Name: Roll No. :

## End Semester exam EEL101: Basic Electrical Engineering

Exam duration: 180 mins Date: 05/05/2025

## Instructions:

- a. There are total 50 questions and each question carry 1 mark. Questions are of either one word answer type or MCQ.
- b. No step marking is there, marks will be awarded only for the complete correct answer.
- c. For MCQs, mention the option (a, b, c, or d) of the correct answer. Only one option must be there for each MCQ. In case of multiple options mentioned as answer, zero mark will be awarded even if one of the answers is correct
- d. Mention the answer in the units asked in the question. Answer in other units will be regarded incorrect.

A single-phase load is supplied through a 10MVA, 35-kV/3500-V transformer whose series impedances on the HV side is  $0.3 + j0.9 \Omega$  and the series impedance on LV side is  $0.003 + j0.009 \Omega$ . The LV side contains 528 turns. The shunt branch admittance is (0.00001 - j.0002) referred to HV side. Operating frequency is 50 Hz. (Q1-Q8)

- 1. The peak flux in the core (in Wb) when operating at rated input voltage is:
- 2. The number of turns on the HV side is
- 3. The base impedance of the transformer on HV side and LV sides are (in ohm):
- 4. The total transformer series impedance in ohm, referred to LV side (R+jX form):
- 5. The value of core loss resistance and magnetizing reactance in ohms, referred to LV side
- 6. The value of core loss (in W) under rated voltage is
- 7. Neglecting the series impedance, the magnitude of no-load current (A) when rated voltage is applied to LV side is
- 8. The power factor of no load current is: (neglecting the series impedance)

## The transformer is required to be operated at 90 Hz keeping the maximum flux density same as the flux density when it was operated with the rated voltage at 50 Hz. (Q9-Q10)

- 9. The rms value of 90 Hz voltage that is applied on the LV side is (in V):
- 10. At 90 Hz, the hysteresis loss becomes x times the hysteresis loss at 50 Hz and eddy current loss becomes y times of eddy current loss at 50 Hz. The values of x and y are:
- 11. The power factor of no load current is: (neglecting the series impedance)

a. Very low and lagging	b. Unity	c. Lagging and close to unity	d. Very low and Leading
12. Flux density of a transform	er can be reduc	ed by reducing which quantity:	

a. No of turns b. Supply frequency c. Time period of supply voltage d. cross sectional area of core

Figure 1 shows an inductor made up of two C-cores. Each core has area Ac and mean length lc. There are two air gaps, each of length g and effective area Ag. There are two N-turn coils as shown which are electrically connected in series. The relative permeability of core is 2500. Ac = Ag = 38.7 cm<sup>2</sup>, Core-length (including both cores): lc = 95 cm, Gap length: g = 12 mm The resistance of each coil is  $100\Omega$ . And the number of turns in each winding is 65 (Q13-Q16)

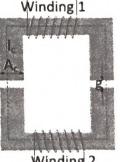
- 13. The inductance value of the inductor (in mH) when both windings are connected in series is. (Flux of both coils add).
- 14. The induced EMF when the are supplied with a 150V DC source is (in V):
- 15. The flux density in the air gap (in T) when 150V DC voltage is applied is:
- 16. The core loss and copper loss when supplied with 150V DC voltage is (in W):
- 47. If the inductor is to be used for high frequency application, the core can be made up of Silicon steel. True/False

A 220 V shunt dc generator supplies 4 kW at a terminal voltage of 220 V when operated at 1450 rpm. The armature resistance being 0.4  $\Omega$  and field resistance is 440  $\Omega$  (Q16-Q21) Keeping the flux unchanged (Q18-Q19):

- 18. If the machine is now operated as a motor at the same terminal voltage with the half the armature current as in generator case, The speed under motoring mode is (rpm).
- 19. The load torque under this condition is (motoring) (Nm):

It is required to decrease flux/pole by 10% as the operation is changed over from generator to motor. Under this condition (Q20-Q24)

- 20. The value and connection of resistance to be added with field winding to achieve this change in flux is (in Ohm):
- 21. The machine is to be operated as a motor at the same terminal voltage with the half the armature current as in original generator case (with higher flux), calculate speed under motoring mode (rpm).



