	no
Minor Axis Length	0.914555	1.03865	1.15556	no
Equivalent Diameter	-4.4616	-4.20975	-3.94027	no
Voids number	-0.550939	-0.2	-0.0646082	no

Table 2: Confidence intervals for df\_old\_parts against df\_new\_parts variables.

As the majority of intervals do not include zero, we can confidently reject the null hypothesis in most cases with a confidence level of 95%, which means there is a substantial difference between df\_old\_parts and df\_new\_parts.

Regarding the voids the same test was conducted, albeit with a variation: in this case, we considered 40 distinct datasets, each corresponding to a different image (since originally we had ten images of trays, each of which with four objects) in order to compare the different variables related to the same image. So for each variable i referred to the image j we tested

$$H_0: \mathbb{E}(\mathtt{df\_old\_voids}^{(j)}[i]) = \mathbb{E}(\mathtt{df\_new\_voids}^{(j)}[i]) \quad \mathrm{vs} \quad H_1: H_0^c$$

and we obtained the following intervals (for the sake of example we show only the ones related to the first image, i.e.  $Part_ID = 0$ ):

Variable name	Lower CI	Point Estimate	Upper CI
Area	-27.3227	18.8049	63.3162
Perimeter	-3.93578	3.15383	9.72439
Eccentricity	-0.0363188	-0.00497561	0.0276549
Orientation	-0.462142	-0.0247073	0.382791
Solidity	-0.0273247	-0.0168537	-0.00623376
Extent	-0.0241511	0.00826829	0.0376097
Major Axis Length	-1.79098	0.688024	2.91621
Minor Axis Length	-1.0699	0.578268	2.20956
Equivalent Diameter	-1.0602	0.667683	2.34608

Table 3: Confidence intervals for the difference of variables between df\_old\_voids and df\_new\_voids; reported for Part\_ID = 0.

Almost all intervals seem to include zero and so we cannot reject the null hypothesis in the majority of the cases.

These tests show how there is a substantial difference between df\_old and df\_new (or regarding what we will focus on hereafter, df\_old\_parts and df\_new\_parts). However, this difference should be read as an improvement step, since the new dataset proved to have better regularity and properties with respect to the old one, for example granting gaussianity to some variables that didn't have it in the old dataset, not even after a box-cox transformation.

## Variables Analysis

In order to reduce the dimensionality and select only the necessary variables, we started from the ones respecting the assumptions of gaussianity (through a Shapiro-Wilk test) and excluding Voids number which being discrete couldn't be easily implemented in control charts.

As we will better describe in Section 1.3, we studied correlation both graphically, through a scatter plot, and quantitatively, through the correlation matrix (of which Figure 3 gives a visualization). From that we noticed how we could exclude some highly correlated variables and filter just a few "representatives" among them, in order to have a single variable carrying the information shared by multiple ones (e.g. Area, Extent and Solidity all relate to the amount of white pixels in the image). Indeed some variables conveyed the same information as others, a perfectly explainable result since the rotation and cropping had "standardized" the images, thus making some measurements redundant.

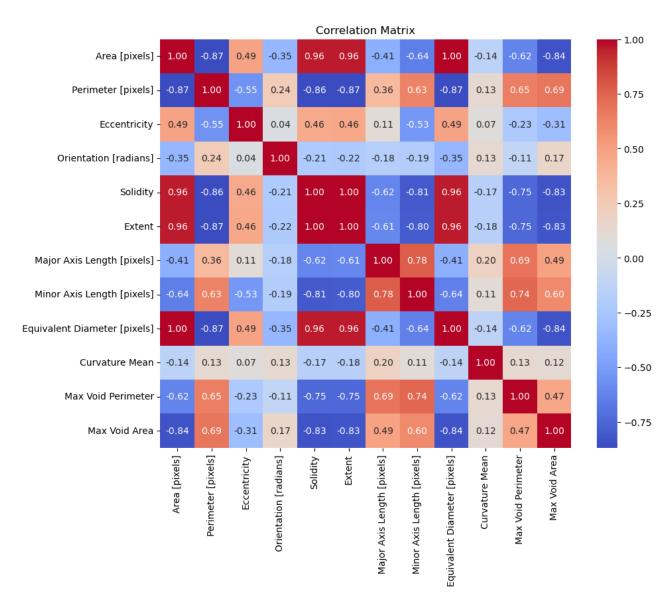


Figure 3: Correlation matrix of the variables of the dataset df\_new\_parts. The newly introduced variables Curvature Mean, Max Void Perimeter and Max Void Area will be defined in Section 1.3.

