

Name:

ID:.....

1. (a) smallest, largest (2) _____
(b) number of numbers (1) _____
(c) fraction, distance (2) _____
(d) fraction, distance (2) _____

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2. (a) r1, r2, errors (2) _____
(b) new r1 (2) _____
(c) improved algorithm (2) _____
(d) improved r1, r2, errors (2) _____
(e) improved r1, r2, errors (2) _____

...../10

3. stability analysis

...../5

4. (a) quadratic interpolating spline (2) _____
(b) plot (2) _____

...../4

5. not-a-knot spline

...../6

6. (1) plots (2), code (2) (4) _____
(2) plots (2), code (2) (4) _____
(3) plots (2), code (6) (8) _____

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Total: (48) _____

1. (a) The smallest positive number is 0.1×2^{-1022} ; the largest is $0.\underbrace{1\dots1}_{53 \text{ one's}} \times 2^{1023}$ ■

(b) F has

$$|F| = \underbrace{1}_{\text{for 0}} + \underbrace{1}_{\text{leading one}} \times \underbrace{2^{52}}_{52 \text{ remaining digits}} \times \underbrace{(1022 + 1023)}_{\text{exponents of 2}} \\ = 1 + 2025(2^{52})$$

(c) Rewrite the inequality:

$$1 \leq x < 2 \iff 0.1 \times 2^1 \leq x < 0.1 \times 2^2$$

$$\text{Fraction} = \frac{\underbrace{1}_{\text{leading one}} \times \underbrace{2^{52}}_{52 \text{ remaining digits}} \times \underbrace{1}_{\text{one exponent}}}{|F|} \approx 0.0004938$$

The distance for consecutive numbers is $1 \times 2^{-53} \times 2 = 2^{-52}$ ■

(d) Rewrite the inequality:

$$\frac{1}{64} \leq x < \frac{1}{32} \iff \frac{1}{2^6} \leq x < \frac{1}{2^5} \iff 0.1 \times 2^{-5} \leq x < 0.1 \times 2^{-4}$$

$$\text{Fraction} = \frac{1 \times 2^{52} \times 1}{|F|} \approx 0.0004938$$

The distance for consecutive numbers is $1 \times 2^{-53} \times 2^{-5} = 2^{-58}$ ■

2. (a) First calculate the parts:

$$b^2 = 12345.4321 \approx 12345$$

$$4ac = 4 \times 1 \times 1.2121 = 4.8484$$

$$b^2 - 4ac = 12340.1516 \approx 12340$$

$$\sqrt{b^2 - 4ac} = 111.085552615990527825 \dots \approx 111.09$$

$$-b + \sqrt{b^2 - 4ac} = -0.02$$

$$-b - \sqrt{b^2 - 4ac} = -222.2$$

Hence, $(fl(r_1), fl(r_2)) \approx (-0.01, -111.1)$. By calculator,
 $(r_1, r_2) \approx (-0.0109100803694867128, -111.099089919630513287)$.
Hence, the errors are $(\delta_{r_1}, \delta_{r_2}) \approx (0.083416, -8.1916 \times 10^{-6})$. ■

(b) Rationalize the numerator:

$$\begin{aligned}
r_1 &= \frac{\sqrt{b^2 - 4ac} - b}{2a} \\
&= \frac{(\sqrt{b^2 - 4ac} - b) \times (\sqrt{b^2 - 4ac} + b)}{2a \times (\sqrt{b^2 - 4ac} + b)} \\
&= \frac{b^2 - 4ac - b^2}{2a \times (\sqrt{b^2 - 4ac} + b)} \\
&= \frac{-2c}{\sqrt{b^2 - 4ac} + b} \\
&= \frac{2c}{-b - \sqrt{b^2 - 4ac}}
\end{aligned}$$

