

Type of textures

8-19-2021 5:15 x 132

- There are two kind of classification:

1. Explicit Texture Map: Consist of a regular bitmap.

we require to provide the texture coordinates and a subsystem for the texture processing.

2. Procedural Texture: output of the program which computes the texture map. The texture is decomposed in primitive equations and functions.

The advantage over explicit texture mapping is that they are resolution independent, they are usually not as repetitive.

However, they can take system resources.

- Another classification is between static and dynamic texture maps.

While dynamic maps are computed in real time, static maps are created once. Using a sequence of bitmaps to create a fire effect that can be wrapped around an object is an example of dynamic and explicit texturing mapping.

- Textures can be 1D, 2D, and 3D data set. Example: 3D textures are called volume textures.

- Texture mapping is the specification of how the texture map should stretch and wrap the object.

In the case of 2D textures, the texture mapping is a function that goes from (x, y, z) to (u, v) where (u, v) are mapping coordinates. This defines the correspondence between vertices on the geometry and the pixels in the map. Example:

$$\begin{aligned} u &= x + z \\ v &= y \end{aligned}$$

11	12	13
21	22	23
31	32	33

In

$[U(), V()]$
←

						13	43
				12	13	43	13
11	14	12	12	12	13	43	43
21	21	22	22	22	23	23	23
31	31	22	22	22	23	23	23
		31	32	32	33	33	33

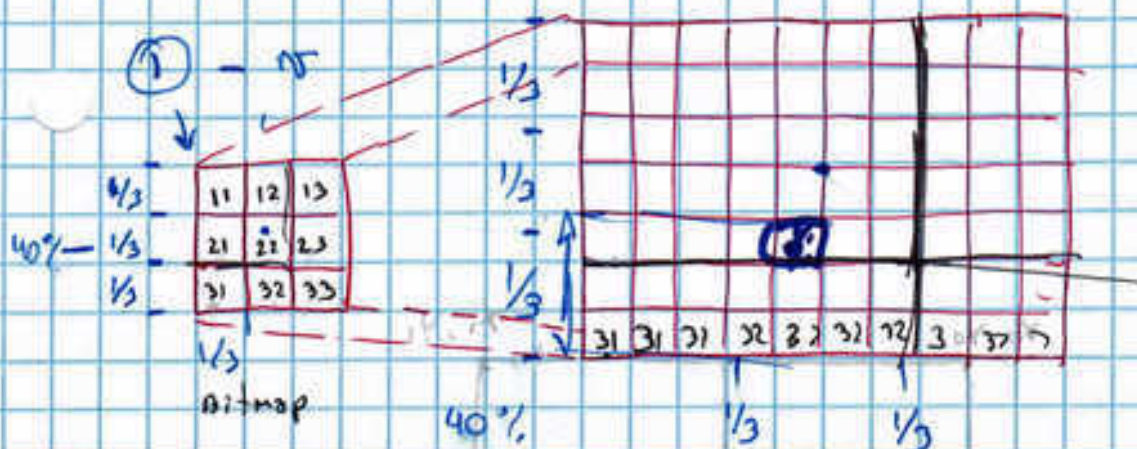
Inverse map give complete covers

Out

~~Inverse map is a solution to the problem of forward image mapping process~~

Instead of sending each input pixel to an output pixel (as in forward image mapping) and determine what input pixel(s) map should be use, we invert.

1 1 1



Paroxentrol

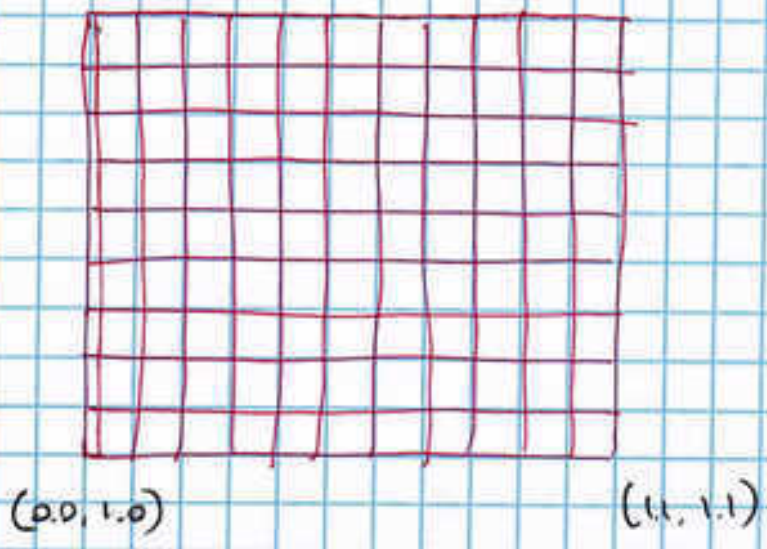
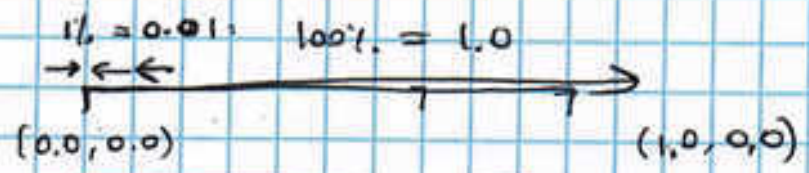
$$(mv_{\text{avg}} = \frac{1}{2} p_{\text{avg}})$$

