

Lab 3 - Exercise 4

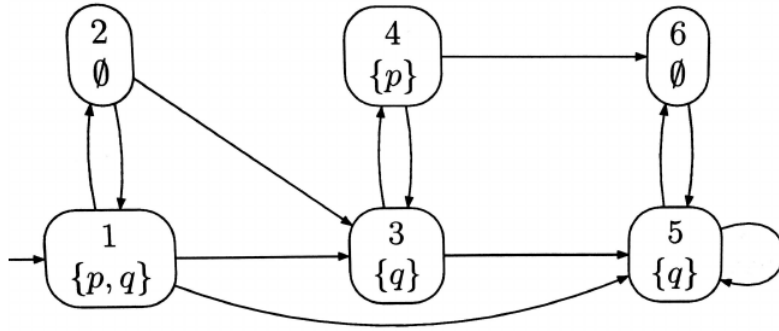
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1 Exercise 6

For the Labelled Transition System below, compute the following sets of states:



1. $\llbracket EFp \rrbracket$
2. $\llbracket AFq \rrbracket$
3. $\llbracket \varphi \rrbracket$, where $\varphi = E(qU(p \wedge \neg q))$
4. $\llbracket \varphi \rrbracket$, where $\varphi = EGq \vee (EGp \wedge EFq)$

2 Solving of exercise 6

Elementary temporal modalities that are present in the most temporal logics include the operators:

$F(\diamond)$ "eventually" (eventually in the future)

$G(\Box)$ "always" (now and forever in the future)

Definition(Semantics of CTL and CTL*)

Let $\pi = s_0, s_1, \dots$ be a path and φ a CTL* formula. If π_i is the suffix of π starting from position i ,

- $\pi, i \models \top$
- $\pi, i \models p$ iff $p \in L(s_i)$
- $\pi, i \models \neg\varphi$ iff $\pi, i \not\models \varphi$

- $\pi, i \models \varphi_1 \vee \varphi_2$ iff $\pi, i \models \varphi_1$ or $\pi, i \models \varphi_2$
- $\pi, i \models X\varphi$ iff $\pi, i+1 \models \varphi$
- $\pi, i \models \varphi_1 \mathcal{U} \varphi_2$ iff $\exists j \geq 0$ such that $\pi, j \models \varphi_2$ and $\pi, k \models \varphi_1$ for all $0 \leq k < j$
- $\pi, i \models E\varphi$ iff there is an infinite path $\pi' = s'_0, s'_1, s'_2, \dots$ s.t. $s'_0 = s_i$ and $\pi', 0 \models \varphi$
- $\pi, i \models A\varphi$ iff for every infinite path $\pi' = s'_0, s'_1, s'_2, \dots$ s.t. $s'_0 = s_i$, we have $\pi', 0 \models \varphi$

Solving Model Checking Problem

Let define:

$$pre_{\exists}(Y) = \{s \in S \mid \exists s' \in Y \text{ s.t. } (s, s') \in \mathcal{R}\}$$

$$pre_{\forall}(Y) = \{s \in S \mid \mathcal{R}(s) \subseteq Y\}$$

Compute $\llbracket \varphi \rrbracket = \{s \in S \mid s \models \varphi\}$

$$\llbracket p \rrbracket = \{s \in S \mid p \in L(s)\}$$

$$\llbracket \neg \varphi \rrbracket = S \setminus \llbracket \varphi \rrbracket$$

$$\llbracket \varphi_1 \vee \varphi_2 \rrbracket = \llbracket \varphi_1 \rrbracket \cup \llbracket \varphi_2 \rrbracket$$

$$\llbracket EX\varphi \rrbracket = pre_{\exists}(\llbracket \varphi \rrbracket)$$

$$\llbracket AF\varphi \rrbracket = MC_{CTL}^{AF}(\varphi)$$

$$\llbracket E(\varphi_1 \mathcal{U} \varphi_2) \rrbracket = MC_{CTL}^{EU}(\varphi_1, \varphi_2)$$

Test if the input state $s \in \llbracket \varphi \rrbracket$.

$MC_{CTL}^{AF}(\varphi)$ is computed as:

- $Y := S; Z := \llbracket \varphi \rrbracket;$
- **while** $Y \neq Z$ **do**:
 - $Y = Z;$
 - $Z = Z \cup pre_{\forall}(Z);$
- **return** $Y;$

$MC_{CTL}^{EU}(\varphi_1, \varphi_2)$ is computed as:

- $Y := \emptyset; Z := \llbracket \varphi_2 \rrbracket;$
- **while** $Z \not\subseteq Y$ **do**:
 - $Y = Y \cup Z;$
 - $Z = pre_{\exists}(Y) \cap \llbracket \varphi_1 \rrbracket$
- **return** $Y;$

Having these definitions at hand will help us solve the exercise:

Let S be the set of states of the transition system: $S = \{1, 2, 3, 4, 5, 6\}$, where $L(1) = \{p, q\}; L(2) = \emptyset; L(3) = \{q\}; L(4) = \{p\}; L(5) = \{q\}; L(6) = \emptyset$.

$$1. \llbracket EFp \rrbracket \equiv E(\top \mathcal{U}p) = MC_{CTL}^{EU}(\top, p)$$

$$\llbracket \varphi_1 \rrbracket = \llbracket \top \rrbracket = S$$

$$\begin{aligned} Y &= \emptyset & Z &= \llbracket \varphi_2 \rrbracket = \llbracket p \rrbracket = \{1, 4\} \\ Y &= \{4\} & Z &= pre_{\exists}(Y) \cap \llbracket \varphi_1 \rrbracket = \{3\} \\ Y &= \{4, 3\} & Z &= pre_{\exists}(\{4, 3\}) \cap S = \{4, 3, 2, 1\} \\ Y &= \{4, 3, 2, 1\} & Z &= pre_{\exists}(\{4, 3, 2, 1\}) \cap S = \{4, 3, 2, 1\} \quad Z \subseteq Y \Rightarrow \text{stop here.} \end{aligned}$$

$$\llbracket EFp \rrbracket = \{4, 3, 2, 1\}.$$

$$2. \llbracket AFq \rrbracket = MC_{CTL}^{AF}(q)$$

$$\begin{aligned} Y &= S = \{1, 2, 3, 4, 5, 6\} & Z &= \llbracket \varphi \rrbracket = \llbracket q \rrbracket = \{1, 3, 5\} \\ Y &= \{1, 3, 5\} & Z &= \{1, 3, 5\} \cup pre_{\forall}(\{1, 3, 5\}) = \{1, 3, 5\} \quad Y = Z \Rightarrow \text{stop here.} \end{aligned}$$

$$\llbracket AFq \rrbracket = \{1, 3, 5\}$$