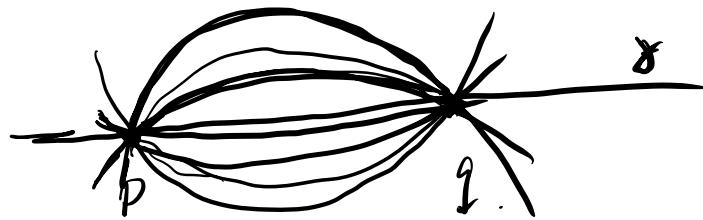


§7.2 Geodesics as shortest paths.



$$\gamma_\tau(t) : (-\delta, \delta) \rightarrow S \quad \tau \in \underline{G(-\delta, \delta)}$$

$$-\epsilon < \alpha < b < \epsilon$$

$$(1) \quad \gamma_\tau(a) = P, \quad \gamma_\tau(b) = Q, \quad \forall \tau \in \underline{G(-\delta, \delta)}$$

$$(2) \quad \gamma : (-\delta, \delta) \times (-\epsilon, \epsilon) \rightarrow S$$

$$(\tau, t) \mapsto \gamma_\tau(t), \quad (\text{smooth})$$

$$L(\gamma_\tau) = \int_a^b \|\dot{\gamma}_\tau\| dt. \quad \tau = 0, \quad \gamma_0 = \gamma(t)$$

Thm 7.2.1. The unit speed curve γ is a geodesic if and only

if

$$\underbrace{\frac{d}{d\tau} L(\gamma_\tau)}_{\text{variation}} \Big|_{\tau=0} = 0.$$

variation

Pf

$$\begin{aligned} \frac{d}{d\tau} L(\gamma_\tau) &= \cancel{\frac{d}{d\tau}} \int_a^b \cancel{\|\dot{\gamma}_\tau\|} dt \\ &= \int_a^b \cancel{\left(\frac{\partial}{\partial \tau} \right)} \left(\cancel{E \dot{u}^2 + 2f \dot{u} \dot{v} + G \dot{v}^2} \right)^{\frac{1}{2}} dt \end{aligned}$$

$$= \frac{1}{2} \int_a^b g^{-\frac{1}{2}} \underbrace{\frac{\partial g}{\partial t}}_{\text{circled}} dt.$$

$$\begin{aligned} \frac{\partial J}{\partial v} &= \underbrace{\frac{\partial E}{\partial t} \dot{u}^2 + 2 \frac{\partial F}{\partial t} \dot{u}\dot{v} + \frac{\partial G}{\partial t} \dot{v}^2 + 2E \dot{u} \frac{\partial u}{\partial t} + 2F \left(\frac{\partial u}{\partial t} \dot{v} + \dot{u} \frac{\partial v}{\partial t} \right)}_{+ 2G \dot{v} \frac{\partial v}{\partial t}} \\ &= \underbrace{(E_u \frac{\partial u}{\partial t} + E_v \frac{\partial v}{\partial t})}_{+ 2E \dot{u} \frac{\partial^2 u}{\partial t \partial t}} \dot{u}^2 + 2(F_u \frac{\partial u}{\partial t} + F_v \frac{\partial v}{\partial t}) \dot{u}\dot{v} + (G_u \frac{\partial u}{\partial t} + G_v \frac{\partial v}{\partial t}) \dot{v}^2 \\ &\quad + 2F \left(\frac{\partial^2 u}{\partial t \partial t} \dot{v} + \frac{\partial^2 v}{\partial t \partial t} \dot{u} \right) + 2G \dot{v} \frac{\partial^2 v}{\partial t \partial t} \end{aligned}$$

$$\int_a^b g^{-\frac{1}{2}} \left\{ (E \dot{u} + F \dot{v}) \frac{\partial u}{\partial t} + (F \dot{u} + G \dot{v}) \frac{\partial v}{\partial t} \right\} dt$$

$$= \underbrace{g^{-\frac{1}{2}} (E \dot{u} + F \dot{v}) \frac{\partial u}{\partial t}}_{\text{circled}} + \underbrace{(F \dot{u} + G \dot{v}) \frac{\partial v}{\partial t}}_{\text{circled}} \Big|_a^b$$

