# ECE 521 - Computer Design Techniques Fall 2014

## Branch Predictor Implementation Project Report

Prepared by

Aravindhan Dhanasekaran adhanas@ncsu.edu

## Contents

inti	roduction	2
For	mulas	2
2.1	Program Counter to Branch Predictor Table Index Conversion	2
	2.1.1 Index Calculation for Bimodal Predictor	2
	2.1.2 Index Calculation for Gshare Predictor	2
	2.1.3 Index Calculation for Hybrid Predictor	2
2.2	Misprediciton Rate	3
2.3	Predictor Table Size	3
Exp	periments	3
3.1	Bimodal Predictor Experiments	3
3.2	Gshare Predictor Experiments	3
Bra	anch Predictor Performance Analysis	3
4.1	Analysis of Bimodal Predictor	7
	4.1.1 Benchmark Comparison	7
	4.1.2 Best Design Selection	7
4.2	Analysis of Gshare Predictor	8
	4.2.1 Benchmark Comparison	8
	4.2.2 Best Design Selection	9
Cor	nclusion	10
$\mathbf{ist}$	of Figures	
3.1	Bimodal predictor misprediction rate for gcc trace	4
3.2	Bimodal predictor misprediction rate for jpeg trace	5
3.3	Bimodal predictor misprediction rate for perl trace	6
3.4	Ghsare predictor misprediction rate for gcc trace	7
3.5	Gshare predictor misprediction rate for jpeg trace	8
3.6	Gshare predictor misprediction rate for perl trace	9
ist	of Tables	
3.1	Experiment Data for bimodal predictor for different 'm' values and traces	4
3.2	Experiment Data for g share predictor for different 'm' and 'n' values for gc c $\operatorname{trace}$	5
3.3	Experiment Data for gshare predictor for different 'm' and 'n' values for jpeg trace	5
3.4	Experiment Data for gshare predictor for different 'm' and 'n' values for perl trace $\dots$	6
	For 2.1  2.2 2.3  Exp 3.1 3.2  Bra 4.1  4.2  Con ist 3.1 3.2 3.3 3.4 3.5 3.6  ist 3.1 3.2 3.3	2.1.1 Index Calculation for Bimodal Predictor 2.1.2 Index Calculation for Gshare Predictor 2.1.3 Index Calculation for Hybrid Predictor. 2.1.4 Index Calculation for Hybrid Predictor. 2.1.5 Mispredictor Rate 2.2 Mispredictor Table Size  Experiments 3.1 Bimodal Predictor Experiments 3.2 Gshare Predictor Experiments 3.3 Bimodal Predictor Experiments 3.4 Analysis of Bimodal Predictor 4.1.1 Benchmark Comparison 4.1.2 Best Design Selection 4.2 Analysis of Gshare Predictor 4.2.1 Benchmark Comparison 4.2.2 Best Design Selection  Conclusion  Conclusion  Conclusion  Sist of Figures 3.1 Bimodal predictor misprediction rate for gec trace 3.2 Bimodal predictor misprediction rate for perl trace 3.3 Bimodal predictor misprediction rate for gec trace 3.4 Ghsare predictor misprediction rate for gec trace 3.5 Gshare predictor misprediction rate for perl trace 3.6 Gshare predictor misprediction rate for perl trace 3.7 Experiment Data for bimodal predictor for different 'm' values and traces 3.8 Experiment Data for gshare predictor for different 'm' values for gec trace 3.9 Experiment Data for gshare predictor for different 'm' values for gec trace 3.1 Experiment Data for gshare predictor for different 'm' values for gec trace 3.3 Experiment Data for gshare predictor for different 'm' values for jpeg trace

#### 1 Introduction

In this project, a branch predictor has been built which can simulate 3 types of branch predictors: bimodal, gshare and hybrid. Also, set-associative Branch Target Buffer (BTB) cache support is available, using which a branch can be predicted during instruction fetch cycle itself. The BTB uses LRU replacement policy to age out entries.

#### 2 Formulas

Some of the important formulas that are used to characterize branch predictor performance are briefly discussed in this section.

