1 REPLICATED SOFTMAX MODEL

1.1 Replicated Softmax Model

Salakhutdinov and Hinton (2009) proposed the Replicated Softmax to model and extract low-dimensional latent semantic representations of an unstructured collection of documents. The authors applied the Replicated Softmax to a Natural Language Problem known as topic modelling where the topic of a document is defined based on its words probability distribution. As a basic engine, the Replicated Softmax uses a variation of the Restricted Boltzmann Machine.

Salakhutdinov (2015) published a compilation of Generative Models, and we will consider his notation in the followin explanation.

Considering a dictionary that has K words, a document with D words, and $\mathbf{h} \in \{0, 1\}^F$ stochastic hidden units. Let $\mathbf{V}$ be an $D \times K$ observed binary matrix whose entries $v_{ik} = 1$ means the ith word of the document is the kth word of the dictionary, and $v_{ik} = 0$ otherwise. For a state $\{\mathbf{V}, \mathbf{h}\}$, the energy is defined as follows:

$$E(\mathbf{V}, \mathbf{h}) = -\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K} W_{ijk} h_j v_{ik} - \sum_{i=1}^{D}\sum_{k=1}^{K} v_{ik} b_{ik} - \sum_{j=1}^{F} h_j a_j, \tag{1}$$

where the set of parameters $\{\mathbf{W}, \mathbf{b}, \mathbf{a}\}$ refers to the set of model parameters. $\mathbf{W}$ is the weight tensor, each element W_{ijk} is a symmetric interaction between a visible unit i that takes on value k and a hidden unit j, b_{ik} is the bias of unit i that takes on value k, and a_j is the bias of hidden unit j.

The normalized joint probability of state $\{\mathbf{V}, \mathbf{h}\}$ is given by:

$$P(\mathbf{V}, \mathbf{h}) = \frac{e^{-E(\mathbf{V}, \mathbf{h})}}{Z}, \tag{2}$$

where Z is the partition function, the normalization constant to keep the probability within interval $[0, 1]$:

$$Z = \sum_{\mathbf{V}'}\sum_{\mathbf{h}'} e^{-E(\mathbf{V}', \mathbf{h}')}. \tag{3}$$

The marginal probabilities of the visible binary matrix $\mathbf{V}$ and of the hidden binary vector $\mathbf{h}$ are, respectively:

$$P(\mathbf{V}) = \frac{1}{Z}\sum_{\mathbf{h}} e^{-E(\mathbf{V}, \mathbf{h})}, \tag{4}$$

$$P(\mathbf{h}) = \frac{1}{Z}\sum_{\mathbf{V}} e^{-E(\mathbf{V}, \mathbf{h})}. \tag{5}$$

From the joint and marginal probability, we are able to derive the conditional probabilities for the hidden units $P(\mathbf{h}|\mathbf{V})$ given the visible matrix $\mathbf{V}$:

$$P(\mathbf{h}|\mathbf{V}) = \frac{P(\mathbf{V},\mathbf{h})}{P(\mathbf{V})}. \tag{6}$$

Equation (6), by definition, devides equation (2) by equation (4):

$$P(\mathbf{h}|\mathbf{V}) = \frac{\frac{1}{Z}e^{-E(\mathbf{V},\mathbf{h})}}{\frac{1}{Z}\sum_{\mathbf{h}'}e^{-E(\mathbf{V},\mathbf{h}')}} \tag{7}$$

$$= \frac{\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K}W_{ijk}h_j v_{ik} + \sum_{i=1}^{D}\sum_{k=1}^{K}v_{ik}b_{ik} + \sum_{j=1}^{F}h_j a_j\right)}{\sum_{\mathbf{h}'}\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K}W_{ijk}h_j' v_{ik} + \sum_{i=1}^{D}\sum_{k=1}^{K}v_{ik}b_{ik} + \sum_{j=1}^{F}h_j' a_j\right)}$$

