Optimization-Based Meta-Learning (finishing from last time)

Non-Parametric Few-Shot Learning

CS 330

Logistics

Homework 1 due, Homework 2 out this Wednesday

Fill out **poster presentation preferences**! (Tues 12/3 or Weds 12/4)

Course project details & suggestions posted

Proposal due Monday 10/28

Plan for Today

Optimization-Based Meta-Learning

- Recap & discuss advanced topics

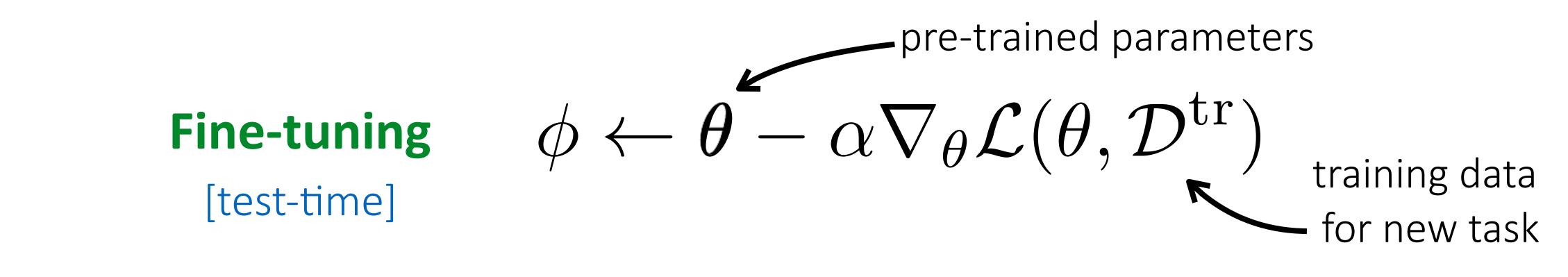
Non-Parametric Few-Shot Learning

- Siamese networks, matching networks, prototypical networks

Properties of Meta-Learning Algorithms

- Comparison of approaches

Recap from Last Time



MAML

$$\min_{\theta} \sum_{\text{task } i} \mathcal{L}(\theta - \alpha \nabla_{\theta} \mathcal{L}(\theta, \mathcal{D}_{i}^{\text{tr}}), \mathcal{D}_{i}^{\text{ts}})$$

Optimizes for an effective initialization for fine-tuning.

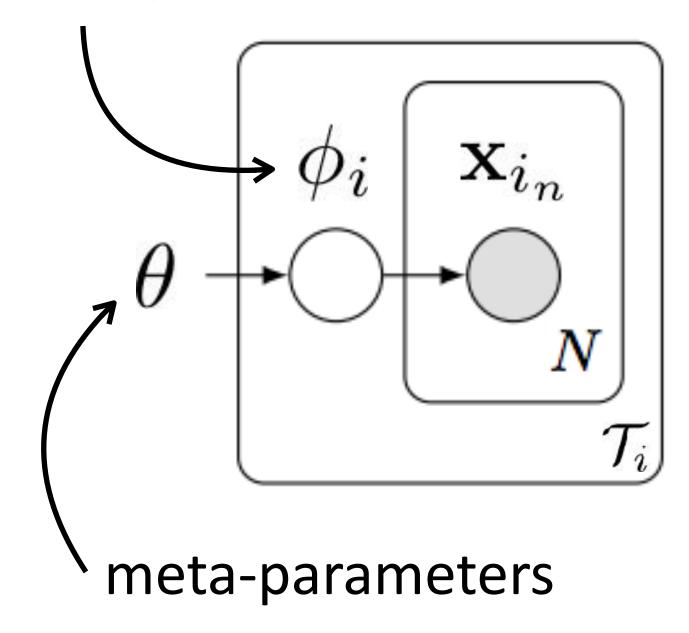
Discussed: performance on extrapolated tasks, expressive power

Probabilistic Interpretation of Optimization-Based Inference

Key idea: Acquire ϕ_i through optimization.

Meta-parameters θ serve as a prior. One form of prior knowledge: initialization for fine-tuning

task-specific parameters



$$\begin{split} \max_{\theta} \log \prod_{i} p(\mathcal{D}_{i}|\theta) \\ &= \log \prod_{i} \int p(\mathcal{D}_{i}|\phi_{i}) p(\phi_{i}|\theta) d\phi_{i} \quad \text{(empirical Bayes)} \\ &\approx \log \prod_{i} p(\mathcal{D}_{i}|\hat{\phi}_{i}) p(\hat{\phi}_{i}|\theta) \\ &\approx \text{MAP estimate} \end{split}$$

How to compute MAP estimate?

Gradient descent with early stopping = MAP inference under

Gaussian prior with mean at initial parameters [Santos '96]

(exact in linear case, approximate in nonlinear case)

MAML approximates hierarchical Bayesian inference. Grant et al. ICLR '18

Key idea: Acquire ϕ_i through optimization.

Meta-parameters θ serve as a prior. One form of prior knowledge: initialization for fine-tuning

Gradient-descent + early stopping (MAML): implicit Gaussian prior $\phi \leftarrow \theta - \alpha \nabla_{\theta} \mathcal{L}(\theta, \mathcal{D}^{\mathrm{tr}})$

Other forms of priors?

Gradient-descent with explicit Gaussian prior $\phi \leftarrow \min_{\phi'} \mathcal{L}(\phi', \mathcal{D}^{\mathrm{tr}}) + \frac{\lambda}{2} ||\theta - \phi'||^2$

Rajeswaran et al. implicit MAML '19

Bayesian linear regression on learned features Harrison et al. ALPaCA '18

Closed-form or convex optimization on learned features

ridge regression, logistic regression
Bertinetto et al. R2-D2 '19

support vector machine

Lee et al. MetaOptNet '19

Current **SOTA** on few-shot image classification

Key idea: Acquire ϕ_i through optimization.

