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## **Exploring the Critical Radius Between mini-Neptunes and super-Earths using Kepler**

We propose to combine a Bayesian reanalysis of short-period Kepler exoplanet transits with standard models of tidal theory in order to identify the planetary radius that separates rocky and gaseous exoplanets. We exploit the conventional assumption that gaseous planets dissipate orders of magnitude less tidal energy than rocky planets, leading to the expectation that the latter will be on circular orbits out to larger orbital periods. Preliminary dynamical simulations show that short period (2-10 days) gaseous bodies should be found with eccentricities near their primordial value, but rocky bodies are preferentially found at low eccentricity due to tidal circularization. Thus, a study of the eccentricities of short-period planets can constrain the planetary radius of this transition. The identification of the boundary between rocky and gaseous bodies, independently from mass measurements, is vital for understanding the planetary conditions needed to support life.

A lower limit to the orbital eccentricity can be calculated by comparing the difference between the modeled transit duration and the transit duration that would be seen if the orbit were circular. To assess this difference, we analyze Kepler lightcurves using a purely geometric model that includes no assumptions about the orbital dynamics. We cast our measurement of minimum eccentricity in terms of two model parameters, whose posterior distributions we explore using Markov Chain Monte Carlo methods, and two physical parameters (e.g. stellar mass and radius) that must be estimated from other means. We have run a suite of simulations using a grid in transit depth, stellar brightness (lightcurve signal-to-noise), and the number of transits included in the model to gauge our sensitivity to these model parameters. We validated this method on the confirmed exoplanet system Kepler 62-b, and successfully recovered the published results and expected parameter uncertainties. We propose here to extend this analysis to an ensemble of 1100+ KOIs that have been selected based upon their Kepler-reported periods and planetary radius. This reanalysis will enable the first measurements of the boundary between gaseous and rocky exoplanets, as well as of tidal dissipation as a function of planetary radius.

This project spans the fields of high-performance computation, statistical modeling of experimental data, and celestial mechanics, which will make it a valuable contribution to the field of exoplanet studies. We will release code and data using open-source collaboration tools, and help to guide the adoption of reproducible research standards by releasing interactive analysis packages as part of our publication process.

## I. Introduction

The discovery of an inhabited planet is a primary goal of exoplanetary science and NASA’s exobiology program. The *Kepler* spacecraft has now found several small candidates in potentially habitable orbits, (e.g. Kepler-62 f; [Borucki et al., 2013](#)), and radial velocity surveys are also detecting apparently low-mass planets in habitable zones (HZs), e.g. Gl 667C c ([Anglada-Escudé et al., 2012](#)). While the location of an orbit with respect to the HZ is an important first cut on habitability, the composition of the planet is at least as important. Life as we understand it cannot survive on gaseous planets, yet we do not know the mass and/or radius that separates gaseous from terrestrial planets. In particular, the identification of the critical radius between the two,  $R_{crit}$ , would provide crucial information for *Kepler*’s mission to discover a terrestrial planet in the HZ of a G dwarf.

The primary goal of this proposal is to determine this critical planetary radius between rocky and gaseous bodies using *Kepler* data. We will exploit the expected discrepancy in tidal dissipation of gaseous and rocky bodies to determine the largest orbital periods at which the two classes of bodies circularize. We will use the so-called transit duration deviation, the quotient of the observed transit duration and that of a circular orbit, to estimate the minimum eccentricity permitted from transit data. We will also include the effects of additional planetary companions and atmospheric mass loss, as they also influence the evolution of eccentricity. In order to successfully constrain these theoretical results from *Kepler* data, we require robust characterization of each candidate, and hence we will perform state-of-the-art modeling of all relevant *Kepler* transits. To optimize our sensitivity to these effects, we will examine only those systems with short periods (less than 15 days) and having planetary radii near the anticipated boundary (less than  $10 R_{\oplus}$ ). Our proposed research offers the best route to determine which *Kepler* candidates are rocky, independent of mass measurements. In summary:

**We propose to use the observed minimum eccentricity and the theory of tidal dynamics to determine the critical radius between rocky and gaseous exoplanets  $R_{crit}$ , to constrain their tidal quality factors ( $Q_r$  and  $Q_g$ , respectively), and to understand the efficiency of hydrogen loss for close-in, small, gaseous exoplanets, using *Kepler* lightcurves.**

## II. Objectives and Significance

### TIDAL THEORY

Tidal dissipation in celestial bodies is extremely challenging to measure ([Goldreich & Soter, 1966](#); [Hut, 1981](#); [Aksnes & Franklin, 2001](#); [Jackson et al., 2008, 2009](#); [Lainey et al., 2012](#)) due to the dearth of known worlds in highly dissipative configurations, the long timescales involved (Gyrs), and the intractability of derivations based on first principles. However, the *Kepler* space telescope has now discovered thousands of exoplanet candidates ([Batalha et al., 2013](#)), of which about 1000 orbit FGK stars with orbital periods less than 15 days, and that may experience significant tidal evolution ([Rasio et al., 1996](#); [Jackson et al., 2008](#); [Matsumura et al., 2010](#)).

In the equilibrium tide model ([Darwin, 1880](#); [MacDonald, 1964](#); [Goldreich & Soter, 1966](#); [Hut, 1981](#); [Ferraz-Mello et al., 2008](#); [Leconte et al., 2010](#)), the figure of a tidally deformed

body is a superposition of surface waves with different frequencies. The sum of these waves corresponds to the tidally-deformed figure, and allows for the relatively simple derivation of the time rates of change of orbital and spin properties. While two qualitatively different models have emerged, the constant-phase-lag (CPL) and constant-time-lag (CTL) models (Greenberg, 2009), both rely on this assumption of superposition, and neither has been rejected observationally. Both models make a critical prediction that we will exploit in this proposal: Tidal dissipation in rocky planets is orders of magnitude larger than in gaseous bodies. This disparity implies that rocky planets will evolve much more rapidly than gaseous ones and be tidally circularized on larger orbits. The key is to recognize that gaseous bodies will tidally circularize more slowly than rocky planets, and may still retain non-zero eccentricities after Gyrs. As we show below, the canonical values for  $Q_g$  of  $10^6$  and  $Q_r$  of 100 should be measurable, if the transit data and stellar properties can be known to sufficient accuracy. While transit data cannot measure the eccentricity (Barnes, 2007; Burke, 2008; Ford et al., 2008), they *can* provide a lower limit.

### THE TRANSIT DURATION DEVIATION (TDD)

The transit duration is the time required for a planet to traverse the disk of its parent star, and to first order is:

$$T = \frac{2\sqrt{R_*^2 - b^2}}{v}, \quad (1)$$

where  $R_*$  is the radius of the star,  $b$  is the minimum impact parameter, and  $v$  is the instantaneous velocity of the planet. On a circular orbit,  $v$  is constant ( $v_c$ ) and we expect

$$T_c = \frac{\sqrt{R_*^2 - b^2}}{\pi a} P, \quad (2)$$

where  $P$  is the orbital period. However, for an eccentric orbit the azimuthal velocity as a function of longitude, and is given by

$$v_\theta = \frac{2\pi a}{P} \frac{1 + e \cos \theta}{\sqrt{1 - e^2}}, \quad (3)$$

where  $e$  is the eccentricity and  $\theta$  is the true anomaly, the angle between the longitude of pericenter and the actual position of the planet in its orbit. From transit data alone, the value of  $\theta$  is unknown, and hence so is  $e$ .