Another attempt at dimensionality reduction was brought through Principal Component Analysis. We applied PCA on the standardization of the dataset consisting of the previously selected uncorrelated columns, but the remaining dimensionality was still pretty high, and the loadings

didn't allow a simple interpretation (and were not gaussian).

A PCA had also been made on the complete dataset, but even if it highly reduced the number of dimensions needed, the problems with normality of the selected PCs and interpretability made the attempt unsuccessful.

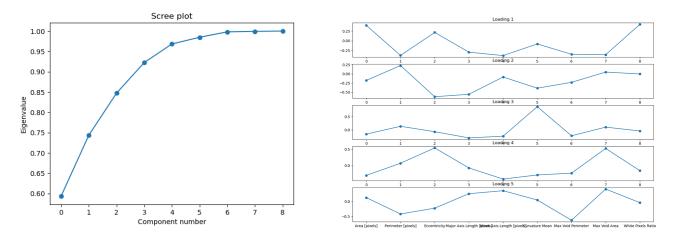


Figure 4: PCA results on the complete dataset.

# 1.3. Proposed metodology

Before describing in details the steps we performed, we would like to highlight a first important modeling choice. The structure of the collected data led us thinking about two possible approaches:

- 1. using the original images, in which there were four objects in each tray;
- 2. using the objects-isolating images, obtained trough the segmentation code.

Having in total 40 objects, case 1 would have implied to use m=10 samples with n=4 as sample size; while in case 2 we would have set m=40 and n=1, i.e. considering individual observations.

Since the printer prints objects individually, we though the second approach to be more useful in a real-life scenario, since it would imply a more accurate monitoring on each object, rather than waiting for a set of them to be printed and then control that set.

This clarification will be important only in Idea 1 and 2 sections; while now we illustrate the work we performed on the dataset variables.

Note that the second approach will be discussed in Section 1.4 as it will be one of the methods we will use in the second phase.

#### Variable selection and definition

As mentioned before, towards the building of control charts we decided to consider only the necessary variables, looking for the ones respecting the assumptions of gaussianity (through a Shapiro-Wilk test) and randomness (through a Runs test), and that seemed worthy and meaningful to be included.

Therefore, our main idea was to select a minimal set of variables (i.e., avoiding redundancies), which could be useful to detect objects' defects, taking into account both mathematical assumptions and qualitative reasoning.

In this direction, we chose to remove the following variables:

- Orientation, since the new dataset cropping removed any difference in orientation between images.
- Solidity and Extent, as the information was already captured by Area after the recentering correction.
- Eccentricity, as we were not sure about how the computation behind it worked, nor if it could be useful.
- Minor Axis Length, since we decided to keep Major Axis Length instead, which together with the minor (through a ratio) were highly correlated to Eccentricity; therefore including also the minor axis would have morally meant to include the eccentricity information, which instead we had discarded.

So we were left having saved Area, Perimeter and Major Axis Length.

To support our argument about Eccentricity ineffectiveness, we created an image with a visible deformation, but the obtained value seemed to be (wrongly) close to the correct ones. So in the end we did not valued this variable as interesting.

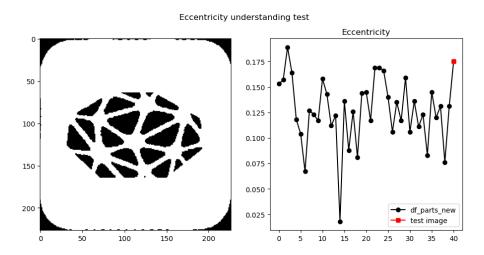


Figure 5: Plot of the test that we performed to understand the eccentricity variable.

Related to the df\_new\_voids, we decided not to keep any of the proposed variables because it made sense for us to include a variable if and only if it had a normal distribution in all images. However, we did not find any variable that satisfied this constraint. Moreover, we couldn't think the variables in that dataset as i.i.d. since the voids were different in terms of location and dimension, and problematic to group and compare. So we did not use this dataset as it was, but processed it to generate two new variables illustrated below.

