

Note del corso di Calcolabilità e Linguaggi Formali - Lezione 12

Alberto Carraro
14 dicembre 2016

IIS Bruno-Franchetti, Mestre (VE) <http://www.dsi.unive.it/~acarraro>

1 Nondeterministic tree automata

Definition 1. A nondeterministic parity tree automaton (NPTA) for Σ -labelled full binary trees is a tuple $A = (Q, \Sigma, q_I, \delta, \Omega)$ where Q is a finite set of states, $q_I \in Q$ is the initial state, $\delta : Q \times \Sigma \rightarrow \mathcal{P}(Q^2)$ is the transition function and $\Omega : Q \rightarrow \{1, \dots, k\}$ is the priority function.

A run-tree of an automaton A over a tree t is a map $\rho : \{0, 1\}^* \rightarrow Q$ such that

1. $\rho(\varepsilon) = q_I$ and
2. for all $u \in \{0, 1\}^*$ we have $(\rho(u0), \rho(u1)) \in \delta(\rho(u), t(u))$.

A run-tree ρ of A over t is *accepting* iff in every path π of ρ the least priority that occurs infinitely often is even. An automaton A *accepts* a tree t just if there exists an accepting run-tree of A over t .

Definition 2. Given an NPTA $A = (Q, \Sigma, q_I, \delta, \Omega)$ and a tree t the acceptance parity game $\mathcal{G}_{A,t} = (V_V, V_R, E, v_I, \Omega')$ where

- $V_V = \{0, 1\}^* \times Q$
- $V_R = \{0, 1\}^* \times Q^2$
- $v_I = (\varepsilon, q_I)$
- $E \subseteq (V_V \times V_R) \cup (V_R \times V_V)$ is the smallest relation such that
 - if $(v, q) \in V_V$ and $(q_0, q_1) \in \delta(q, a)$ and $t(v) = a$, then $((v, q), (v, (q_0, q_1))) \in E$
 - if $(v, (q_0, q_1)) \in V_R$, then $((v, (q_0, q_1)), (v0, q_0)) \in E$ and $((v, (q_0, q_1)), (v1, q_1)) \in E$
- $\Omega'(v, q) = \Omega(q)$ and $\Omega'(v, (q_0, q_1)) = \max\{\Omega(q_0), \Omega(q_1)\}$

The acceptance parity game of Definition 2 can be read as follows:

- Verifier can exploit the nondeterminism of A by choosing the run-tree
- Refuter chooses the path

Their combined action is headed towards checking that there exists (\exists) a run-tree all (\forall) of whose paths are accepting. Again Verifier represents (\exists) and Refuter represents (\forall).

Lemma 1. Verifier has a winning strategy in $\mathcal{G}_{A,t}$ from vertex v_0 iff $t \in L(A)$.

Proof. (\Rightarrow) Suppose Verifier has a winning strategy σ in $\mathcal{G}_{A,t}$ from v_0 . Define the map $\rho : \{0,1\}^* \rightarrow Q$ inductively as

- $\rho(\varepsilon) = q_I$;
- $\rho(v0) = q_0$ if $\rho(v) = q$ and $\sigma(v, q) = (v, (q_0, q_1))$;
- $\rho(v1) = q_1$ if $\rho(v) = q$ and $\sigma(v, q) = (v, (q_0, q_1))$.

Clearly ρ is a run-tree of A over t . A path π of ρ has vertices

$\dots, (v, q), (v, (q_0, q_1)), (v0, q_0), (v0, (q'_0, q'_1)), (v01, q'_1), \dots$

and therefore has priorities

$\dots, \Omega(q), \max\{\Omega(q_0), \Omega(q_1)\}, \Omega(q_0), \max\{\Omega(q'_0), \Omega(q'_1)\}, \Omega(q'_1), \dots$

The least priority occurring infinitely often is even but since each priority appearing at an even position is \geq than its immediate successor, the subsequence obtained by removing all priorities at even positions is such that the least priority occurring infinitely often is still even. Such a subsequence witnesses an accepting path of ρ and all paths of ρ are obtained this way. Hence ρ is accepting.

(\Leftarrow) Suppose ρ is an accepting run-tree for A over t . Then define the map $\sigma : (V_V \times V_R^*)V_V \rightarrow V_R$ as

- $\sigma(\alpha(v, q)) = (v, (q_0, q_1))$ iff $\rho(v0) = q_0$ and $\rho(v1) = q_1$.

Clearly σ is a strategy for Verifier in $\mathcal{G}_{A,t}$ from v_0 . A play π respecting σ has vertices

$\dots, (v, q), (v, (q_0, q_1)), (v0, q_0), (v0, (q'_0, q'_1)), (v01, q'_1), \dots$

and therefore has priorities

$\dots, \Omega(q), \max\{\Omega(q_0), \Omega(q_1)\}, \Omega(q_0), \max\{\Omega(q'_0), \Omega(q'_1)\}, \Omega(q'_1), \dots$

The subsequence obtained by removing all priorities at even positions is the run-tree ρ and the least priority occurring infinitely often in it is even. Since each priority appearing at an even position is \geq than its immediate successor, the least priority occurring infinitely often in π is still even. Such a play is winning for Verifier.