However, we can exploit the difference between  $T$  and  $T_c$  to obtain a minimum value of the eccentricity (Barnes, 2007), and in some cases provide tighter constraints on the eccentricity itself, although this is more resolvable for Jupiter-sized planets with longer ingress/egress times than the terrestrial-sized planets studied here (Dawson & Johnson, 2012). The situation is somewhat complicated because  $T$  can be larger or smaller than  $T_c$  depending on  $\theta$ . If the planet is close to apoapse,  $T > T_c$ , while at periapse  $T < T_c$ . To derive  $e_{min}$  we must assume that  $\theta = 0$  or  $\pi$ . While the velocity could be larger at some other position in the orbit, we know that the maximum deviation from the circular velocity is at least as large as the measured velocity, and hence  $e$  must be at least a certain value. If we define the transit duration deviation,  $\Delta$ , as

$$\Delta = \frac{T}{T_c} = \frac{v_c}{v_\theta} = \frac{1 + e \cos \theta}{\sqrt{1 - e^2}}. \quad (4)$$

If we assume we observe the planet at either apocenter or pericenter then we find

$$e_{min} = \left| \frac{\Delta^2 - 1}{\Delta^2 + 1} \right| \quad (5)$$

is the minimum eccentricity permitted by the transit data. The  $e_{min}$  signal is effectively a measure of the actual to circular transit duration, or physically, the circular to actual transverse velocity. Note that in the ratio  $T/T_c$ , the minimum impact parameter cancels out (although it is explicitly included in the transit model and will affect other parameters through covariance). This leaves  $e_{min}$  a function of 4 parameters:  $P$ ,  $a$ ,  $v$ , and  $R_*$ . We will use the *Kepler* lightcurves to constrain  $P$  and  $R_*/v$ , meaning that we must determine though other means the semi-major axis and stellar radius. The semi-major axis, and also the reference circular velocity, may be determined through the host star mass, making it critical that we are able to estimate the stellar mass and radius reliably.

As outlined in Ford et al. (2008), transit durations that are *less* than the circular duration may be due to a poorly constrained impact parameter or eccentricity. However, transit durations that are *longer* than circular for  $b = 0$  may only arise due to eccentricity. For long cadence *Kepler* data, the impact parameter is typically the most poorly known of all model parameters, because its primary constraint comes from the ingress/egress durations, which are poorly resolved for small planets at a 30-minute cadence. However, there are now several hundred transits per system that allow us to constrain ingress/egress. Our KOI 701.02 analysis below suggests that the dependence of other model parameters on  $b$  will not compromise the  $e_{min}$  analysis.

The TDD has been used in several studies to constrain the eccentricity distribution. Moorhead et al. (2011) analyzed the first 3 quarters of *Kepler* data and found that the KOIs appeared to be consistent with a mean eccentricity near 0.2. As impact parameters were poorly constrained, they only considered cases in which  $T > T_c(b = 0)$ . They also found that eccentricities appear to be large regardless of orbital period, and that small planets tend to have larger eccentricities. More recent work has failed to determine if the *Kepler* eccentricity distribution is consistent with the radial velocity planets (Plavchan et al., 2012; Kane et al., 2012). These studies were limited by the number of known candidates, as well as the relatively poor characterization of the transits themselves.

### THE BOUNDARY BETWEEN ROCKY AND GASEOUS PLANETS

That transit data provide a minimum eccentricity, while tidal theory damps eccentricity to zero, is crucial for our proposed research. If  $e_{min} > 0$ , then the orbit is not circular. Of course circular orbits could be primordial, but Jackson et al. (2008) and Matsumura et al. (2010) showed that the observed radial-velocity-detected planets in tight orbits could have formed with eccentricities consistent with the more distant planets and were subsequently tidally damped in both the CPL and CTL frameworks. If  $e_{min} > 0$  then tides have not damped the eccentricity, and, if we know the age of the system, then we can estimate the tidal  $Q$  (or in the CTL model, the time lag).

As an example consider the two curves in Fig. 1, produced using the classical tidal theory as described in Barnes et al. (2013). The line shows 10 Gyr of tidal evolution of a  $2 R_\oplus$  planet with a density of  $1 \text{ g/cm}^3$  and tidal  $Q$  of  $10^6$  (i.e. a  $3.8 M_\oplus$  “mini-Neptune”), while the

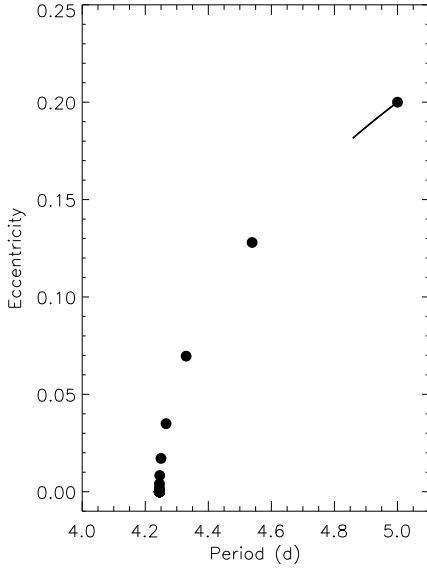


Figure 1: Comparison of the tidal evolution of a  $2 R_{\oplus}$  mini-Neptune (solid line; for 10 Gyr) and a  $2 R_{\oplus}$  super-Earth (circles; in 100 Myr intervals). The mini-Neptune experiences little orbital evolution, but the super-Earth circularizes in about 1 Gyr. This discrepancy is due to the 4 orders of magnitude difference in tidal dissipation between gaseous and rocky planets.

filled circles represent the orbit of a  $2 R_{\oplus}$  planet with a mass of  $10 M_{\oplus}$  and a tidal  $Q$  of 100 (i.e. a “super-Earth”) every 100 Myr. Both objects start with the same initial orbit. The super-Earth circularizes in about 1 Gyr; the mini-Neptune does not evolve significantly, even after 10 Gyr. This discrepancy is evident despite the fact that equilibrium tidal models predict that evolution scales as mass to the  $3/2$  power and radius to the  $5^{th}$  power – instead, the large difference between  $Q_r$  and  $Q_g$  dominates. We therefore hypothesize that the TDD may be able to identify the radius that separates gaseous planets from rocky planets.