Challenges

How to choose architecture that is effective for inner gradient-step?

Idea: Progressive neural architecture search + MAML (Kim et al. Auto-Meta)

- finds highly non-standard architecture (deep & narrow)
- different from architectures that work well for standard supervised learning

Minilmagenet, 5-way 5-shot MAML, basic architecture: 63.11%

MAML + AutoMeta: **74.65%**

Key idea: Acquire ϕ_i through optimization.

Challenges

Bi-level optimization can exhibit instabilities.

Idea: Automatically learn inner vector learning rate, tune outer learning rate (Li et al. Meta-SGD, Behl et al. AlphaMAML)

Idea: Optimize only a subset of the parameters in the inner loop (Zhou et al. DEML, Zintgraf et al. CAVIA)

Idea: Decouple inner learning rate, BN statistics per-step (Antoniou et al. MAML++)

Idea: Introduce context variables for increased expressive power.

(Finn et al. bias transformation, Zintgraf et al. CAVIA)

Takeaway: a range of simple tricks that can help optimization significantly

Key idea: Acquire ϕ_i through optimization.

Challenges

Backpropagating through many inner gradient steps is compute- & memory-intensive.

Idea: [Crudely] approximate $\frac{d\phi_i}{d\theta}$ as identity (Finn et al. first-order MAML '17, Nichol et al. Reptile '18)

Takeaway: works for simple few-shot problems, but (anecdotally) not for more complex meta-learning problems.

Can we compute the meta-gradient without differentiating through the optimization path?

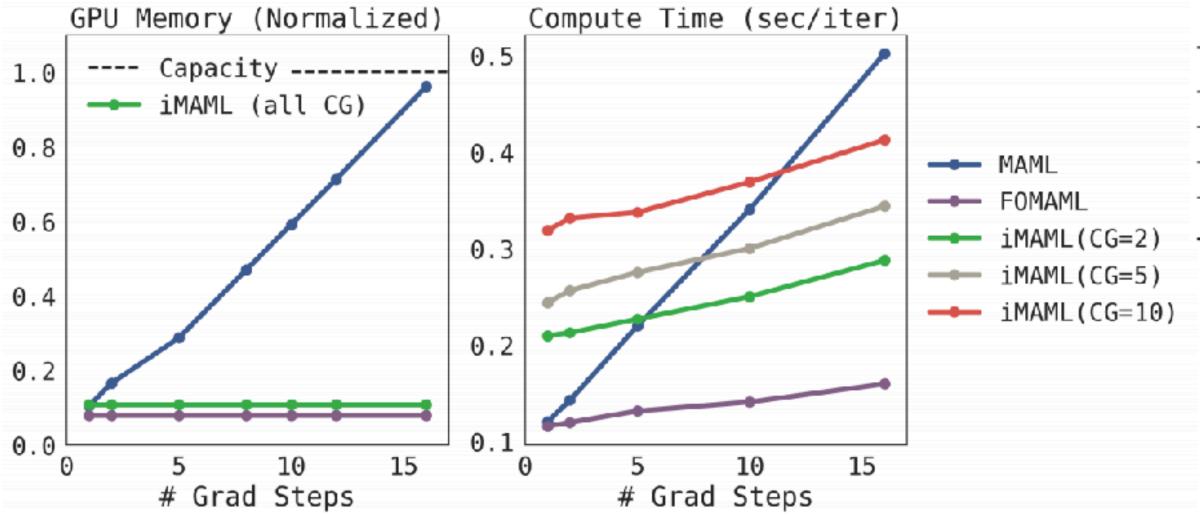
-> whiteboard

Idea: Derive meta-gradient using the implicit function theorem (Rajeswaran, Finn, Kakade, Levine. Implicit MAML '19)

Can we compute the meta-gradient without differentiating through the optimization path?

Idea: Derive meta-gradient using the implicit function theorem (Rajeswaran, Finn, Kakade, Levine. Implicit MAML)

Memory and computation trade-offs



Allows for second-order optimizers in inner loop

Algorithm	5-way 1-shot	5-way 5-shot	20-way 1-shot	20-way 5-shot
MAML [15]	$98.7 \pm 0.4\%$	$\textbf{99.9} \pm \textbf{0.1\%}$	$95.8 \pm 0.3\%$	$98.9 \pm 0.2\%$
first-order MAML [15]	$98.3 \pm 0.5\%$	$99.2 \pm 0.2\%$	$89.4 \pm 0.5\%$	$97.9 \pm 0.1\%$
Reptile [43]	$97.68 \pm 0.04\%$	$99.48 \pm 0.06\%$	$89.43 \pm 0.14\%$	$97.12 \pm 0.32\%$
iMAML, GD (ours)	$99.16 \pm 0.35\%$	$99.67 \pm 0.12\%$	$94.46 \pm 0.42\%$	$98.69 \pm 0.1\%$
iMAML, Hessian-Free (ours)	$99.50 \pm 0.26\%$	$99.74 \pm 0.11\%$	$96.18 \pm 0.36\%$	$\textbf{99.14} \pm \textbf{0.1}\%$

A very recent development (NeurIPS '19) (thus, all the typical caveats with recent work)

Key idea: Acquire ϕ_i through optimization.

Takeaways: Construct bi-level optimization problem.

- + positive inductive bias at the start of meta-learning
- + consistent procedure, tends to extrapolate better
- + maximally expressive with sufficiently deep network
- + model-agnostic (easy to combine with your favorite architecture)
- typically requires second-order optimization
- usually compute and/or memory intensive

Can we embed a learning procedure without a second-order optimization?