As required. ■

(c) Derive r_2 in term of r_1 :

$$\begin{aligned}
r_2 &= \frac{-b - \sqrt{b^2 - 4ac}}{2a} \\
&= \frac{-(b + \sqrt{b^2 - 4ac})}{2a} \\
\implies &= \frac{-(b^2 - b^2 - 4ac)}{2a \times (b - \sqrt{b^2 - 4ac})} \\
&= \frac{2c}{b - \sqrt{b^2 - 4ac}} \\
\implies &= \frac{-2c}{-b + \sqrt{b^2 - 4ac}} \\
\implies &= \frac{-2c}{\frac{-b + \sqrt{b^2 - 4ac}}{2a} \times 2a} \\
&\implies = \frac{-c}{ar_1}
\end{aligned}$$

Algorithm R.

if $b > 0$ then

$$\begin{aligned}
r_2 &= \frac{-b - \sqrt{b^2 - 4ac}}{2a} \\
r_1 &= \frac{c}{ar_2}
\end{aligned}$$

else

$$\begin{aligned}
r_1 &= \frac{\sqrt{b^2 - 4ac} - b}{2a} \\
r_2 &= \frac{-c}{ar_1}
\end{aligned}$$

end ■

(d)

$$r_2 = -111.1 \text{ (from before)}$$

$$r_1 = \frac{1.2121}{1 \times -111.1} = -0.010910$$

Hence, the errors $(\delta_{r_1}, \delta_{r_2}) \approx (7.3665 \times 10^{-6}, -8.1916 \times 10^{-6})$. Unlike (a), the errors for (d) are close to 0. Hence, Algorithm R is a better algorithm than the one used in (a). ■

(e)

$$b^2 = 111.1^2 = 12343.21 \approx 12340$$

$$4ac = 4 \times 1 \times 1.212 \approx 4.848$$

$$b^2 - 4ac = 12335.152 \approx 12340$$

$$\sqrt{b^2 - 4ac} = 111.0855526 \dots \approx 111.1$$

$$-b - \sqrt{b^2 - 4ac} = -222.2$$

$$r_2 = -111.1$$

$$r_1 = \frac{1.212}{1 \times -111.1} = -0.01090909 \dots \approx -0.01090$$

Hence, the errors $(\delta_{r_1}, \delta_{r_2}) \approx (9.2395 \times 10^{-4}, -8.1916 \times 10^{-6})$. Unlike (a), the errors for (d) are close to 0. Hence, Algorithm R is a better algorithm than the one used in (a). ■

3. Take the limit of p_n :

$$\begin{aligned} \lim_{n \rightarrow \infty} p_n &= a \lim_{n \rightarrow \infty} 7^n + b \lim_{n \rightarrow \infty} \frac{1}{7^n} \\ &= a \lim_{n \rightarrow \infty} 7^n + 0 \end{aligned}$$

But a , which is a constant based on p_0 and p_1 , $a = \frac{1}{48}(7(\frac{1}{7}) - 1) = 0$. Hence the limit goes to zero. Therefore, the given computation is stable. ■

4. (a) Check whether $q(S) = \hat{f}(S)$ at $S1, S2, S3$, and continuity:

$$q(99.9) = 50(99.9 - 99.9)^2 = \hat{f}(99.9) = 0$$

$$q(100) = 50(100 - 99.9)^2 = 1 - 50(100 - 100.1)^2 = \hat{f}(100) = 0.5$$

$$q(100.1) = 1 - 50(100.1 - 100.1)^2 = \hat{f}(100.1) = 1$$

Hence q is continuous at $S1, S2, S3$ and contains the break-points. Now check the

continuity of q' :

$$q'(S) = \begin{cases} 0 & \text{if } S \leq 99.9 \\ 100(S - 99.9) & \text{if } 99.9 \leq S \leq 100 \\ -100(S - 100.1) & \text{if } 100 \leq S \leq 100.1 \\ 0 & \text{if } S \geq 100.1 \end{cases}$$