To test this possibility, we performed the following test. We created 25,000 synthetic star-planet configurations with initial semi-major axes uniformly in the range  $[0.01, 0.1]$  AU, radii in the range  $[0.5, 10] R_{\oplus}$ , stellar masses in the range  $[0.8, 1.2] M_{\odot}$ , and ages in the range  $[2, 8]$  Gyr. If the planetary radius is less than  $2 R_{\oplus}$ , we assume Earth-like composition and scale the mass as  $(R/R_{\oplus})^{3.68} M_{\oplus}$  (Sotin et al., 2007) and assign a tidal  $Q$  in the range  $[30, 300]$ . If larger than  $2 R_{\oplus}$ , then we assume the density is  $1 \text{ g/cm}^3$ , and a tidal  $Q$  in the range  $[10^6, 10^7]$ . The initial eccentricity is drawn from the currently observed distribution of distant planets ( $a > 0.2 \text{ AU}$ )<sup>1</sup>. We then integrate the CPL tidal model forward for the randomly chosen age and assume we observe the system in that final configuration. In Fig. 2, we show the resulting average eccentricities of these planets as a function of planetary radius,  $R_p$ , and orbital period,  $P$ . The small values of  $e$  at low  $R_p$  and  $P$  shows the effect of the large difference in tidal  $Q$ s. Furthermore, we can see the features that correspond directly to three parameters that are currently very poorly constrained:  $R_{crit}$  via the rapid rise in  $\langle e \rangle$  at  $2 R_{\oplus}$ ;  $Q_g$  via the rapid rise in  $\langle e \rangle$  at 1 day above  $2 R_{\oplus}$ ; and  $Q_r$  via the rise over 4–8 days and below  $2 R_{\oplus}$ . Thus in this simple model, we see three constraints for three unknowns, yielding the possibility that the right observations may provide values for these elusive quantities.

However, as *Kepler* data do not provide eccentricity, we must transform this output into a form that is directly comparable to an observable, i.e.  $e_{min}$ . In order to calculate  $e_{min}$  from these synthetic data, we choose a random value for  $\theta$  and calculate the velocity according

<sup>1</sup>www.exoplanets.org

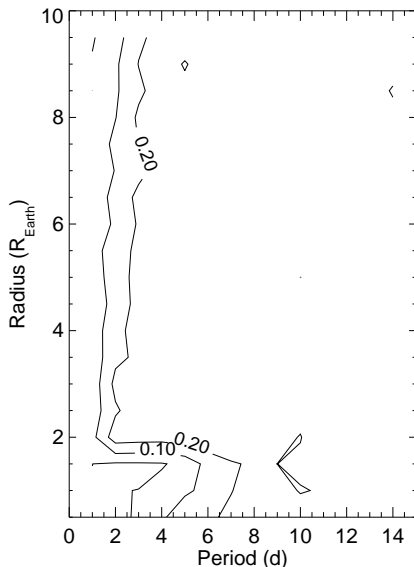


Figure 2: Average final eccentricity of a suite of 25,000 systems of one star and one planet. Planets larger than  $2 R_{\oplus}$  are gaseous, and those smaller are rocky. The bin-sizes are  $0.5 R_{\oplus}$  in radius and  $0.5$  d in period. Gaseous planets retain a residual eccentricity if  $P > 1.5$  d, while rocky planets require  $P > 4$  d. The transition occurs at  $2 R_{\oplus}$ , which in this case is  $R_{crit}$ .

to Eq. 3. We calculate the average minimum eccentricity  $\langle e_{min} \rangle$  for our rocky and gaseous planets in  $0.5$  day orbital period intervals and plot  $\langle e_{min} \rangle$  as a function of orbital period for different radii as solid lines in Fig. 3. For  $R < 2 R_{\oplus}$ ,  $\langle e_{min} \rangle \sim 0$  up to about a 4 day period. However, for larger radii, circular orbits are only guaranteed for periods less than about 2 days. *Despite the order of magnitude ranges for each physical planetary property, the disparity in tidal  $Q$ 's produces a strong signal in  $\langle e_{min} \rangle$  that distinguishes the rocky and gaseous planets.*

This pilot study is encouraging, but its feasibility rests on the precision of the models of the *Kepler* data. Specifically, impact parameters, stellar and planetary radii, orbital period, and stellar mass must be known and their uncertainties well-modeled. The first four properties are measurable from transit data alone, while the fifth must be estimated by other means. The *Kepler* team has provided these data in various publications and websites. The solid squares show the values of  $\langle e_{min} \rangle$  with quantities from the *Kepler* Planet Candidate Data Explorer<sup>2</sup>. Nearly all the observed data are above the predictions. There are two possible explanations for this discrepancy: 1) The theory is wrong, or 2) the reported model parameters are of poor quality. We outline limits of the theory next.

### NON-TIDAL EFFECTS

First, we note that additional companions can pump eccentricity through mutual gravitational interactions, even if tidal damping is ongoing (Mardling & Lin, 2002; Bolmont et al., 2013). Therefore we must be cautious when interpreting Fig. 3, as additional companions, both seen and unseen, can maintain non-zero eccentricities. However, there are limits: Bolmont et al. (2013) showed that planet-planet interactions cannot maintain the eccentricity of the hot super-Earth 55 Cnc e above 0.1. That system is particularly relevant as there are many close-in planets orbiting a typical G dwarf. Therefore, we conclude that eccentricity pumping can be significant but cannot explain the discrepancy between the observed and

<sup>2</sup><http://planetquest.jpl.nasa.gov/kepler>



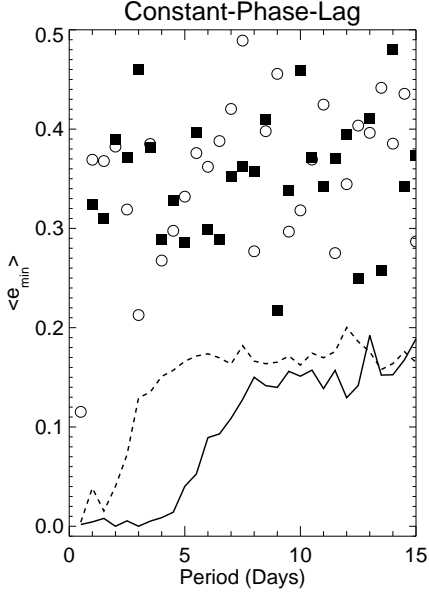


Figure 3: Average minimum eccentricities for transiting exoplanets as a function of period and radius. The solid curve and filled squares represent planets with radii below the selected critical radius of  $2 R_{\oplus}$ , while the dashed curve and open circles are larger planets. The lines are the relationships for the simulated data set, symbols for KOIs. The latter all have values near 0.3–0.4 days regardless of period, whereas model gaseous planets have non-zero eccentricities if the period is larger than 1.5 days, and rocky planets at larger than 4. If tidal dissipation is a function of exoplanet radius, it should be detectable.

simulated systems shown in Fig. 3.

