

## Lab 3 - Exercise 4

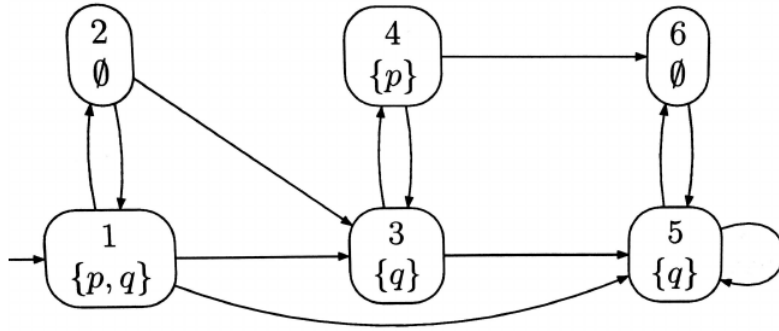
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March 7, 2021

### 1 Exercise 6

For the Labelled Transition System below, compute the following sets of states:



1.  $\llbracket EFp \rrbracket$
2.  $\llbracket AFq \rrbracket$
3.  $\llbracket \varphi \rrbracket$ , where  $\varphi = E(qU(p \wedge \neg q))$
4.  $\llbracket \varphi \rrbracket$ , where  $\varphi = EGq \vee (EGp \wedge EFq)$

### 2 Solving of exercise 6

Elementary temporal modalities that are present in the most temporal logics include the operators:

$F(\diamond)$  "eventually" (eventually in the future)

$G(\Box)$  "always" (now and forever in the future)

#### Definition(Semantics of CTL and CTL\*)

Let  $\pi = s_0, s_1, \dots$  be a path and  $\varphi$  a CTL\* formula. If  $\pi_i$  is the suffix of  $\pi$  starting from position  $i$ ,

- $\pi, i \models \top$
- $\pi, i \models p$  iff  $p \in L(s_i)$
- $\pi, i \models \neg\varphi$  iff  $\pi, i \not\models \varphi$

- $\pi, i \models \varphi_1 \vee \varphi_2$  iff  $\pi, i \models \varphi_1$  or  $\pi, i \models \varphi_2$
- $\pi, i \models X\varphi$  iff  $\pi, i+1 \models \varphi$
- $\pi, i \models \varphi_1 \mathcal{U} \varphi_2$  iff  $\exists j \geq 0$  such that  $\pi, j \models \varphi_2$  and  $\pi, k \models \varphi_1$  for all  $0 \leq k < j$
- $\pi, i \models E\varphi$  iff there is an infinite path  $\pi' = s'_0, s'_1, s'_2, \dots$  s.t.  $s'_0 = s_i$  and  $\pi', 0 \models \varphi$
- $\pi, i \models A\varphi$  iff for every infinite path  $\pi' = s'_0, s'_1, s'_2, \dots$  s.t.  $s'_0 = s_i$ , we have  $\pi', 0 \models \varphi$

### Solving Model Checking Problem

Let define:

$$pre_{\exists}(Y) = \{s \in S \mid \exists s' \in Y \text{ s.t. } (s, s') \in \mathcal{R}\}$$

$$pre_{\forall}(Y) = \{s \in S \mid \mathcal{R}(s) \subseteq Y\}$$

Compute  $\llbracket \varphi \rrbracket = \{s \in S \mid s \models \varphi\}$

$$\llbracket p \rrbracket = \{s \in S \mid p \in L(s)\}$$

$$\llbracket \neg \varphi \rrbracket = S \setminus \llbracket \varphi \rrbracket$$

$$\llbracket \varphi_1 \vee \varphi_2 \rrbracket = \llbracket \varphi_1 \rrbracket \cup \llbracket \varphi_2 \rrbracket$$

$$\llbracket EX\varphi \rrbracket = pre_{\exists}(\llbracket \varphi \rrbracket)$$

$$\llbracket AF\varphi \rrbracket = MC_{CTL}^{AF}(\varphi)$$

$$\llbracket E(\varphi_1 \mathcal{U} \varphi_2) \rrbracket = MC_{CTL}^{EU}(\varphi_1, \varphi_2)$$

Test if the input state  $s \in \llbracket \varphi \rrbracket$ .

$MC_{CTL}^{AF}(\varphi)$  is computed as:

- $Y := S; Z := \llbracket \varphi \rrbracket;$
- **while**  $Y \neq Z$  **do**:
  - $Y = Z;$
  - $Z = Z \cup pre_{\forall}(Z);$
- **return**  $Y;$

$MC_{CTL}^{EU}(\varphi_1, \varphi_2)$  is computed as:

- $Y := \emptyset; Z := \llbracket \varphi_2 \rrbracket;$
- **while**  $Z \not\subseteq Y$  **do**:
  - $Y = Y \cup Z;$
  - $Z = pre_{\exists}(Y) \cap \llbracket \varphi_1 \rrbracket'$
- **return**  $Y;$

Having these definitions at hand will help us solve the exercise:

Let  $S$  be the set of states of the transition system:  $S = \{1, 2, 3, 4, 5, 6\}$ , where  $L(1) = \{p, q\}; L(2) = \emptyset; L(3) = \{q\}; L(4) = \{p\}; L(5) = \{q\}; L(6) = \emptyset$ .

1.  $\llbracket EFp \rrbracket \equiv E(\top \mathcal{U} p) = MC_{CTL}^{EU}(\top, p)$

$$\llbracket \varphi_1 \rrbracket = \llbracket \top \rrbracket = S$$

$$\begin{aligned} Y &= \emptyset & Z &= \llbracket \varphi_2 \rrbracket = \llbracket p \rrbracket = \{1, 4\} \\ Y &= \{4\} & Z &= pre_{\exists}(Y) \cap \llbracket \varphi_1 \rrbracket = \{3\} \end{aligned}$$