Exercise No. 2

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2 - Error analysis of the Euler scheme

a)

At first we write the code for the 2 - body problem by using the forward Euler algorithm. We integrate the problem for one orbit and plot it on a double - logarithmic scale. The error will be plotted as a function of Δt . Therefore we will be using three different eccentricities and various different time steps.

Function that integrates the 2 - body problem using the forward Euler algorithm.

Listing 1: Exercise02a.py

```
import numpy as np
   import matplotlib.pyplot as plt
   plt.figure(figsize = (8,6))
   #function that integrates the 2 - body - problem using the forward
   #euler algorithm. The initial velocity needs to be two dimensional
   #vector, the step size h can be choosen. The program breaks when the
8
   #orbit is complete.
   def euler (v_0, h, s_0 = np.array([0, 1])):
10
                  #list for spatial coordinate
        S = [s_0]
11
       V = [v_0]
                  #list for relative velocity
12
        E = []
                    #list for the Energy
13
        test = 0
                    #variable to check if the orbit is complete
14
        step = 0
        maxstep = 1000000
15
16
        while((test < 2) and (step < maxstep)):</pre>
17
18
            S.append(S[-1] + h * V[-1])
            V.append(V[-1] - h * S[-1] / (np.sqrt(S[-2][0]**2 + S[-2][1]**2)**3))
19
            E.append ((0.5 * (V[-1]**2)[0] + (V[-1]**2)[1]) - (1/((S[-1]**2)[0] + (S[-1]**2)[0])
20
                [-1]**2)[1])**0.5)
21
            if ((S[-1])[0] < 0):
22
23
                test = 1
            if (test == 1 and (S[-1])[0] > 0):
24
25
                test = 2
26
        return np.array(S), np.array(V), np.array(E)
```

Now we plot a circular orbit with the error in energy in a additional plot. The values that were used are given in the code and We repeat the calculation for two more different initial velocities.

Listing 2: Exercise02a.py

```
#for the given initial values the eccentricity is zero,
31
    #therefore the orbit is circular
32
    orbits = [1, 0], [1.3, 0], [.8, 0]
33
34
    for o in orbits:
         S, V, E = euler(np.array(o), 0.0001)
35
36
         plt.plot(S[:, 0], S[:, 1], label="$v_{init}$=" + "{}".format(o[0]))
37
38
    plt.xlabel('x')
    plt.ylabel('y')
39
    plt.legend()
40
    plt.axis('equal')
    plt.savefig('fig_a1.png')
    plt.clf()
    # plt.cla()
45
    # plt.close()
46
47
    for o in orbits:
48
         energyerror = []
49
         H = [0.01, 0.001, 0.0001, 0.00001, 0.00001]
50
         for h in H:
51
              S, V, E = euler(np.array(o), h)
52
              energyerror.append\left(\left(\left.abs\left(E[-1]\right.-\left.E\left[0\right]\right)\right)\right)\ /\ \left(\left.abs\left(E\left[0\right]\right)\right)\right)
53
         plt.plot(H, energyerror, label="$v_{init}$=" + "{}".format(o[0]))
54
55
56
    plt.xscale('log')
    plt.yscale('log')
57
    plt.xlabel('Stepsize_h')
plt.ylabel('error_in_energy')
    plt.legend()
61 plt.savefig('fig_a2.png')
```

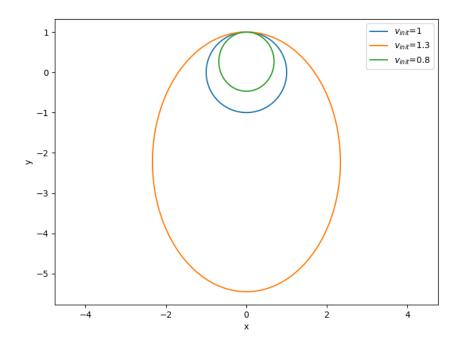


Figure 1: First orbit with forward Euler algorithm

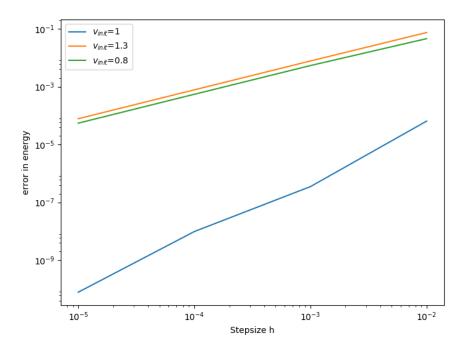


Figure 2: First orbit energy error with forward Euler algorithm

b)

Now we write the code for the 2 - body problem by using the Leapfrog algorithm. We integrate the problem for one orbit and plot it on a double - logarithmic scale. The error will be plotted as a function of Δt . Therefore we will be using three different eccentricities and various different time steps.

Function that integrates the 2 - body problem using the Leapfrog algorithm.

