OPERATING SYSTEMS: COMMUNICATION AND SYNCHRONIZATION AMONG PROCESSES



Threads and communication and synchronization mechanisms



Before classes

Class

After class

Prepare the prerequisites.

Study the material associated with the **bibliography**: slides alone are not enough.

Please ask questions (especially after study).

Exercising skills:

- Perform all exercises.
- Carrying out the practice notebooks and the practical exercises progressively.



- I. Carretero 2020:
 - 1. Cap. 6
- 2. Carretero 2007:
 - . Cap. 6.1 and 6.2

Suggested



- I. Tanenbaum 2006:
 - (es) Chap. 5
 - 2. (en) Chap. 5
- 2. Stallings 2005:
 - 1. 5.1, 5.2 and 5.3
- Silberschatz 2006:
 - 1. 6.1, 6.2, 6.5 and 6.6

Contents

□ Introduction (definitions)	:
------------------	--------------	---

- Concurrent processes.
- Concurrency, communication and synchronization.
- Critical section and Race conditions.
- Mutual exclusion and critical section.
- Synchronization mechanisms (I):
 - Initial basic primitives.
 - Semaphores.
- Classic concurrency problems (I):
 - Producer-consumer
 - Reader-writers

Synchronization mechanisms of threads (II)

- Semaphores
 - System calls for semaphores.
 - Classic concurrency problems.
- Mutex and condition variables
 - System calls for mutex.
 - Classic concurrency problems.
- Case study: concurrent server development

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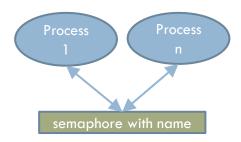
 Synchronization mechanism for processes and/or threads on the same machine.

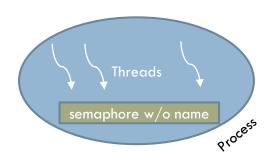
#include <semaphore.h>

□ Two types of POSIX semaphores:

POSIX Semaphores

- Semaphores with name:
 - It can be used by different processes that know the name.
 - No shared memory required.
 - sem_t *semaphore; // named
- Semaphores without name:
 - They can be used only by the processes that create them (and their threads) or by processes that have a shared memory area.
 - **sem t** semaphore; // no named





POSIX Semaphores

```
    int sem_init(sem_t *sem, int shared, int val);
    Initializing an unnamed semaphore
    int sem_destroy(sem_t *sem);
    Destroy an unnamed semaphore
    sem_t *sem_open(char *name, int flag, mode_t mode, int val);
    Creates (or opens) a named semaphore.
    int sem_close(sem_t *sem);
    Closes a named semaphore.
    int sem_unlink(char *name);
    Remove a named semaphore.
```

- int sem_wait(sem_t *sem);
 - Performs the wait operation on the semaphore.
- int sem_trywait (sem_t *sem)
 - Attempts to wait but if it needs to block the process -> it does not block and gives -1
- int sem post(sem t *sem);
 - Performs the signal operation on the semaphore.

Semaphores operations

```
sem wait(s) {
    s = s - 1;
    if (s < 0) {
       <Blocking
        the process>
```

```
sem post(s) {
    s = s + 1;
    if (s <= 0)
       <Unblock a
        process blocked
        by a wait
        operation>
```

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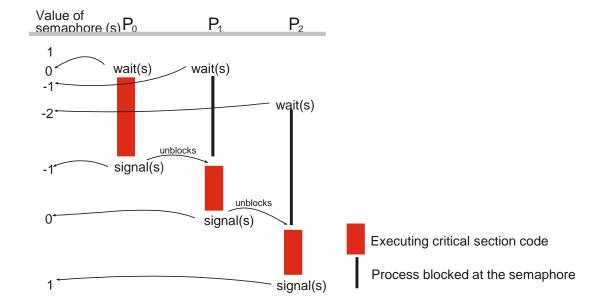