After experimenting a bit trying to extract some more information from the images, we generated some new variables, to improve the descriptive capabilities of our model, and here we report the ones that made it to the control charts:

- 1. Curvature Mean. From our own segmentation code, we took the section about the main contour extraction and from there we computed the curvature for each set of three consecutive points. This new variable stores the mean of all those values.
- 2. Max Void Area. The voids of the objects were not i.i.d., due to different sizes and positions, so we could not use them altogether. Instead, we decided to consider, for each object, only the void with the biggest area (and not the one of smallest area because it wouldn't have been much informative as the segmentation of smaller voids was heavily affected by pixels noise).
- 3. Max Void Perimeter. With a reasoning similar to the previous variable, we decided to include the information about the perimeter of the biggest void inside each object. In

fact, the coefficient of correlation with Max Void Area was just 0.47, therefore we thought this variable as also worthy to be included.

Regarding voids but being related to each object individually, the last two variables were computed from df\_new\_voids but stored as new variable in df\_new\_parts, to have a single dataset to work on. Another new variable not included but still worth mentioning is White pixels ratio, created as an attempt to obtain a more robust equivalent of Area, being the new one a percentage of white pixels rather than a simple count.

The following table summarizes how these new variables, together with those already present, could detect defected pieces:

Variable	Kind of defect it could help to detect
Area	too many holes; broken pieces
Perimeter	wrong dimensions; presence of bulges
Major Axis Length	flattening deformations
Curvature Mean	cracks along perimeter
Max Void Area	too big void in the inside; wrongly shaped voids
Max Void Perimeter	voids collapsed together; weirdly shaped voids

Table 4: Interpretation about which kind of defects these selected variables could help to detect, through their control charts.

All the variables satisfied the gaussianity assumption but we had some problems regarding the independence assumption. We proposed two approaches to deal with it, based on the different weight and role given to time.

Variable	Shapiro Test pvalues	Dasaset
Area	0.7310	df_new_parts
Perimeter	0.8690	df_new_parts
Major Axis Length	0.0967	df_new_parts
Curvature Mean	0.5501	df_new_parts
Max Void Area	0.5666	df_new_parts
Max Void Perimeter	0.9064	df_new_parts

Table 5: Pvalues of the Shapiro test to check normality on the variables we selected for the control charts.

### Idea 1: FVC and SCC

The first approach we tried out consisted in treating the data as time series, assuming that issues with independence were caused by underlying models and patterns.

We started with I-MR-R charts, noticing an improvement already, but dealing whit the independence problems and building Fitted-Values chart (FVC) and Special-Cause chart (SCC), where needed, was a better idea.

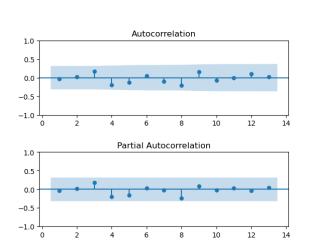
We present the results a variable at a time as ordered in Table 5.

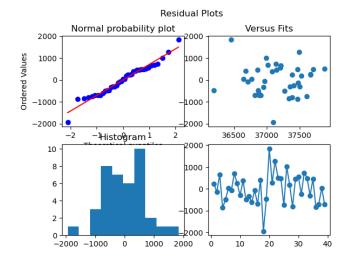
#### Area

Looking at the pvalue of the runs test (0.025) and at the auto-correlation plots, we noticed that the independence assumption was not reached.

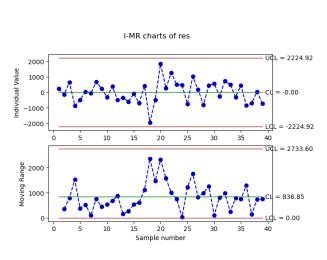
We decided to build an autoregressive model of order one (AR(1)) to model the data and obtain SCC and FVC control charts. The residuals were indipendent, with a pvalue for the runs test

of 0.254, gaussian with pvalue of shapiro-wilk of 0.496, and homoschedastic as shown in the plots below.