(over)

Be

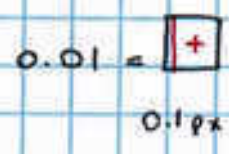
(知)

 $\lambda, \lambda_1, \lambda_2$ x_0, y_0 x_1, y_1 (x_m, y_m) $x_{0,73}$
$$x_2 \quad y_2$$



→ 10px
↓
10px

400 cars — 100%
 $\frac{400}{100} = 4$ cars — 1%
48 — 12%



$\frac{512}{12} \approx 42.6$

$100 = 1$
 $\frac{100}{100} = 0.1$

512px — 1
5.12px — 0.1

(width + height)



$$0.1 = \sqrt{0.01} \quad 1.0 = 1$$

(0.0, 0.0)

(0.0, 0.0)

29.01

29.01

1.001 — 20.001

1.0 — 20.001

1.01 — 20.001

(0.1, 0.1)

(0.1, 0.1)

0.1 — 0.0

0.0

0.0

+ 10.0

29.0

1 — 20.0

1.0 — 20.0

0.01 — 0.0

0.0

1 — 20.0

1.0 — 20.0



f(0.0, 0.0)

- ① vertex 2f (x, y)
vertex 2f (x_2, y_2)



- ② DRAW

- ③ Mouse.x Mouse.y

- ④ Vector

N/A

Mouse.x \neq vertex 2f

for (1) {

x, y

vertex 2f (x, y)

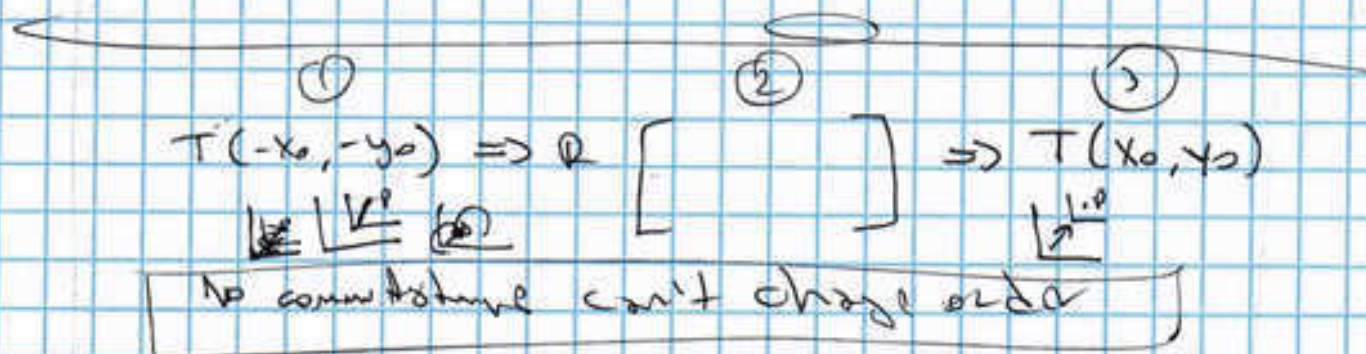
}

vertex (mouse.x, mouse.y)