The semaphore must have an initial value of 1:

```
sem wait(s); /* enter in the critical section */
  < critical section >
sem post(s); /* leave the critical section */
```

Critical sections with semaphores

Example:



Producer-consumer with bounded buffered Semaphores without name

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```
void Producer(void)
{
   int pos = 0;
   int dato, i;

   for (i=0; i<DATA_TO_PRODUCE; i++)
   {
      dato = i;
      sem_wait(&huecos);
      sem_wait(&mutex);
      buffer[pos] = i;
      pos = (pos + 1) % MAX_BUFFER;
      sem_post(&mutex);
      sem_post(&elements);
   }
   pthread_exit(0);
}</pre>
```

```
void Consumer ( void )
{
   int pos = 0;
   int dato, i;

   for (i=0; i<DATA_TO_PRODUCE; i++)
   {
      sem_wait(&elements);
      sem_wait(&mutex);
      dato = buffer[pos];
      pos = (pos + 1) % MAX_BUFFER;
      sem_post(&mutex);
      sem_post(&huecos);
      /* consume data */
   }
   pthread_exit(0);
}</pre>
```

Semaphores without name (1/4)

Producer-consumer with bounded buffered

```
#include <semaphore.h>
/* buffer size */
#define MAX BUFFER
/* datos a producir */
#define DATA_TO_PRODUCE 100000
                             /* elements in the buffer */
/* spaces in the buffer */
sem_t elements;
sem_t huecos;
int buffer[MAX BUFFER]; /* shared buffer */
int main ( int argc, char*argv[] )
   pthread_t th1, th2;
   sem_init(&mutex, 0, 1);
sem_init(&elements, 0, 0);
    sem init(&huecos, 0, MAX BUFFER)
    /* create threads */
    pthread create(&th1, NULL, Producer, NULL);
pthread_create(&th2, NULL, Consumer, NULL);
    /* wait for its completion */
   pthread_join(th1, NULL);
pthread_join(th2, NULL);
    sem_destroy(&mutex);
    sem destroy (&huecos);
    sem_destroy(&elements);
void Producer (void)
    int dato, i;
    for (i=0; i<DATA TO PRODUCE; i++)
       sem wait(&huecos);
       sem_wait(&mutex);
buffer[pos] = i;
pos = (pos + 1) % MAX_BUFFER;
        sem_post(&mutex);
       sem_post(&elements);
   pthread_exit(0);
void Consumer ( void )
    int pos = 0;
    int dato, i;
    for (i=0; i<DATA TO PRODUCE; i++)
       sem wait(&elements);
       dato = buffer[pos];
pos = (pos + 1) % MAX BUFFER;
        sem post(&mutex);
        sem_post(&huecos);
           consume data *
   pthread_exit(0);
```

```
#include <semaphore.h>
                          Productor
/* buffer size*/
#define MAX BUFFER
/* data to produce */
#define DATA TO PRODUCE
                          100000
                                        Consumidor
sem t mutex; /* critical section */
sem t elements; /* eltos in the buffer */
                /* spaces in the buffer */
sem t huecos;
int buffer[MAX BUFFER]; /* shared buffer */
int main ( int argc, char *argv[])
   pthread t th1, th2;
   /* initialize the semaphores */
   sem init(&mutex,
                         0, 1);
   sem init(&elements, 0, 0);
   sem init(&huecos,      0, MAX BUFFER);
```

pthread exit(0);

Semaphores without name (2/4)

Producer-consumer with bounded buffered

