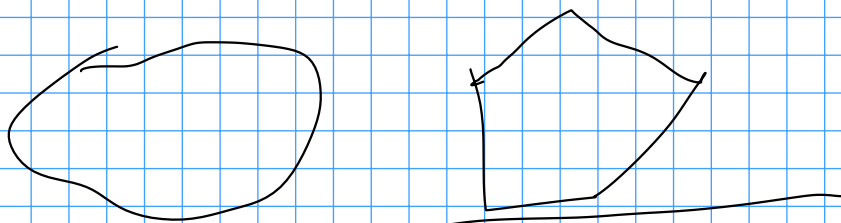
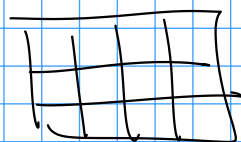


• ELEMENTI FINITI



$$a(u, v) = F(v)$$

$$\forall v \in V$$

TROVA $u \in V$

APPROSSIMAZIONE DI $V \rightarrow V_h$

$$h \rightarrow 0$$

$$V_h \rightarrow V$$

$h = \text{size elementi}$

DOLLA DISCRET.
SPAZIALE

$$1. V_h \text{ HILBERT} \subset V \subset H^1(\Omega)$$

$$2. a_h(\cdot, \cdot) : V_h \times V_h \rightarrow \mathbb{R}$$

CONT, CONT, (SYM)

$$3. F_h(\cdot) : V_h \rightarrow \mathbb{R}$$

CONT, LINEARE

$$\bullet V_h \subset V$$

$$\dim(V_h) = N_h$$

$$< \infty \quad \forall h > 0$$

$$\bullet a_h = a|_{V_h \times V_h}$$

$$\bullet F_h = F$$

TROVA $u_h \in V_h$:

$$a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h$$

PROBLEMA DI GALERKIN

$$\underline{u} = \begin{pmatrix} u_0 \\ \vdots \\ u_{N_h} \end{pmatrix} \in \mathbb{R}^{N_h}$$

$$V_h = \text{Span}(\{\varphi_i\}_{i=1}^{N_h}) = \langle \{\varphi_i\}_{i=1}^{N_h} \rangle$$

$$V_h = \{u \in V : u = \sum_{i=1}^{N_h} u_i \varphi_i, u_i \in \mathbb{R} \forall i=1, \dots, N_h\}$$

$$\dim(V_h) = N_h$$

$$u \in V_h \longleftrightarrow \underline{u} = \begin{pmatrix} u_1 \\ \vdots \\ u_{N_h} \end{pmatrix} \in \mathbb{R}^{N_h}$$

TROVA $u_h \in V_h$:

$$a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h$$



$$a(u_h, \varphi_i) = F(\varphi_i) \quad \forall i=1, \dots, N_h$$

$$u_h = \sum_{j=1}^{N_h} u_j \varphi_j$$

$$\sum_{j=1}^{N_h} a(\varphi_j, \varphi_i) u_j = F(\varphi_i)$$

$$\underline{A} \cdot \underline{u} = \underline{F}$$

$$\underline{u} = [u_j] \quad \text{INCOGNITE}$$

$$\underline{A} = [a_{ij}]$$

$$a_{ij} = a(\varphi_j, \varphi_i)$$

$$u_h = \sum_{j=1}^{N_h} u_j \varphi_j(x)$$

$$\underline{F} = [F_i]$$

$$F_i = F(\varphi_i)$$

Se $a(\cdot, \cdot)$ FUOR. BILIN ASS AL PROBLEMA

ELLIPTICO $a(u, v) = F(v) \quad \forall v \in V$

è un BILINFORME
COERCIVO

$\Rightarrow A$ è DEFINITA POSITIVA.

$$A \text{ è DEF POS} \Leftrightarrow V^T A V \geq 0 \wedge V^T A V = 0 \Leftrightarrow V = \underline{0}$$

Def $u_h \Leftrightarrow \underline{u}$

$$V^T A V = \sum_{i,j=1}^{N_h} v_i a_{ij} v_j = \sum_{i,j} v_i a(\varphi_j, \varphi_i) v_j$$

$$= a\left(\sum_{j=1}^{N_h} v_j \varphi_j, \sum_{i=1}^{N_h} v_i \varphi_i\right) =$$

$$= a(V_h, V_h) \geq \alpha \|V_h\|_V^2 \geq 0$$

$$\geq 0 \Leftrightarrow \|V_h\|_V^2 = 0$$

$$\Downarrow \\ \underline{V} = 0$$



1. ESISTENZA e UNICITÀ di u_h ?

2. STABILE CASUALITÀ?

3. $u_h \rightarrow u$ per $h \rightarrow 0$ ||

$$\begin{array}{c} \uparrow \\ \boxed{f \Delta u = f} \end{array}$$

1. LEMMA LAX-NIKOLSKAN

$\forall V_h$ HILBERT

$$\boxed{F(V) = \int f \cdot V}$$

$$\Rightarrow a(\cdot, \cdot) = F(\cdot)$$

$$\boxed{a = \int \nabla u \cdot \nabla v \, dx}$$

$$\Rightarrow \exists! u_h \in V_h : a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h$$