Another possibility is that stellar winds and activity can strip an atmosphere, reducing the mass and radius, and potentially changing the planet from a mini-Neptune to a super-Earth (Jackson et al., 2010; Valencia et al., 2010; Leitzinger et al., 2011; Poppenhaeger et al., 2012). Recently, Owen & Wu (2013) argued that the *Kepler* sample is consistent with hydrodynamic mass loss, and that some low-mass planets could have formed with substantially more mass. Mass loss should decrease the time to circularize the orbit, assuming the radius doesn’t become very large, which is unlikely after about 100 Myr (Lopez et al., 2012). Therefore, mass loss could stall circularization for mini-Neptunes, but not for super-Earths. Although few radial velocity measurements exist, planets with radii less than  $\sim 1.5 R_{\oplus}$  have densities consistent with silicate compositions (Batalha et al., 2011). Thus, mass loss seems unlikely to explain the differences seen for the smallest candidates in the *Kepler* field.

Other effects, such as stellar mass loss or the galactic tide will be negligible, but to properly treat the problem, planetary mass loss and planet-planet perturbations must be considered. On the theoretical side, the path forward to determine  $R_{crit}$ ,  $Q_r$  and  $Q_g$  is clear: We must first model the full range of plausible values for these three parameters to calculate  $\langle e_{min} \rangle(R_p, P)$ ; include the planet-planet interactions of multiple planet systems over the lifetimes of the systems; and incorporate mass loss, including the possibility that a mini-Neptune can become a super-Earth with its associated change in tidal  $Q$ .

In summary, the effects of tidal circularization appear not to be present in publicly available fits to the *Kepler* data, in sharp contradiction with the radial velocity exoplanet sample (Butler et al., 2006). These fits are therefore inadequate to identify  $R_{crit}$  and tidal  $Q$ s, meaning a state-of-the-art statistical re-analysis of *Kepler* photometry is required to determine these fundamental parameters.

### III. Technical Approach and Methodology

We describe below our technical approach to the re-analysis of *Kepler* data, including

simulations to understand how we will be able to constrain system parameters, a validation of this technique using a known exoplanet system, and outline how we will fold these results into tidal theory to determine  $R_{crit}$ ,  $Q_r$  and  $Q_g$ .

We will use the quadratic limb-darkened model of [Mandel & Agol \(2002\)](#) to describe the lightcurves. We emphasize that at its core, the Mandel & Agol model is a purely geometric one that describes an opaque planetary disk occulting a limb-darkened stellar disk. Many applications of this technique use planetary orbital parameters such as semi-major axis and inclination as inputs to the model, along with frequent assumptions of zero eccentricity, *but this need not be the case*. Instead we use a purely geometric implementation of [Mandel & Agol \(2002\)](#) whose only assumption is that the planet has constant transverse velocity during transit. This generalization is especially important for our proposal, as we need to compare our measured transit duration with what would be observed in the zero-eccentricity limit.

The main observable in this model is the time it takes the planet to cross the stellar equator,  $\tau$  (this may also be thought of as a measure of the transverse velocity,  $v = R_*/\tau$ ). This allows us to cast  $e_{min}$  in terms of  $\tau$ , period  $P$ , and the (unknown) ratio of the planet's semi-major axis to stellar radius. The uncertainty in impact parameter will affect our knowledge of the other system parameters through covariance. However, this uncertainty may be marginalized over by examining posterior distributions, which drives us to use Markov-Chain Monte Carlo (MCMC) modeling in our analysis, described below.

#### TRANSIT MODEL

We adopt the quadratic limb-darkened model of [Mandel & Agol \(2002\)](#), which describes transit lightcurves in terms of two (nuisance) limb-darkening coefficients and two (important) system parameters. The first of the system parameters is the planetary radius divided by the stellar radius ( $\zeta \equiv R_p/R_*$ ), which determines the fractional area of the stellar disk that may be occulted by the planet. The second is the instantaneous impact parameter of the planet ( $\beta \equiv b/R_*$ ). This variable is a function of time, due to the objects' relative motion. This function is dependent on the chord that the planet takes across the stellar disk, itself typically estimated using the orbital parameters semi-major axis ( $\alpha \equiv a/R_*$ ) and inclination.

Instead we describe the impact parameter as a function of time using the minimum impact parameter  $\beta_0$  – when the centers of the sources are maximally aligned at center-of-transit time  $t_0$  – and the location of the planet on the transit chord across the stellar disk. The coordinate of the planet as a function of time is represented as  $x(t)/R_* = (t - t_0) * v/R_* = (t - t_0)/\tau$ , where  $v$  is the (unknown) perpendicular velocity, and  $\tau$  is the (fitted) amount of time it takes the planet to traverse a distance equal to the stellar radius assuming no acceleration. This allows us to express geometrically the impact parameter as a function of time:

$$\beta(t) = \sqrt{\beta_0^2 + ((t - t_0)/\tau)^2}, \quad (6)$$

which is then used along with  $\zeta$  to generate a model transit lightcurve. This model yields a 4-parameter fit to each transit:  $t_0, \beta_0^2, \tau, \zeta$ . The system period  $P$  is determined using multiple ( $N$ ) transits and the ensemble of  $t_{0;i=1...N}$ . The transit duration  $T$  is found from the 2 solutions to  $\beta(t) = 1$ :

$$T = 2 * \tau \sqrt{1 - \beta_0^2}. \quad (7)$$



Combining Equations 4,5 and 7 we express  $e_{min}$  in terms of our model parameters:

$$e_{min} = \left| \frac{P^2 - 4\pi^2\alpha^2\tau^2}{P^2 + 4\pi^2\alpha^2\tau^2} \right| \quad (8)$$

or, more intuitively,

$$e_{min} = \left| \frac{1 - (v_c/v)^2}{1 + (v_c/v)^2} \right|. \quad (9)$$

Equation 8 indicates that  $e_{min}$  is purely a function of the fitted parameter  $\tau$ , the derived period  $P$ , and an externally estimated semi-major axis for the planet (in units of the stellar radius)  $\alpha$ .

### KOI 701.02

We validate our proposed methodology by analyzing *Kepler* data from KOI 701.02 (Kepler 62-b; [Borucki et al., 2013](#)). This planet has a period of 5.715 days,  $\zeta = 0.018$  ( $R_p \sim 1.3 R_E$ ), and a transit depth of  $4 \times 10^{-4}$ . We use the limb darkening parameters for the host star from [Sing \(2010\)](#). The *Kepler* data have correlated (red) noise which we must account for before model fitting. To do so, we perform a local detrending by first dividing the data by the proposed model, and fitting a low order spline to the result. The goodness of fit is determined by comparing the product of the spline and the model to the data. We were able to model the first 32 transits before this proposal deadline.

To examine how our knowledge of system parameters evolves as a function of number of transits, we have fit *all* the data up to the time of each transit, for each of  $N = 32$  transits. This means that for transit  $n \leq N$ , we have common model parameters  $\beta_0^2, \tau, \zeta$  and per-transit parameters  $t_{0;i=1..n}$ , for a total of  $n + 3$  model parameters. This yields an ensemble of  $N$  system models, each incorporating one more transit than the previous one.

