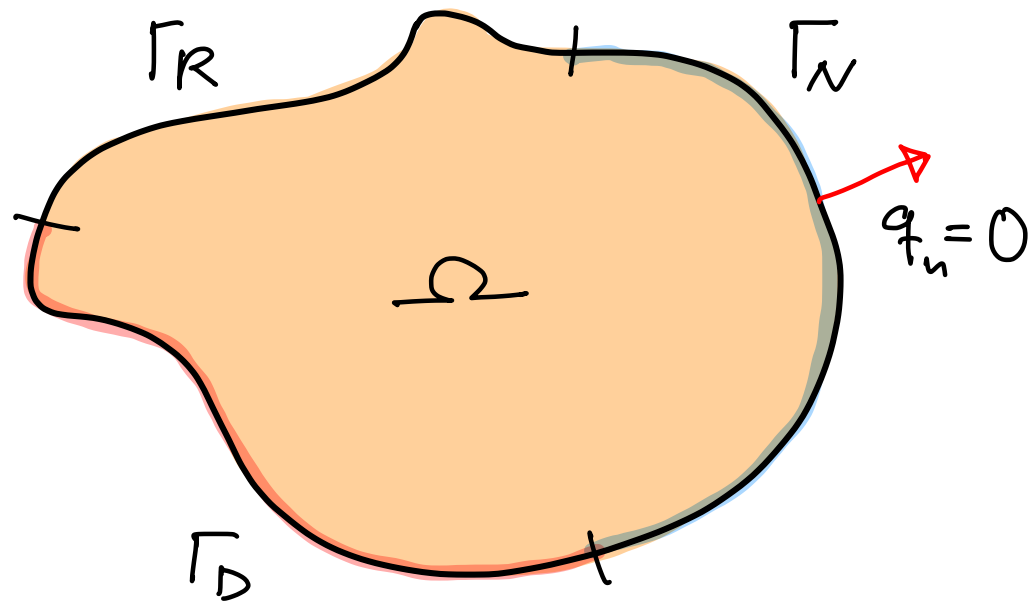


# FEM for 2D problems

Heat conduction: Dirichlet boundary conditions

# Background



(V): Find  $\theta \in V_0$  such that  
$$a(\theta, \delta\theta) = b(\delta\theta)$$
for all  $\delta\theta \in V_0$ . The space  $V_0$  contains "nice" functions  $u: \Omega \rightarrow \mathbb{R}$  with  $u(x, y) = 0$  for  $(x, y) \in \Gamma_D$ .

## Reminder

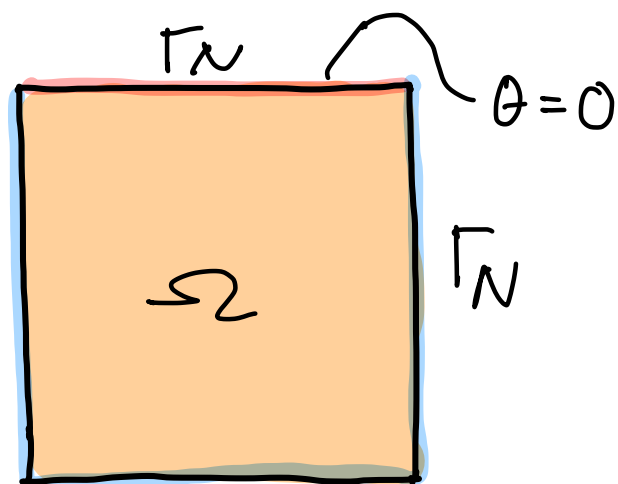
$\nabla\theta(x, y) \cdot \underline{n}(x, y) = 0$  for  $(x, y) \in \Gamma_N$  is (automatically) satisfied by solution of (V). We consider  $\Gamma_R$  later.

## Question

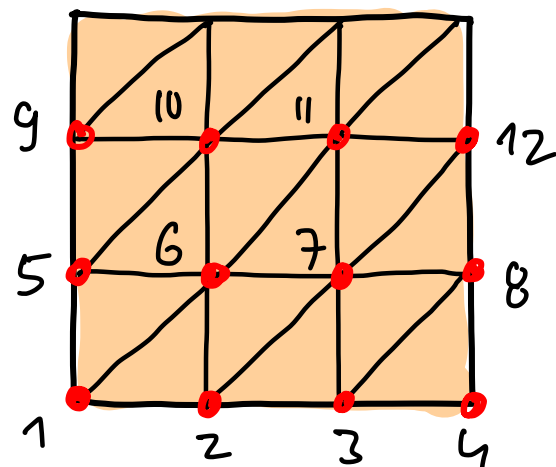
How to make sure that  $\theta_n = \sum \varphi_i \hat{\theta}_i$  is in  $V_0$ ?