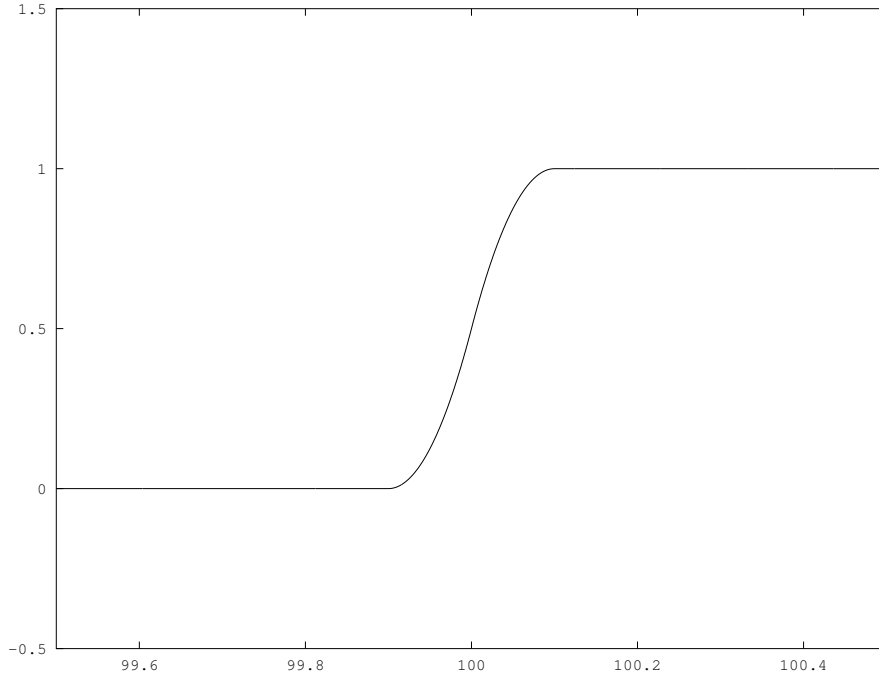
$$q'(99.9) = 100(99.9 - 99.9) = 0$$

$$q'(100) = 100(100 - 99.9) = -100(100 - 100.1) = 10$$

$$q'(100.1) = -100(100.1 - 100.1) = 0$$

Hence, q' is continuous at the break points. Also, since $\hat{f}'(S) = 0$ for all S , $q'(S_1) = 0 = \hat{f}'(S_1)$ and $q'(S_3) = 0 = \hat{f}'(S_3)$. Hence, the end conditions are satisfied. Therefore, q is a quadratic interpolating spline for \hat{f} at S_1, S_2, S_3 . ■

(b) The graph:



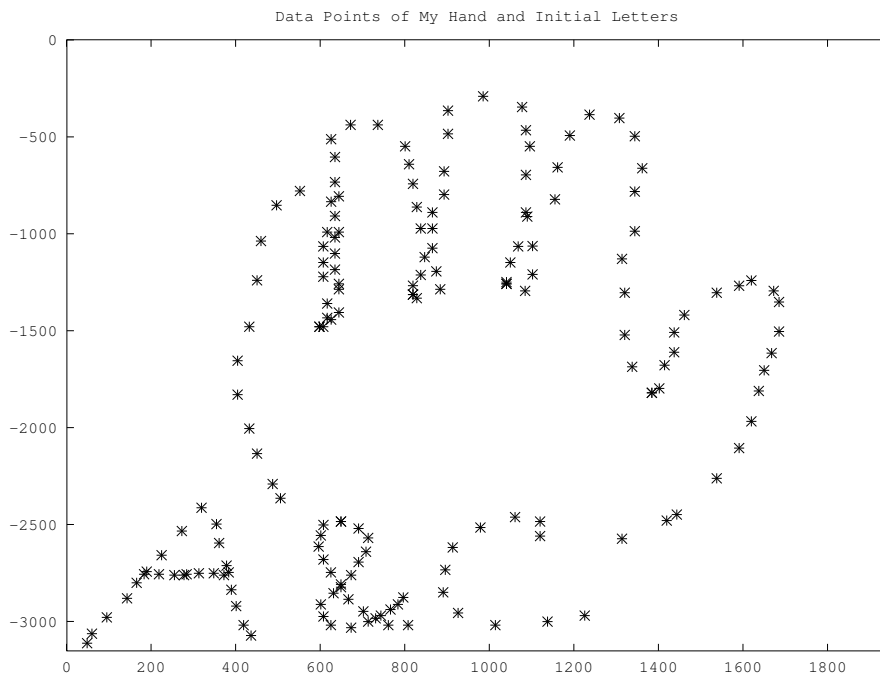
5. First, the end conditions of not-a-knot cubic spline implies $S'''(x_1) = S'''(x_2)$ and $S'''(x_2) = S'''(x_3)$. Hence,