#### 2.1 Program Counter to Branch Predictor Table Index Conversion

The branch instruction addresses are always 4-byte aligned starting from 0. Thus, the last two bits of all addresses will be zero. Since, we use a part of lower order bits of the instruction address as an index to the predictor table, we need to ignore the leftmost 2-bits to minimize collisions.

#### 2.1.1 Index Calculation for Bimodal Predictor

The bimodal predictor table index for bimodal predictor can be calculated using the below formula.

```
pc >>= 2;
index = m-bit lower order mask
index &= pc
```

#### 2.1.2 Index Calculation for Gshare Predictor

In gshare preditor, the global history register is also used in index calculation. This minimizes the number of collisions in the predictor table. The gshare predictor table index for bimodal predictor can be calculated using the below formula.

```
pc >> = 2
index = m-bit lower order mask
index &= pc
index ^= bhr
```

#### 2.1.3 Index Calculation for Hybrid Predictor

The hybrid predictor uses a 2<sup>k</sup> bit chooser table for prediction. Its index is calculated similar to bimodal index.

```
pc >>= 2;
index = k-bit lower order mask
index &= pc
```

#### 2.2 Misprediciton Rate

Misprediciton rate denotes the ratio of number of branch mispredicitons (predicted differently from the actual branch outcome) by the predictor to the total number of branches. The lower the misprediction rate, the better is the perdictor's performance. This rate is one of the important attribute of a predictor which helps in understanding the characteristics it. All predictor performance improvement methods would decrease the misprediction rate in one way or the other.

$$mispredicitonRate = \frac{numMisPredicitons}{numTotalBranches}$$

#### 2.3 Predictor Table Size

The predictor table size is determined by the number of bits that are available to index the table (i.e,2<sup>num of bits in index</sup>), which is in turn governed by the value 'm'.

Size of predictor table = (# of bits in counter) \* 
$$(2^m)$$
 bits

#### 3 Experiments

Various experiments with bimodal and gshare predictors were run in order to understand the predictor's performance affecting attributes. This section represents the different runs, predictor parameters and statistics of every run in tables and in graphs. The data will be analyzed in following section.

In all the following experiments, three different trace files are used: gcc\_trace, jpeg\_trrace and perl\_trace.

#### 3.1 Bimodal Predictor Experiments

In this experiment, the 2-bit bimodal predictor is tested against different values of m (the number of lower order bits of PC to be used as an index of the predictor table) and different benchmarks - gcc, jpeg and perl. The misprediction rate is calculated in each case and plotted against the m value. This data is available in table 3.1 and the reuslts are plotted as graphs in figures 3.1, 3.2 and 3.3.

#### 3.2 Gshare Predictor Experiments

In this experiment, the ghsare branch predictor is run against different values of m (the number of lower order bits of PC to be used as an index of the predictor table), n (the number of bits in global branch history register) and different benchmarks - gcc, jepg and perl. The misprediction rate is calculated in each case and plotted against the m value. This data is available in tables 3.2, 3.3 and 3.4 and the results are plotted as graphs in figures 3.4, 3.5 and 3.6.

### 4 Branch Predictor Performance Analysis

The branch predictor's performance depends on many factors such as number of bits available to store the history of predictions, size of the predictor table, size of the branch target buffer and the branch instruction patterns themselves. In this section, we will analyze the data that we obtained in section 3 for bimodal and ghsare predictors.