# Possible approaches

## Example



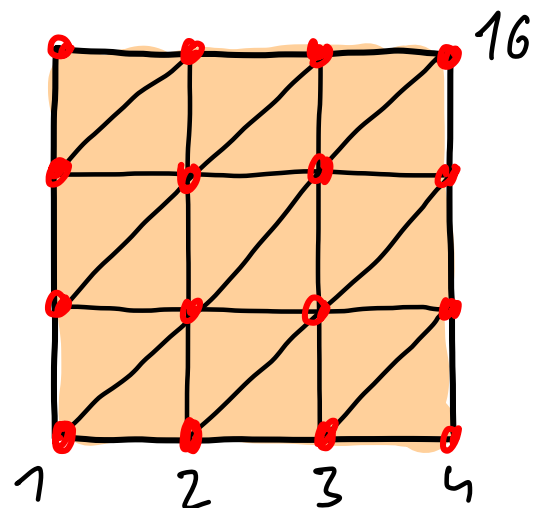
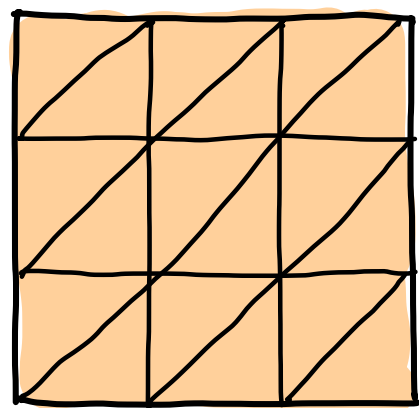
1. Only basis functions  $\varphi_i \in V_0$ , then  $\theta_h \in V_0$



Exclude nodes on  $\Gamma_D$  when assembling the linear system  $\underline{K}$  and  $\underline{r}$ . Requires explicit enumeration of DOFs.

→ Bit complicated for  $\theta^* \neq 0$

2. Basis functions for all nodes



Assemble  $\underline{K}$  and  $\underline{r}$  for all nodes. Requires modification of linear system in order to ensure that  $\hat{\theta}_i = 0$  for all nodes  $(x_i, y_i) \in \Gamma_D$ .

→ Easy to extend to  $\theta^* \neq 0$

# Modification of linear system

## Original system

$$\begin{pmatrix} k_{11} & k_{12} & k_{13} & k_{14} & k_{15} \\ k_{21} & k_{22} & k_{23} & k_{24} & k_{25} \\ k_{31} & k_{32} & k_{33} & k_{34} & k_{35} \\ k_{41} & k_{42} & k_{43} & k_{44} & k_{45} \\ k_{51} & k_{52} & k_{53} & k_{54} & k_{55} \end{pmatrix} \begin{pmatrix} \hat{\theta}_1 \\ \hat{\theta}_2 \\ \hat{\theta}_3 \\ \hat{\theta}_4 \\ \hat{\theta}_5 \end{pmatrix} = \begin{pmatrix} r_1 \\ r_2 \\ r_3 \\ r_4 \\ r_5 \end{pmatrix}$$

$\hat{\theta}_2$  and  $\hat{\theta}_5$  should be zero.

## Modified system

$$\begin{pmatrix} k_{11} & k_{12} & k_{13} & k_{14} & k_{15} \\ 0 & 1 & 0 & 0 & 0 \\ k_{31} & k_{32} & k_{33} & k_{34} & k_{35} \\ k_{41} & k_{42} & k_{43} & k_{44} & k_{45} \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \hat{\theta}_1 \\ \hat{\theta}_2 \\ \hat{\theta}_3 \\ \hat{\theta}_4 \\ \hat{\theta}_5 \end{pmatrix} = \begin{pmatrix} r_1 \\ 0 \\ r_3 \\ r_4 \\ 0 \end{pmatrix}$$

Alternative  
• Lagrange-Multiplikatoren