x, y
 x, y

Mouse.x | Mouse.y



- ① align everything to origin
② then do rotations



(1) vector $\vec{v}(x)$ after

(2) vector $\vec{v}(x)$ after

(3) vector

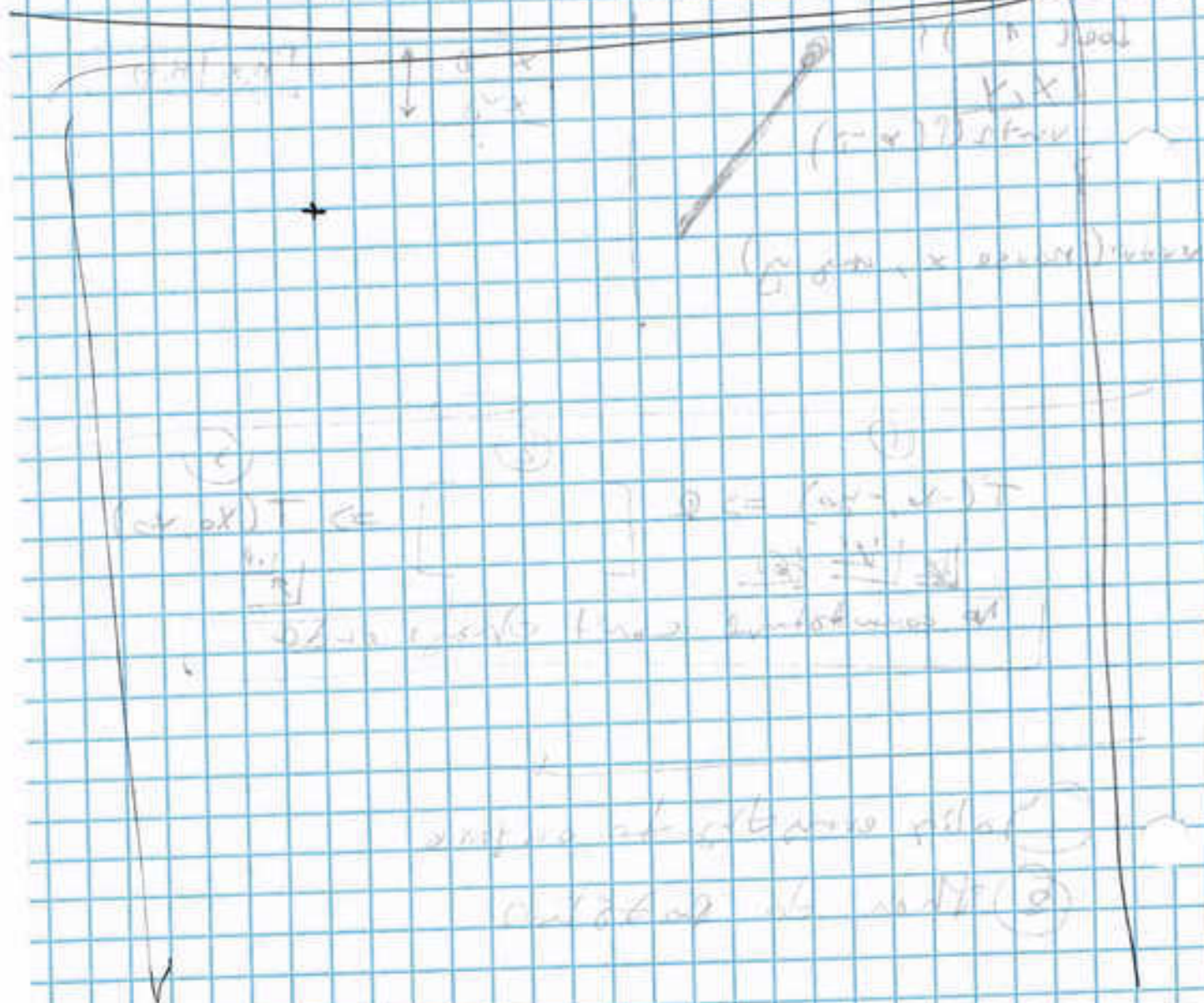
(4) (vector $\vec{v}(x)$ after)

(5) vector

(6) $\vec{v}(x)$

(7) vector $\vec{v}(x)$

(8) vector $\vec{v}(x)$



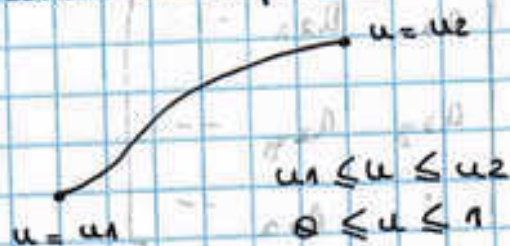
$$\vec{v}(x) = \begin{bmatrix} v_x \\ v_y \end{bmatrix} \quad \vec{v}(x) = \begin{bmatrix} v_x \\ v_y \end{bmatrix}$$

5. The vector field is defined by

6. The vector field is defined by

Modeling of Curves

- If we have any curve general 2D curve, we can express this curve in a parameter form:

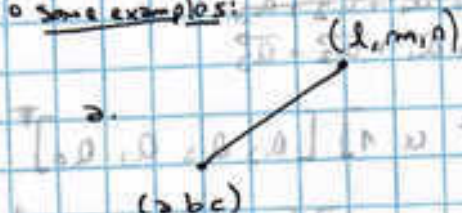


$$\left. \begin{aligned} x &= X(u) \\ y &= Y(u) \\ z &= Z(u) \end{aligned} \right\} \text{ (cubic expression)}$$

- or -

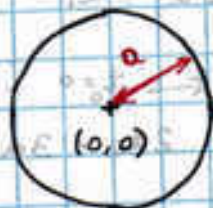
$$f(x, y, z) = 0$$

o some examples:



$$\begin{aligned} x &= a + lu \\ y &= b + mu \\ z &= c + nu \end{aligned}$$

b.



$$\begin{aligned} x &= a \cos \theta \\ y &= a \sin \theta \\ x^2 + y^2 &= a^2 \end{aligned}$$

