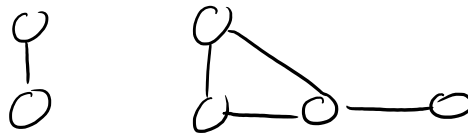


# 2019-04-18 Introduction to Graphs

Thursday, April 18, 2019 8:59 AM

## Graph Preliminaries

- Graphs are the "capstone" data structure in that it employs many of the data structures discussed in class. Depending on the problem, a graph might employ:
  - Hash tables
  - Priority queues
  - Vectors
  - Linked Lists
  - Queues
  - Stacks
- Graphs are trees that allow for multiple paths between two nodes
  - In math and more formal computer science, graph nodes are often called vertices
- Unlike trees in which all nodes are reachable, graphs may contain disconnected segments (not every node is reachable from every other node)
- Example:

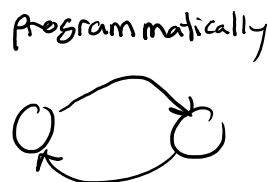
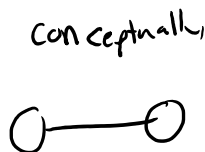


- All trees are graphs, but not all graphs are trees
- Graph edges can be unidirectional (one way) or bidirectional

unidirectional  
→

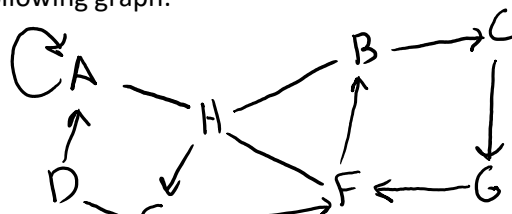
bidirectional  
↔

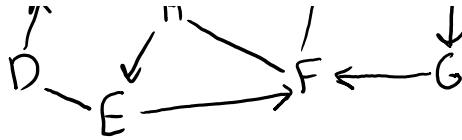
- In computer science, all edges are unidirectional? Why?
  - This is because we represent edges with pointers. Pointers can only point to one thing!
  - Thus, we need two pointers to represent a bidirectional edge.



## Programmatically representing a graph

- Consider the following graph:





## Vector-based representation (Adjacency matrix)

- Adjacency matrix doesn't require any special custom classes
- Matrix typically is in row-major order (we read across the matrix)
- In the matrix, 0 represents not connected, 1+ represents connected

	A	B	C	D	E	F	G	H
A	1	0	0	0	0	0	0	1
B	0	0	1	0	0	0	0	1
C	0	0	0	0	0	0	1	0
D	1	0	0	0	1	0	0	0
E	0	0	0	1	0	1	0	0
F	0	1	0	0	0	0	0	1
G	0	0	0	0	0	1	0	0
H	1	1	0	0	1	1	0	0

- In an adjacency matrix, there is a quadratic relationship between the number of nodes and the number of cells.
- In many circumstances, graphs are "sparse" meaning that the number of possible edges that a node may far exceeds the actual number of edges.
  - Implication: we're wasting a lot of space
- When graphs are sparse and large, it is often more memory efficient to use an edge list representation

## Pointer-based (pseudo LL) Representation: Edge List

- (Adam's approach): Use a hashtable to store each vertex. Each item in the hash table, has a hash table of pointers
  - In C++: `unordered_map<string, unordered_map<string, int>>`

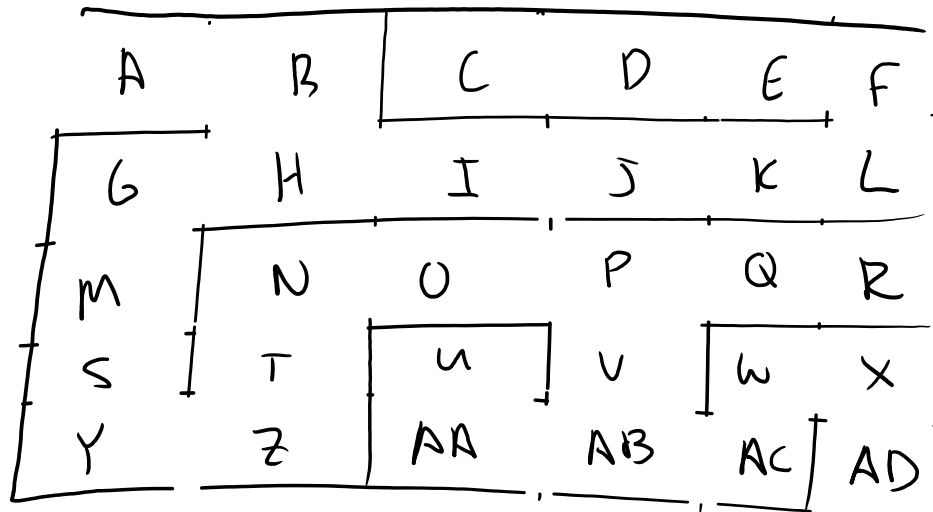
Key (string)	Value (HT<string,int>)
A	{A:1}, {H:1}
B	{C:1}, {H:1}
C	{G:1}
D	{A:1}, {E:1}
E	{D:1}, {F:1}
F	{B:1}, {H:1}
G	{F:1}
H	{A:1}, {B:1}, {E:1}, {F:1}