We used the affine-invariant MCMC sampler `emcee` ([Foreman-Mackey et al., 2013](#)) to sample the posterior distribution of the model parameters. This program uses the method of [Goodman & Weare \(2010\)](#) to achieve high sampling performance independent of the aspect ratio of the posterior distribution, meaning covariances between parameters are less important to the efficacy of the MCMC sampling. This provided a set of MCMC chains that we examine to determine our constraints on the fitted parameters. We used the Gelman-Rubin  $\hat{R}$ -statistic ([Gelman & Rubin, 1992](#)) to assure that each chain sufficiently samples model space, and required effective chain lengths larger than  $10^4$  to ensure sufficient mixing in the MCMC sample (e.g. [Tegmark et al., 2004](#)). Our trial runs using KOI 701.02 indicated that our chains typically have autocorrelation lengths of  $\sim 100$ , requiring a total number of steps per chain of  $10^6$ . We used burn-in times having 10% the requested number of steps, which are then discarded before the final chain commences.

For each transit, we marginalized over all other parameters, to examine the per-parameter confidence limits. Figure 4 demonstrates how our marginalized constraints on  $\tau$  (left panel) and  $\zeta$  (center panel) evolved as a function of the number of transits used in the fit for 701.02. The solid line provides the maximum of the posterior distribution, and the dashed line indicates its median. The shaded area encloses 68.3% of the distribution. In this manner, we find a maximum likelihood value of  $\tau = 0.051_{0.002}^{0.003}$ . This may be contrasted to

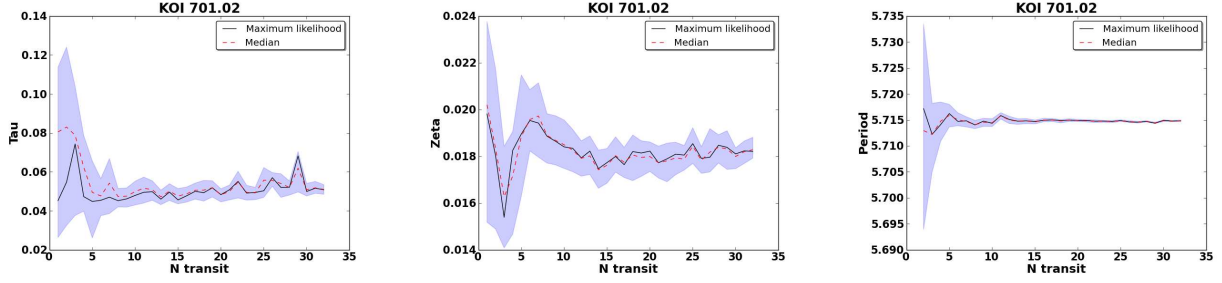


Figure 4: The marginalized distributions of  $\tau$  (left panel),  $\zeta$  (center panel), and period  $P$  (right panel) as a function of the number of transits being used, for KOI 701.02. For each transit  $n \leq 32$  we use *all* data up to and including transit  $n$ . The *solid* line represents the maximum of the posterior distribution, while the *dashed* line indicates its median. The shaded area contains 68.3% of the posterior samples.

$\tau = 0.049 \pm 0.003$  derived from reported [Borucki et al. \(2013\)](#) parameters, where they used 171 transits. For completeness, we note our confidence limits on  $\zeta = 0.0182^{+0.0006}_{-0.0003}$  vs the [Borucki et al. \(2013\)](#) result  $\zeta = 0.0188 \pm 0.0003$ .

To examine our constraints on the system period, we used the  $t_{0;1..n}$  posterior distributions from the fits described above. We used `emcee` to sample the posterior space of (nuisance parameter)  $t_{0;1}$  and period  $P$ . For a given trial  $(t_{0;1}, P)$  pair, the likelihood was determined through:

$$\mathcal{L}(t_{0;1}, P) = \prod_{i=1}^{i=n} \kappa_i(t_{0;1} + P * (i - 1)) \quad (10)$$

where  $\kappa_i$  is a kernel density estimate of each posterior distribution  $t_{0;i}$ , which is evaluated at the predicted time of transit  $t_0 + P * (i - 1)$ . By modeling the times of transit separately in the original MCMC analysis, we allow the possibility of using a more complex ephemeris model at this stage of the analysis, such as may be expected from transit timing variations ([Agol et al., 2005](#); [Holman & Murray, 2005](#)). The results of this analysis for KOI 701.02 are presented in the right panel of Figure 4.

For the derived period after 32 transits, we find  $P = 5.71484^{+0.00009}_{-0.00015}$ . The uncertainty in the period roughly scales as a power law with an e-folding timescale of approximately 15 transits. This may be contrasted to  $P = 5.714932 \pm 0.000009$  days reported in [Borucki et al. \(2013\)](#). The differences in  $e_{min}$  are more substantial. Using their reported value of  $\alpha = 18.7 \pm 0.5$ , we derive  $e_{min} = 0.043 \pm 0.009$ , compared to  $e_{min} = 0.021 \pm 0.005$  using the [Borucki et al. \(2013\)](#) results. This difference is almost entirely driven by the (1-sigma) differences in  $\tau$ , which makes it of utmost importance to model this parameter directly.

To examine our ability to constrain system parameters as a function of transit depth and signal-to-noise (S/N), we generated simulated lightcurves at the *Kepler* cadence. We used a subset of the synthetic systems described in the first section of this proposal. For each, we

simulated lightcurves at magnitude 8/10/12/14, adding a random draw from a Gaussian with widths 11.3/29/80/296 ppm (respectively) to each datapoint to simulate white noise. We find that after 10 transits, we are able to recover  $\tau$  to better than ten percent for all transits deeper than 0.5% down to 14<sup>th</sup> magnitude; deeper than 0.1% down to 12<sup>th</sup> mag; deeper than 0.05% down to 10<sup>th</sup> mag; and deeper than 0.01% down to 8<sup>th</sup> mag. This analysis is consistent with our results from KOI 701.02, where the host star’s magnitude is 13.6, the transit depth is 0.04%, and measured S/N in  $\tau$  is  $\sim 7.8$  after modeling 10 transits:  $0.0479^{0.0073}_{0.0049}$ . Note the measured precision in  $\tau$  increases to a S/N of approximately 20 after 32 transits (Figure 4).

### TARGET SELECTION AND CHARACTERIZATION

We have examined the current KOIs to establish a preliminary target list. We find 1168 objects with appropriate values of  $P$  and  $R_p$ , and with host star mass estimates between 0.7 and 1.4  $M_\odot$ , i.e. FGK stars. We expect this list to expand somewhat with on-going study of the *Kepler* data; we anticipate running our pipeline on approximately 1300 systems.