- Parametric Cubic Curves (PC curves)



$$f(u) = \vec{a}_0 + \vec{a}_1 u + \vec{a}_2 u^2 + \vec{a}_3 u^3$$

where $0 \leq u \leq 1$ and $\vec{a}_0, \dots, \vec{a}_3$ are constant vectors

- or -

$$x(u) = a_{0x} + a_{1x}u + a_{2x}u^2 + a_{3x}u^3$$

$$y(u) = a_{0y} + a_{1y}u + a_{2y}u^2 + a_{3y}u^3$$

$$z(u) = a_{0z} + a_{1z}u + a_{2z}u^2 + a_{3z}u^3$$

$$\vec{f} = [u^3 \ u^2 \ u \ 1] [\vec{a}_3 \ \vec{a}_2 \ \vec{a}_1 \ \vec{a}_0]^T$$

$$\vec{f} = \underset{\text{matrix}}{U} \cdot \underset{\text{matrix}}{A}$$

3 components each

$$\begin{bmatrix} a_3 & a_2 & a_1 & a_0 \end{bmatrix} = 12 \text{ components}$$

4 vectors

$$\begin{bmatrix} a_{3x} & a_{2x} & \dots \\ a_{3y} & a_{2y} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

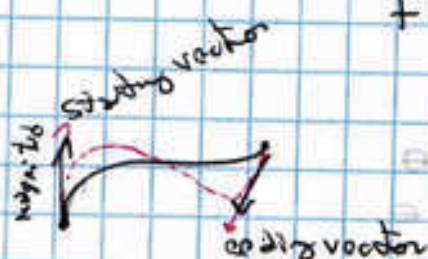
$$\vec{f} = [u^3 \ u^2 \ u \ 1] [\vec{a}_3 \ \vec{a}_2 \ \vec{a}_1 \ \vec{a}_0]^T$$

o. start point: $u=0 \Rightarrow f(0) = \vec{a}_0 + \vec{a}_1 + \vec{a}_2 + \vec{a}_3$
 $f(1) = \vec{a}_0 + \vec{a}_1 + \vec{a}_2 + \vec{a}_3$

Tangent Vectors: $f(u) = [u^3 \ u^2 \ u \ 1] [a_3 \ a_2 \ a_1 \ a_0]^T$

$$f'(u) = [3u^2 \ 2u \ 1 \ 0] [a_3 \ a_2 \ a_1 \ a_0]^T$$

$$= 3u^2 a_3 + 2u a_2 + a_1$$



so $f'(0) = a_1 \leftarrow t_0 = 0$ (starting vector)

$f'(1) = a_1 + 2a_2 + 3a_3 \leftarrow t_1 = 1$ (ending)

$$a_0 = f(0)$$

$$a_1 = t_0$$

$$a_2 = -3 f(0) + 3 f(1) - 2 f'(0) - f'(1)$$

$$a_3 = 2 f(0) - 2 f(1) + f'(0) + f'(1)$$

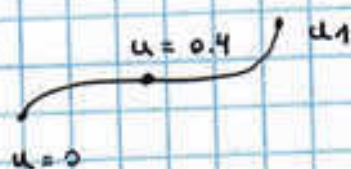
$$f = U A \Leftrightarrow \text{Algebraic Form}$$

$$\begin{aligned} f(u) &= a_3 u^3 + a_2 u^2 + a_1 u + a_0 \\ &= (2u^3 - 3u^2 + 1) \cdot f(0) + (-2u^3 + 3u^2) f(1) + \\ &\quad (u^3 - 2u^2 + u) \cdot f'(0) + (u^3 - u^2) \cdot f'(1) \end{aligned}$$

$$f(u) = [F_1(u) \ F_2(u) \ F_3(u) \ F_4(u)] \begin{bmatrix} f_0 \\ f_1 \\ t_0 \\ t_1 \end{bmatrix}$$

Blending functions

- A by the length of the curve, at any specific point, we need to define the blending functions for this point to follow vectors f_0, f_1, t_0, t_1 as we move along the curve. So the blending function will change



$$f(u) = [F_1(u) \ F_2(u) \ F_3(u) \ F_4(u)] \cdot B$$

$$B = [f_0 \ f_1 \ t_0 \ t_1]^T$$

Geometric Matrix

$$f = FB$$

standard Geometric Matrix

$$F = \begin{bmatrix} 2u^3 - 3u^2 + 1 \\ -2u^3 + 3u^2 \\ u^3 - 2u^2 + u \\ u^3 - u^2 \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} u^3 & u^2 & u & 1 \end{bmatrix}}_U \underbrace{\begin{bmatrix} 2 & -3 & 1 & 0 \\ -3 & 3 & -2 & -1 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_M$$