$$S'''(x_1) = S'''(x_2) = S'''(x_3)$$

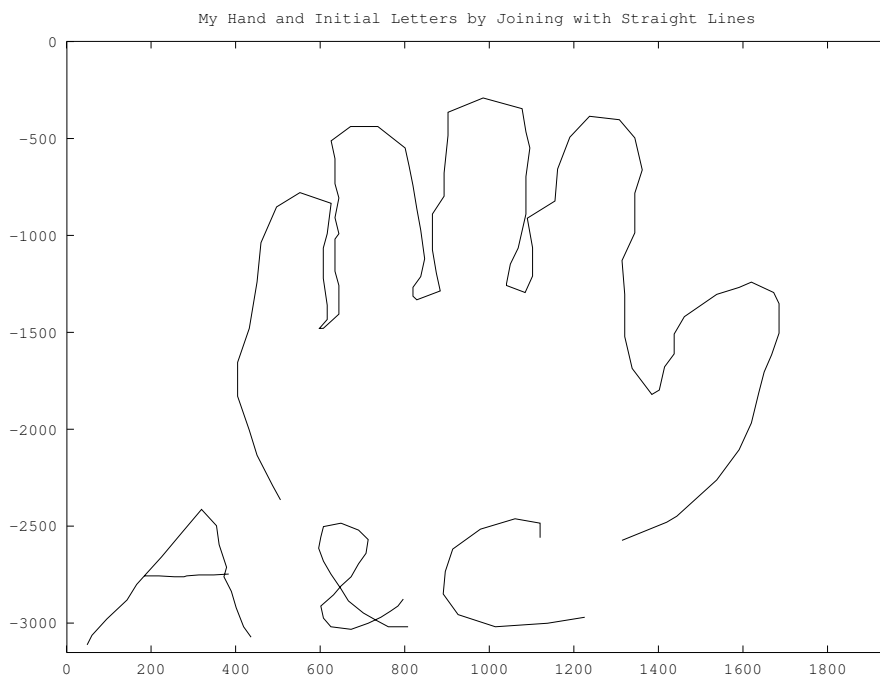
But $P'''(x) = 6$, a constant, which fits the end conditions of S . Secondly, P and its first and second derivatives are continuous, because P is a polynomial (fact). Lastly, P maps all $(x_i, y_i), i \in \{1, 2, 3, 4\}$. Therefore, P is a not-a-knot spline interpolant for S . ■

6. The graphs:

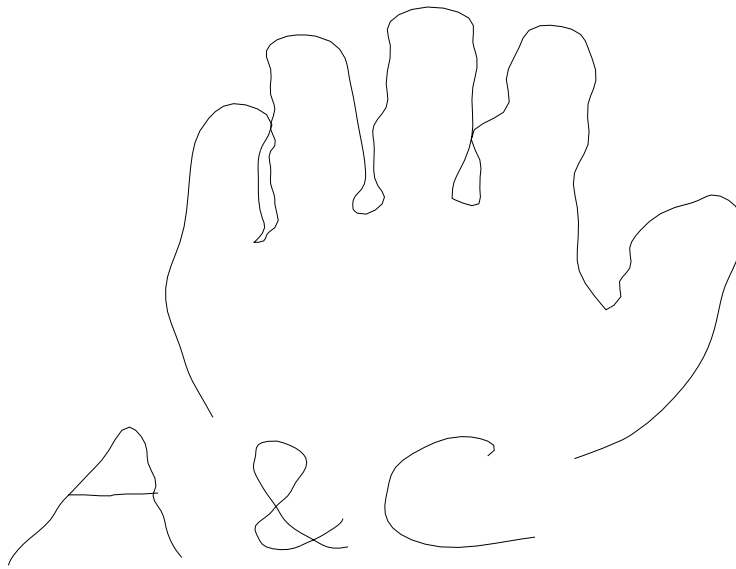
(a) The Data Points



(b) Data Points Connected With Straight Lines



(c) Data Points With Interpolation



The codes (assuming that the splines package is already being loaded):

