

**Department of Mathematics**  
**Indian Institute of Technology Bhilai**  
**IC104: Linear Algebra-I**  
**Hints of Tutorial Sheet 3: Linear Transformation**

---

1. (a) It is easy to verify that  $T(c\alpha + \beta) = cT(\alpha) + T(\beta)$  for every  $c \in F$  and  $\alpha, \beta \in V$ . We know that  $\text{null}(T) = \{x \in F^3 : T(x) = 0\}$ . Now  $(x + y + z, x - y + z, x + z) = (0, 0, 0)$  implies that

$$\begin{aligned}x + y + z &= 0 \\x - y + z &= 0 \\x + z &= 0,\end{aligned}$$

which can be written as  $\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . Then system equivalent to

$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . Then  $x + z = 0$  and  $y = 0$ ,  $z$  is arbitrary. Let  $z = t$ ,  $x = -t$ . Then  $(x, y, z) = (-t, 0, t) = t(-1, 0, 1)$ . Therefore  $\text{null}(T) = \{t(-1, 0, 1) : t \in \mathbb{F}\}$ . Then basis of  $\text{null}(T)$  is  $\{(-1, 0, 1)\}$ .

Now  $\eta$  be a arbitrary vector in range of  $T$ . Then

$$\begin{aligned}\eta &= (x + y + z, x - y + z, x + z) \\ &= x(1, 1, 1) + y(1, -1, 0) + z(1, 1, 1).\end{aligned}$$

Thus  $\eta$  is a linear combination of the vectors  $(1, 1, 1), (1, -1, 0)$ . Hence range of  $T$  is the subspace spanned by  $\{(1, 1, 1), (1, -1, 0)\}$ . As  $\{(1, 1, 1), (1, -1, 0)\}$  is linearly independent and hence is a basis of range of  $T$ .

- (b) It is easy to verify that  $T(c\alpha + \beta) = cT(\alpha) + T(\beta)$  for every  $c \in F$  and  $\alpha, \beta \in V$ . By following the similar process as in point (a)  $\text{null}(T) = \{c(-2, 4, 3) : c \in \mathbb{F}\}$  and basis of  $\text{null}(T) = \{(-2, 4, 3)\}$ . Again range  $T$  is spanned by  $\{(-1, 1, -2), (2, 0, 2)\}$ . Then the basis of range of  $T$  is  $\{(-1, 1, -2), (2, 0, 2)\}$ .

2. It is given that  $T \neq 0$  but  $T^2 = 0$ . As  $T \neq 0$ , then there exists a non-zero vector  $x^* \in \mathbb{R}^n$  such that  $T(x^*) \neq 0$ . Now consider a relation  $c_1x^* + c_2T(x^*) = 0$ . Then  $T(c_1x^* + c_2T(x^*)) = T(0)$ . As  $T$  is linear map, then  $c_1T(x^*) + c_2T^2(x^*) = 0$ . Again  $T^2(x) = 0$ , for all  $x \in \mathbb{R}^n$ , then we get that  $c_1 = 0$ . Then it is easy to observe that  $c_2 = 0$ . Therefore  $\{x^*, T(x^*)\}$  is linearly independent. In general all  $x \in \mathbb{R}^n \setminus N(T)$  will qualify for the solution.

3. Let  $\beta = (x, y, z)$  such that  $T(\beta) = (9, 3, \alpha)$ . Then we have

$$2x + 3y + 4z = 9$$

$$x + y + z = 3$$

$$x + y + 3z = \alpha$$

Which can be written as  $\begin{bmatrix} 2 & 3 & 4 \\ 1 & 1 & 1 \\ 1 & 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 9 \\ 3 \\ \alpha \end{bmatrix}$ . After row operation on the augmented matrix is  $\left[ \begin{array}{ccc|c} 2 & 3 & 4 & 9 \\ 0 & -\frac{1}{2} & -1 & -\frac{3}{2} \\ 0 & 0 & 2 & \alpha - 3 \end{array} \right]$ . This implies that  $x = \frac{\alpha-3}{2}$ ,  $y = 6 - \alpha$ ,  $z = \frac{\alpha-3}{2}$ . Therefore  $\beta = (\frac{\alpha-3}{2}, 6 - \alpha, \frac{\alpha-3}{2})$ .