coefficients

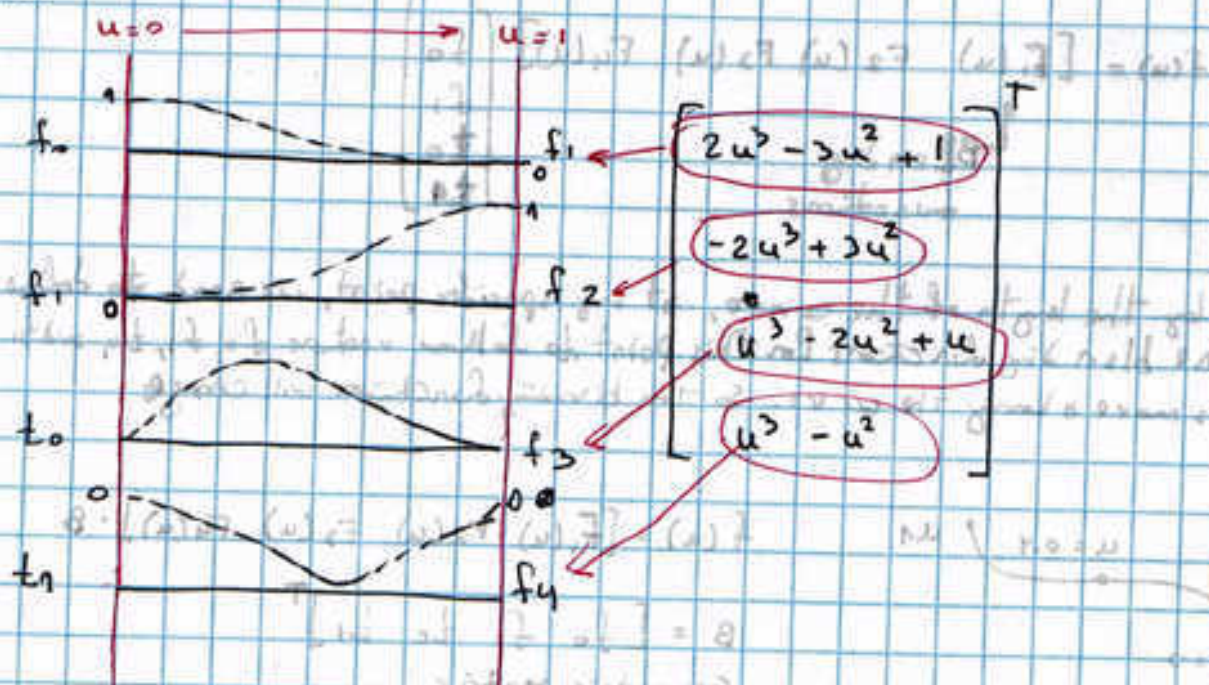
$$= UM$$

$$\left. \begin{aligned} f &= UA \\ &= FB \\ &= UM B \end{aligned} \right\} A = \underline{M} B^T$$

$$B = [f_0 \ f_1 \ t_0 \ t_1]^T$$

$$= [f_0 \ f_1 \ R_1 \hat{t}_0 \ R_2 \hat{t}_1]^T$$

These functions change as we go from $u=0$ to $u=1$



$$f(u) = F_1 f_0 + F_2 f_1 + F_3 f_2 + F_4 f_3$$

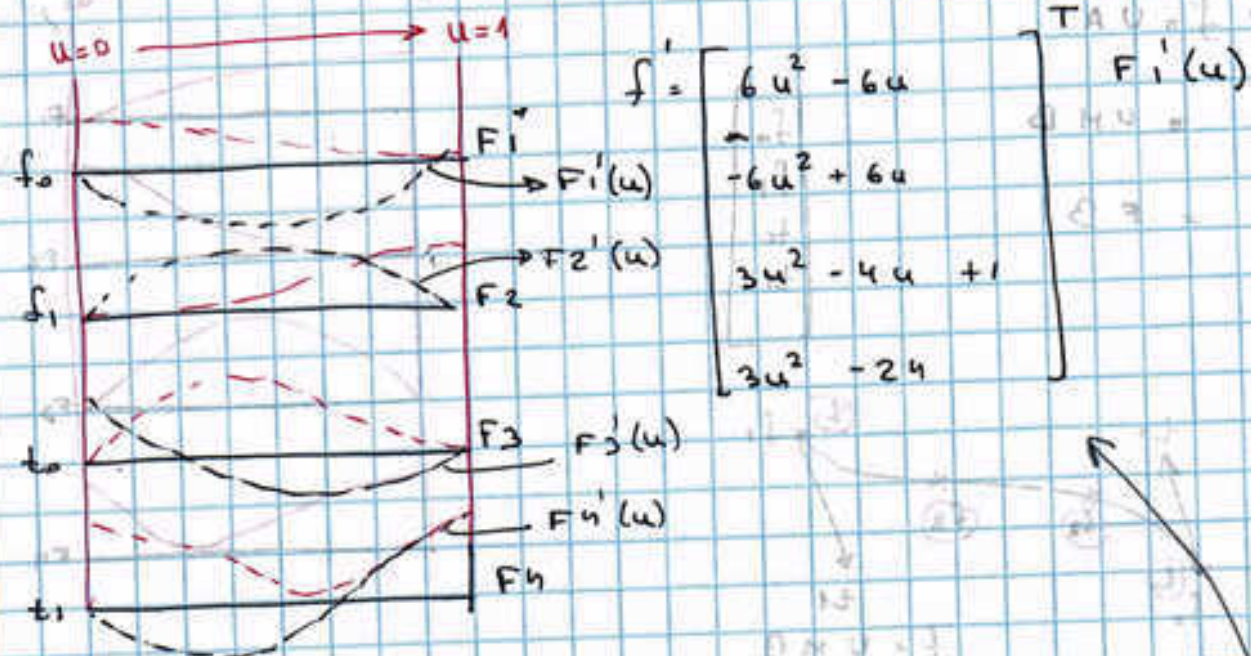
$$f'(u) = F_1' f_0 + F_2' f_1 + F_3' f_2 + F_4' f_3$$