```
//...
#include <semaphore.h>
/* buffer size */
#define MAX BUFFER
/* datos a producir */
#define DATA_TO_PRODUCE 100000
                              /* elements in the buffer */
/* spaces in the buffer */
sem_t elements;
sem_t huecos;
int buffer[MAX BUFFER]; /* shared buffer */
int main ( int argc, char*argv[] )
    pthread_t th1, th2;
   sem_init(&mutex, 0, 1);
sem_init(&elements, 0, 0);
    sem init(&huecos, 0, MAX BUFFER)
    /* create threads */
    pthread create(&th1, NULL, Producer, NULL);
pthread_create(&th2, NULL, Consumer, NULL);
    /* wait for its completion */
   pthread_join(th1, NULL);
pthread_join(th2, NULL);
    sem destroy (&mutex);
    sem destroy (&huecos);
    sem_destroy(&elements);
void Producer (void)
    int dato, i;
    for (i=0; i<DATA TO PRODUCE; i++)
        sem wait(&huecos);
       sem_wait(&mutex);
buffer[pos] = i;
pos = (pos + 1) % MAX_BUFFER;
        sem_post(&mutex);
        sem post(&elements);
   pthread_exit(0);
void Consumer ( void )
    int pos = 0;
    int dato, i;
    for (i=0; i<DATA TO PRODUCE; i++)
        sem wait(&elements);
       dato = buffer[pos];
pos = (pos + 1) % MAX BUFFER;
        sem post(&mutex);
        sem_post(&huecos);
           consume data *
```

```
Productor
                             Consumidor
```

```
/* create threads */
pthread create (&th1, NULL, Producer, NULL);
pthread create (&th2, NULL, Consumer, NULL);
/* wait for its completion */
pthread join(th1, NULL);
pthread join(th2, NULL);
sem destroy(&mutex);
sem destroy(&huecos);
sem destroy(&elements);
return (0);
```

Semaphores without name (3/4)

Producer-consumer with bounded buffered

```
//...
#include <semaphore.h>
/* buffer size */
#define MAX BUFFER
/* datos a producir */
#define DATA_TO_PRODUCE 100000
                              /* elements in the buffer */
/* spaces in the buffer */
sem_t elements;
sem_t huecos;
int buffer[MAX BUFFER]; /* shared buffer */
int main ( int argc, char*argv[] )
   pthread_t th1, th2;
   sem_init(&mutex, 0, 1);
sem_init(&elements, 0, 0);
    sem_init(&huecos, 0, MAX_BUFFER);
    /* create threads */
   pthread create(&th1, NULL, Producer, NULL);
pthread_create(&th2, NULL, Consumer, NULL);
    /* wait for its completion */
   pthread_join(th1, NULL);
pthread_join(th2, NULL);
    sem destroy (&mutex);
    sem_destroy(&huecos);
    sem_destroy(&elements);
void Producer (void)
    int dato, i;
    for (i=0; i<DATA TO PRODUCE; i++)
       sem wait(&huecos);
       sem_wait(&mutex);
buffer[pos] = i;
pos = (pos + 1) % MAX_BUFFER;
        sem_post(&mutex);
       sem_post(&elements);
    pthread_exit(0);
 void Consumer ( void
    int dato, i;
    for (i=0; i<DATA TO PRODUCE; i++)
       sem wait(&elements);
       dato = buffer[pos];
pos = (pos + 1) % MAX BUFFER;
        sem_post(&mutex);
        sem_post(&huecos);
           consume data *
   pthread exit(0);
```

```
void Producer(void)
   int pos = 0;
   int dato;
   int i;
   for (i=0; i<DATA TO PRODUCE; i++)
      dato = i; /* produce... */
      sem wait(&huecos);
      sem wait(&mutex);
      buffer[pos] = i;
      pos = (pos + 1) % MAX BUFFER;
      sem post(&mutex);
      sem post(&elements);
   pthread exit(0);
```

Producer-consumer with bounded buffered

Semaphores without name (4/4)

