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 CSCI S-89c Deep Reinforcement Learning
 Part I of Assignment 8

Please consider a Markov Decision Process (MDP) with $\mathcal{S} = \{s^A, s^B, s^C\}$.

Given a particular state $s \in \mathcal{S}$, the agent is allowed to either try staying there or switching to any of the other states. Let's denote an intention to move to state s^A by a^A , to state s^B by a^B , and to state s^C by a^C . The agent does not know transition probabilities, including the distributions of rewards. There is, however, some evidence that the agent gets rewards only at the entrance to s^C ; and transition MDP probabilities to/from s^A appear to be same (or nearly same) as to/from s^B .

Suppose the agent chooses policy $\pi(a^A|s) = 0.05$, $\pi(a^B|s) = 0.05$, $\pi(a^C|s) = 0.90$ for all $s \in \{s^A, s^B, s^C\}$. Because of the apparent symmetry between s^A and s^B , it makes sense to assume that $v_\pi(s^A) \approx v_\pi(s^B)$ and approximate the state-values as follows:

$$v_\pi(s) \approx \hat{v}(s, \mathbf{w}) = w_1 \cdot \mathbb{1}_{(s=s^A)} + w_1 \cdot \mathbb{1}_{(s=s^B)} + w_2 \cdot \mathbb{1}_{(s=s^C)}.$$

Please notice that $\hat{v}(s^A, \mathbf{w}) = \hat{v}(s^B, \mathbf{w})$ for any choice of weights.

Assume the agent runs the TD(λ) with Approximation for estimating v_π :

$$\begin{aligned} \mathbf{z}_{-1} &\doteq (0, 0)^T, \\ \mathbf{z}_t &\doteq \gamma \lambda \mathbf{z}_{t-1} + \nabla \hat{v}(S_t, \mathbf{w}_t) \text{ for } t \geq 0, \\ \mathbf{w}_{t+1} &\doteq \mathbf{w}_t + \alpha [R_{t+1} + \gamma \hat{v}(S_{t+1}, \mathbf{w}_t) - \hat{v}(S_t, \mathbf{w}_t)] \mathbf{z}_t \text{ for } t \geq 0, \end{aligned}$$

where $\lambda = 0.2$, $\alpha = 0.1$, $\gamma = 0.9$, and weights \mathbf{w}_t are set to zero at time $t = 0$.

If the agent observes the following sequence of states, actions, and rewards:

$$\begin{aligned} S_0 &= s^A, A_0 = a^C, R_1 = 20, \\ S_1 &= s^C, A_1 = a^B, R_2 = 0, \\ S_2 &= s^B, A_2 = a^C, R_3 = 20, \\ S_3 &= s^C, A_3 = a^C, R_4 = 20, \\ S_4 &= s^C, A_4 = a^B, R_5 = 0, \\ S_5 &= s^B, \end{aligned}$$

find (a) weights \mathbf{w}_t and (b) corresponding approximations $\hat{v}(s, \mathbf{w}_t)$ for $t = 1, 2, \dots, 5$. Specifically, please fill the tables in below:

SOLUTION:

(a) weights $\mathbf{w}_t = (w_{1,t}, w_{2,t})^T$:

	$t = 0$	$t = 1$	$t = 2$	$t = 3$	$t = 4$	$t = 5$
$w_{1,t}$	0	2	2.03	3.88	4.25	4.255
$w_{2,t}$	0	0	0.18	0.5	2.55	2.73

(b) approximations $\hat{v}(s, w_t)$:

	$t = 0$	$t = 1$	$t = 2$	$t = 3$	$t = 4$	$t = 5$
$\hat{v}(s^A, w_t)$	0	2	2.03	3.88	4.55	4.26
$\hat{v}(s^B, w_t)$	0	2	2.03	3.88	4.55	4.26
$\hat{v}(s^C, w_t)$	0	0	0.18	0.5	2.55	2.73

0.18

$$V_{\pi}(s) \approx \hat{v}(s, \omega) = \omega_1 \mathbb{1}_{s^A} + \omega_2 \mathbb{1}_{s^B} + \omega_3 \mathbb{1}_{s^C}$$

$$\boxed{t=1}$$

$$Z_{t+1} = \gamma \lambda Z_0 + \nabla \hat{v}(s^A, \omega)$$

$$= \begin{bmatrix} 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\omega_{t+1} = \omega_t + \alpha [R_{t+1} + \gamma \hat{v}(s_{t+1}, \omega_t) - \hat{v}(s_t, \omega_t)] Z_{t+1}$$

$$= \begin{bmatrix} 0 \\ 0 \end{bmatrix} + \alpha [20 + 0.9 \hat{v}(s^C, \omega_t) - 0] \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= 0.1 [20 + 0.9 \cdot 0] \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$V(s) \approx \hat{v}(s, \omega) \Rightarrow \begin{cases} V(s^A, \omega) = 2 + 0 + 0 \\ V(s^B, \omega) = 0 + 2 + 0 \\ V(s^C, \omega) = 0 + 0 + 0.1 = 0 \end{cases}$$