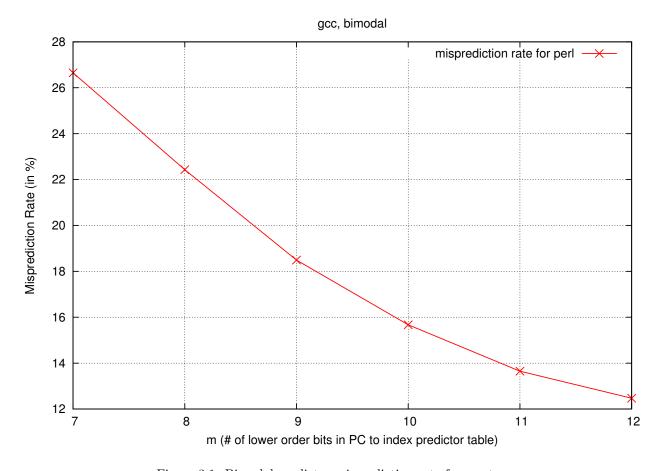


Figure 3.1: Bimodal predictor misprediction rate for gcc trace

(1.1.)	Misprediction Rate				
m (bits)	gcc	jpeg	perl		
7	26.65	7.92	21.31		
8	22.43	7.79	16.45		
9	18.49	7.74	14.14		
10	15.67	7.70	11.95		
11	13.65	7.62	11.05		
12	12.47	7.60	9.09		
13	11.72	7.59	8.92		
14	11.37	7.59	8.82		
15	11.30	7.59	8.82		
16	11.21	7.59	8.82		

Table 3.1: Experiment Data for bimodal predictor for different 'm' values and traces

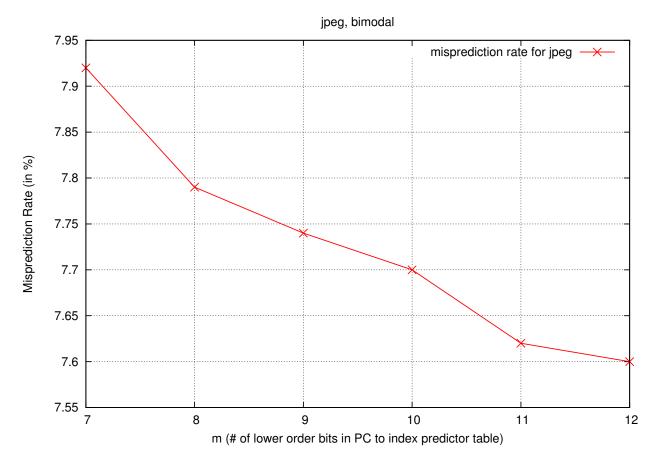


Figure 3.2: Bimodal predictor misprediction rate for jpeg trace

	Misprediction Rate					
m (bits)	n = 2	n = 4	n = 6	n = 8	n = 10	n = 12
7	28.98	30.76	32.22	-	-	-
8	25.81	26.57	27.82	30.56	-	-
9	20.25	22.43	24.14	26.08	-	-
10	16.39	17.99	19.36	21.10	22.77	-
11	13.71	14.49	15.14	16.47	18.34	-
12	12.20	12.23	12.46	13.00	14.33	15.40

Table 3.2: Experiment Data for gshare predictor for different 'm' and 'n' values for gcc trace

	Misprediction Rate					
m (bits)	n = 2	n = 4	n = 6	n = 8	n = 10	n = 12
7	8.08	8.92	9.74	-	-	-
8	7.79	7.88	8.87	9.20	-	-
9	7.58	7.68	8.13	8.30	-	-
10	7.49	7.38	7.58	7.45	7.95	-
11	7.45	7.27	7.38	7.17	7.44	-
12	7.44	7.26	7.19	6.84	7.18	7.35

Table 3.3: Experiment Data for gshare predictor for different 'm' and 'n' values for jpeg trace

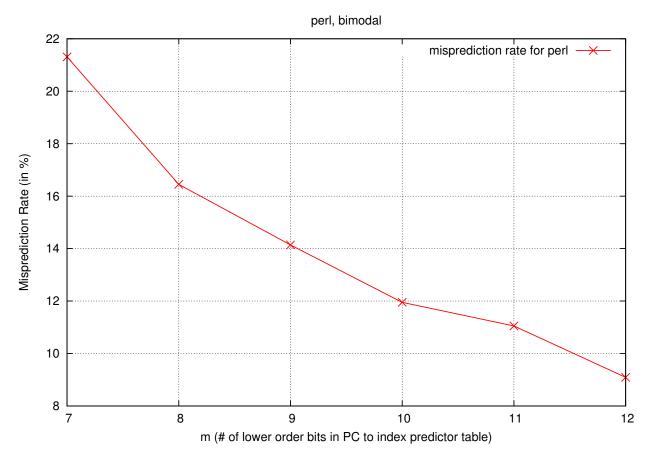


Figure 3.3: Bimodal predictor misprediction rate for perl trace

	Misprediction Rate					
m (bits)	n = 2	n = 4	n = 6	n = 8	n = 10	n = 12
7	24.34	25.96	28.71	-	-	-
8	16.92	19.09	20.45	24.79	-	-
9	13.57	14.68	16.25	17.66	-	-
10	10.63	11.35	11.52	12.42	14.57	-
11	10.11	9.68	8.60	9.00	8.98	-
12	9.04	8.09	7.50	6.49	6.71	7.16