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Non-Parametric Few-Shot Learning

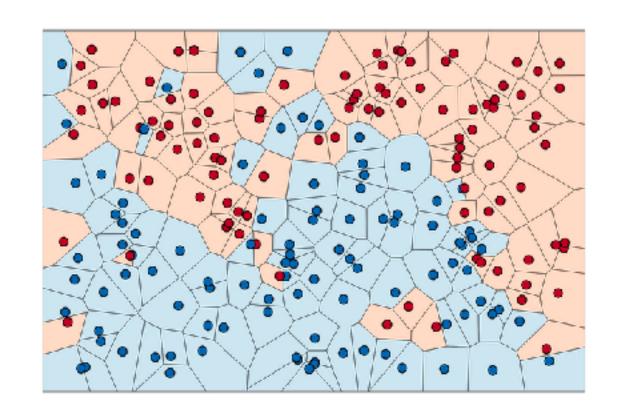
- Siamese networks, matching networks, prototypical networks

Properties of Meta-Learning Algorithms

- Comparison of approaches

So far: Learning parametric models.

In low data regimes, **non-parametric** methods are simple, work well.



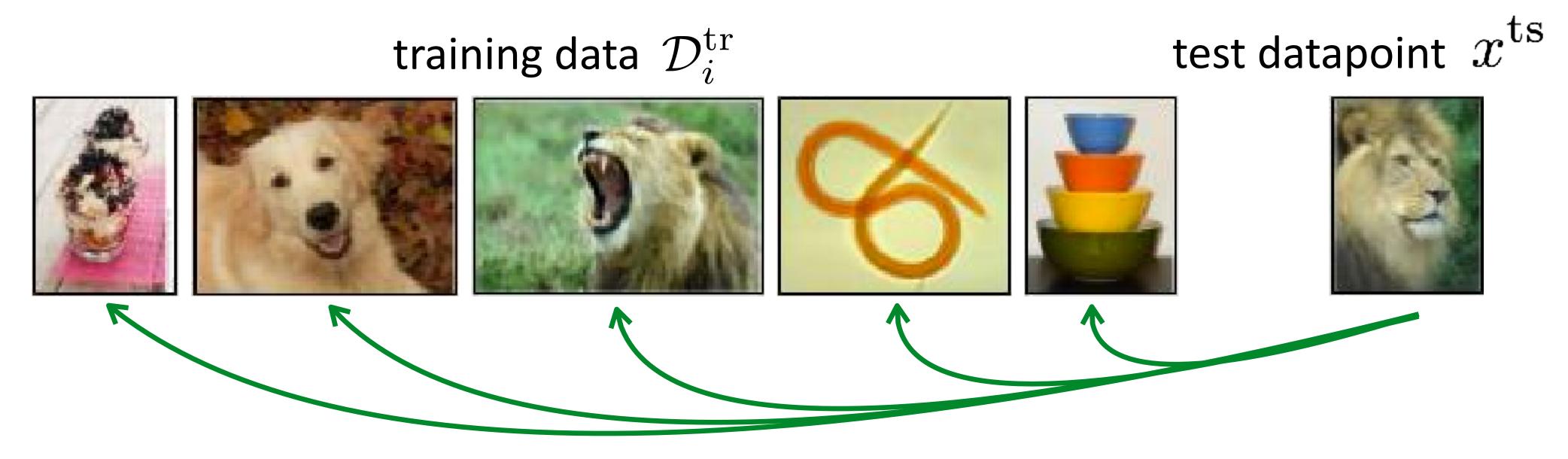
During meta-test time: few-shot learning <-> low data regime

During meta-training: still want to be parametric

Can we use parametric meta-learners that produce effective non-parametric learners?

Note: some of these methods precede parametric approaches

Key Idea: Use non-parametric learner.



Compare test image with training images

In what space do you compare? With what distance metric?

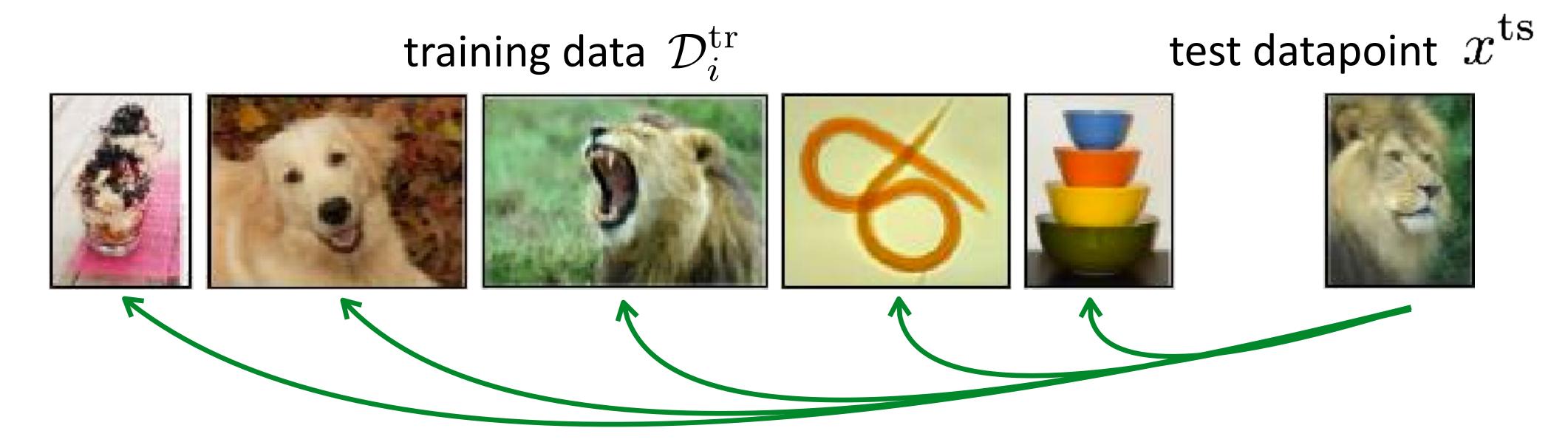
pixel space, l₂ distance?