$$- \int \left(\frac{d}{dt} \left(g^{-\frac{1}{2}} (E \dot{u} + F \dot{v}) \frac{\partial u}{\partial t} + \frac{d}{dt} g^{-\frac{1}{2}} (F \dot{u} + G \dot{v}) \frac{\partial v}{\partial t} \right) \right) dt.$$

$$\partial_x(a) = p, \quad \partial_x(b) = q.$$

$$\underbrace{\frac{\partial \partial_x}{\partial t}(a)}_0, \quad \underbrace{\frac{\partial \partial_x}{\partial t}(b)}_0$$

$$\Rightarrow \frac{\partial u}{\partial t} \partial_u + \frac{\partial v}{\partial t} \partial_v = 0 \Rightarrow$$

$$\boxed{\begin{array}{l} \frac{\partial u}{\partial t}(a) = 0, \quad \frac{\partial v}{\partial t}(a) = 0 \\ \frac{\partial u}{\partial t}(b) = 0, \quad \frac{\partial v}{\partial t}(b) = 0 \end{array}}$$

$$\frac{d}{dt} L(\gamma_t) = \int_a^b U \frac{\partial u}{\partial t} + V \frac{\partial v}{\partial t} dt \quad , \quad t=0$$

$$U = \frac{1}{2} g^{-\frac{1}{2}} (\underbrace{\bar{E}_u \dot{u}^2 + 2f_u \dot{u}\dot{v} + G_u \dot{v}^2}_{\text{red box}}) - \frac{d}{dt} (g^{-\frac{1}{2}} (\underbrace{\bar{E}_u + F_u}_{\text{red box}}))$$

$$V = \frac{1}{2} g^{-\frac{1}{2}} (\bar{E}_v \dot{u}^2 + 2f_v \dot{u}\dot{v} + G_v \dot{v}^2) - \frac{d}{dt} (g^{-\frac{1}{2}} (F_u + G_v))$$

① $\gamma_0 = \gamma$ unit speed . $\|g(0, t)\| = 1$

\Rightarrow γ is a geodesic .

\Leftarrow $\|\gamma\| = \text{const}$



It suffices to show

$$\underbrace{\int_a^b U \frac{\partial u}{\partial t} + V \frac{\partial v}{\partial t} dt}_{\text{underbrace}} \Big|_{t=0} = 0 \Rightarrow U=0, V=0 \Big|_{t=0}$$

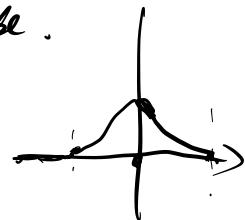
\exists to $G(a, b)$ s.t. $U|_{[0, t_0]} > 0$. $\exists \eta > 0$, s.t. $\forall t \in [t_0, t_0 + \eta]$

continuity

$U(0,t) \geq 0$. Let $\phi(t)$ be a ^{smooth.} function such that

$\phi > 0$ on $(t_0-\eta, t_0+\eta)$, $\phi = 0$, else.

$$u(z,t) = u(t) + z\phi(t) . \quad v(z,t) = v(t)$$



$$\frac{\partial u}{\partial z} = \phi(t) . \quad \frac{\partial v}{\partial z} = 0 .$$

$$\Rightarrow \int_a^b U \phi(t) dt = 0 , \quad z=0$$

$$\Rightarrow \int_{t_0-\eta}^{t_0+\eta} U \phi(t) dt = 0 , \quad z=0 .$$

> 0 , contradiction.

$$\Rightarrow \underline{U(0,t) = 0} . \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow \underline{\gamma \text{ is a geodesic}} . \quad \checkmark$$

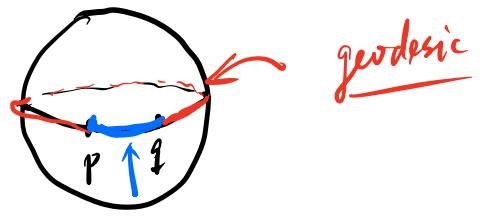
Similarly, $v(0,t) = 0$.

$$\theta(t) = \begin{cases} e^{-\frac{1}{t^2}}, & t > 0 \\ 0, & t \leq 0 \end{cases}$$

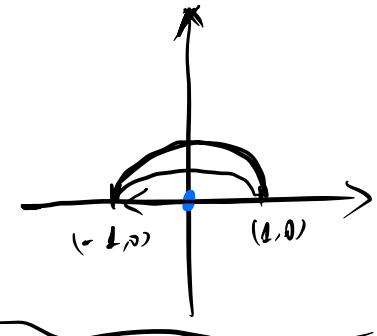
\Leftarrow smooth

- If γ is shortest path, then γ is a geodesic.