4. Yes, because  $T(aA_1 + bA_2) = (aA_1 + bA_2)B - B(aA_1 + bA_2) = aT(A_1) + bT(A_2)$ . Now, nullity of  $T = \{A \mid T(A) = 0\} = \{A \mid AB = BA\}$ , i.e. set of all matrices that commutes with  $B$ . As  $M_{2 \times 2}(\mathbb{R})$  can be written as the union of sets of commutative and non commutative matrices with  $B$ . The range of  $T$  contains all those matrices which are images of non commutative matrices with  $B$  together with 0 matrix.
5. Since  $(1, -1, 1)$  and  $(-1, 1, 2)$  are linearly independent, hence extend to basis of  $\mathbb{R}^3$  and define  $T(0, 1, 0) = (1, 1)$ , then a simple calculation gives us the linear transformation as  $T(x, y, z) = (\frac{4x+3y+2z}{3}, \frac{7x+3y+2z}{3})$ . No, it is not a unique linear transformation of this type.
6. The range and null spaces are identical, hence assume  $\dim(\text{range } T) = \dim(\text{null } T) = m$ . Applying rank-nullity theorem we get  $n = 2m$  which is even. Define  $T$  as  $T(1, 0) = (0, 0)$  and  $T(0, 1) = (1, 0)$ , then the range space and null space are equal as it is generated by  $(1, 0)$ .
7. Let  $B = \{a_1, a_2, \dots, a_n\}$  be a basis for  $V$ . Let  $x \in \text{range } T \cap \text{null } T$  then as  $\{T(a_1), T(a_2), \dots, T(a_n)\}$  spans range of  $T$ , we can write  $x = c_1Ta_1 + \dots + c_nTa_n$ . Now as  $x \in N(T)$ , we have  $0 = T(x) = T(c_1Ta_1 + \dots + c_nTa_n) = c_1T^2a_1 + \dots + c_nT^2a_n$ . Now if  $C = \{T^2a_1, T^2a_2, \dots, T^2a_n\}$  is linearly independent set, then  $c_k = 0$  for all  $k = 1, 2, \dots, n$  which results into  $x = 0$ . Thus it will be enough to show that nullity of  $T^2$  is zero (then  $T^2$  will be one to one and it will map a linearly independent set  $B$  to a linearly independent set  $C$ ). Now, as  $T^2\alpha = T(T\alpha)$  for all  $\alpha \in V$ , we can apply rank nullity theorem for  $T^2$  on  $T(V) = R(T)$  to get nullity of  $T^2$  as 0.

8. Here  $A = \begin{bmatrix} 1 & 0 & 4 \\ 3 & 2 & -1 \\ 2 & 1 & 0 \end{bmatrix}$ . We know that the vectors  $\{(1, 3, 2), (0, 2, 1), (4, -1, 0)\}$  span

column space and it is easy to see that these vectors are linearly independent. Hence rank of  $A$  is 3.

9. In this problem it is given that  $m > n$ .

- (a) On the contrary, there is a linear transformation  $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$ , which is one-one (injective). Then nullity of  $T = 0$ . Again by the rank-nullity theorem we know that

$$\text{nullity of } T + \text{rank of } T = \dim(\mathbb{R}^m) = m.$$

Then we have rank of  $T = m$ , which is not possible as range of  $T$  is subset of  $\mathbb{R}^n$ , that is rank of  $T$  is less than equal to  $n$ .

- (b) On the contrary, suppose there is a linear map  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ , which is onto. That is range of  $T = \mathbb{R}^m$ . Therefore rank of  $T = m$ . Again by the rank-nullity theorem we got the contradiction.

10. The matrix of  $T$  corresponding to the standard basis is  $\begin{bmatrix} 1 & 0 & i \\ 0 & 1 & 1 \\ i & 1 & 0 \end{bmatrix}$ . Since  $\det(T) = 0$ , then  $T$  is not invertible.