$$= \frac{\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K}W_{ijk}h_j v_{ik} + \sum_{j=1}^{F}h_j a_j\right)\exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K}v_{ik}b_{ik}\right)}{\left[\sum_{\mathbf{h}'}\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K}W_{ijk}h_j' v_{ik} + \sum_{j=1}^{F}h_j' a_j\right)\right]\exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K}v_{ik}b_{ik}\right)}$$

$$= \frac{\exp\left[\sum_{j=1}^{F}h_j\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}{\sum_{\mathbf{h}'}\exp\left[\sum_{j=1}^{F}h_j'\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}$$

$$= \frac{\prod_{j=1}^{F}\exp\left[h_j\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}{\sum_{h_1'\in\{0,1\}}\cdots\sum_{h_F'\in\{0,1\}}\left\{\prod_{j=1}^{F}\exp\left[h_j'\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]\right\}}$$

$$= \frac{\prod_{j=1}^{F}\exp\left[h_j\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}{\left\{\sum_{\substack{h_1'\\\in\{0,1\}}}\exp\left[h_1'\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{i1k}v_{ik} + a_1\right)\right]\right\}\cdots\left\{\sum_{\substack{h_F'\\\in\{0,1\}}}\exp\left[h_F'\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{iFk}v_{ik} + a_F\right)\right]\right\}}$$

$$= \frac{\prod_{j=1}^{F}\exp\left[h_j\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}{\left[1+\exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{i1k}v_{ik} + a_1\right)\right]\cdots\left[1+\exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{iFk}v_{ik} + a_F\right)\right]}$$

$$= \prod_{j=1}^{F}\frac{\exp\left[h_j\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}{\left[1+\exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K}W_{ijk}v_{ik} + a_j\right)\right]}$$

$$P(\mathbf{h}|\mathbf{V}) = \prod_{j=1}^{F} P(h_j|\mathbf{V}), \tag{8}$$

where, considering the probability of $h_j = 1$ given $\mathbf{V}$, than equation (8) for a hidden unit j is written as:

$$P(h_j = 1|\mathbf{V}) = \frac{\exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K} W_{ijk}v_{ik} + a_j\right)}{\left[1 + \exp\left(\sum_{i=1}^{D}\sum_{k=1}^{K} W_{ijk}v_{ik} + a_j\right)\right]} = \sigma\left(\sum_{i=1}^{D}\sum_{k=1}^{K} W_{ijk}v_{ik} + a_j\right), \tag{9}$$

which is also known as the logistic function $\sigma(x) = \frac{1}{1+e^{-x}}$. Thus, as in an common restricted Boltzmann Machine, each of the hidden units have an activation probability given by the logistic function.

On the other hand, the conditional probability of the visible units given the state of the hidden units $P(\mathbf{V}|\mathbf{h})$ is given by:

$$P(\mathbf{V}|\mathbf{h}) = \frac{P(\mathbf{V}, \mathbf{h})}{P(\mathbf{h})}. \tag{10}$$

The following derivation of equation (10) is not quite straight forward, and we will try to keep it as clear as possible:

$$P(\mathbf{V}|\mathbf{h}) = \frac{\frac{1}{Z}e^{-E(\mathbf{V},\mathbf{h})}}{\frac{1}{Z}\sum_{\mathbf{V}'} e^{-E(\mathbf{V}',\mathbf{h})}} \tag{11}$$

$$= \frac{\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K} W_{ijk}h_j v_{ik} + \sum_{i=1}^{D}\sum_{k=1}^{K} v_{ik}b_{ik} + \sum_{j=1}^{F} h_j a_j\right)}{\sum_{\mathbf{V}'}\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K} W_{ijk}h_j v'_{ik} + \sum_{i=1}^{D}\sum_{k=1}^{K} v'_{ik}b_{ik} + \sum_{j=1}^{F} h_j a_j\right)}$$

