

Total No. of Questions : 8]

SEAT No. :

PA-1630

[Total No. of Pages : 2

[5926]-264

T.E. (Honors)

ROBOTICS

Principles of Robotics

(2019 Pattern) (Semester - I) (304181HR)

Time : 2½ Hours]

[Max. Marks : 70

Instructions to the candidates:

- 1) Attempt all questions : Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6 & Q.7 or Q.8.
- 2) Draw sketches where required.

Q1) a) State the factors in selection and design of grippers. [9]

b) Explain with neat sketch Mechanical grippers. [9]

OR

Q2) a) State and explain various tools used as end effectors. [9]

b) Explain with neat sketch Tactile Sensor Gripper. [9]

Q3) a) Explain with neat sketch piezo electric sensors. [8]

b) Explain with neat sketch LVDT sensor. [9]

OR

Q4) a) Explain with neat sketch Force sensors. [9]

b) Explain with neat sketch range sensors. [8]

Q5) a) Enlist steps in forward kinematic analysis. [9]

b) Explain with neat sketch D-H parameter. [9]

OR

Q6) a) State properties of generalised composite Rotation matrix. [9]

b) A 2 DOF planar RR manipulator has  $L_1 = 120\text{mm}$  &  $L_2 = 75\text{mm}$ . Determine joint angles using geometric approach, so that face end is located at ( 100, 70). [9]

P.T.O.

- Q7)** a) Explain various Image processing Techniques in Robotics . [9]  
b) State and explain economic aspects in Robotics. [8]

OR

- Q8)** a) What is Robot safety. Explain 5 groups of Humans that are at risk of direct injury from Robot. [9]  
b) Write notes on (any 2). [8]  
i) Agriculture & farming.  
ii) Home sector.  
iii) Service sector.  
iv) Research & exploration.