In what space do you compare? With what distance metric?

pixel space, l₂ distance?



Key Idea: Use non-parametric learner.



Compare test image with training images

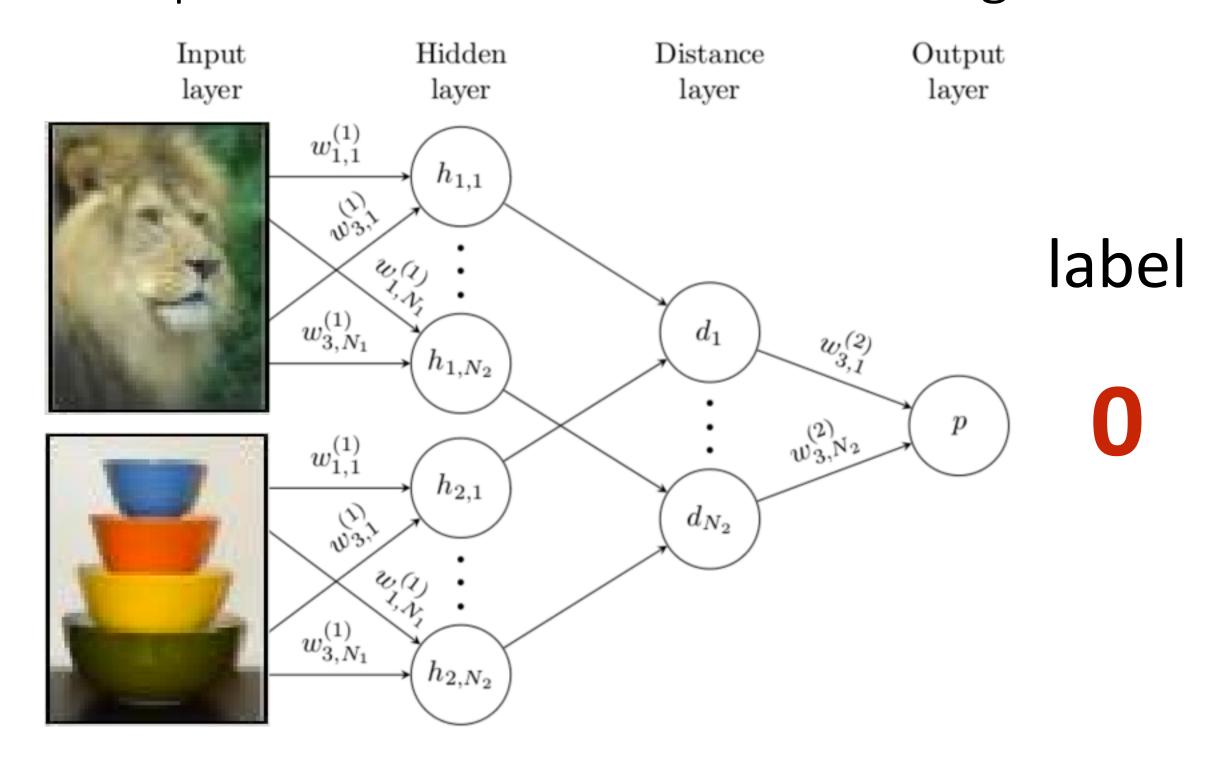
In what space do you compare? With what distance metric?

pixel space, l₂ distance?

Learn to compare using meta-training data!

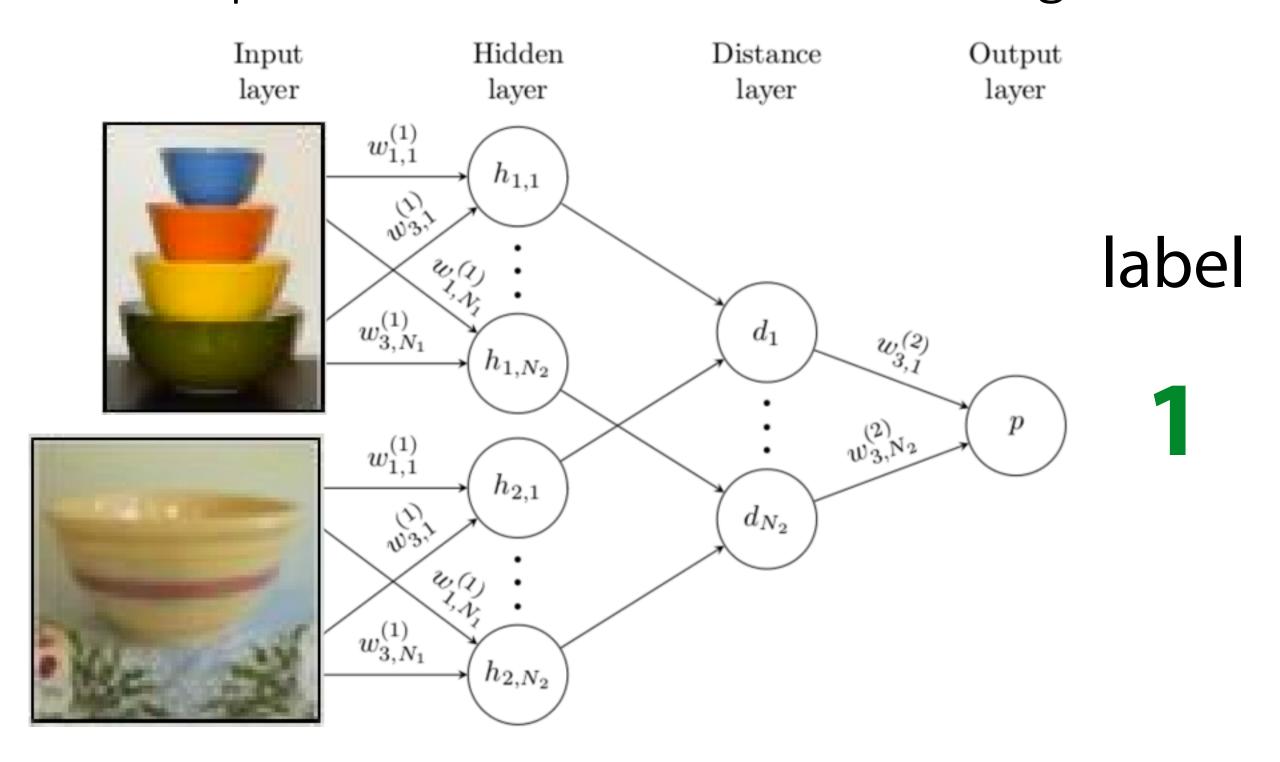
Key Idea: Use non-parametric learner.