$$= F' B$$

$$f = U \begin{bmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} B$$

M

$$F' = \begin{bmatrix} 6u^2 - 6u \\ -6u^2 + 6u \\ 3u^2 - 4u + 1 \\ 3u^2 - 2u \end{bmatrix}^T$$



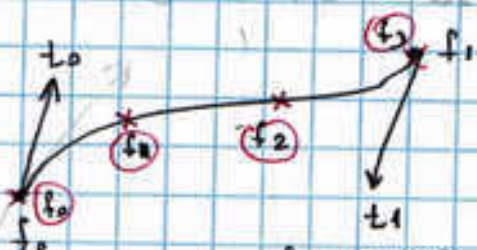
$f'(u) = F' B = U M' B$ where M' are the coefficients of this matrix

$$M' = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 6 & -6 & 3 & 3 \\ -6 & +6 & -4 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$f''(u) = F'' B = U M'' B$$

$$\begin{aligned} \bullet \quad \mathbf{f} &= \mathbf{U} \mathbf{A} \mathbf{T} \\ &= \mathbf{U} \mathbf{M} \mathbf{B} \\ &= \mathbf{F} \mathbf{B} \end{aligned}$$

$$\begin{bmatrix} f_0 \\ f_1 \\ t_0 \\ t_1 \end{bmatrix}$$



$$\mathbf{f} = \mathbf{U} \mathbf{M} \mathbf{B}$$

$$u = u_0 \Rightarrow \mathbf{f}_0 = \mathbf{U}_0 \mathbf{M} \mathbf{B} = \begin{bmatrix} u_0^3 & u_0^2 & u_0 & 1 \end{bmatrix} \mathbf{M} \mathbf{B}$$

$$u = u_1 \Rightarrow \mathbf{f}_1 = \mathbf{U}_1 \mathbf{M} \mathbf{B} = \begin{bmatrix} u_1^3 & u_1^2 & u_1 & 1 \end{bmatrix} \mathbf{M} \mathbf{B}$$

$$u = u_2 \Rightarrow \mathbf{f}_2 = \mathbf{U}_2 \mathbf{M} \mathbf{B} = \begin{bmatrix} u_2^3 & u_2^2 & u_2 & 1 \end{bmatrix} \mathbf{M} \mathbf{B}$$

$$u = u_3 \Rightarrow \mathbf{f}_3 = \mathbf{U}_3 \mathbf{M} \mathbf{B} = \begin{bmatrix} u_3^3 & u_3^2 & u_3 & 1 \end{bmatrix} \mathbf{M} \mathbf{B}$$

$$\mathbf{P} = \begin{bmatrix} \mathbf{f}_0 \\ \mathbf{f}_1 \\ \mathbf{f}_2 \\ \mathbf{f}_3 \end{bmatrix} = \begin{bmatrix} u_0^3 & u_0^2 & u_0 & 1 \\ u_1^3 & u_1^2 & u_1 & 1 \\ u_2^3 & u_2^2 & u_2 & 1 \\ u_3^3 & u_3^2 & u_3 & 1 \end{bmatrix} \mathbf{M} \mathbf{B}$$