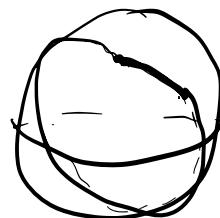


geodesic



complete 完备

- \mathbb{R}^3 closed subset



§7. Gauss's Theorema Egregium.

§7.1. Gauss's remarkable theorem

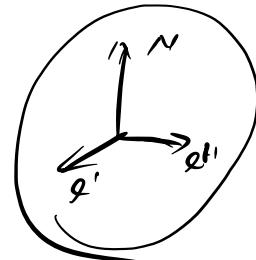
$$K = \frac{k_1 k_2}{E G - F^2} = \frac{LN - M^2}{EG - F^2} \text{ det II.}$$

Thm 7.1.1. The gaussian curvature of a surface depends only on its first fundamental form, i.e. it is preserved by isometric

Intrinsic

orthonormal basis $\{e', e''\}$ of $T_p S$. $g(a_u, a_v)$

$$\begin{cases} e' \cdot e'' = 0 \\ \|e'\| = 1, \|e''\| = 1. \end{cases}$$



$$e'_u = a e' + N$$

$$e'_{uv} = \beta e'' - \mu N$$

$$e''_u = -\alpha e' + \lambda' N$$

$$e''_{uv} = -\beta e' + \mu' N$$

$$\boxed{e' \cdot e'' = 0} \Rightarrow a = a', b = b'.$$

$$\underline{e'_u = a e'' + \lambda' N}$$

$$e'_{uv} = \beta e'' - \mu' N$$

$$\underline{e''_u = -\alpha e' + \lambda'' N}$$

$$\underline{e''_{uv} = -\beta e' + \mu'' N}$$

Lem

$$e'_u \cdot e''_v - e''_u \cdot e'_v = \lambda' \mu'' - \lambda'' \mu'$$

$$\begin{aligned}
 &= \underline{\alpha_v - \beta_u} \\
 &= \frac{LN - M^2}{(\bar{E}G - F^2)^{\frac{1}{2}}} = \underline{K} (\bar{E}G - F^2)^{\frac{1}{2}}
 \end{aligned}$$

Pf.

$$\begin{aligned}
 \underline{\alpha_v - \beta_u} &= \frac{\partial}{\partial u} (\underline{e} \cdot \underline{e''}) - \frac{\partial}{\partial v} (\underline{e'} \cdot \underline{e''}) \\
 &= \underline{e''} \cdot \underline{e''} + \cancel{e' \cdot e''} - \cancel{e'' \cdot e''} - \cancel{e' \cdot e''} \\
 &= \underline{e''} \cdot \underline{e''} - \underline{e''} \cdot \underline{e''}
 \end{aligned}$$

$$\underline{N_u \times N_v} = \underline{K} \underline{\alpha_u \times \alpha_v}$$

$$N = \frac{\alpha_u \times \alpha_v}{\|\alpha_u \times \alpha_v\|}, \quad \|\alpha_u \times \alpha_v\| = \underline{(\bar{E}G - F^2)^{\frac{1}{2}}}$$

$$\Rightarrow \underline{N_u \times N_v} = \frac{LN - M^2}{(\bar{E}G - F^2)^{\frac{1}{2}}} \underline{N}$$

$$\underline{(N_u \times N_v) \cdot N} = \frac{LN - M^2}{(\bar{E}G - F^2)^{\frac{1}{2}}}$$