The obtained control charts were:



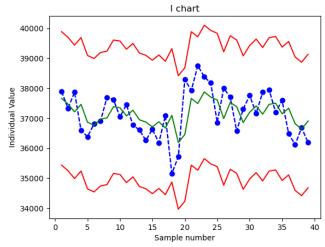


Figure 6: SCC for Area

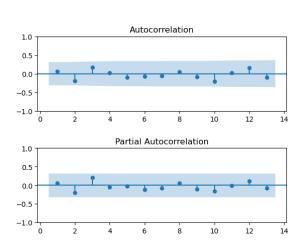
Figure 7: FVC for Area

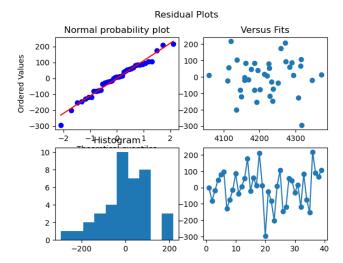
No strange pattern, outliers or out of control observations appear.

#### Perimeter

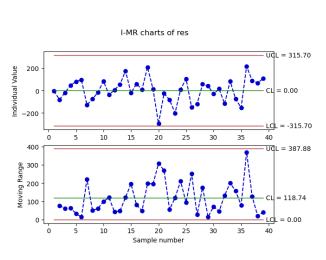
In the following variable we observed the same situation we experienced with the Area variable: we had Gaussian distribution but we missed independence (the pvalue of the run test was equal to 0.026).

As done before, we modeled the data with an AR(1) model obtaining independent residuals (the pvalue of the run test was equal to 0.436) with gaussian distribution (Shapiro-Wilk test p-value equal to 0.685) and same variance.





The related control charts were:



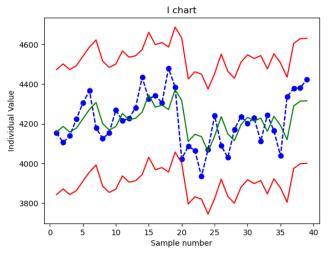


Figure 8: SCC for Area

Figure 9: FVC for Area

As before, no strange pattern, outliers or out of control observations appear.

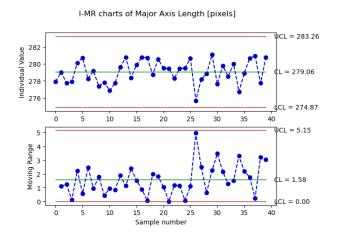
### Major Axis Length, Curvature Mean, Max Void Area and Max Void Perimeter

For all the remaining variables considered, both the assumptions, gaussianity and independence were satisfied. We measured, in fact, the following pvalues of the runs test:

Variable	Runs Test pvalues
Major Axis Length	0.749
Curvature Mean	0.522
Max Void Area	0.749
Max Void Perimeter	0.161

Table 6: Pvalues of the runs test to check independence.

So, we were able to build the "classical" SPC control charts on the original variables and not on the residuals.



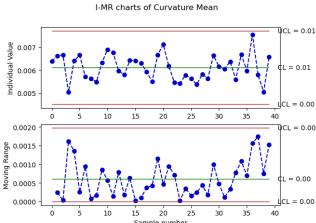
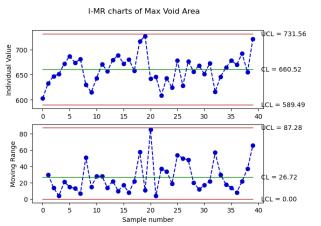


Figure 10: SPC for Major Axis Length

Figure 11: SPC for Curvature Mean



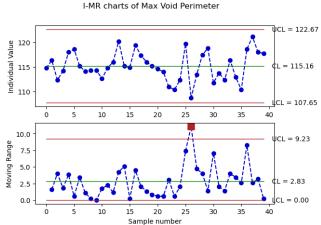


Figure 12: SPC for Max Void Area

Figure 13: SPC for Max Void Perimeter

As we can see, only an out of control observation seems to be present in our control charts but no assignable cause were found. In addition to this, it is related to the Moving Range control chart that, as explained below, it will not useful for our scope. So, all the previous control charts are acceptable.

#### 1.4. Results

As final models for Phase 1 and in anticipation of Phase 2, we present the following approaches:

- 1. Individual control charts on shuffled data, i.e Idea 2
- 2. Multivariate control charts on not shuffled data
- 3. Multivariate control charts on shuffled data

More details will be given in the sections below.