train Siamese network to predict whether or not two images are the same class



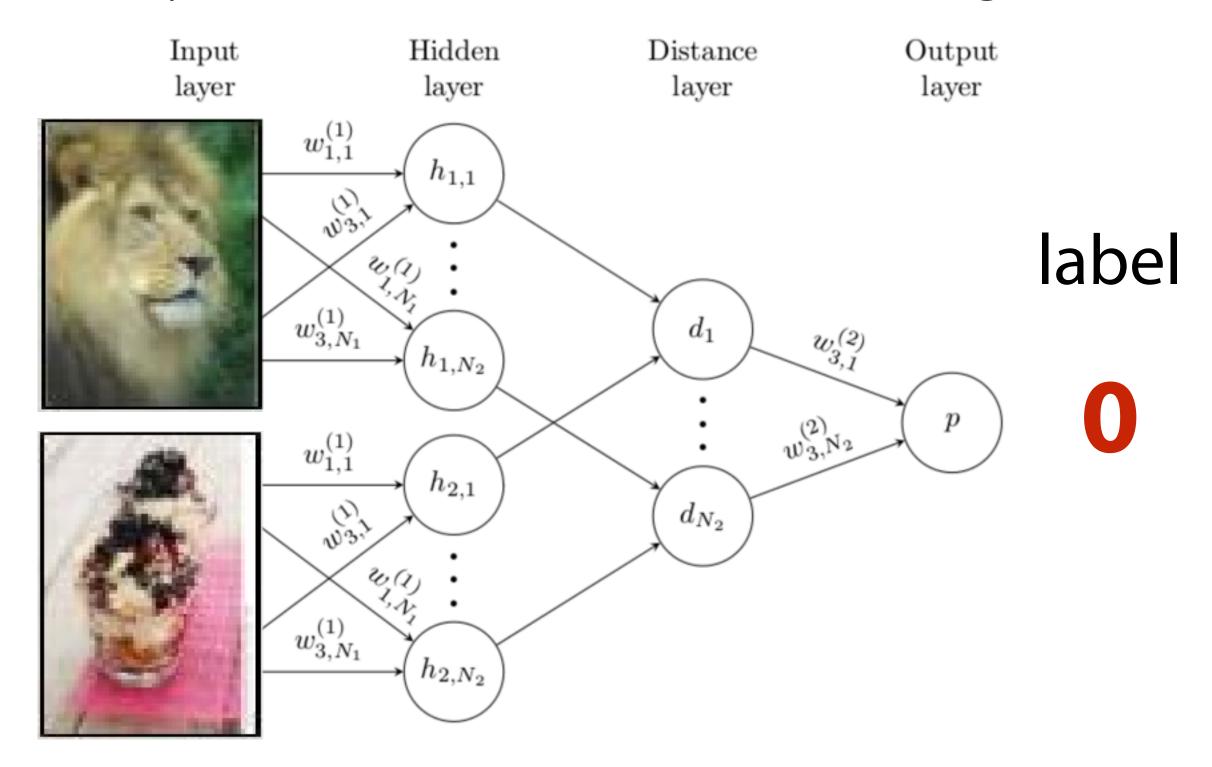
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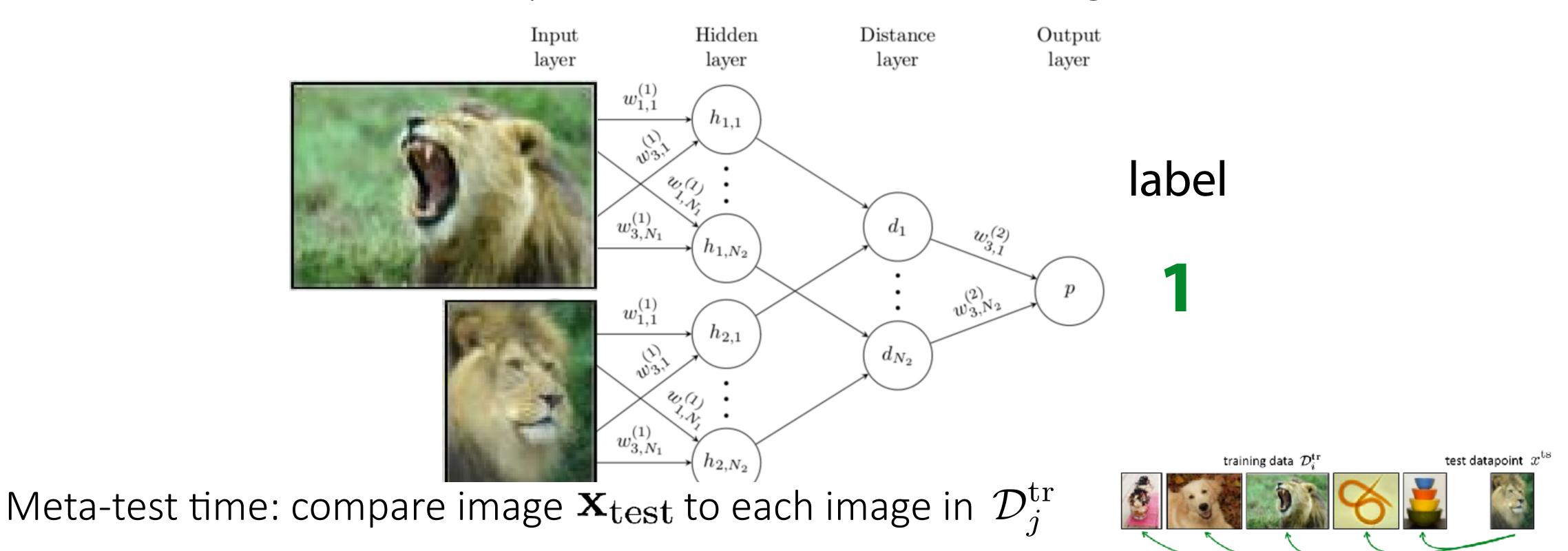
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Meta-training: Binary classification