Listing 3: Exercise02b.py

```
1
                 import numpy as np
                 import matplotlib.pyplot as plt
                 plt.figure(figsize = (8,6))
   5
   6
                 \#function\ that\ integrates\ the\ 2-body-problem\ using\ the\ leapfrog
   7
                 #algorithm. The initial velocity needs to be two dimensional
   8
                 #vector, the step size h can be choosen. The program breaks when the
   9
                 #orbit is complete.
10
                 def leapfrog(v_0, h, s_0 = np.array([0, 1])):
11
                                     S = [s_0]
                                                                                            #list for spatial coordinate
                                                                                              #list for relative velocity
12
                                    V = [v_{-}0]
13
                                    E = []
                                                                                              #list for the Energy
                                     #first value for the acceleration
14
                                     a = [-1*(np.array([(S[-1])[0], (S[-1])[1]))/(((S[-1]**2)[0] + (S[-1]**2)[1]))
15
                                                        **1.5)]
                                     test = 0
                                                                                               #variable to check if the orbit is complete
16
17
                                     step = 0
                                     maxstep = 1000000
18
19
20
                                     while((test < 2) and (step < maxstep)):</pre>
                                                         vhalf = V[-1] + 0.5 * h * a[-1]
21
                                                        S.append(S[-1] + h*vhalf)
22
                                                        a.append(-1*(np.array([(S[-1])[0], (S[-1])[1]]))/(((S[-1]**2)[0] + (S[-1])[1])))/(((S[-1]**2)[0] + (S[-1])[1]))/(((S[-1]**2)[0] + (S[-1]**2)[0] + (S[-
23
                                                                          [-1]**2)[1])**1.5)
                                                       V.append(vhalf + 0.5*h*a[-1])
24
                                                         \texttt{E.append} \left( (0.5 * (V[-1] * * 2)[0] + (V[-1] * * 2)[1] \right) - (1/((S[-1] * * 2)[0] + (S[-1] * * 2)[0] \right) \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * * 2)[0] + (S[-1] * * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (S[-1] * 2)[0] + (S[-1] * 2)[0] \\ + (S[-1] * 2)[0] + (
25
                                                                          [-1]**2)[1])**0.5))
26
27
                                                         if ((S[-1])[0] < 0):
28
                                                                            test = 1
29
                                                         if (test == 1 and (S[-1])[0] > 0):
30
                                                                            test = 2
```

Now we plot a circular orbit with the error in energy in a additional plot. The values that were used are given in the code. To be precise we going to use the same values as before and we also repeat the calculation for two more different initial velocities.

Listing 4: Exercise02b.py

```
34
35
   #for the given initial values the eccentricity is zero,
36
   #therefore the orbit is circular
   orbits = [1, 0],[1.3,0],[.8,0]
37
38
39
   for o in orbits:
40
       S, V, E = leapfrog(np.array(o), 0.0001)
        plt.plot(S[:, 0], S[:, 1], label="$v_{\{init\}}$=" + "{}".format(o[0]))
41
42
   plt.xlabel('x')
43
   plt.ylabel('y')
44
   plt.legend()
   plt.axis('equal')
   plt.savefig('fig_b1.png')
   plt.clf()
49
   # plt.cla()
50
   # plt.close()
51
52
   for o in orbits:
53
       energyerror = []
54
       H = [0.01, 0.001, 0.0001, 0.0001, 0.00001]
55
        for h in H:
56
            S, V, E = leapfrog(np.array(o), h)
57
            energyerror.append((abs(E[-1] - E[0])) / (abs(E[0])))
58
        plt.plot(H, energyerror, label="$v_{init}$=" + "{}".format(o[0]))
59
60
   plt.xscale('log')
61
   plt.yscale('log')
62
   plt.xlabel('Stepsize_h')
   plt.ylabel('error_in_energy')
64
   plt.legend()
66 | plt.savefig('fig_b2.png')
```

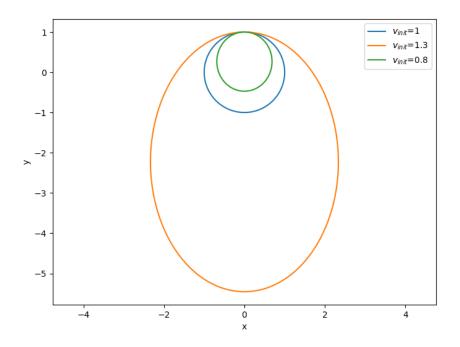


Figure 3: First orbit with leapfrog algorithm

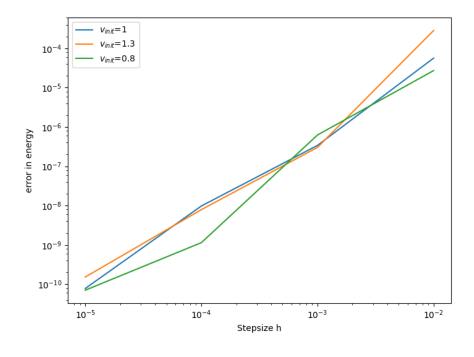


Figure 4: First orbit energy error with leapfrog algorithm

The errors decrease with decreasing time steps for both integration schemes. For the Euler algorithm we expect a drop with $O(h^2)$, for the Leapfrog algorithm $O(h^3)$. This is also what we can observe. The errors of the Leapfrog integration are much smaller than those of the Euler integration. However, the slope of the error-curve is steeper which we also expected. Another difference between the error-plots, of the two integration variants is, that for the Euler integration we get straight lines whereas for the Leapfrog integration the errors seem to scatter around the expected line.