As described above, our analysis requires a measure of the orbital separation relative to the stellar radius,  $\alpha = a/R_*$ , to derive  $e_{min}$  (Equation 8). The separation is obtained trivially from Kepler’s 3rd Law according to,  $a = (M_* P^2)^{2/3}$  where  $M_*$  is the mass of the host star. Unfortunately, the mass of an isolated star is not directly observable. Instead, it must be inferred by comparing observed stellar properties to theoretical stellar evolution models and/or empirical calibrations. Thus, to derive the stellar mass, we will interpolate state-of-the-art stellar evolution models from the Dartmouth group (Dotter et al., 2008) in three parameters: effective temperature ( $T_{eff}$ ), metallicity ([Fe/H]), and gravity ( $\log g$ ), as we (L. Hebb) have done for many other confirmed transiting planets with radial velocity measurements (e.g. Hebb et al., 2009, 2010).

We plan to primarily use the information available in the literature for  $T_{eff}$  and [Fe/H]. Several teams have large, observing programs to obtain spectra of KOIs. Everett et al. (2013) derived stellar parameters for  $\sim 400$  faint KOIs from low resolution data; approximately 1000 targets have been observed with Keck HIRES (J. Johnson et al. in prep) and are currently being analyzed with a new Spectroscopy Made Easy (SME) pipeline (Cargile, Hebb et al. in prep); and the 2.5m Nordic Optical Telescope (NOT) has an ongoing program to derive stellar parameters of Kepler KOIs (L. Buchave, PI). However, if certain targets lack observed spectra or derived stellar parameters, we will obtain the necessary data with the ARC 3.5m echelle spectrograph through the University of Washington’s guaranteed access to the Apache Point Telescopes. We will analyze these data as necessary with our SME pipeline, as we have done for many other targets (e.g. Wisniewski et al., 2012).

We will obtain the  $\log g$  values based on a novel characterization of the high frequency variability in the *Kepler* light curves (Bastien, Stassun et al. 2013, to appear in Nature) which has been shown to reproduce the exquisite astroseismically measured  $\log g$  values (Huber et al., 2013) for dwarf and subgiant stars. The authors present a technique that can be used to derive  $\log g$  values for the majority of Kepler targets with uncertainties of  $\leq 0.1$  by empirically detecting granulation on the stellar surface. This allows for significantly more accurate and precise gravity measurements than can be derived from typical modeling of broad absorption line wings.

We will interpolate the Dartmouth models considering the uncertainties in the photo-

metrically measured  $\log g$  and in the spectroscopically determined  $[\text{Fe}/\text{H}]$  and  $T_{\text{eff}}$ . Typical uncertainties of  $\leq 0.1$  dex in  $[\text{Fe}/\text{H}]$ ,  $\leq 100$  K in  $T_{\text{eff}}$ , and  $\leq 0.1$  in  $\log g$  result in uncertainties on the resulting stellar mass of 5–8% for well understood F, G and K-dwarf stars. This error budget includes the formal errors from the measured uncertainties on the parameters, and systematic uncertainties arising from variation between different stellar evolution models (2-4%; Southworth, 2009). We expect to generate a catalogue of  $\alpha = a/R_*$  values for all the short period KOI transiting planet candidates in our sample with conservative uncertainties of  $\leq 10\%$ . Finally, our comparison of the stellar parameters to the evolutionary models also allows us to estimate stellar age, which is critical to understanding the tidal quality factors.

### COMPUTATIONAL REQUIREMENTS

Using KOI 701.02 as a benchmark, we find a linear relationship in the computation time required to reach  $10^6$  steps vs. the number of transits:  $\text{time}_{10^6}(n) = -1105 + 5943 \times n$  seconds. For a 5-day period system having  $\sim 300$  transits over the assumed 17-quarter operational lifetime of *Kepler*, this comes out to  $\sim 21$  CPU-days of analysis. The `emcee` code is natively able to use multiprocessing capabilities, making this trivial to implement on a multi-core system. However, with  $\sim 1300$  systems on our analysis path, this will require  $\sim 75$  CPU-years of computation, requiring the use of NASA’s High-End Computing (HEC) facilities. We will also make use of the local Hyak compute cluster when it is available.

### DATA INTERPRETATION

In the following sections, we describe the theoretical component of our research plan in more detail. In Task A, we consider systems consisting of one star and one planet. In Task B, we include multiple planet systems. In Task C, we incorporate mass loss. For each task, our final step will be a comparison between simulated data and the ensemble of well-characterized *Kepler* targets. This will be done by comparing the measured distributions of  $e_{\text{min}}$  to those simulated using  $R_{\text{crit}}$ ,  $Q_r$ , and  $Q_g$  (and possibly factoring in multiplicity, metallicity, and mass loss).

### TASK A: TIDES IN STAR-PLANET SYSTEMS

We begin with the simplest treatment, a single planet orbiting a single star in an orbit that can be modified by tides. We will mostly follow the procedure described for our pilot study, but will expand the analysis to a broader range of initial conditions as well as include alternative tidal models. The pilot study (25,000 simulations of  $\sim 5$  Gyr each) required about 4 hours on a modern workstation, and therefore many such trials are easily tractable. The free parameters are the mass-radius relationship for both rocky and gaseous bodies, the value of  $R_{\text{crit}}$ , the  $Q$ s of rocky and gaseous bodies, the initial eccentricity distribution, and the age distribution of *Kepler* stars.

The choices in the pilot study were necessarily limited, and we will explore many more options during this investigation. While we assumed that rocky bodies were Earth-like in their composition, other scaling laws are possible (e.g. Seager et al., 2007; Fortney et al., 2007; Lissauer et al., 2011). We will use these other scalings for the masses of the rocky planets, as well as mixing the models to allow for a range of compositions. For the gaseous planets, we will assume different densities in the range  $0.5 - 3 \text{ g/cm}^3$ . The value of  $R_{\text{crit}}$  is the parameter we are most interested in; we will grid from  $1$  to  $2.5 R_{\oplus}$  in  $0.1 R_{\oplus}$  intervals. We will

consider two different models for  $Q(R)$ , the tidal  $Q$  as a function of planetary radius. First we will use the same differences as in the pilot study, but we will also consider a three-tiered model, in which intermediate mass planets have intermediate  $Q$ s. Neptune, and possibly even Saturn, have a  $Q$  value of  $10^4$  (Zhang & Hamilton, 2008; Lainey et al., 2012), and hence we must consider this possibility. This also introduces a new radius cut-off,  $R_{mid}$ , which we will allow to move from 2 to 5  $R_{\oplus}$ . The  $Q$  range for these systems will have values between 3000 and 30,000. We will randomly choose a stellar mass in the range 0.7–1.4  $M_{\odot}$  as we are interested in FGK stars. Finally, we will keep the initial eccentricity distribution consistent with that of more distant exoplanets. Ultimately we expect to run several hundred suites of systems, easily do-able on a modern multi-core workstation.

The examples in Figs. 1–3 used one tidal model, in which the lag angle between the tidal bulge and the perturber is constant regardless of frequency (e.g. Goldreich & Soter, 1966; Jackson et al., 2008). Another popular model assumes that the lag angle is instead a function of frequency (e.g. Hut, 1981; Matsumura et al., 2010). We will also employ this model with the same ranges as described above, and relating  $Q$  to the time lag  $\tau$  as  $Q = 1/n\tau$ , where  $n$  is the mean motion (e.g. Correia et al., 2012). In reality there is no general conversion between the two, but this relation is in common use. Thus, our work may also shed light on the frustrating ambiguity in determining the most appropriate equilibrium tidal model.