• 1. BIS $\Rightarrow \boxed{\underline{A} \underline{y} = \underline{F}} \quad A \text{ DEF POS} \Rightarrow \exists A^{-1}$

2. STABILITÀ

$$\alpha \in \mathbb{R} \text{ COEFFICIENTE CORRELATIVITÀ di } a$$

$$\Rightarrow a(u, u) \geq \alpha \|u\|^2 \quad \forall u$$

$$\|u_h\|_V \leq \frac{1}{\alpha} \|F\|_{V^*}$$

$$F: V \rightarrow \mathbb{R}$$

$$a: V \times V \rightarrow \mathbb{R}$$

DIN

$$a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h$$

$$\|u_h\|_V^2 = \|u_h\|_{V_h}^2 \leq \frac{1}{\alpha} a(u_h, u_h) = \frac{1}{\alpha} F(u_h)$$

$$\leq \frac{1}{\alpha} \|F\|_{V^*} \cdot \|u_h\|_V$$

$$\|u_h\|_V \leq \frac{1}{\alpha} \|F\|_{V^*}$$

□

COROLLARIO

$$u_h: a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h$$

$$w_h: a(w_h, v_h) = G(v_h) \quad \forall v_h \in V_h$$

$$\Rightarrow \|u_h - w_h\|_V \leq \frac{1}{\alpha} \|F - G\|_{V^*}$$

es. $F(u) = \int_{\Omega} p \cdot v - \int_{\partial\Omega} g \cdot v$

3. CONVERGENZA

OBBIETTIVO: $u_h \rightarrow u \quad h \rightarrow 0$

PROIEZIONE DI GALERKIN / ORTOGONALITÀ DI GALERKIN

$$a(u_h - u, v_h) = 0 \quad \forall v_h \in V_h$$

$$u_h \text{ è soluzione di } a(u_h, v_h) \stackrel{(1)}{=} \bar{F}(v_h) \quad \forall v_h \in V_h$$

$$u \text{ è solut. di } a(u, v) \stackrel{(2)}{=} \bar{F}(v) \quad \forall v \in V$$

$$V_h \subset V$$

$$a(u_h, v_h) = \bar{F}(v_h) \stackrel{(2)}{=} a(u, v_h) \quad \forall v_h \in V_h \subset V$$

$$\Rightarrow a(u_h - u, v_h) = 0 \quad \forall v_h \in V_h$$

• $a(\cdot, \cdot)$ è un prodotto scalare e a sym

$$\|v_h\|_a = \sqrt{a(v_h, v_h)}$$

$$u_h = \arg \min_{v_h \in V_h} \|v_h - u\|_a$$

$$\|u_h - u\|_a = \sqrt{a(u_h - u, u_h - u)}$$

• LEMMA DI CÉA

$$a(u - u_h, u - u_h) \stackrel{(1)}{=} a(u - u_h, u - v_h) + \underbrace{a(u - u_h, v_h - u_h)}_{=0}$$

CONTINUITÀ di a $\forall v_h \in V_h$

$$|a(u - u_h, u - v_h)| \stackrel{(2)}{\leq} C \cdot \|u - u_h\|_V \cdot \|u - v_h\|_V$$

$$\|u - u_h\|_V^2 \leq \frac{1}{\alpha} a(u - u_h, u - u_h) \stackrel{(1+2)}{\leq} \frac{C}{\alpha} \|u - u_h\|_V \cdot \|u - v_h\|_V \quad \forall v_h \in V_h$$

$$\|u - u_h\|_V \leq \frac{C}{\alpha} \|u - v_h\|_V \quad \forall v_h \in V_h$$

$$\|u - u_h\|_V \leq \inf_{v_h \in V_h} \frac{C}{\alpha} \|u - v_h\|_V \quad \square$$

u_h POTREBBE NON ESSERE LA MIGLIORE

APPROSSIMAZIONE IN $\|\cdot\|_V$

PERCÌ $\|u - u_h\|_V$ DIMINUISCE CON

LA MIGLIORE APPROSSIMAZIONE DI u IN V_h

• SE SCEGLIAMO V_h SE

$$\lim_{h \rightarrow 0} \inf_{v_h \in V_h} \|v - v_h\|_V = 0 \quad \forall v \in V$$

$$\Rightarrow \|u - u_h\| \xrightarrow{h \rightarrow 0} 0$$

$$\inf_{v_h \in V_h} \|v - v_h\|_V = \mathcal{O}(h^p) \Rightarrow \|u - u_h\|_V = \mathcal{O}(h^p)$$