11. It is easy to check that the matrix of  $T$  corresponding to the standard basis is  $[T]_{\beta} = \begin{bmatrix} 3 & 0 & 0 \\ 1 & -1 & 0 \\ 2 & 1 & 1 \end{bmatrix}$ . As  $\det([T]_{\beta}) \neq 0$ , hence  $T$  is invertible and the inverse is  $\begin{bmatrix} \frac{1}{3} & 0 & 0 \\ \frac{1}{3} & -1 & 0 \\ -1 & 1 & 1 \end{bmatrix}$ .

Now putting the value of  $T$  and  $I$  we get that  $(T^2 - I)(T - 3I) = 0$  (zero map).

12. Here

$$T(1, 0, -1) = (1, -1) = 5(1, 1) + (-2)(2, 3)$$

$$T(1, 1, 1) = (2, 1) = 4(1, 1) + (-1)(2, 3)$$

$$T(1, 0, 0) = (1, -1) = 5(1, 1) + (-2)(2, 3).$$

Thus the matrix of  $T$  relative to the basis  $\beta, \beta'$  is  $\begin{bmatrix} 5 & 4 & 5 \\ -2 & -1 & -2 \end{bmatrix}$

13. (a) It is easy to check that the matrix of  $T$  corresponding to the standard matrix is

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

- (b) As  $\beta = \{(1, 2), (1, -1)\}$  and  $T(1, 2) = (-2, 1) = \frac{-1}{3}(1, 2) + \frac{-5}{3}(1, -1)$ ,  $T(1, -1) = (1, 1) = \frac{2}{3}(1, 2) + \frac{1}{3}(1, -1)$ . Therefore the matrix of  $T$  corresponding to the matrix is  $\begin{bmatrix} \frac{-1}{3} & \frac{2}{3} \\ \frac{-5}{3} & \frac{1}{3} \end{bmatrix}$ .

(c) As  $(T - cI)(x, y) = (-y - cx, x - cy)$ , then the matrix of  $T - cI$  corresponding to the standard basis is  $\begin{bmatrix} -c & -1 \\ 1 & -c \end{bmatrix}$ . Therefore  $\det(T - cI) = c^2 + 1 \neq 0 \forall c \in \mathbb{R}$ .

(d)

14. (a) Calculating we have  $T(1, 0, 0) = (3, -2, -1)$ ,  $T(0, 1, 0) = (0, 1, 2)$ ,  $T(0, 0, 1) = (1, 0, 4)$ . Then the matrix of  $T$  corresponding to the standard basis is  $\begin{bmatrix} 3 & 0 & 1 \\ -2 & 1 & 0 \\ -1 & 2 & 4 \end{bmatrix}$ .

(b) Again the matrix of  $T$  corresponding to the ordered basis  $\{(1, 0, 1), (-1, 2, 1), (2, 1, 1)\}$  is  $\begin{bmatrix} \frac{13}{4} & \frac{47}{4} & \frac{11}{2} \\ \frac{-3}{4} & \frac{11}{4} & \frac{-3}{2} \\ \frac{1}{2} & \frac{-11}{2} & 0 \end{bmatrix}$ .

(c) As determinant of  $T$  corresponding to the standard basis is non-zero, then it is invertible. Now inverse of the matrix of  $T$  corresponding to the standard basis is  $\begin{bmatrix} \frac{4}{9} & \frac{2}{9} & \frac{-1}{9} \\ \frac{8}{9} & \frac{13}{9} & \frac{-2}{9} \\ \frac{-1}{3} & \frac{-2}{3} & \frac{1}{3} \end{bmatrix}$ . Then we have

$$T^{-1}(x, y, z) = \left( \frac{4}{9}x + \frac{2}{9}y + \frac{-1}{9}z, \frac{8}{9}x + \frac{13}{9}y + \frac{-2}{9}z, \frac{-1}{3}x + \frac{-2}{3}y + \frac{1}{3}z \right).$$