$$t=2$$

$$Z_{t=2} = \gamma \lambda Z_{t=1} + \gamma \hat{V}(s^L, \omega)$$

$$= 0.18 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0.18 \\ 1 \end{bmatrix}$$

$$\omega_{t=2} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} + \alpha \left[0 + \gamma \hat{V}(s^B, \omega_t) - \hat{V}(s^L, \omega_t) \right] \begin{bmatrix} 0.18 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ 0 \end{bmatrix} + \alpha \left[\gamma \cdot 2 - 0 \right] \begin{bmatrix} 0.18 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} + 0.18 \begin{bmatrix} 0.18 \\ 1 \end{bmatrix} = \begin{bmatrix} 2.03 \\ 0.18 \end{bmatrix}$$

$$V_{\pi}(s^A) = V_{\pi}(s^B) = 2.03$$

$$V_{\pi}(s^L) = 0.18$$

$$t=3$$

$$Z_{t=3} = \gamma \lambda Z_{t=2} + \gamma \hat{V}(s^B, \omega)$$

$$= 0.18 \begin{bmatrix} 0.18 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0.03 + 1 \\ 0.18 + 0 \end{bmatrix} = \begin{bmatrix} 1.03 \\ 0.18 \end{bmatrix}$$

$$\omega_{t=3} = \begin{bmatrix} 2.03 \\ 0.18 \end{bmatrix} + \alpha \left[2.0 + \gamma \hat{V}(s^L, \omega_t) - \hat{V}(s^B, \omega_t) \right] \begin{bmatrix} 1.03 \\ 0.18 \end{bmatrix}$$

$$= \begin{bmatrix} 2.03 \\ 0.18 \end{bmatrix} + 0.1 \left[2.0 + \gamma(0.18) - 2.03 \right] \begin{bmatrix} 1.03 \\ 0.18 \end{bmatrix}$$

$$= \begin{bmatrix} 2.03 \\ 0.18 \end{bmatrix} + 1.8 \begin{bmatrix} 1.03 \\ 0.18 \end{bmatrix} = \begin{bmatrix} 2.03 + 1.85 \\ 0.18 + 0.32 \end{bmatrix} = \begin{bmatrix} 3.88 \\ 0.50 \end{bmatrix}$$

$$V_{\pi}(A) = V_{\pi}(B) = 3.88$$

$$V_{\pi}(C) = 0.5$$

$$\boxed{t=4} \quad Z_{t=4} = \gamma \lambda Z_{t=3} + \nabla \hat{V}(s^L, \omega) = 0.18 \begin{bmatrix} 1.03 \\ 0.18 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\ = \begin{bmatrix} 0.185 \\ 1.03 \end{bmatrix}$$

$$\omega_{t=4} = \begin{bmatrix} 3.88 \\ 0.5 \end{bmatrix} + \alpha [Z_0 + \gamma \hat{V}(s^L, \omega) - \hat{V}(s^L, \omega)] \begin{bmatrix} 0.185 \\ 1.03 \end{bmatrix} \\ = \begin{bmatrix} 3.88 \\ 0.5 \end{bmatrix} + \alpha [20 + \gamma \cdot 0.5 - 0.5] \begin{bmatrix} 0.185 \\ 1.03 \end{bmatrix} \\ = \begin{bmatrix} 3.88 \\ 0.5 \end{bmatrix} + 1.995 \begin{bmatrix} 0.185 \\ 1.03 \end{bmatrix} = \begin{bmatrix} 3.88 + 0.37 \\ 0.5 + 2.05 \end{bmatrix} = \begin{bmatrix} 4.25 \\ 2.55 \end{bmatrix}$$

$$V_{\pi}(A) = V_{\pi}(B) = 4.55$$

$$V_{\pi}(C) = 2.55$$

$$\boxed{t=5} \quad Z_{t=5} = \gamma \lambda Z_{t=4} + \nabla \hat{V}(s^L, \omega) = 0.18 \begin{bmatrix} 0.185 \\ 1.03 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\ = \begin{bmatrix} 0.033 \\ 1.185 \end{bmatrix}$$

$$\omega_{t=5} = \begin{bmatrix} 4.25 \\ 2.55 \end{bmatrix} + \alpha [0 + \gamma \hat{V}(a^B, \omega) - \hat{V}(a^L, \omega_t)] \begin{bmatrix} 0.033 \\ 1.185 \end{bmatrix} \\ = \begin{bmatrix} 4.25 \\ 2.55 \end{bmatrix} + \alpha [0.9(4.55) - 2.55] \begin{bmatrix} 0.033 \\ 1.185 \end{bmatrix}$$

$$= \begin{bmatrix} 4.25 \\ 2.55 \end{bmatrix} + 0.1545 \begin{bmatrix} 0.033 \\ 1.185 \end{bmatrix} = \begin{bmatrix} 4.25 + 0.005 \\ 2.55 + 0.18 \end{bmatrix} = \begin{bmatrix} 4.255 \\ 2.73 \end{bmatrix}$$