$$= \frac{\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K} W_{ijk}h_j v_{ik} + \sum_{i=1}^{D}\sum_{k=1}^{K} v_{ik}b_{ik}\right)\exp\left(\sum_{j=1}^{F} h_j a_j\right)}{\left[\sum_{\mathbf{V}'}\exp\left(\sum_{i=1}^{D}\sum_{j=1}^{F}\sum_{k=1}^{K} W_{ijk}h_j v'_{ik} + \sum_{i=1}^{D}\sum_{k=1}^{K} v'_{ik}b_{ik}\right)\right]\exp\left(\sum_{j=1}^{F} h_j a_j\right)}$$

$$= \frac{\exp\left[\sum_{i=1}^{D}\sum_{k=1}^{K} v_{ik}\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\sum_{\mathbf{V}'}\exp\left[\sum_{i=1}^{D}\sum_{k=1}^{K} v'_{ik}\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}$$

$$= \frac{\prod\limits_{i=1}^{D} \prod\limits_{k=1}^{K} \exp\left[v_{ik}\left(\sum\limits_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\sum\limits_{\mathbf{V}'}\left\{\prod\limits_{i=1}^{D}\prod\limits_{k=1}^{K}\exp\left[v'_{ik}\left(\sum\limits_{j=1}^{F}W_{ijk}h_j + b_{ik}\right)\right]\right\}}$$

$$= \frac{\prod\limits_{i=1}^{D} \prod\limits_{k=1}^{K} \exp\left[v_{ik}\left(\sum\limits_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\sum\limits_{\mathbf{V}'_1}\sum\limits_{\mathbf{V}'_2}\cdots\sum\limits_{\mathbf{V}'_D}\left\{\prod\limits_{i=1}^{D}\prod\limits_{k=1}^{K}\exp\left[v'_{ik}\left(\sum\limits_{j=1}^{F}W_{ijk}h_j + b_{ik}\right)\right]\right\}}$$

$$= \frac{\prod\limits_{i=1}^{D} \prod\limits_{k=1}^{K} \exp\left[v_{ik}\left(\sum\limits_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\left\{\sum\limits_{\mathbf{V}'_1}\prod\limits_{k=1}^{K}\exp\left[v'_{1k}\left(\sum\limits_{j=1}^{F}W_{1jk}h_j + b_{1k}\right)\right]\right\}\cdots\left\{\sum\limits_{\mathbf{V}'_D}\prod\limits_{k=1}^{K}\exp\left[v'_{Dk}\left(\sum\limits_{j=1}^{F}W_{Djk}h_j + b_{Dk}\right)\right]\right\}}$$

$$P(\mathbf{V}|\mathbf{h}) = \frac{\prod\limits_{i=1}^{D} \prod\limits_{k=1}^{K} \exp\left[v_{ik}\left(\sum\limits_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\prod\limits_{i=1}^{D}\left\{\sum\limits_{\mathbf{V}'_i}\prod\limits_{k=1}^{K}\exp\left[v'_{ik}\left(\sum\limits_{j=1}^{F}W_{ijk}h_j + b_{ik}\right)\right]\right\}} \tag{12}$$

To contunue with derivation of equation (12), we will take a closer look at the denominator. For a document $\mathbf{V}$, in which there are D words positions that are chosen from a dictionary of K available words, when $v_{ik} = 1$, it means that the ith word of the document is the kth word of the dictionary, and 0 otherwise. Whenever we sum over all K words of the dictionary, this sum is 1 for each word i of the document, $\sum_{k=1}^{K} v_{ik} = 1$. In this case we exclude empty documents, and even for a single word document, the summation above will be 1. In order to help with readability, we consider the simplification presented on (JORG THESIS, 2011), we take $r_{ik} = \sum_{j=1}^{F} W_{ijk}h_j + b_{ik}$, then, for a particular word i of the document, the denominator of equation (12) becomes:

$$\sum_{\mathbf{V}'_i}\prod_{k=1}^{K}\exp\left[v'_{ik}\left(\sum_{j=1}^{F}W_{ijk}h_j + b_{ik}\right)\right] = \sum_{\mathbf{V}'_i}\prod_{k=1}^{K}\exp\left(v'_{ik}r_{ik}\right)$$

$$= \sum_{\mathbf{V}'_i}\left[\exp\left(v_{i1}r_{i1}\right)\exp\left(v_{i2}r_{i2}\right)\ldots\exp\left(v_{iK}r_{iK}\right)\right]$$

$$= \left[\exp\left(r_{i1}(1)\right)\exp\left(r_{i2}(0)\right)\ldots\exp\left(r_{iK}(0)\right)\right] + \left[\exp\left(r_{i1}(0)\right)\exp\left(r_{i2}(1)\right)\ldots\exp\left(r_{iK}(0)\right)\right] +$$

$$\ldots + \left[\exp\left(r_{i1}(0)\right)\exp\left(r_{i2}(0)\right)\ldots\exp\left(r_{iK}(1)\right)\right]$$

$$= \sum_{q=1}^{K}\exp\left(r_{iq}\right)$$

$$= \sum_{q=1}^{K}\exp\left(\sum_{j=1}^{F}W_{ijq}h_j + b_{iq}\right). \tag{13}$$

Equation (13) can be replaced at equation (12) denominator:

$$P(\mathbf{V}|\mathbf{h}) = \frac{\prod_{i=1}^{D} \prod_{k=1}^{K} \exp\left[v_{ik}\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\prod_{i=1}^{D} \left\{\sum_{\mathbf{V}_i'} \prod_{k=1}^{K} \exp\left[v_{ik}'\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]\right\}}$$

$$= \frac{\prod_{i=1}^{D} \prod_{k=1}^{K} \exp\left[v_{ik}\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\prod_{i=1}^{D} \left[\sum_{q=1}^{K} \exp\left(\sum_{j=1}^{F} W_{ijq}h_j + b_{iq}\right)\right]}$$

$$P(\mathbf{V}|\mathbf{h}) = \prod_{i=1}^{D} \frac{\prod_{k=1}^{K} \exp\left[v_{ik}\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)\right]}{\sum_{q=1}^{K} \exp\left(\sum_{j=1}^{F} W_{ijq}h_j + b_{iq}\right)}. \tag{14}$$

Considering we would like to know the probability of having visible unit i on at word k, $v_{ik} = 1$, given the hidden units state $\mathbf{h}$:

$$P(v_{ik} = 1|\mathbf{h}) = \frac{\exp\left(\sum_{j=1}^{F} W_{ijk}h_j + b_{ik}\right)}{\sum_{q=1}^{K} \exp\left(\sum_{j=1}^{F} W_{ijq}h_j + b_{iq}\right)}, \tag{15}$$

which is the softmax function.