Winding 2

Fig. 1

and the terms of t			
22. The load torque under the	his condition is (motoring) (N	m):	
23. The current drawn by th	is machine when the rotor sta	alls is (A):	
24. The torque generated by	the motor when rotor stalls	is (Nm):	
25. For a series DC motor, to	orque is proportional to LX	hammed to	e value of v under
flux condition is	and under saturated flux b. 2,2 osses are than	condition is	e value of x under unsaturated
a. 1,2	b. 2,2	c. 1,1	21
			e. 2,1
51. 10 page ab voltage in 9	self excited DC generator, a	needs to be so	proceed initially with the
disconnected once the g	enerator starts supplying volt	Tage	nnected initially which can be
a. Capacitor	b. Battery		
28. The windings to compen	sate for armature reaction ar	c. Resistor e connected in with	d. Inductor
a. Series	b. Shunt	e to lot and	
29. In a excited D	OC motor the speed variation	c. Isolated	d. None
a. Separate	h Sarios	with load is minimum	
	luy can be	c. Permanent Magnet	d. Shunt
30. In a series DC machine, f	iux can be us	sing a diverter resistance (incre	ased/reduced)
delivering 12.8 kW to the	load. The power lost in fricti	3 phase, 50 Hz supply is operon is given by $0.0038\omega^3$ where	rating at a slip of 3% and is e ω is rotor speed in rad/sec
and stator losses to be 600			
	at the given operating conditi	ion is:	
32. The torque being delive			
33. The frequency of currer			
34. Rotor copper loss is equ			
35. Power drawn by the ma	chine from supply mains is (V	V):	
36. Air gap power is equal t	o (W):		
∠37. Efficiency of the machin	, ,		
38. Assuming Rth=Xth=0, fo	r an induction machine to ge	narata mavimum tarqua at tha	ctarting.
J	all induction machine to get	nerate maximum torque at the	starting.
a. $R'_2 > X'_2$	b. $R_2' < X_2'$	c. $R'_2 = X'_2$	d. $R'_2 = 0$
a. $R'_2 > X'_2$		c. $R'_2 = X'_2$	d. $R_2' = 0$
a. $R'_2 > X'_2$ 39. An induction machine was a. Generate no torque b.	b. $R'_2 < X'_2$ with zero resistance in the roto. Generate very high torque	c. $R'_2 = X'_2$ or will c. Rotate at very high speed	d. $R_2' = 0$ d. Have 100% efficiency
a. $R'_2 > X'_2$ 39. An induction machine was a. Generate no torque b.	b. $R'_2 < X'_2$ with zero resistance in the roto. Generate very high torque	c. $R'_2 = X'_2$ or will c. Rotate at very high speed	d. $R_2' = 0$ d. Have 100% efficiency
a. $R'_2 > X'_2$ 39. An induction machine was a. Generate no torque b.  40. For an induction machine	b. $R'_2 < X'_2$ with zero resistance in the roto. Generate very high torque to generate a negative torq	c. $R'_2 = X'_2$ or will c. Rotate at very high	d. $R_2' = 0$ d. Have 100% efficiency
a. $R_2' > X_2'$ 39. An induction machine was a. Generate no torque b. 40. For an induction machine a. $\omega_s > \omega_r$	b. $R_2' < X_2'$ with zero resistance in the roto. Generate very high torque to generate a negative torque b. $\omega_s < \omega_r$	c. $R_2' = X_2'$ or will  c. Rotate at very high speed  ue ( $\omega_s$ and $\omega_r$ are synchronous  c. $\omega_s = \omega_r$	d. $R_2' = 0$ d. Have 100% efficiency speed and rotor speeds resp)
a. $R_2' > X_2'$ 39. An induction machine was a. Generate no torque b.  40. For an induction machine a. $\omega_s > \omega_r$ 41. The direction of rotation	b. $R_2' < X_2'$ with zero resistance in the roto. Generate very high torque to generate a negative torque b. $\omega_s < \omega_r$ of an induction machine can	c. $R_2' = X_2'$ or will  c. Rotate at very high speed  ue ( $\omega_s$ and $\omega_r$ are synchronous  c. $\omega_s = \omega_r$ be reversed by:	d. $R_2'=0$ d. Have 100% efficiency speed and rotor speeds resp) d. $\omega_S=0$
a. $R_2' > X_2'$ 39. An induction machine was a. Generate no torque b.  40. For an induction machina. $\omega_s > \omega_r$ 41. The direction of rotation a. Changing phase	b. $R_2' < X_2'$ with zero resistance in the roto Generate very high torque te to generate a negative torq b. $\omega_s < \omega_r$ of an induction machine can b. Applying voltage in	c. $R_2' = X_2'$ or will  c. Rotate at very high speed  ue ( $\omega_s$ and $\omega_r$ are synchronous  c. $\omega_s = \omega_r$ be reversed by:  c. Applying very high	d. $R_2'=0$ d. Have 100% efficiency speed and rotor speeds resp) d. $\omega_S=0$
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