```
void Consumer ( void )
   int pos = 0;
   int dato;
   int i;
   for (i=0; i<DATA TO PRODUCE; i++)
      sem wait(&elements);
      sem wait(&mutex);
      dato = buffer[pos];
      pos = (pos + 1) % MAX BUFFER;
      sem post(&mutex);
      sem post(&huecos);
      /* consume data */
   pthread exit(0);
```

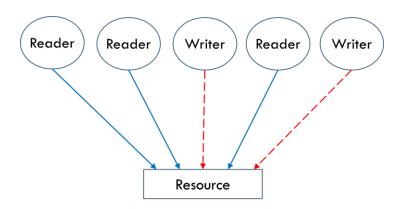
Reader-writer problem



- Problem that arises when you have:
 - A shared storage area.
 - Multiple processes read information.
 - Multiple processes write information.

Conditions:

- Any number of readers can read from the data zone concurrently: multiple readers possible at the same time.
- Only one writer can modify the information at a time.
- During a writing no reader can read



Readers and writers Semaphores without name

int dato = 5; /* resource */

```
int n readers = 0; /* num. of readers */
sem t sem reader; /* control access to n readers */
```

```
void Reader(void)
  sem wait(&sem reader);
  n = aders = n = aders + 1;
  if (n readers == 1)
      sem wait(&mutex);
  sem post(&sem reader);
  printf("%d\n", dato);
  sem wait(&sem reader);
  n readers = n readers - 1;
  if (n readers == 0)
      sem post(&mutex);
  sem post(&sem reader);
  pthread exit(0);
```

```
void Writer(void)
   sem wait(&mutex);
   dato = dato + 2;
   sem post(&mutex);
   pthread exit(0);
```

Readers and writers

Semaphores without name

```
int dato = 5;  /* resource */
int n readers = 0; /* num. of readers */
sem t sem reader; /* control access to n readers */
sem t mutex; /* control access to dato */
int main ( int argc, char *argv[] )
  pthread t th1, th2, th3, th4;
   sem init(&mutex, 0, 1);
   sem init(&sem reader, 0, 1);
  pthread create(&th1, NULL, Reader, NULL);
  pthread create(&th2, NULL, Writer, NULL);
  pthread create(&th3, NULL, Reader, NULL);
  pthread create(&th4, NULL, Writer, NULL);
  pthread join(th1, NULL);
  pthread join(th2, NULL);
  pthread join(th3, NULL);
  pthread join(th4, NULL);
   sem destroy(&mutex);
   sem destroy(&sem reader);
  return 0;
```

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```
SHARED MEMORY:
int nreaders; semaphore s read=1; semaphore s write=1;
```

Reader-writers (readers have priority)

```
READER:
for(;;) {
 sem_wait(s_read);
  nreaders++;
  if (nreaders==1)
      sem wait(s write);
 sem signal(s read);
  perform_read();
 sem wait(s read);
  nreaders --;
  if (nreaders==0)
      sem_signal(s_wrike);
  sem_signal(s_read);
```

```
WRITER:
for(;;) {
>> sem wait(s write);
  perform_write();
  sem_signal(s_write);
```

Reader-writers (writers have priority) Semaphores without name



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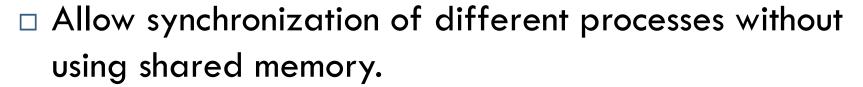
```
SHARED MEMORY:
int nreaders, nescr = 0; semaphore lect, s write = 1;
semaphore x, y, z = 1;
```

```
WRITER:
READER:
for(;;) {
                                       for(;;) {
 →sem wait(z);
                                        →sem wait(y);
 sem wait(lect);
                                            nescr++;
  sem wait(x);
                                            if (nescr==1)
     nreaders++;
                                                 sem wait(lect);
     if (nreaders==1)
                                        →sem signal(y);
         sem wait(s writ
   sem_signa\overline{I}(x);
                                        →sem_wait(s_write);
                                            // doWriting();
 sem_signal(lect);
 sem_signal(z);
                                        sem signal(s write);
     // doReading();
                                        →sem wait(y);
   sem wait(x);
                                            nescr--;
     nreaders --:
                                            if (nescr==0)
     if (nreaders==0)
                                                sem_signal(s_readt);
         sem signal(s write);
                                        →sem signal(y);
   sem_signa\overline{I}(x);
```

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Naming

Semaphores with name



- The name of a semaphore is a string of characters (with the same restrictions as a filename).
 - If the name (path) is relative, only the process that creates it and its children can access the semaphore.
 - If the name is absolute (starts with "/") the semaphore can be shared by any process that knows its name and has permissions.
- Common mechanism for creating semaphores shared by parents and children
 - "Unnamed" does not apply -> processes do NOT share memory.