Table 3.4: Experiment Data for gshare predictor for different 'm' and 'n' values for perl trace

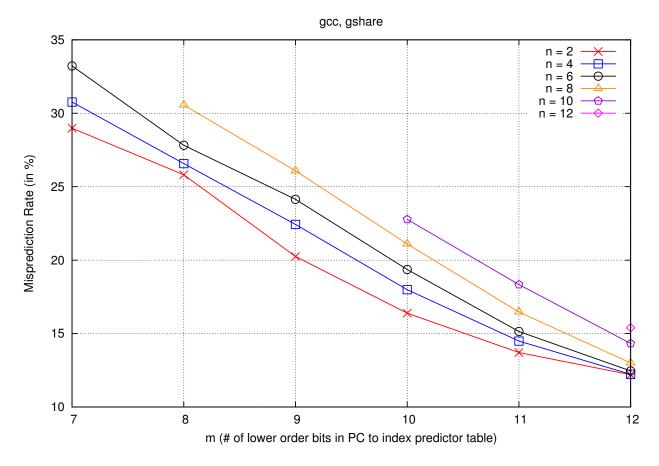


Figure 3.4: Ghsare predictor misprediction rate for gcc trace

#### 4.1 Analysis of Bimodal Predictor

From the graphs in figures 3.1, 3.2 and 3.3, it can be clearly seen that the misprediction rate decreases as 'm' value increases. This is due to the fact that using more bits of PC to index the predictor table reduces the collision domain of branch instructions in the predictor table. But, this also increases the storage cost as every additional bit used doubles the memory requirements.

#### 4.1.1 Benchmark Comparison

From table 3.1 it can be inferred that jpeg trace has the lowest misprediction rate among all given benchmarks, followed by perl and finally gcc. This could be attributed to the reason that jpeg benchmark has the branch instructions in a widely distributed manner thus reducing the collisions within the predictor table.

#### 4.1.2 Best Design Selection

In this section, we choose the best possible design (lowest misprediction rate) for each given benchmark with the constraint that the size of the predictor table should be no more than 16 KB.

From section 2.3, we know that the size of the bimodal predictor table is defined by 'm'. i.e., size of the predictor table =  $2 * 2^{m}$  bits.

• gcc: For a bimodal predictor table size of 16KB, we can use up to 16 bits in PC ( $2 * 2^{17}/8192 = 16$  KB). From table 3.1, it can be observed that for m = 16 and gcc trace, the misprediction rate is 11.21, which

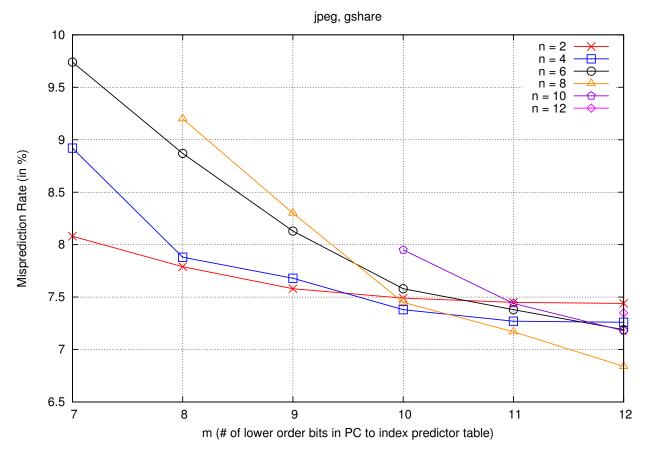


Figure 3.5: Gshare predictor misprediction rate for jpeg trace

is better than the rates for lower values of m.