#### Idea 2: Charts on shuffled data

Due to the mechanism of the image acquisition, we could assume that the obtained data should not be considered as a time series. In fact, the objects to be placed in the trays were selected in a random order (not "carefully" as if they had a precise time indication). In other words, even if originally existed a particular time ordering, the one in which the objects came out from the printer, the acquisition procedure made it to be lost; and we would have considered time only if their placement in the trays followed the precise order in which they came out from the printer. Indeed all the objects were in control, by design of the project, and they were disposed in the trays randomly, not according to a particular order.

Therefore, consistently with this idea, we could assert that there should be no problems with independence in the data, considering any independence problem as being caused by chance.

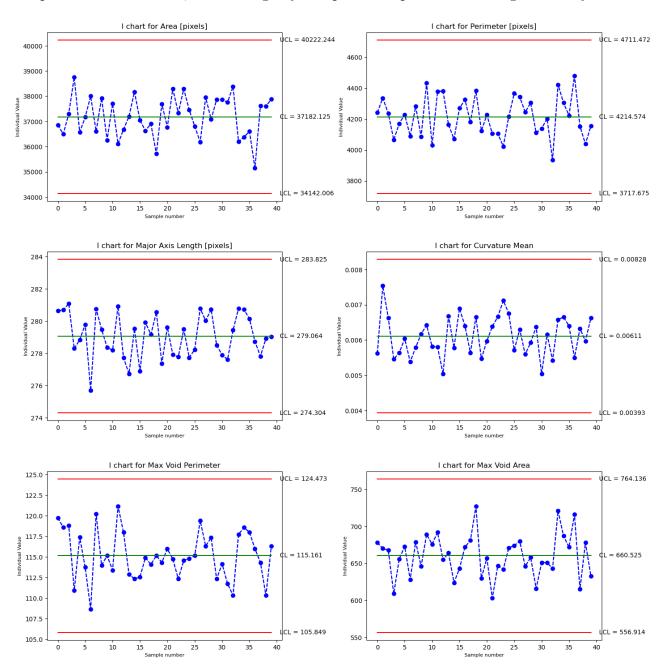


Figure 14: I charts, for the six variables we selected, generated according to the Idea 2.

For this reason, since the order in which objects were originally stored in the dataset caused problems with independence through the Runs test, as mentioned in Idea 1 section, we decided to shuffle the data.

This suited the new context since this procedure had no problems with respect to time issues, and having the objects randomly placed at the beginning meant that we could possibly re-order them in any way, without altering the design and construction of the experiment. This shuffling made us obtain independence (as the Runs tests showed in Table 7) which, as said, according

to the experiment design should have been there "by default".

Variable	Runs Test pvalues
Area	0.521
Perimeter	0.193
Major Axis Length	0.200
Curvature Mean	0.749
Max Void Perimeter	0.789
Max Void Area	0.109

Table 7: Pvalues of the Runs test to check randomness assumption in the shuffled dataset.

As we saw in the previous sections we had no problems with the gaussianity assumption, and therefore we built the control chart using this shuffled df\_new\_parts dataset. The resulting charts are depicted in Figure 14.

The random permutation introduced slight changes in the MR computation, as the random re-ordering made that the moving range values changed from shuffle to shuffle. But on average they were very close so this was not considered as a problem. Due to this slight variability, however, we just focused on the I charts and ignored the MR ones.

We decided to apply a Bonferroni correction in the end, since we made multiple (six) univariate charts on the same data so that each chart was individually built with a  $\alpha = \frac{\alpha_{\text{tot}}}{6} = \frac{0.0027}{6}$ , which gave a K = 3.5. The correction leads to larger value of K, so a more precise choice could be to try a single multivariate chart; but nonetheless the univariate charts would allow for better interpretability in identifying the variable causing the defect.

Even if we were not sure of this Idea 2, lacking some theoretical results to support it, we considered it convincing; a sense proved by the comparison with the "classical" ones found in Idea 1. Indeed, for the variables which satisfied both the assumptions of normality and independence (Major Axis Length, Curvature Mean, Max Void Perimeter, Max Void Area) the limits obtained are very similar. This proves somehow the robustness of this approach. For the remaining variables Area and Perimeter we cannot compare them since in Idea 1 we built the limits on the residuals of their models. In addition to this, they are the ones with the most plausible and consistent hypothesis, as well as lacking issues of hugging or false alarms.