I want to find out B

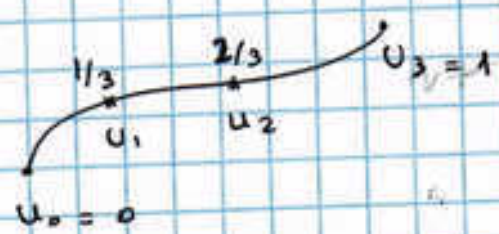
$$\mathbf{B} = \mathbf{M}^{-1} \mathbf{U}^{-1} \mathbf{P}$$

$$= \mathbf{M}^{-1} \begin{bmatrix} u_0 & u_1 & u_2 & u_3 \end{bmatrix}^{\mathbf{T}-1} \mathbf{P}$$

$$= \mathbf{K} \mathbf{P}$$

$$\begin{bmatrix} \mathbf{f}_0 \\ \mathbf{f}_1 \\ \mathbf{f}_2 \\ \mathbf{f}_3 \end{bmatrix} \begin{bmatrix} \mathbf{f}_1 & \mathbf{f}_2 & \mathbf{f}_3 \end{bmatrix}$$

f1 given
f2 given
f3

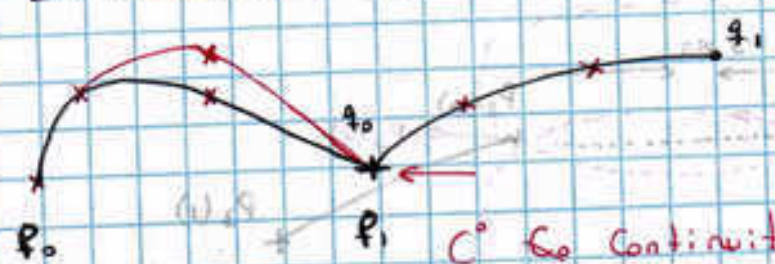


$$k = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ -1/2 & 1 & -1/2 & 1 \\ -1 & 1/2 & -1 & 1/2 \end{bmatrix} \quad B = KP$$

$$K = M^{-1}C$$

$$C = M^T [u_0 \ u_1 \ u_2 \ u_3]$$

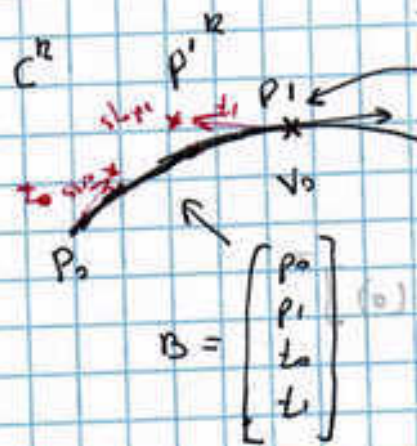
Composite Curves



C^0 Continuity - Common End-Point

C^1 Continuity - Common Tangent

C^2 Continuity - Common Curvature



$$B = \begin{bmatrix} p_0 \\ p_1 \\ t_0 \\ t_1 \end{bmatrix}$$

if they have the same continuity the tangent line would be the same at this point