• ELEMENTI FINITI:

$$\underline{\text{1D}} \quad \Omega = (a, b)$$

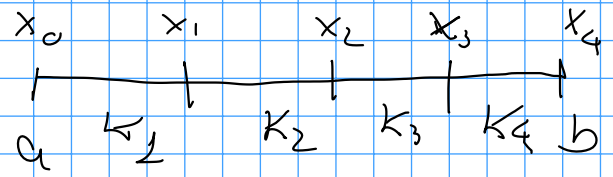
$$V = H^1((a, b)) \quad V_h \subset V$$

$$\mathcal{T}_h = \{K_j\}_{j=1}^{N_h}$$

$$K_j = [x_{j-1}, x_j] \quad \forall j=1, \dots, N_h$$

$$|x_j - x_{j-1}| = h$$

$$h = \max_j |x_j - x_{j-1}|$$



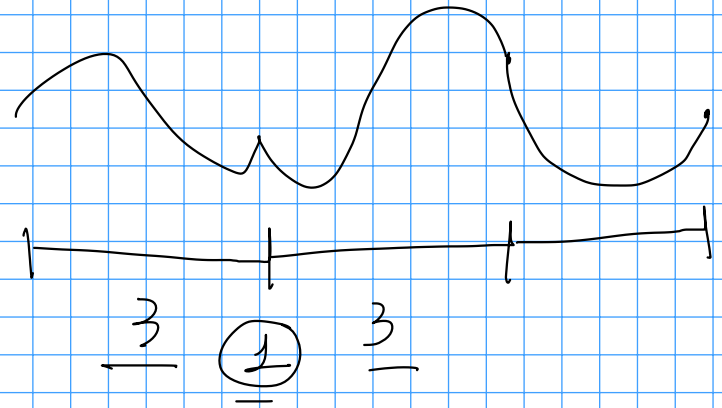
$$H^1((a,b)) \subset C^0([a,b])$$

V_h CONTINUO

$$V_h = X_h^r = \left\{ v_h \in C^0(\bar{\Omega}) : v_h|_{K_j} \in \mathbb{P}^r(K_j) \quad \forall K_j \in \mathcal{T}_h \right\} \\ \subset H^1((a,b))$$

$$V_h = X_h^r = \langle \varphi_1, \dots, \varphi_{N_h} \rangle$$

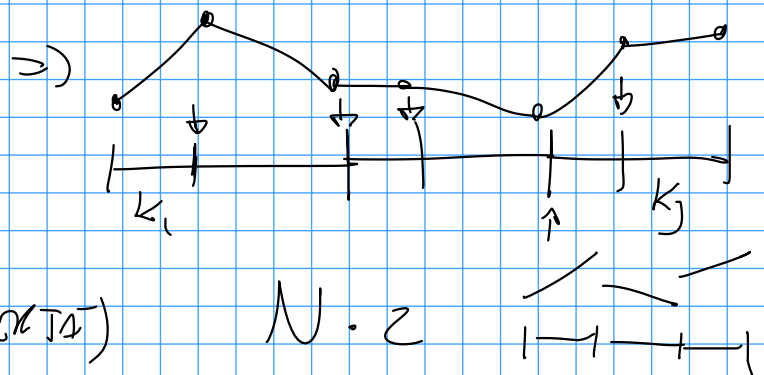
$$a_{ij} = a(\varphi_i, \varphi_j) \\ = \int \Omega \varphi_i \nabla \varphi_j$$



$$r=1 \quad \mathbb{P}^1(K_j)$$

$$y = \boxed{ax + b}$$

2 DOF (GRADI DI LIBERTÀ)



~~MA~~ VINCOLI CONTINUITÀ

$N-1$ VINCOLI \Rightarrow

$$2N - (N-1) = N+1 \text{ DOF}$$

\Rightarrow SE HO IL VALORE ALLE INTERFACCIE

$$\Rightarrow \exists! \quad u_h \in X_h^1 : u_h(x_j) = u_j \quad j=0, \dots, N$$