- `init.m` (only used in extraction of data points)

```
1 data = imread('hand_final.png');
2 clf;
3 h = imagesc(data);
4 axis image;
5 [x, y] = ginput;
```

- `findt.m` (helper function for the generation of the `t` parameters)

```
1 function [t] = findt(x,y)
2     len = length(x);
3     t = zeros(1, len);
4     for p = 2:length(x)
5         prev = p-1;
6         distance = sqrt((x(prev) - x(p))^2 + (y(prev)-y(p))^2);
7         t(p) = t(prev) + distance;
8     end
9 endfunction
```

- `refinet.m` (helper function for refining `t`)

```
1 function [tref] = refinet(t,fac)
2     N = length(t);
3     tref = zeros(1, fac*(N-1) + 1);
```

```

4   for k = 1:N-1
5       i = fac*(k-1)+1;
6       dt = t(k+1)-t(k);
7       for l = 0:fac-1
8           tref(i+l) = t(k) + l*dt/fac;
9       end
10  end
11  tref(fac*(N-1)+1) = t(N);
12 endfunction

```

- interpolate.m (helper function that returns the interpolated vectors)

```

1 function [tx ty] = interpolate(x,y,end_type,refine_fac)
2     t = findt(x,y);
3     ppx = csape(t,x,end_type);
4     ppy = csape(t,y,end_type);
5     tref = refinet(t,refine_fac);
6     tx = ppval(ppx,tref);
7     ty = ppval(ppy,tref);
8 endfunction

```

- alq6.data.m (the data)

```

1 % initials data
2 x0 = [48.833 60.161 95.407 143.239 165.897 189.813 225.058
       272.891 319.465 354.710 361.004 378.626 372.333 389.955
       401.284 418.907 436.529];
3 y0 = [3112.3 3063.2 2979.2 2881.0 2800.7 2743.1 2658.2 2533.5
       2413.6 2497.6 2595.8 2712.0 2761.1 2836.6 2920.7 3018.9
       3072.7];
4 x1 = [183.52 218.76 255.27 277.93 284.22 313.17 348.42
       383.66];
5 y1 = [2756.4 2756.4 2761.1 2761.1 2756.4 2751.6 2751.6
       2746.9];
6 x2 = [649.26 607.72 601.43 596.39 607.72 625.34 649.26 666.88
       702.13 731.08 761.29 807.86];
7 y2 = [2484.4 2502.3 2556.2 2613.8 2680.8 2746.9 2823.4 2885.7
       2948.0 2983.9 3018.9 3018.9];
8 x3 = [796.53 783.95 766.32 743.67 713.46 673.18 625.34 607.72
       601.43 631.64 649.26 673.18 690.80 708.42 713.46 690.80
       649.26];
9 y3 = [2876.3 2912.2 2938.6 2969.8 3000.9 3032.1 3018.9 2974.5
       2912.2 2854.6 2809.2 2761.1 2694.0 2640.2 2569.4 2520.3
       2484.4];
10 x4 = [1120.03 1120.03 1060.87 979.05 913.60 895.97 890.94
       926.18 1014.30 1137.66 1225.77];