What kind of changes would affect the continuity

P' 2nd degree

P'' 1st degree

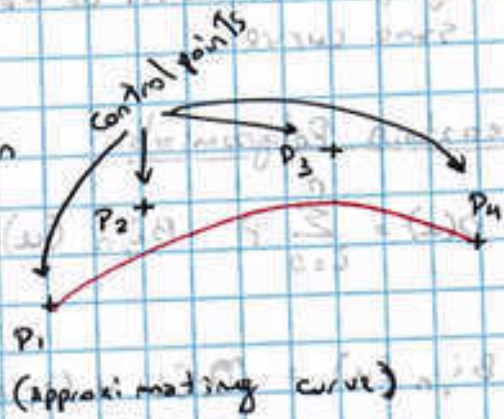
P''' constant

P^{IV} 0

BEZIER Curves

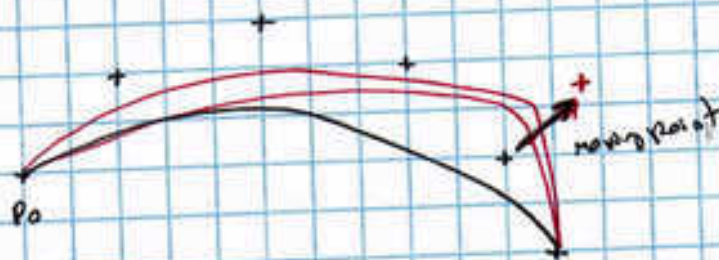


approximation of these points \Rightarrow

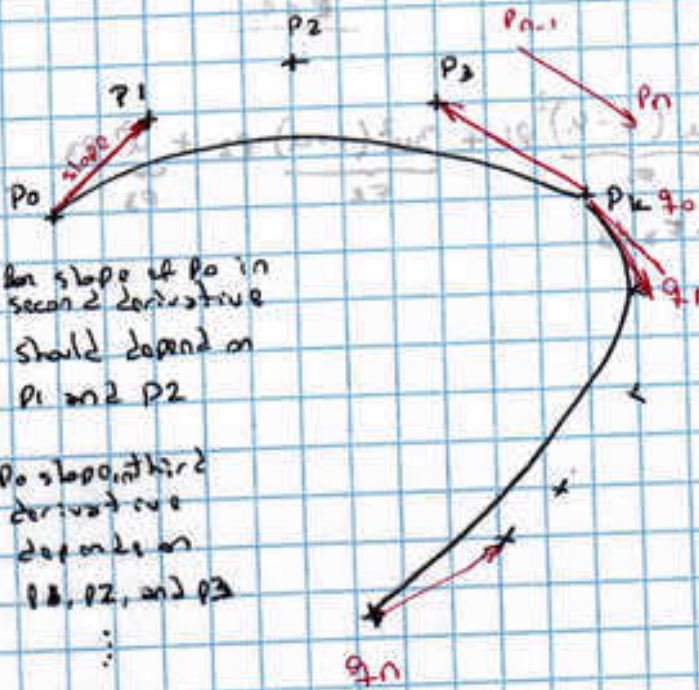


• Basic properties of curves:

• Curves should start and end at the first and last point $P_0 \rightarrow P_n$



• slope at P_0 should be $\overrightarrow{P_0 P_1}$ and slope at P_n is given by $\overrightarrow{P_n P_{n-1}}$



• slope at P_0 in second derivative should depend on P_1 and P_2

• slope in third derivative depends on $P_0, P_1, P_2, \text{ and } P_3$

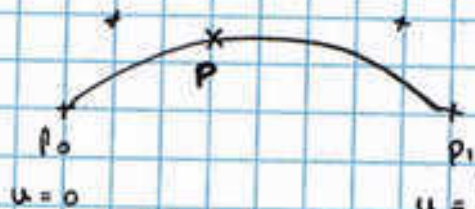
• R^{th} derivative at end points should depend on next R -points

170 - Symmetric w.r.t depends on u and $(1-u)$ which means that going from P_0 to P_n or from P_n to P_0 would produce the same curve.

Bernstein Polynomials

$$P(u) = \sum_{i=0}^n P_i \cdot B_{i,n}(u)$$

$$B_{i,n}(u) = \underbrace{n \cdot C_i \cdot u^i \cdot (1-u)^{n-i}}_{\text{Bernstein expression}} \quad \text{where } 0 \leq u \leq 1$$



3rd Degree BEZIER CURVES

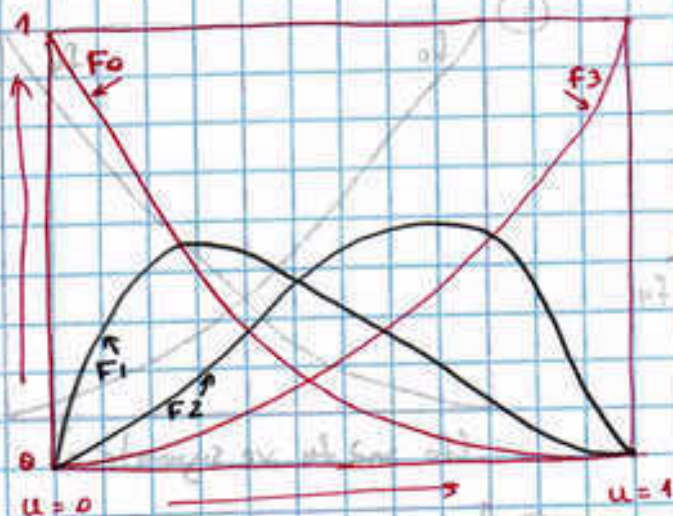
$n=3$ Points: 0, 1, 2, 3

$$P(u) = \sum P_i B_{i,n}(u)$$

$$\begin{aligned} &= P_0 \underbrace{(1-u)^3}_{F_0} + \underbrace{3u(1-u)^2}_{F_1} P_1 + \underbrace{3u^2(1-u)}_{F_2} P_2 + \underbrace{u^3}_{F_3} P_3 \\ &= F_0 P_0 + F_1 P_1 + F_2 P_2 + F_3 P_3 \end{aligned}$$

$$\begin{matrix} n=3 \\ n=3 \\ i=1 \\ \vdots \end{matrix} \quad \boxed{n C_i B_{i,n}(1-u)^{n-i}}$$

Hand-drawn diagram of a 3D curve segment defined by four control points P0, P1, P2, and P3. The curve starts at P0, goes up and over P1, then down and over P2, and ends at P3.



All these Bézier functions F_0, \dots, F_3 are in symmetry with u as before u and $(1-u)$.

p_0, p_1, p_2, p_3 } same curves
 p_3, p_2, p_1, p_0

• $n=2$ with 3 control points

$$P(u) = (1-u)^2 p_0 + 2u(1-u) p_1 + u^2 p_2$$

• Another example

$$P(u) = \sum p_i f_i(u) \quad n=3$$

$$f_i(u) = B_{i,n}(u) = n C_i u^i (1-u)^{n-i}$$

$$p(u) = 3C_0 (1-u)^3 p_0 + 3C_1 u(1-u)^2 p_1 + 3C_2 u^2(1-u) p_2 + 3C_3 u^3 p_3$$