- $$(axb) \cdot (cx d) = (a \cdot c)(b \cdot d) - (a \cdot d)(b \cdot c)$$

(exercise)

$$a, b, c, d$$

$$\begin{aligned}
 \Rightarrow (N_u \times N_v) \cdot N &= (N_u \times N_v) \cdot (\underline{e'} \times \underline{e''}) \\
 &= (\underline{N_u \cdot e'}) (\underline{N_v \cdot e''}) - (\underline{N_u \cdot e''}) (\underline{N_v \cdot e'})
 \end{aligned}$$

$$\begin{aligned}
 \bullet \quad & \underline{N \cdot e' = 0} \Rightarrow \underline{N_u \cdot e'} + \underline{N \cdot e'_u} = 0 \\
 & = (\underline{N \cdot e'_u}) \cdot (\underline{N \cdot e''_u}) - (\underline{N \cdot e''_u}) (\underline{N \cdot e'_u}) \\
 & = \underline{\lambda' \mu'' - \lambda'' \mu'}.
 \end{aligned}$$

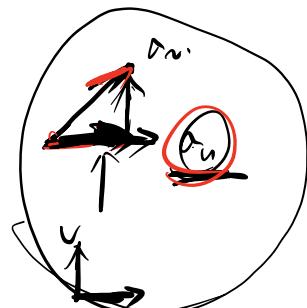
Pf of Th 7.1.1. Note that

$$K = \frac{\alpha_v - \beta_u}{(\bar{E}G - F^2)^{\frac{1}{2}}}.$$

$\{a_u, a_v\}$ is a basis of T_{pS}.

Gram-Schmidt process

$$\underline{e'} = \frac{a_u}{\|a_u\|} = \underline{\varepsilon a_u} \quad \underline{e} = \underline{\|(a_u)\|^{-1}}$$



$$\underline{e''} = \underline{\gamma a_u + \delta a_v}. \quad \underline{e' \cdot e'' = 0}, \quad \underline{\|e''\| = 1}$$

$$\begin{aligned}
 \Rightarrow \quad & \bar{E}^{-\frac{1}{2}} (\gamma \bar{E} + \delta F) = 0 \\
 & \gamma^2 \bar{E} + 2\gamma \delta F + \delta^2 G = 1
 \end{aligned}$$

\Rightarrow

$$\left\{ \begin{array}{l} \gamma = \frac{F \bar{E}^{-\frac{1}{2}}}{(EG - F^2)^{\frac{1}{2}}} \\ \delta = \frac{\bar{E}^{\frac{1}{2}}}{(EG - F^2)^{\frac{1}{2}}} \end{array} \right. , \quad \underline{\underline{\epsilon = \bar{E}^{-\frac{1}{2}}}}$$

$\underline{\underline{\epsilon' = \epsilon_{uu} + \epsilon_{vv}}}$, $\underline{\underline{\epsilon'' = \gamma \alpha_u + \delta \alpha_v}}$.

$\underline{\underline{\alpha = \epsilon_u \cdot \epsilon_v}}$

$$= (\underline{\underline{\epsilon_u \alpha_u}} + \underline{\underline{\epsilon_v \alpha_v}}) \cdot (\underline{\underline{\gamma \alpha_u + \delta \alpha_v}})$$

$$= \frac{\epsilon_u}{\epsilon} \cancel{\alpha' \cdot \alpha''} + \cancel{\epsilon \gamma} \underline{\underline{\alpha_u \cdot \alpha_u}} + \cancel{\epsilon \delta} \underline{\underline{\alpha_v \cdot \alpha_v}}.$$

$$= \frac{1}{2} \cancel{\epsilon \gamma} (\underline{\underline{\alpha_u \cdot \alpha_u}})_u + \cancel{\epsilon \delta} \left((\underline{\underline{\alpha_u \cdot \alpha_v}}_u - \frac{1}{2} \underline{\underline{\alpha_u \cdot \alpha_v}}_v) \right)$$

$$= \underline{\underline{\frac{1}{2} \epsilon \gamma \bar{E}_u + \epsilon \delta \left(F_u - \frac{1}{2} \bar{E}_v \right)}}$$

