Total No. of Questions: 8]				9	5	SEAT No. :					
P473						[Total]	No. of Pages	s:2			
[6003] 581 T.E. (Computer Engineering) (Honors)											
VIRTUAL REALITY AUGMENTED REALITY											
Augmented Reality											
(2019 Pattern) (Semester - II) (310703)											
Time: 2½ Hours] Instructions to the candidates:						[Max. Marks : 70					
	исп 1)		ine canaiaates: er Q.1 or Q.2, Q.3 or Q	0.4, Q.5 or Q.6,	Q.7 or Q.8	3.					
	2) 3)		liagrams must be draw es to the right indicate		essary.	-90					
	3)	rigur	es to the right indicate	juu marks.							
Q 1)	a)	Exp	lain in detail role of (Computer Visi	on in Aug	omented Re	eality	[9]			
Q1)	b)	. 9	lain outdoor tracking	•			arry.	[8]			
	U)	D. A.	iam outdoor tracking		Y)		լօյ			
		× ′		OR	0.						
Q2)	a)	Exp	lain natural feature tr	racking by dete	ection in a	augmented	reality.	[9]			
	b)		v pose estimation for	rom Homogra	phy is d	lone in ma	rker tracki				
		Expl	iain.	0, 10,				[8]			
				2 00				25			
Q 3)	a)	Exp	lain marker based tra	acking in detail	ls?		,	[6]			
	b) What are different types of marker			of markers?			, S	[6]			
c) What is scene generator?			?			.5	[6]				
			80.	OR		29	C.Y.				
Q4)	a)	Writ	te note on: (Any 2)					[6]			
		i)	Template markers			2, 6					
		ii)	2D barcode market	rs							
		iii)	Imperceptible mark			O.X.					
	b)	,		· ·	xplain			[6]			
	b) When to use marker-based tracking. Explain.c) How to select a marker type. Explain with respect to system in										
	-)	110 (. 15 Solovi a marker t	JPC. Zapium W	X Sp	220 03 03 0001	requirem	[6]			
				8.			P'	T.O.			
				V .			4.1				

<i>Q5</i>)	a)	Explain with diagram monitor based augmented reality display.						
	b)	Explain different components of augmented reality.	[8]					
		OR						
Q6)	a)	a) Compare optical see-through and video see-through head mounted d						
	b)	Explain virtual retinal systems.	[8]					
Q7)	a)	Explain the working of SLAM technique.	[9]					
	b)	What is mixed reality? Explain the different application of mixed realit OR	y. [9]					
Q 8)	a)	Explain the difference between computer vision and mixed reality.	[9]					
	b)	Explain parallel tracking and mapping (PTAM) in detail.	[9]					
		Service of the servic						
[600	03]-5	2 2 2						