
Introduction to Computational Physics SS2017

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Exercise 8 (June 7, 2017)
Return by noon of June 16, 2017

1 Many Species Population Dynamics

In this exercise we study the evolution of 6 populations according to the following equations for population dynamics: 3 predator- (P_i) and 3 prey-species (N_i), all parameters positive, always $i, j = 1, \dots, 3$:

$$\begin{aligned}\frac{dN_i}{dt} &= N_i \left(a_i - N_i - \sum_j b_{ij} P_j \right) \\ \frac{dP_i}{dt} &= P_i \left(\sum_j c_{ij} N_j - d_i \right)\end{aligned}$$

The parameters chosen are $a_1 = 56$, $a_2 = 12$, $a_3 = 35$; $d_1 = 85$, $d_2 = 9$, $d_3 = 35$; the parameters b_{ij} and c_{ij} are given in matrix form here:

$$\begin{aligned}b_{ij} &= \begin{pmatrix} 20 & 30 & 5 \\ 1 & 3 & 7 \\ 4 & 10 & 20 \end{pmatrix} \\ c_{ij} &= \begin{pmatrix} 20 & 30 & 35 \\ 3 & 3 & 3 \\ 7 & 8 & 20 \end{pmatrix}\end{aligned}$$

Notice: the unusual feature here in the equations is that the prey populations N_i have a growth limiting factor in their equations, which limits their growth even if there is no predator.

Another Notice: please do not try to make the equations dimensionless, just use the numbers given here.

2 Stability Analysis (Homework)

1. (5 points) What are the fixed points for the system of equations given above? Hint: No complicated computations are necessary, the idea is that you should guess the two fixed points very easily. Compare our previous examples.

2. (5 points) What is the Jacobi matrix \mathbf{A} at the non-trivial fixed point?
3. (10 points) Determine the eigenvalues and eigenvectors λ_i and \mathbf{v}_i , $i = 1, \dots, 6$ of \mathbf{A} with Mathematica or any other helpful program you may have.

Choose an initial state $\mathbf{n} = \sum_{i=1}^6 c_i \mathbf{v}_i$, with $c_1 = c_2 = 3$, $c_3 = c_4 = 1$, $c_5 = 5$, $c_6 = 0.1$.

Plot and discuss the time dependent evolution of the six populations (given by this linear model) until instability occurs.