Total No. of Questions: 8	3]
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SEAT No.:	
[Total]	No. Of Pages : 2

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		T.E. (E & TC)
		HONORS IN ROBOTICS
		Robot Programming & Simulation
		(2019 Pattern) (Semester-II) (304183)
Time	: 21/2	Hours [Max. Marks: 70]
		as to the candidates:
	<i>1</i>)	Attempt Q.1 or Q.2 Q.3 or Q.4 Q.5 or Q.6 Q.7 or Q.8.
	2)	Neat diagrams must be drawn wherever necessary.
	<i>3</i>)	Assume suitable data, if necessary.
	<i>4</i>)	Figures to the right indicates full marks.
<i>Q1</i>)	a)	Explain in detail robot language structure. Using VAL language, explain
		the structure of the program for a typical pick and place operation. [6]
	b) \(\bar{b}	Explain any four VAL programming commands with example. [6]
	U)	Explain any four VAL programming continues with example. [6]
	c)	With schematic diagram, explain the robotic applications in welding
		industry. [6]
<i>Q</i> 2)	a)	Explain the four statements of VAL robot programming language. List
		the commands used in VAL programming and describe its functions. [6]
	b)	Explain Wait, DELAY, SIGNAL commands with suitable examples. [6]
	U)	
	c)	List the commands used in VAL II programming and describe its
		functions. [6]
<i>Q3</i>)	a)	List and explain program control statement in AML [6]
	b)	Explain manual and automatic mode of operation of industrial robot. [6]
	U)	Explain manual and automatic mode of operation of industrial robot. [6]
	c)	Explain the various Move master commands with example. [5]
		OR (C.)

<i>Q4</i>)	a)	List and explain the sensor commands used in AML language with exam	ple. [6]
	b)	Describe the elements and function used in AML robotic language.	[5]
	c)	Which syntax move master command language uses? List and exp different types of commands.	lain [6]
Q5)	a)	What is robotic process automation? Explain with an example.	[6]
	b)	Describe use of Computer vision, Augmented Reality & Virtual Reality robotics.	ty in [6]
	c)	Discuss how collision detection works in robotics. OR	[6]
Q6)	a)	Write in brief about robot work planning.	[6]
	b)	Why is repeatability of robot is important explain in detail?	[6]
	c)	Describe in brief about robot studio online software.	[6]
Q7)	a)	Explain basic steps in simulation with example.	[6]
	b)	Write in brief about Monte Carlo method of simulation.	[6]
	c)	Distinguish between hybrid and Analog model.	[5]
		OR	
<i>Q8</i>)	a)	Write classification of simulation software	[6]
	b)	Write in brief about cobweb models continuous models.	[6]
	c)	Write in brief about distributed lag models.	[5]
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