Semaphores with name Creation and use

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□ To create:

```
sem t *sem open(char *name, int flag, mode t mode, int val);
Flag = O_CREAT will create it.
□ Flag: O_CREAT | O_EXECL will create it if it does not exist. -1 in case it exists.
Mode: access permissions;
```

- \square Val: initial value of the semaphore (>=0);
- □ To use:

```
sem t *sem open(char *name, int flag);
■ With flag 0. If it does not exist, it returns -1.
```

- Important:
 - All processes must know "name" and use the same name.

Readers and writers semaphores with name

```
int main (int argc, char *argv[])
    int i, n= 5; pid t pid;
    /* Creates the named semaphore */
    if ((mutex=sem open("/tmp/sem 1", O CREAT, 0644, 1)) == (sem t *)-1)
        { perror("Cannot create a semaphore: "); exit(1); }
    if ((sem reader=sem open("/tmp/sem 2", O CREAT, 0644, 1)) == (sem t *)-1)
        { perror("Cannot create a semaphore: "); exit(1); }
    /* Creates the processes */
    for (i = 1; i < atoi(arqv[1]); ++i)
      pid = fork();
      if (pid ==-1)
         { perror("The process cannot be created: "); exit(-1);}
      if (pid==0)
         { reader(getpid()); break; }
      else writer (pid);
    sem close(mutex);
    sem close(sem reader);
    sem unlink("/tmp/sem 1");
    sem unlink("/tmp/sem 2");
    return 0;
```

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Readers and writers semaphores with name

Contents

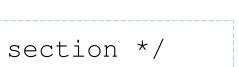
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□ A mutex is a synchronization mechanism suitable for threads.

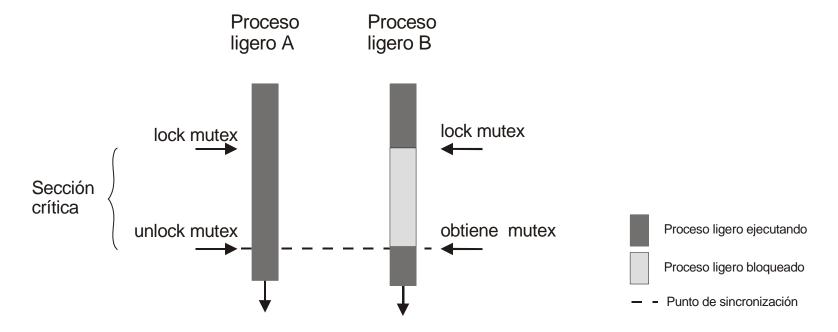
Mutex and conditional variables

- □ It is a binary semaphore with 2 atomic operations:
 - lock(m) Lock the mutex and if the mutex is already locked the process is suspended.
 - unlock(m) Unlocks the mutex and if there are suspended processes in the mutex then it unblock one.
- □ TIP: The unlock operation must be performed by the thread that executed lock

Critical sections with mutex



```
lock(m); /* enter in the critical section */
 < critical section >
unlock(m); /* leave the critical section */
```



