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# Short-term Strategy Optimization for the Bridgestone World Solar Challenge

#### Subtitle

#### Master's Thesis

Institute for Dynamic Systems and Control Swiss Federal Institute of Technology Zurich

#### Supervision

Giona Fieni Prof. Dr. Second Supervisor

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### Abstract

Abstract goes here

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### Introduction

- 1.1 Motivation
- 1.2 Objective
- 1.3 Context
- 1.4 State of Research
- 1.5 Structure of the report

### System Modeling

- 2.1 Overview
- 2.2 Vehicle Dynamics
- 2.3 Electric Motor Model
- 2.4 Battery Dynamics
- 2.5 Pv Model
- 2.6 Weather Data
- 2.6.1 Global Irradiance
- 2.6.2 Wind
- 2.6.3 Ambient Temperature
- 2.7 Route on Stuart Highway

## Optimal Control Problem

- 3.1 Objective Function
- 3.2 Dynamic Programming and Battery Target
- 3.3 Constraints
- 3.3.1 State Constraints
- 3.3.2 Input Constraints
- 3.3.3 Battery Target Slack Variable

6 3.3. Constraints

## Nonlinear Model Predictive Control

- 4.1 From OCP to a NLP
- 4.1.1 Integration Method
- 4.1.2 Receding Horizon
- 4.1.3 Multiple Shooting
- 4.1.4 Numerical Implementation
- 4.2 Online Race Framework

### Case Studies and Results

#### Appendix A

### Example Appendix Chapter

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organization = {Institute for Dynamic Systems and Control ({IDSC})},
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# Bibliography

[1] A. Ritter, P. Elbert, and C. Onder, *How to Use the IDSCreport LATEX Class*, Version 1.7.0, Institute for Dynamic Systems and Control (IDSC), ETH Zürich, Switzerland, Jan. 2021.



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