- jpeg: For jpeg trace in table 3.1, bimodal predictor misprediction rate saturates at m = 13. So, we can build a table of size  $(2 * 2^{13}) = 2$  KB.
- perl: For m = 13, the misprediction rate is 8.92 and for higher values of m, the misprediction rate is less by a negligible value. So, we can safely build a predictor table of size 2 KB.

#### 4.2 Analysis of Gshare Predictor

From the graphs in figures 3.4, 3.5 and 3.6 it can be inferred that the misprediction rate decreases as 'm' increases as expected. The curve flattens for higher values of 'm' (for gcc) and for higher values of 'n' (for jpeg and perl).

But, the graphs also exhibit "laws of dimnishing" returns for 'n' value. i.e., while increasing 'n' enables more bits in history register to XOR with PC (thus minimizing the collision domain), it increases the overall misprediction rate of the predictor.

#### 4.2.1 Benchmark Comparison

The benchmarks for ghsare are similar to that of bimodal predictor. The jpeg trace has much more wide distribution of the branch instructions in the predictor tables (and thus has less collisions) and thereby has

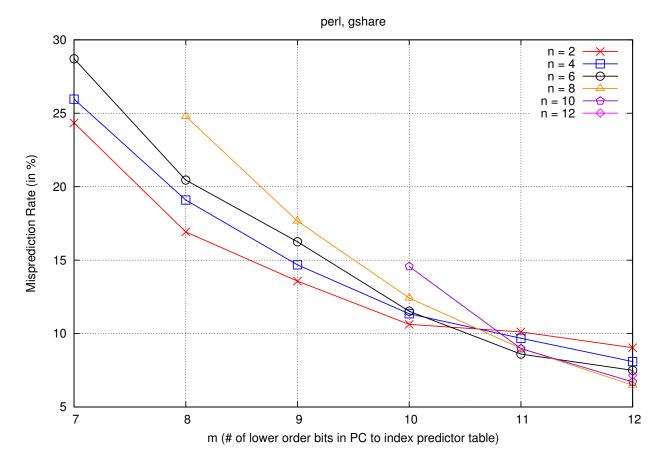


Figure 3.6: Gshare predictor misprediction rate for perl trace

the lowest misprediction rate. Of the remaining two, perl has better misprediction rate than gcc trace. The results of the experiments for different benchmarks are tabulated in tables 3.2,3.3 and 3.4 for reference.

#### 4.2.2 Best Design Selection

In this section, we choose the best possible design (lowest misprediction rate) for each given benchmark with the constraint that the size of the predictor table should be no more than 16 KB.

From section 2.3, we know that the size of the predictor table is defined by 'm'. i.e., size of the predictor table =  $2 * 2^m$  bits.

- gcc: From table 3.2, it can be seen that the misprediction rate is lower for lower values of n. i.e., for m <14 and n = 2, the misprediction rate is less. Also, the misprediction rate is less by a negligible value for m >13. So, we can use m = 13 and n = 2 for our predictor table to get best results. The size of the predictor table for this configuration will be  $((2^{13}/8) * 2) = 2 \text{ KB}, <16 \text{ KB constraint}.$
- jpeg: From the graph in figure 3.5, it is very clear that the misprediction rate is the lowest for n = 8 and m = 12. The size of the predictor table for such a configuration would be  $((2^{12}/8) * 2) = 1$  KB, which is way less than the 16 KB constraint.
- perl: Similar to jpeg benchmark, the misprediction rate is lowest for n = 8 and m = 12 for perl benchmark from table 3.4. The curve in figure 3.6 flattens out for higher values of n and m after that. So, the predictor table size would be similar to that of jpeg benchmark, 1 KB.

## 5 Conclusion

The key takeaway of this project and the project report is the understanding of different branch predictors and their attributes and how it affects the performance of a predictor (in both positive and negative way). The experiments and the associated plots shows that the 'm' value of a predictor plays an important role in bringing down the misprediction rate. Other factors include 'n' value and branch target buffer size.