However we would compare it with the following multivariate charts, to see which method will perform better on Phase 2 data and investigate the strength and weaknesses of the two approaches.

#### Multivariate Control Charts

After the variable selection we performed, the multivariate charts seemed a natural and valid alternative to the individual charts. As we have seen, we saved six variables, and on them we conducted the multivariate analysis.

Normality assumption (marginally) was satisfied, as we checked before. Regarding the independence assumption not all the variables passed the Runs test, as we saw when describing Idea 1. Nonetheless we proceeded building the charts, considering that time, as described in Idea 2, was not really to be considered for this Phase 1 data.

Regarding the estimate of the variance matrix S, we explored both short and long period approximations, using the upper control limit given by the Beta distribution, as we are in Phase 1. However, the short one caused a false alarm in an observation. This was surely a false alarm, since all the images in this phase were of good objects, and was probably caused by

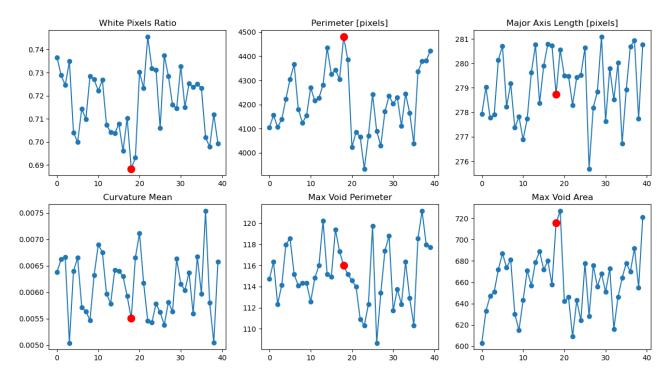


Figure 15: Highlight on the statistics of the object which produced the false alarm.

an object having two quite extreme values on Area and Perimeter variables, as we saw when inspecting the data in Figure 15 highlighting the values of the signaled object.

We therefore decided to keep the long period one, which did not raise any alarms and should in any case be accurate since we don't have outliers nor out of control data in this design phase. We employed an  $\alpha = 0.0027$  and the final chart is reported in Figure 16.

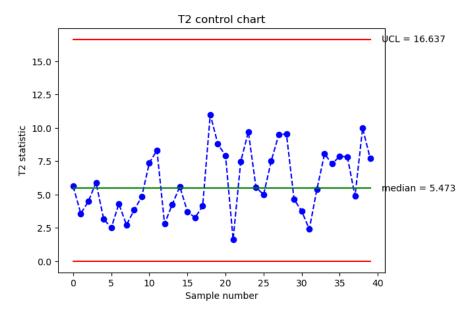


Figure 16: Multivariate chart for Phase 1, combining the six variables we selected, using *long period* estimation for S and the *original version* of df\_new\_parts.

Actually, we saw that the problem of the alarm in the short period estimation case was solved by using the shuffled version of the dataset, in a similar way in which it solved the MR issue. So as a final chart we propose the one of Figure 17, derived from the union of the multivariate and shuffling ideas.

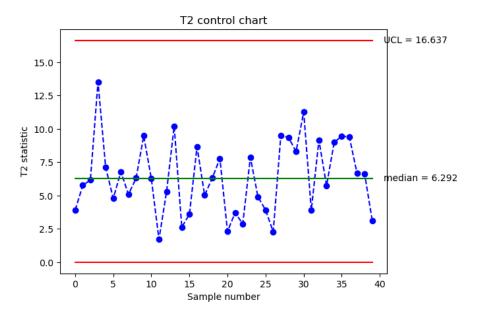


Figure 17: Multivariate chart for Phase 1, combining the six variables we selected, using *short period* estimation for S and the *shuffled version* of df\_new\_parts.

# References

- [1] J. Hao. Segmentation implementation: Given an image and a 4 points in the image (no 3 points are co-linear). find the rotated rectangle enclosing the polygon formed by the 4 points and crop the rotated rectangle from the image. all done by opency. https://gist.github.com/jdhao/1cb4c8f6561fbdb87859ac28a84b0201, 2018.
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