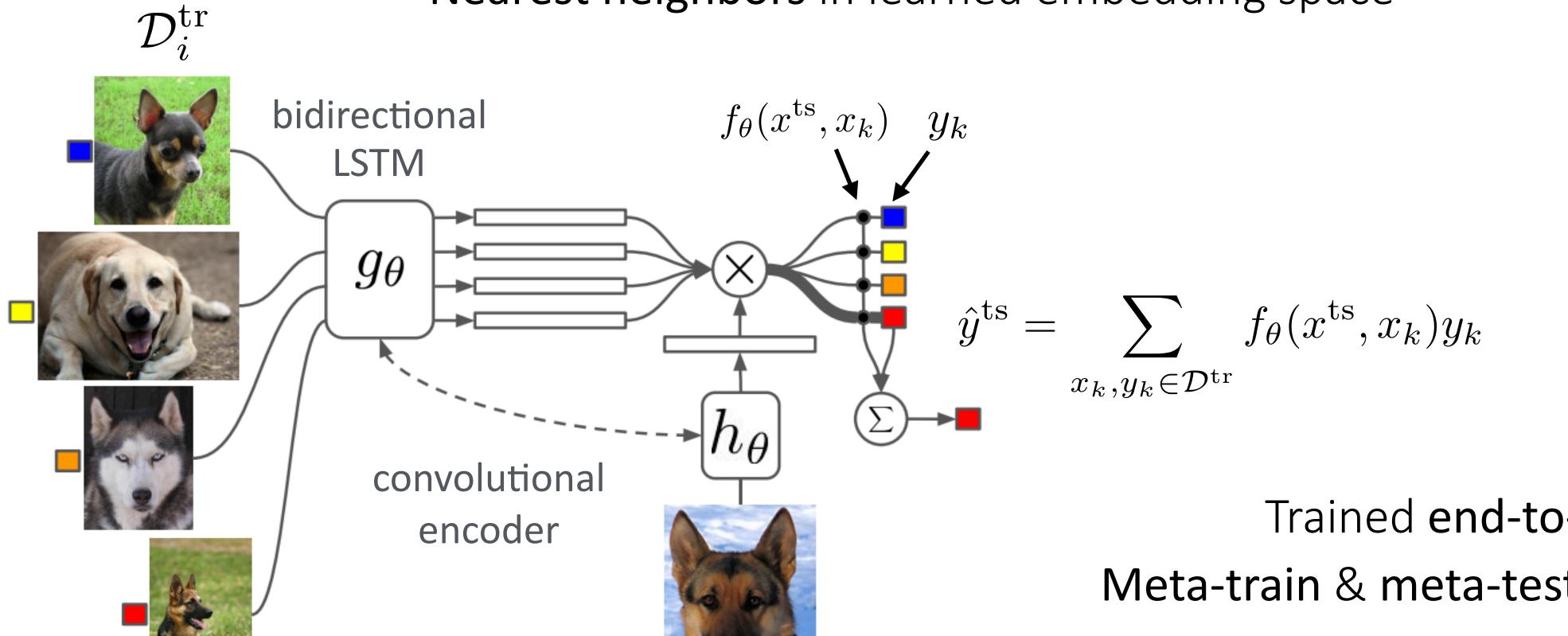
Meta-test: N-way classification

Can we **match** meta-train & meta-test?

Key Idea: Use non-parametric learner.

Can we **match** meta-train & meta-test?

Nearest neighbors in learned embedding space



Trained end-to-end.

Meta-train & meta-test time match.

Key Idea: Use non-parametric learner.

General Algorithm:

Amortized approach Non-parametric approach (matching networks)

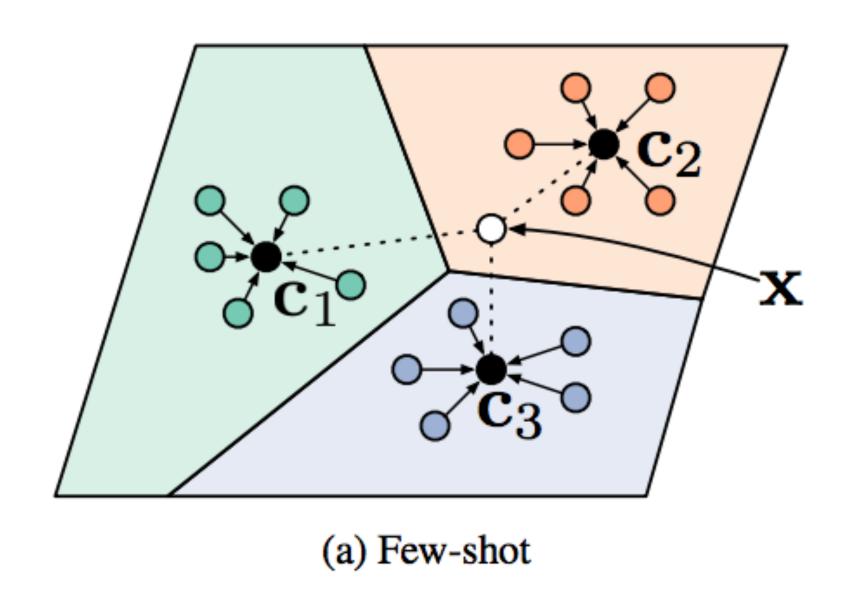
- 1. Sample task \mathcal{T}_i (or mini batch of tasks)