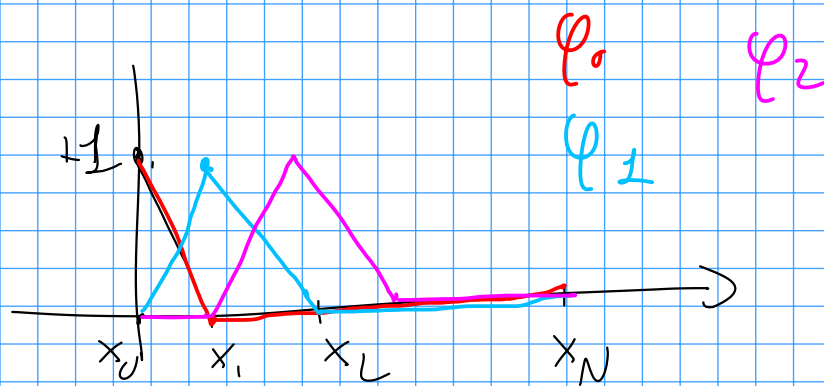
$$u_0 = 1 \quad \Rightarrow \quad u_h = \sum u_i \varphi_i = \varphi_0$$

$$u_1 = 0$$

$$u_2 = 0$$

$$u_3 = 0$$

$$|$$



$$u_0 = 1 \Rightarrow u(x_0) = 1$$

$$u(x_i) = u_i$$

$$\varphi_i(x_j) = \delta_{ij}$$

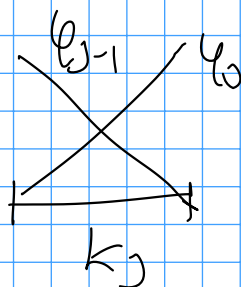
$$\varphi_i(x) = \begin{cases} \frac{x - x_{i-1}}{x_i - x_{i-1}} & \text{se } x \in [x_{i-1}, x_i] \\ \frac{x_{i+1} - x}{x_{i+1} - x_i} & \text{se } x \in [x_i, x_{i+1}] \\ 0 & \text{altimenti} \end{cases}$$

$$\text{supp}(\varphi_i) = (x_{i-1}, x_{i+1})$$

$$i = j-1, j \Rightarrow \neq 0 \quad \wedge \quad i = j, j+1 \Rightarrow \neq 0$$

$$a_{ij} = \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j \, dx = \int_{K_j} \nabla \varphi_i \cdot \nabla \varphi_j + \int_{K_{j+1}} \nabla \varphi_i \cdot \nabla \varphi_j$$

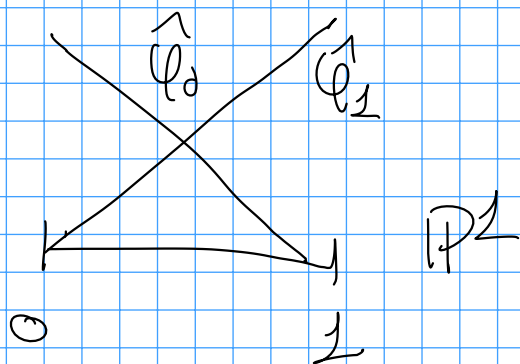
$$\Rightarrow a_{ij} = 0 \quad \text{se } |i - j| > 1$$



$$\int_{K_j} \partial_x \varphi_i \partial_x \psi_k$$

$$i = j-1, j$$

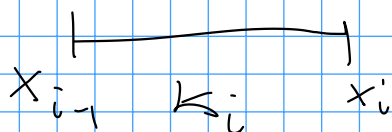
$$k = j-1, j$$



$$\hat{\varphi}_0(\xi) = 1 - \xi$$

$$\hat{\varphi}_1(\xi) = \xi$$

$$T_i : [0, 1] \rightarrow [x_{i-1}, x_i]$$



$$T_i(\xi) = \xi(x_i - x_{i-1}) + x_{i-1}$$

$$T_i^{-1}(x) = \frac{x - x_{i-1}}{x_i - x_{i-1}}$$

$$\varphi_i(x) = \hat{\varphi}_1(T_i^{-1}(x)) = \hat{\varphi}_1\left(\frac{x - x_{i-1}}{x_i - x_{i-1}}\right)$$

$$\forall x \in K_i$$

$$\varphi_i(x) = \hat{\varphi}_0(T_{i+1}^{-1}(x)) = \hat{\varphi}_0\left(\frac{x - x_i}{x_{i+1} - x_i}\right)$$

$$\forall x \in K_{i+1}$$

$$X_h^2 = \{u \in C^0([0, b]) : u|_{K_j} \in P^2(K_j) \forall j\}$$

$$P^2([0, 1])$$

LAGRANGIANA \Rightarrow

$$\hat{x}_0 = 0$$

$$\hat{x}_1 = \frac{1}{2}$$

$$\hat{x}_2 = 1$$