## TASK B: MULTI-PLANET SYSTEMS

Mutual gravitational interactions between planets can maintain an eccentricity, even in the presence of strong tidal damping (Mardling & Lin, 2002; Greenberg & Van Laerhoven, 2011; Correia et al., 2012). To assess this effect, we will perform simulations of multiplanet systems undergoing tidal damping. The Gyr timescales for damping are too long for accurate N-body modeling, so will use classical secular theory to model the planet-planet interactions. The second order theory is insufficient for many of the cases we consider, which will have eccentricities up to 0.9. Therefore, we will use higher order theories, which have been previously developed (e.g. Ford et al., 2000; Veras & Armitage, 2004; Libert & Henrard, 2005). To maximize accuracy, and take advantage of the high degree of coplanarity of close-in *Kepler* systems Fabrycky et al. (2012), we will use the coplanar 12th order theory of Libert & Henrard (2005) to evaluate the evolution.

More challenging is the choice of initial conditions. While many *Kepler* systems are multiple, we do not yet know the underlying distribution of orbital architectures. A full exploration of parameter space with arbitrary multiplicity and orbital elements would be intractable. We therefore will limit our study to suites of 25,000 systems with multiplicity that follows from the observations. To better match the *Kepler* systems, we will limit the size of our planetary systems to  $< 0.5$  AU. The physical properties of the planets will be in the same ranges as above. We will perform numerical tests of stability of initial conditions, and will throw out systems that divergently cross strong mean motion resonances – such 2:1, 3:1, and 3:2 – that lead to system break-up (e.g. Gomes et al., 2005).

Additionally, it may be that many of the close-in systems cannot have initial eccentricities comparable to the non-tidally-evolved planets because they would be unstable. In those cases, the orbits are probably close to their primordial morphologies and migrated during the protoplanetary disk phase. Recently Dawson & Murray-Clay (2013) showed compelling



evidence that high metallicity stars are more likely to host eccentric planets. Therefore, we will make two comparisons with the *Kepler* sample: the full set and the high metallicity set.

### TASK C: ATMOSPHERIC MASS LOSS

We will employ the classic mass loss of model of [Erkaev et al. \(2007\)](#) in which XUV photons liberate hydrogen atoms in the upper atmosphere. Mass loss can be a very complicated process ([Yelle, 2004](#); [Lammer et al., 2007](#); [Khodachenko et al., 2007](#); [Leitzinger et al., 2011](#); [Lammer et al., 2013](#)), and with so many unknowns for any given planet, this simple model is most appropriate. The key parameter in this formulation is the efficiency of transforming incident XUV radiation into escaping atoms,  $\epsilon$ . Most studies of hot Jupiter place  $\epsilon$  in the range 0.1 – 0.4. We will therefore explore a range of 0.05 – 0.5 in increments of 0.05 and apply these to the configurations of Task A and Task B. For the XUV flux, we will use the empirical relationship derived in [Ribas et al. \(2005\)](#) for G dwarfs. While this formulation is not strictly valid for F and K dwarfs, analogous studies do not exist for those spectral types, and the Ribas model is probably a close approximation. These analytic models can easily be added to the equilibrium tidal models. This final theoretical task requires about 2–3 times more computational resources than the other two combined, but is still dwarfed by the *Kepler* lightcurve analysis, and can easily be completed within a few months on a workstation, or on UW’s local supercomputer.

Unfortunately the inclusion of mass loss leads to a degeneracy in our model. The three parameters  $R_{crit}$ ,  $Q_r$  and  $Q_g$ , are all related to features in Figure 3. Mass loss complicates the picture by blurring these boundaries. On the other hand, it is entirely possible that we will fail to reproduce the observed  $\langle e_{min} \rangle$  distribution without it. At the conclusion of Task C, we will have about 2000 suites of simulations with different physical parameters to compare to the *Kepler* planet candidates. If we succeed in identifying  $R_{crit}$ , then planets found in the HZ of *Kepler* targets can be characterized as gaseous or rocky (and potentially habitable), independent of measurement of their masses. This is the ultimate goal of this proposal.

## **IV. Team Qualifications and Previous NASA Support**

PI Becker is PI on NASA OSS grant NNX09AB32G, “3.5m Transit Timing Observations at 100% Duty Cycle”, which observed multiple transiting exoplanet systems for evidence of transit timing variations ([Kundurthy et al., 2011, 2013b](#); [Becker et al., 2013](#); [Kundurthy et al., 2013a](#)). Much of the software developed for that project has been modified to operate with the *Kepler* data, and used in the analyses presented here. He has considerable expertise in using modern software packages implemented on distributed computing infrastructures to model multi-dimensional systems.

Co-I Barnes was a Co-I on NASA OSS grant 811073.02.07.01.15 “Simulating the Initial Planetsimal Disk” which produced the first N-body simulation of 1 km planetsimal accretion ([Barnes et al., 2009](#)). As part of this effort, Barnes used several hundred thousand hours of CPU time at NASA HPC facilities, such as the Columbia and Plaides supercomputers. He has published  $\sim 40$  papers on tidal theory and orbital dynamics, including secular modeling ([Barnes & Greenberg, 2006](#)), tidal effects ([Barnes et al., 2013](#)), and coupling with atmospheric mass loss ([Jackson et al., 2010](#); [Barnes et al., 2013](#)). He is also a Co-I on NASA’s Virtual Planetary Laboratory (NNA13AA93A) that began Jan. 1, 2013.



Co-I Agol has originated several important ideas in the field of extrasolar planets, including analytic light curve modeling (Mandel & Agol, 2002), transit timing variations (Agol et al., 2005), and discovery of the smallest diameter planet in the habitable zone of another star (Borucki et al., 2013). He is currently a *Kepler* collaborator.

Co-I Hebb is an expert in the field of characterizing exoplanet host stars using state-of-the-art stellar evolution models (e.g. Hebb et al., 2009, 2010; Bouchy et al., 2010; Gómez Maqueo Chew et al., 2013).

## V. Relevance to NASA Programs

This project directly addresses objectives that are in-scope for the Exobiology and Evolutionary Biology call for proposals, in particular:

- **Planetary Conditions for Life:** This research delineates the planetary conditions conducive to the origin of life by determining the maximum radius permitted for rocky exoplanets. Since gaseous bodies are not expected to be habitable, understanding this boundary is critical in a search for extraterrestrial life. The *Kepler* spacecraft was designed to find small, potentially terrestrial planets in orbits that are not amenable to mass measurements, but the preliminary studies presented here demonstrate that a careful analysis of *Kepler* data *can* provide strong constraints on planetary composition. Furthermore, planetary system architecture, atmospheric mass loss, and tidal dissipation of planets are important aspects of the habitability puzzle, and are directly addressed by this proposal.