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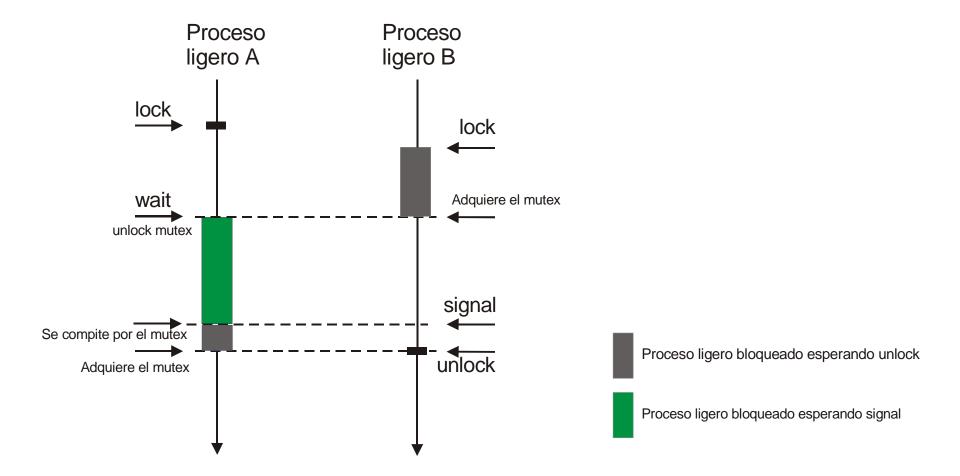
Conditional variables



- Synchronization variables associated with a mutex
- □ Two atomic operations:
 - wait: Blocks the thread that executes it and ejects it from the mutex
 - signal: Unblocks one or more suspended processes in the conditional variable and the waking process competes again to lock the mutex
- □ Convenient to execute between lock and unlock

Conditional variables





Use of mutex and conditional variables

□ Thread A

```
lock (mutex); /* access to the resource
check the data structures;
                                              Proceso
                                                    Proceso
                                              liaero A
while (busy resource)
                                                       lock
        wait(condition, mutex);
mark the resource as busy;
unlock (mutex);
```

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□ Thread B

```
lock (mutex); /* access to the resource
mark the resource as free;
signal (condition);
unlock (mutex);
```

Use of mutex and conditional variables

□ Thread A

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

```
lock(mutex); /* access to the resource */
check the data structures;
while (busy resource)

wait(condition, mutex);
mark the resource as busy;
unlock(mutex);
```

□ Thread B

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

Use of mutex and conditional variables

□ Thread A

```
lock(mutex); /* access to the resource */
    check the data structures;
                                              liaero A
    while (busy resource)
                                                      lock
           wait(condition, mutex);
    mark the resource as busy;
    unlock (mutex);
□ Thread B
    lock(mutex); /* access to the resource */
    mark the resource as free;
    signal (condition);
    unlock (mutex);
```

```
lock (mutex);  /* access to the resource */
check the data structures;
while (busy resource)

wait(condition, mutex);
mark the resource as busy;
unlock (mutex);
```

□ Thread B

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

□ Thread B

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

□ Thread A

```
lock(mutex); /* access to the resource */
check the data structures;
while (busy resource)
```

```
wait(condition, mutex);
mark the resource as busy;
unlock(mutex);
```

Important to use while to reevaluate condition

□ Thread B

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

Use of mutex and conditional variables

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□ Thread A

```
lock(mutex); /* access to the resource */
check the data structures;
while (busy resource)
    wait(condition, mutex);
mark the resource as busy;
unlock(mutex);
```

□ Thread B

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

Use of mutex and conditional variables

□ Thread A

□ Thread B

```
lock(mutex); /* access to the resource */
mark the resource as free;
signal(condition);
unlock(mutex);
```

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Use of mutex and conditional variables

□ Thread A

```
lock (mutex); /* access to the resource
     check the data structures;
     while (busy resource)
              wait(condition, mutex);
                                             · A signal before the wait is "lost".
    mark the resource as busy;

    Herefore, the Boolean
condition (free/busy
resource) is important.

     unlock (mutex);
□ Thread B
     lock(mutex); /* access to the resource */
    mark the resource as free;
     signal (condition);
     unlock (mutex);
```