 2. Sample disjoint datasets $\mathcal{D}_i^{\mathrm{tr}}, \mathcal{D}_i^{\mathrm{test}}$ from \mathcal{D}_i
- (Parameters ϕ integrated 3. Compute $\phi_i \leftarrow f_{\theta}(\mathcal{D}_i^{\text{tr}})$ Compute $\hat{y}^{\text{ts}} = \sum_{x_k, y_k \in \mathcal{D}^{\text{tr}}} f_{\theta}(x^{\text{ts}}, x_k) y_k$ 4. Update θ using $\nabla_{\theta} \mathcal{L}(\phi_i, \mathcal{D}_i^{\text{test}})$ Update θ using $\nabla_{\theta} \mathcal{L}(\hat{y}^{\text{ts}}, y^{\text{ts}})$ out, hence non-parametric)

What if >1 shot?

Matching networks will perform comparisons independently Can we aggregate class information to create a prototypical embedding?

Key Idea: Use non-parametric learner.



$$\mathbf{c}_n = \frac{1}{K} \sum_{(x,y) \in \mathcal{D}_i^{\mathrm{tr}}} \mathbb{1}(y=n) f_{\theta}(x)$$

$$p_{\theta}(y=n|x) = \frac{\exp(-d(f_{\theta}(x), \mathbf{c}_n))}{\sum_{n'} \exp(d(f_{\theta}(x), \mathbf{c}_{n'}))}$$

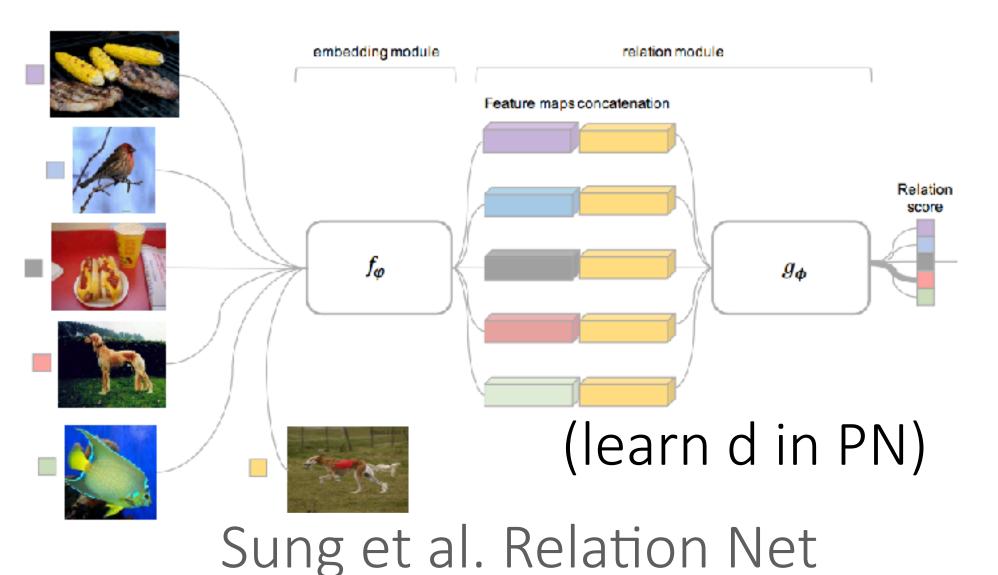
d: Euclidean, or cosine distance

So far: Siamese networks, matching networks, prototypical networks Embed, then nearest neighbors.

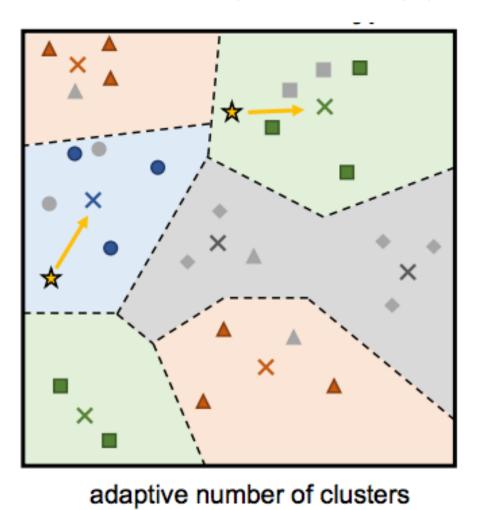
Challenge

What if you need to reason about more complex relationships between datapoints?

Idea: Learn non-linear relation module on embeddings

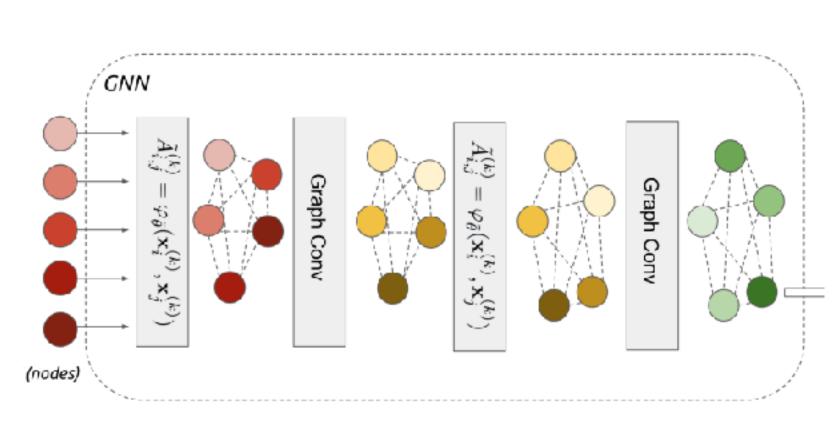


Idea: Learn infinite mixture of prototypes.