```



```

11 y4 = [2559.9 2484.4 2461.7 2515.6 2618.5 2733.7 2849.8 2956.5
      3018.9 3000.9 2969.8];
12
13 % hand data
14 x5 = [506.07 487.64 450.77 432.34 404.69 404.69 432.34 450.77
      459.99 496.86 552.15 625.89 616.67 607.45 607.45 607.45
      616.67 616.67 598.24];
15 y5 = [2364.5 2290.8 2134.1 2005.1 1830 1654.8 1479.7 1240.1
      1037.3 853.01 779.28 834.58 991.26 1065 1147.9 1221.7
      1359.9 1433.6 1479.7];
16 x6 = [598.24 607.45 625.89 644.32 644.32 644.32 635.1 635.1
      635.1 644.32 635.1 644.32 635.1 635.1 625.89 671.97 736.48
      801 810.21 819.43 828.65 837.86 847.08 837.86 819.43
      819.43];
17 y6 = [1479.7 1479.7 1442.9 1406 1286.2 1258.5 1184.8 1101.9
      1018.9 991.26 908.31 806.93 733.2 604.17 512.01 438.28
      438.28 548.87 641.04 742.42 862.23 972.83 1120.3 1212.5
      1267.8 1313.8];
18 x7 = [819.43 828.65 883.94 874.73 865.51 865.51 865.51 893.16
      893.16 902.38 902.38 985.32 1077.5 1086.7 1095.9 1086.7
      1086.7 1068.3 1049.8 1040.6 1040.6];
19 y7 = [1313.8 1332.3 1286.2 1194 1074.2 972.83 889.88 797.72
      677.9 484.36 364.55 290.82 346.11 465.93 548.87 696.34
      889.88 1065 1147.9 1249.3 1258.5];
20 x8 = [1040.6 1084.8 1102.4 1102.4 1089.8 1155.3 1161.6 1190.5
      1237.1 1307.6 1344.1 1361.7 1344.1 1344.1 1313.9 1320.2
      1320.2 1337.8 1384.4];
21 y8 = [1258.5 1294.6 1209.7 1063.3 911.27 822.51 657.26 492.96
      385.31 403.26 496.74 661.98 781.9 986.81 1129.4 1304.1
      1522.2 1686.5 1820.6];
22 x9 = [1384.4 1402 1414.6 1437.2 1437.2 1461.2 1537.9 1590.8
      1619.8 1672.6 1685.2 1685.2 1667.6 1650 1637.4 1619.8
      1590.8 1537.9 1443.5 1419.6 1313.9];
23 y9 = [1820.6 1797.9 1678 1611 1509 1419.3 1304.1 1268.2
      1240.8 1294.6 1352.2 1504.3 1615.7 1704.4 1811.1 1967.9
      2105.8 2261.6 2448.5 2479.7 2573.2];
24 axis_dim = [1 1942 -3152 1];

```

- alq6a.m (plot of the data points)

```

1 clear
2 alq6_data; % load data
3
4 plot(x0,-y0,'*', x1,-y1,'*', x2,-y2,'*', x3,-y3,'*', x4,-y4,'
      *', x5, -y5,'*', x6,-y6,'*', x7,-y7,'*', x8,-y8,'*', x9,-y9

```

```

    , '*' );
5
6 title('Data Points of My Hand and Initial Letters');
7 axis(axis_dim);

```

- alq6b.m (plot of the data points that are connected by lines)

```

1 clear
2 alq6_data; % load data
3
4 plot(x0,-y0, x1,-y1, x2,-y2, x3,-y3, x4,-y4, x5,-y5, x6,-y6,
      x7,-y7, x8,-y8, x9,-y9);
5
6 title('My Hand and Initial Letters by Joining with Straight
      Lines');
7 axis(axis_dim);

```

- alq6c.m (plot of the interpolated data)

```

1 clear
2 type = 'not-a-knot';
3 type2 = 'complete';
4 fac = 3;
5
6 alq6_data; % load data
7
8 % interpolate initials
9 [tx0 ty0] = interpolate(x0,y0,type,fac);
10 [tx1 ty1] = interpolate(x1,y1,type,fac);
11 [tx2 ty2] = interpolate(x2,y2,type,fac);
12 [tx3 ty3] = interpolate(x3,y3,type,fac);
13 [tx4 ty4] = interpolate(x4,y4,type,fac);
14
15 % interpolate hand
16 [tx5 ty5] = interpolate(x5,y5,type2,fac);
17 [tx6 ty6] = interpolate(x6,y6,type2,fac);
18 [tx7 ty7] = interpolate(x7,y7,type2,fac);
19 [tx8 ty8] = interpolate(x8,y8,type2,fac);
20 [tx9 ty9] = interpolate(x9,y9,type2,fac);
21
22 plot(tx0,-ty0, x1,-y1, tx2,-ty2, tx3,-ty3, tx4,-ty4, tx5,-ty5
      , tx6,-ty6, tx7,-ty7, tx8,-ty8, tx9,-ty9);
23 title('My Hand and Initial Letters by Interpolation');
24 axis(axis_dim);
25 axis off;

```