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POSIX Services

```
int pthread mutex init (pthread mutex t *mutex,
                           pthread mutexattr t * attr );
  Initializes a mutex.
int pthread mutex destroy ( pthread mutex t *mutex );
  Destroy a mutex.
int pthread mutex lock (pthread mutex t *mutex);
  Try to obtain the mutex.
  locks the thread if the mutex is acquired by another thread.
int pthread mutex unlock (pthread mutex t *mutex);
  Unlock the mutex.
```

```
int pthread cond init ( pthread cond t*cond,
                           pthread condattr t*attr );
   Initializes a conditional variable.
int pthread cond destroy ( pthread cond t *cond );
   Destroys a conditional variable.
int pthread cond signal (pthread cond t *cond);
   At least one of the threads suspended in cond is reactivated.
   No effect if there is no thread waiting (different from semaphores).
int pthread cond wait (pthread cond t*cond,
                              pthread mutex t*mutex );
   At the same time suspends the calling thread and releases mutex.
```

When another thread calls ..._cond_signal on cond the thread wakes up

and competes again for the mutex.

POSIX Services

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```
int pthread_cond_broadcast ( pthread_cond_t *cond );
```

- All suspended threads in the conditional variable cond are reactivated.
- It has no effect if no thread is waiting.

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Producer-consumer with mutex

```
int main ( int argc, char *argv[] )
   pthread t th1, th2;
   pthread mutex init(&mutex, NULL);
   pthread cond init(&no full, NULL);
   pthread cond init(&no empty, NULL);
   pthread create(&th1, NULL, Producer, NULL);
    pthread create(&th2, NULL, Consumer, NULL);
   pthread join(th1, NULL);
   pthread join(th2, NULL);
   pthread mutex destroy(&mutex);
   pthread cond destroy(&no full);
    pthread cond destroy(&no empty);
    return 0;
```

```
#define MAX BUFFER 1024  /* buffer size */
#define DATA_TO_PRODUCE 100000  /* data to be produced */

pthread mutex t mutex;  /* shared buffer access mutex */
pthread_cond_t no_full;  /* controls the filling of the buffer */
pthread_cond_t no_empty;  /* controls the emptying of the buffer */
int n eTements;  /* number of elements in the buffer */
int buffer[MAX BUFFER];  /* common buffer */
```

Reader-writers with mutex

```
int main ( int argc, char *argv[] )
   pthread t th1, th2, th3, th4;
   pthread mutex init(&mutex, NULL);
   pthread mutex init(&mutex readers, NULL);
   pthread create(&th1, NULL, Reader, NULL);
   pthread create(&th2, NULL, Writer, NULL);
    pthread create(&th3, NULL, Reader, NULL);
   pthread create(&th4, NULL, Writer, NULL);
   pthread join(th1, NULL);
   pthread join(th2, NULL);
   pthread join(th3, NULL);
   pthread join(th4, NULL);
   pthread mutex destroy(&mutex);
   pthread mutex destroy(&mutex readers);
    return 0:
```

```
void *Reader( void *arg )
{
    pthread_mutex_lock(&mutex_readers);
    n_readers++;
    if (n_readers == 1)
        pthread_mutex_lock(&mutex);
    pthread_mutex_unlock(&mutex_readers);

/* read dato */
    printf("%d\n", dato);

pthread_mutex_lock(&mutex_readers);
    n_readers--;
    if (n_readers == 0)
        pthread_mutex_unlock(&mutex);
    pthread_mutex_unlock(&mutex_readers);

pthread_mutex_unlock(&mutex_readers);
```

```
void *Writer ( void *arg )
{
    pthread_mutex_lock(&mutex);

    /* modify the resource */
    dato = dato + 2;

    pthread_mutex_unlock(&mutex);

    pthread_exit(0);
}
```

OPERATING SYSTEMS: COMMUNICATION AND SYNCHRONIZATION AMONG PROCESSES



Threads and communication and synchronization mechanisms