- Generally, as long as the graph is at least 50% sparse, an edge list representation is the more memory efficient approach

## Searching a Graph

- There are two strategies for searching a graph:
  - Depth first - Will touch nodes farther away before touching all nodes near start of search
  - Breadth first - "dropping a rock in a pond" - We start with our immediate neighbors, then examine their neighbors, etc.

### Example search on a maze



### Example Adjacency Matrix

	A	B	C	D	E	F	G	...
A	1	1	0	0	0	0	0	0

### Example Edge List

Key	Value
A	{"Self", A}, {"Right", B}
B	{"Left", A}, {"Self", B}, {"Below", H}

### Depth-First Search

Function search(MazeSpace):

If MazeSpace is null: return

If MazeSpace seen before: return

If MazeSpace is end:

Done

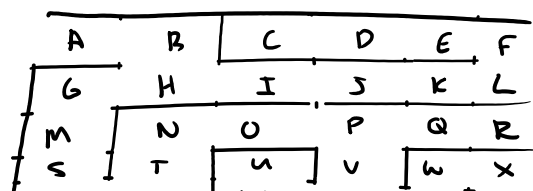
Else:

Search(MazeSpace->Left)

Search(MazeSpace->Right)

Search(MazeSpace->Below)

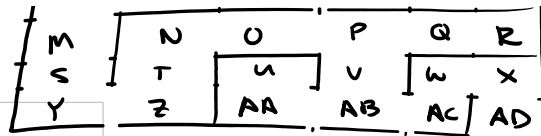
Search(MazeSpace->Up)



### Visit Order

## Visit Order

- |   |  |
|---|--|
| <ul style="list-style-type: none"> <li>• NULL (A-&gt;L)</li> <li>• B (A-&gt;R)</li> <li>• A (B-&gt;L) (seen, return)</li> <li>• NULL (B-&gt;R)</li> <li>• H (B-&gt;B)</li> <li>• G (H-&gt;L)</li> <li>• NULL (G-&gt;L)</li> <li>• H (G-&gt;R) (seen, return)</li> <li>• M (G-&gt;B)</li> <li>• NULL (M-&gt;L)</li> <li>• NULL (M-&gt;R)</li> <li>• S (M-&gt;B)</li> <li>• (ignoring all nulls)</li> </ul> | <ul style="list-style-type: none"> <li>• Y (S-&gt;B)</li> <li>• Z (Y-&gt;R)</li> <li>• Y (Z-&gt;L) (seen)</li> <li>• T (Z-&gt;U)</li> <li>• Z (T-&gt;B) (seen)</li> <li>• (ignore previously seen)</li> <li>• N (T-&gt;U)</li> <li>• O (N-&gt;R)</li> <li>• P (O-&gt;R)</li> <li>• Q (P-&gt;R)</li> <li>• R (Q-&gt;R)</li> <li>• V (P-&gt;B)</li> <li>• AB (V-&gt;B)</li> <li>• AA (AB-&gt;B)</li> <li>• U (AA-&gt;A)</li> <li>• AC, W, X, AD</li> </ul> |
|---|--|



## Breadth-First Search

Function BFS(MazeSpace start):

Queue<MazeSpace> to\_visit

To\_visit.push(start)

While to\_visit is not empty:

Front = to\_visit.pop()

If front is end: done

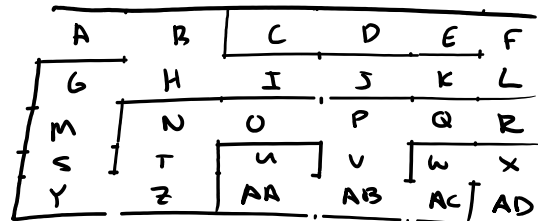
If front not seen and front not null:

To\_visit.push(front->Left);

To\_visit.push(front->Right);

To\_visit.push(front->Down);

To\_visit.push(front->Up);



~~A, B, A, H, G, I, B, H, M, A, S, S, G, I, K, Y, M~~

Visit order

- A, B, H, G, I, M, J, S,