Allen et al. IMP, ICML '19

Idea: Perform message passing on embeddings



Garcia & Bruna, GNN

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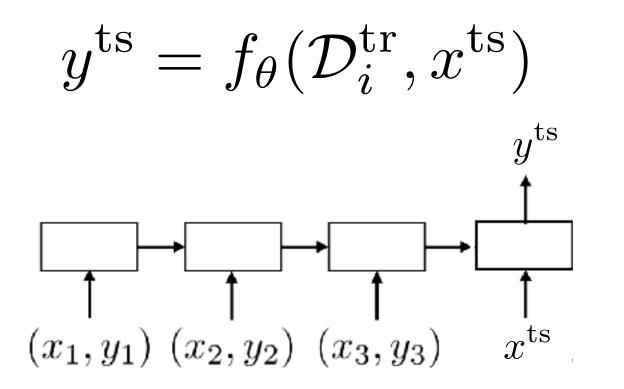
Properties of Meta-Learning Algorithms

- Comparison of approaches

How can we think about how these methods compare?

Computation graph perspective

Black-box



Optimization-based

$$y^{\text{ts}} = f_{\theta}(\mathcal{D}_{i}^{\text{tr}}, x^{\text{ts}}) \qquad y^{\text{ts}} = f_{\text{MAML}}(\mathcal{D}_{i}^{\text{tr}}, x^{\text{ts}}) \qquad y^{\text{ts}} = f_{\text{PN}}(\mathcal{D}_{i}^{\text{tr}}, x^{\text{ts}})$$

$$= softmax(-d\left(f_{\theta}(x^{\text{ts}}), \mathbf{c}_{n}\right))$$

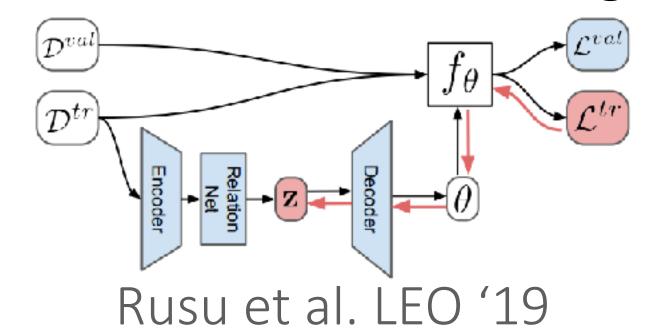
$$\Rightarrow \text{where } \phi_{i} = \theta - \alpha \nabla_{\theta} \mathcal{L}(\theta, \mathcal{D}_{i}^{\text{tr}}) \quad \text{where } \mathbf{c}_{n} = \frac{1}{K} \sum_{(x, y) \in \mathcal{D}^{\text{tr}}} \mathbb{1}(y = n) f_{\theta}(x)$$

Note: (again) Can mix & match components of computation graph

Both condition on data & run gradient descent.

Jiang et al. CAML '19

Gradient descent on relation net embedding.



MAML, but initialize last layer as ProtoNet during meta-training

Non-parametric

Triantafillou et al. Proto-MAML '19

Algorithmic properties perspective

Expressive power

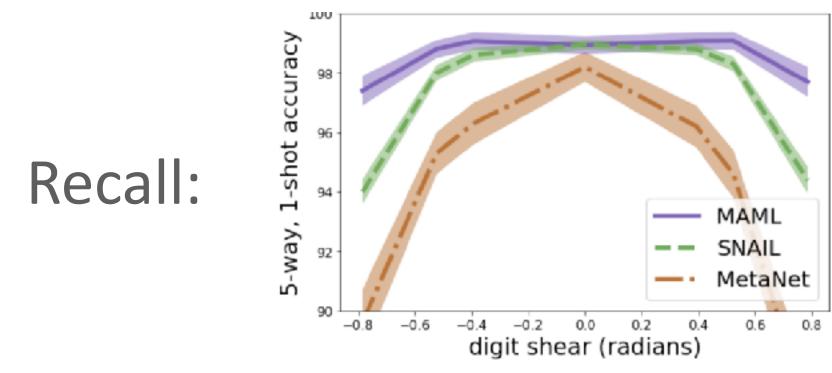
the ability for f to represent a range of learning procedures *Why?* scalability, applicability to a range of domains

Consistency

reduce reliance on meta-training tasks,

why?

good OOD task performance



These properties are important for most applications!

Black-box

- + complete expressive power
- not consistent
- + easy to combine with variety of learning problems (e.g. SL, RL)
- challenging optimization (no inductive bias at the initialization)
- often data-inefficient

Optimization-based

- + consistent, reduces to GD
- ~ expressive for very deep models*
 - + positive inductive bias at the start of meta-learning
 - + handles varying & large K well
 - + model-agnostic
 - second-order optimization
- usually **compute** and **memory** intensive

Non-parametric

- + expressive for most architectures
- ~ consistent under certain conditions
- + entirely **feedforward**
- + computationally fast & easy to optimize
- harder to generalize to varying K
- hard to scale to very large K
- so far, limited to classification

Generally, well-tuned versions of each perform comparably on existing few-shot benchmarks!

(likely says more about the benchmarks than the methods)

Which method to use depends on your use-case.

Algorithmic properties perspective

Expressive power

the ability for f to represent a range of learning procedures *Why?* scalability, applicability to a range of domains

Consistency

learned learning procedure will solve task with enough data reduce reliance on meta-training tasks, good OOD task performance

Uncertainty awareness

ability to reason about ambiguity during learning active learning, calibrated uncertainty, RL principled Bayesian approaches

We'll discuss this next time!

Reminders

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