## VI. Project Development Plan

PI Becker will be technical lead the project for the first 1.5 years, which will constitute the data analysis (MCMC) portion of the project. Co-I Barnes will serve as technical lead for the project for the second 1.5 years, as the project transitions from analysis of the data to interpretation and constraints on tidal evolution theory. Co-I Agol has significant experience with *Kepler* data, and will advise as-needed throughout the project. Co-I Hebb has extensive experience inferring the stellar properties of exoplanet host stars, and will serve as the lead for determining the host stars' mass and radius. PI Becker will serve as the project lead throughout. We will have weekly meetings at the University of Washington to manage progress, and yearly meetings including Hebb to focus on host star characterization.

We regard the professional development of students as an important responsibility of *any* research project. In this regard, the graduate students funded by this proposal will have the opportunity to attend at least one relevant conference each year, and encouraged to give oral presentations on our work. This will become a requirement as the project progresses. We expect the graduate student to become an expert in both areas of this project, both the computational/modeling side and the theoretical side, and will work full-time with both Becker and Barnes throughout. This is a powerful combination and one not seen often enough in the field. We consider this dual-aspect training a strong component of this project.

**Year 1 (2014):** This first year of the project will start with PI Becker bringing the student up to speed in modeling transit lightcurves, in learning Bayesian techniques, and in

implementing a robust application of the `emcee` package (or other affine-invariant sampler, if needed). This includes making the software robust to detrending errors, missing data, and initial conditions. Discovering and understanding the failure modes will be a main focus of this computationally-intensive first year. Becker will lead this effort, and transition the student into lead during the year. The generation of the MCMC chains is expected to take  $\sim 75$  CPU-years, requiring the use of high-end computing facilities. The validation of these chains is expected to take a non-negligible amount of time, as some chains are expected to have to be re-run or extended. The goal of this first year is to have finalized the MCMC chains on  $t_0, \beta_0^2, \tau, \zeta$  for all transits of all KOIs. We will make the chains and modeling software publicly available through a `github` site specifically designed for this project.

**Year 2 (2015):** The second year will begin with the MCMC analyses of the periods, include a strong focus on characterizing the host star mass and radius, and transition to theoretical interpretation of the systems. During this year, Barnes will begin working with the graduate student on the theoretical components. They will design and simulate the models described in Task A and publish preliminary estimates of  $R_{crit}$ ,  $Q_g$ , and  $Q_r$ . During this year we will also begin running simulations of multiplanet systems with tidal damping.

**Year 3 (2016):** During the final year, we will finish all theoretical modeling, including the incorporation of mass loss. We will publish a paper on the role of multiplicity in the  $e_{min}$  distribution. The graduate student will perform a final analysis of all available *Kepler* data and will compare this final data set to the synthetic data produced by the tides+multiplicity+evaporation model. A final paper will summarize the results of the investigation, including final values, with error estimates, for  $R_{crit}$ ,  $Q_r$ ,  $Q_g$ , and  $\epsilon$ .

## VII. Data Sharing Plan

All investigators are committed to the sharing of data and software. PI Becker has been behind real-time public alert systems for many time-domain astronomical surveys. This includes the MACHO survey, the Deep Lens Survey, the SuperMACHO and ESSENCE surveys, and the SDSS-II Supernova Survey, all of which have released their events to the public in near-real time through web pages, Astronomer’s Telegrams, IAU circulars, and VOWEvents. He is currently working part-time on the Large Synoptic Survey Telescope (LSST), which is both open-source and open-data.

We will version release all software developed for this project on the publicly available open-source collaboration website <http://github.com> (`github` hereafter). The website has become a leading collaboration platform; it enables distributed users to download code and contribute back to the project. All code we develop for this project will be made available under the terms of the open source BSD license<sup>3</sup> whenever possible. We will make a new `github` account for this project that we will use to stage code and data releases, as described in the project development plan. Analysis packages used in our publications will be released as `iPython`<sup>4</sup> notebooks to help establish reproducible research standards in the field. `iPython` allows the exchange of portable environments (notebooks) that enable the user to follow the analysis path leading to a given scientific result, and also to interact with it at the code level to understand (and verify) the methodology.

<sup>3</sup><http://www.opensource.org/licenses/bsd-license.php>

<sup>4</sup><http://ipython.org>

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## Budget Justification

### PI SALARIES:

We include 6 months salary in the first year for PI Becker, and 3 months in the second year. Becker is on the Research Faculty at UW, meaning his salary must be obtained through grants such as this one. Benefits are calculated at the rate of 26.9%. We budget for a 2% annual increase in these salaries.

We include 3 months salary in the second year for Co-I Barnes, and 4 months in the third year. Barnes is on the Research Staff at UW, meaning his salary must be obtained through grants such as this one. Benefits are calculated at the rate of 34.0%. We budget for a 2% annual increase in these salaries.

### OTHER SALARIES:

One graduate student will be funded for 3 academic quarters per year at 60% time, and 2 summer quarters at 100% time. Benefits are calculated at the rate of 14.2%. We budget for a 2% annual increase in these salaries.

### TUITION COSTS:

We include tuition fees for one graduate student at the rate of \$4,689 per quarter (first year), for 3 academic quarters per year. We budget for a projected 10% annual increase in these fees after the first year, and 12% subsequently.

### EQUIPMENT:

None

### TRAVEL:

We budget for 2 domestic trips per year for collaboration and conferences, at the rate of 1,500 per trip (to cover travel to and 4 days lodging to the East Coast). This will be shared by the investigators and graduate student. We budget for one additional trip per year specifically for Co-I Hebb to visit the University of Washington.

### PUBLICATION CHARGES:

Publication costs are budgeted at the electronic publishing charge of \$110/page, for 20 pages/year.

### COMPUTING FEES:

Computer support fees are budgeted at the nominal rate of \$67 per person per month by the Physics and Astronomy Computing Services group (PACS) at UW.

### INDIRECT COSTS:

Indirect costs are based on the MTDC rate of 54.5% per the negotiated agreement with DHHS dated 3/5/2013.

#### PERSONNEL AND WORK EFFORT:

PI Becker will work on this project at 50% effort for the first year of the project, and 25% for the second. His focus will be on implementing a robust MCMC analysis of all the Kepler data, in debugging failure modes, and in training the graduate student in the art of Bayesian analysis.

Co-I Barnes will work on this project at 25% effort in the second year of the project, and 33% in the third.

Co-I Hebb will lead the host star characterization effort.

Co-I Agol will assist as-needed.

The graduate student will work on this project at 60% FTE for 3 academic quarters, and 100% FTE for 2 summer quarters, for all 3 years of the project. Their role will be to become an expert in the analysis of the data, and in the interpretation of the results and how it relates to tidal dissipation in the population of planets studied.

#### FACILITIES AND EQUIPMENT:

As this is a compute-heavy proposal, we will be making use of the local University of Washington Hyak compute cluster, as well as applying for time on NASA's High-End Computing (HEC) facilities. The University provides office equipment for all investigators.