Figure (1) shows the Replicated Softmax model describe up to this point. The model has its visible and hidden units, respectively v_{ik} and h_j, which are connected by weights w_{ijk}.
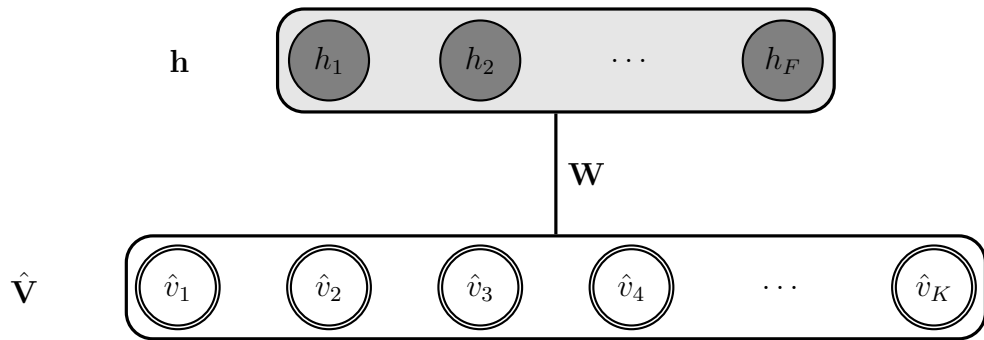
Figure 1 - REPLICATED SOFTMAX MODEL
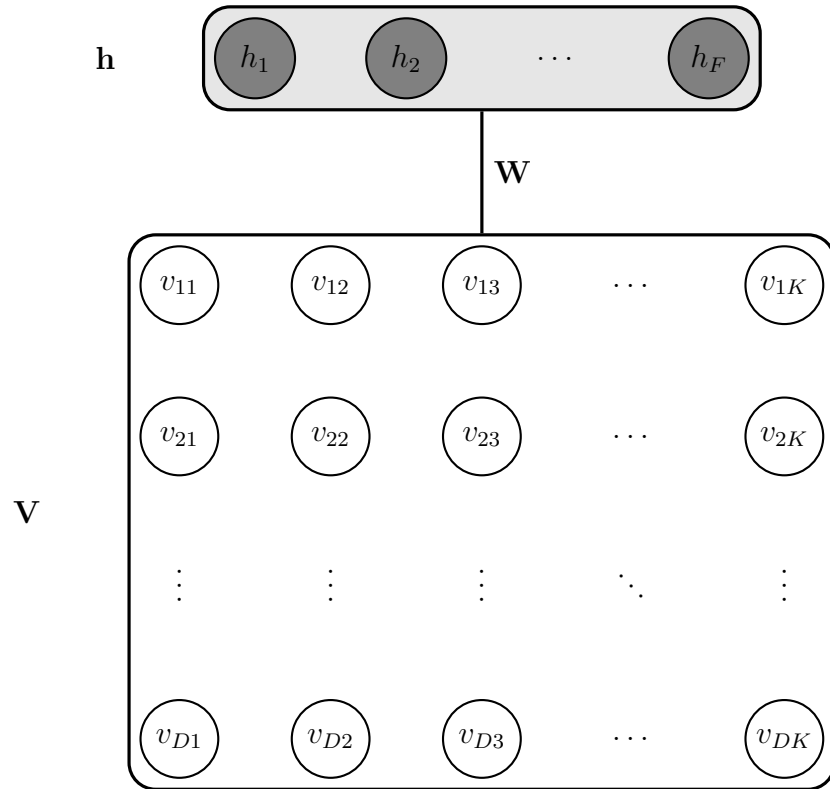
Legend: Replicated Softmax model. The top layer represents the hidden layer, denoted by vector $\mathbf{h} = (h_1, h_2, \ldots, h_F)$, of stochastic binary units. The bottom layer, denoted by matrix $\mathbf{V}$, represents the visible layer with units v_{ik}, $i = 1, \ldots, D$ and $k = 1, \ldots, K$. Between visible and hidden units are the weights w_{ijk}, which is a symmetric connection, denoted by tensor $\mathbf{W}$.

Source: Author

Figure 2 - REPLICATED SOFTMAX MODEL SIMPLIFICATION

Legend: Replicated Softmax model. The top layer represents the hidden layer, denoted by vector $\mathbf{h} = (h_1, h_2, \ldots, h_F)$, of stochastic binary units, the same hidden layer as in Figure (1). The bottom layer, denoted by vector $\hat{\mathbf{V}}$, represents the visible layer with units $\hat{v}_k$, $k = 1, \ldots, K$. These *hat* units represents the frequency count of each k word of the dictionary that appears in document $\mathbf{V}$. Between visible and hidden units are the weights w_{jk}, which is a symmetric connection, denoted by matrix $\mathbf{W}$. These weights are known as **shared weights**, because, even though documents of different sizes are analysed, the dictionary remains the same, and then the weights for each word in the dictionary is shared among the documents. It is important to remember that word order is not taken into consideration.

Source: Author

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