$\underline{\underline{\beta = \epsilon'_v \cdot \epsilon''_v}}$

$$= (\underline{\underline{\epsilon_v \alpha_u + \epsilon_u \alpha_v}}) \cdot (\underline{\underline{\gamma \alpha_u + \delta \alpha_v}})$$

$$= \frac{\epsilon_v}{\epsilon} \cancel{\alpha' \cdot \alpha''} + \cancel{\epsilon \gamma} \underline{\underline{\alpha_v \cdot \alpha_u}} + \cancel{\epsilon \delta} \underline{\underline{\alpha_v \cdot \alpha_v}}.$$

$$= \underline{\underline{\frac{1}{2} \epsilon \gamma \bar{E}_v + \frac{1}{2} \epsilon \delta G_v}}$$

$$K = \frac{\alpha_v - \beta_u}{(Ea - F^2)^{\frac{1}{2}}} \quad \checkmark$$

• $K \sim I$

Cor 7.1.3

$$K = \frac{1}{(Ea - F^2)^{\frac{1}{2}}} \left\{ \begin{vmatrix} -\frac{1}{2}\bar{E}_{vv} + F_{vv} - \frac{1}{2}G_{uu} & \frac{1}{2}\bar{E}_{vu} & F_u - \frac{1}{2}\bar{E}_{vu} \\ F_v - \frac{1}{2}G_u & E & F \\ \frac{1}{2}G_v & F & G \end{vmatrix} \right\}$$

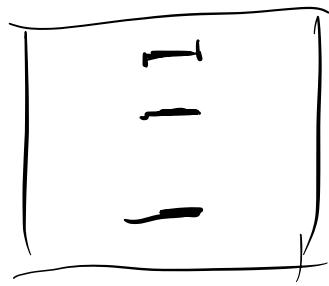
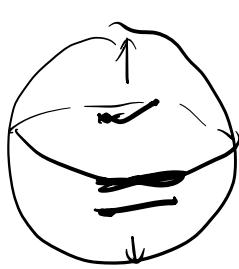
$$- \begin{vmatrix} 0 & \frac{1}{2}\bar{E}_{vu} & \frac{1}{2}G_u \\ \frac{1}{2}\bar{E}_{vv} & E & F \\ \frac{1}{2}G_u & F & G \end{vmatrix} \}$$

Cor (a) $F=0$

$$K = - \frac{1}{2\sqrt{Ea}} \left\{ \frac{\partial}{\partial u} \left(\frac{G_u}{\sqrt{Ea}} \right) + \frac{\partial}{\partial v} \left(\frac{E_v}{\sqrt{Ea}} \right) \right\}.$$

(b) $E=1, F=0$.

$$K = -G^{-\frac{1}{2}} \frac{\partial^2}{\partial u^2} (G^{\frac{1}{2}}).$$



Prop. Any map of any region of the earth's surface must distort distances.

$$\underline{\text{Pf}} \quad f: S^2 \rightarrow \mathbb{R}^2$$

$$\frac{r \mapsto kr}{f}$$

$$f \circ k^{-1}: S^2 \rightarrow \mathbb{R}^2$$

$$\frac{r \mapsto r}{}$$

$$\underbrace{k(S^2)}_{} = K(\mathbb{R}^2) \quad X$$

$$k(S^2) = \frac{1}{R^2}, \quad K(\mathbb{R}^2) = 0.$$

Prop. (Gauss equation) $\alpha(u, v)$

$$\left\{ \begin{array}{l} \alpha_{uu} = \bar{\Gamma}_{11}^1 \alpha_u + \bar{\Gamma}_{11}^2 \alpha_v + L \vec{N} \\ \alpha_{uv} = \bar{\Gamma}_{12}^1 \alpha_u + \bar{\Gamma}_{12}^2 \alpha_v + M \vec{N} \\ \alpha_{vv} = \bar{\Gamma}_{22}^1 \alpha_u + \bar{\Gamma}_{22}^2 \alpha_v + N \vec{N} \end{array} \right.$$

$$\bar{\Gamma}_{11}^1 = \frac{G\bar{E}_u - 2F\bar{E}_v + F\bar{E}_v}{2(\bar{E}G - F^2)}, \quad \bar{\Gamma}_{11}^2 = \frac{2\bar{E}F_u - E\bar{E}_v - F\bar{E}_u}{2(\bar{E}G - F^2)}$$

$$\bar{\Gamma}_{12}^1 = \frac{G\bar{E}_v - F\bar{G}_u}{2(\bar{E}G - F^2)}, \quad \bar{\Gamma}_{12}^2 = \frac{\bar{E}\bar{G}_u - F\bar{E}_v}{2(\bar{E}G - F^2)}$$

$$\bar{\Gamma}_{22}^1 = \frac{2G\bar{F}_v - G\bar{G}_u - F\bar{G}_u}{2(\bar{E}G - F^2)}, \quad \bar{\Gamma}_{22}^2 = \frac{\bar{E}\bar{G}_v - 2F\bar{F}_v + \bar{F}\bar{G}_u}{2(\bar{E}G - F^2)}$$

Pf.

$$\left\{ \begin{array}{l} \alpha_{uu} = \underline{\alpha_1 \alpha_u + \alpha_2 \alpha_v + \alpha_3 \vec{N}} \\ \alpha_{uv} = \underline{\beta_1 \alpha_u + \beta_2 \alpha_v + \beta_3 \vec{N}} \\ \alpha_{vv} = \underline{\gamma_1 \alpha_u + \gamma_2 \alpha_v + \gamma_3 \vec{N}} \end{array} \right.$$

$$\bullet \quad \alpha_{uu} \cdot \vec{N} = \alpha_3 \Rightarrow \alpha_3 = L.$$

$$\alpha_{uv} \cdot \vec{N} = \beta_3 \Rightarrow \beta_3 = M$$

$$\alpha_{vv} \cdot \vec{N} = \gamma_3 \Rightarrow \gamma_3 = N.$$

$$\bullet \quad \alpha_{uu} \cdot \alpha_u = \alpha_1 E + \alpha_2 F = \frac{1}{2} (\alpha_u \cdot \alpha_u)_u = \frac{1}{2} \bar{E}_u.$$

$$\alpha_{uu} \cdot \alpha_v = \alpha_1 F + \alpha_2 G = F_u - \frac{1}{2} \bar{E}_v$$

$$\Gamma_{11}^1 = \alpha_1, \quad \Gamma_{11}^2 = \alpha_2$$

$$\alpha_{uv} \cdot \alpha_u = \beta_1 E + \beta_2 F = \frac{1}{2} E_u.$$

$$\alpha_{uv} \cdot \alpha_v = \beta_1 F + \beta_2 G = \frac{1}{2} G_u$$

$$\underline{\Gamma_{12}^1} = \beta_1, \quad \underline{\Gamma_{12}^2} = \beta_2$$

Γ_{ij}^k $1 \leq i, j, k \leq 2$ sin Christoffel symbols

$$g_{11} = E, \quad g_{12} = g_{21} = F, \quad g_{22} = G.$$

$$G_1 = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$$

$$\begin{pmatrix} g^{11} & g^{12} \\ g^{21} & g^{22} \end{pmatrix} = G_1^{-1}$$

$$\underline{\Gamma_{ij}^k} = \frac{1}{2} g^{kl} (\underline{\partial_i g_{jl}} + \underline{\partial_j g_{il}} - \underline{\partial_l g_{ij}})$$

Riemannian geometry

prop (Codazzi - Mainardi equation) $\alpha_{u,vj} \quad \underline{\Gamma_{ij}^k}$

$$\left. \begin{aligned} L_u - Mu &= L\bar{P}'_{12} + M(\bar{P}^2_{12} - \bar{P}'_{11}) - N\bar{P}^2_{11} \\ Mu - Nu &= L\bar{P}'_{22} + M(\bar{P}^2_{22} - \bar{P}'_{12}) - N\bar{P}^2_{12} \end{aligned} \right\}$$

- constant Gaussian curvature
- plane $k = 0$ space form
- sphere $k = 1$
- Every compact surface whose gaussian curvature is constant
is sphere. \uparrow
 closed, bounded closed subset of \mathbb{R}^3
- open set

 $B_R = \{ (x, y) : |x|^2 + |y|^2 \leq R^2 \}$. closed

Poincaré disc . $k = -1$

