## **Tuning**

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### The Story so Far: Generative Models



• The definition of translation probability follows a mathematical derivation

$$\operatorname{argmax}_{\mathbf{e}} p(\mathbf{e}|\mathbf{f}) = \operatorname{argmax}_{\mathbf{e}} p(\mathbf{f}|\mathbf{e}) \ p(\mathbf{e})$$

• Occasionally, some independence assumptions are thrown in for instance IBM Model 1: word translations are independent of each other

$$p(\mathbf{e}|\mathbf{f}, a) = \frac{1}{Z} \prod_{i} p(e_i|f_{a(i)})$$

- Generative story leads to straight-forward estimation
  - maximum likelihood estimation of component probability distribution
  - EM algorithm for discovering hidden variables (alignment)

### **Log-linear Models**



• IBM Models provided mathematical justification for multiplying components

$$p_{LM} \times p_{TM} \times p_D$$

• These may be weighted

$$p_{LM}^{\lambda_{LM}} \times p_{TM}^{\lambda_{TM}} \times p_D^{\lambda_D}$$

• Many components  $p_i$  with weights  $\lambda_i$ 

$$\prod_{i} p_i^{\lambda_i}$$

• We typically operate in log space

$$\sum_{i} \lambda_{i} \log(p_{i}) = \log \prod_{i} p_{i}^{\lambda_{i}}$$

### **Knowledge Sources**



- Many different knowledge sources useful
  - language model
  - reordering (distortion) model
  - phrase translation model
  - word translation model
  - word count
  - phrase count
  - character count
  - drop word feature
  - phrase pair frequency
  - additional language models
- Could be any function  $h(\mathbf{e}, \mathbf{f}, \mathbf{a})$

$$h(\mathbf{e}, \mathbf{f}, \mathbf{a}) = \begin{cases} 1 & \text{if } \exists e_i \in \mathbf{e}, e_i \text{ is verb} \\ 0 & otherwise \end{cases}$$

### **Set Feature Weights**



- Contribution of components  $p_i$  determined by weight  $\lambda_i$
- Methods
  - manual setting of weights: try a few, take best
  - automate this process
- Learn weights
  - set aside a development corpus
  - set the weights, so that optimal translation performance on this development corpus is achieved
  - requires automatic scoring method (e.g., BLEU)

#### Discriminative vs. Generative Models



#### Generative models

- translation process is broken down to steps
- each step is modeled by a probability distribution
- each probability distribution is estimated from data by maximum likelihood

#### Discriminative models

- model consist of a number of features (e.g. the language model score)
- each feature has a weight, measuring its value for judging a translation as correct
- feature weights are optimized on development data, so that the system output matches correct translations as close as possible

### **Overview**



- Generate a set of possible translations of a sentence (candidate translations)
- Each candidate translation represented using a set of features
- Each feature derives from one property of the translation
  - feature score: value of the property (e.g., language model probability)
  - feature weight: importance of the feature
     (e.g., language model feature more important than word count feature)
- Task of discriminative training: find good feature weights
- Highest scoring candidate is best translation according to model

### **Discriminative Training Approaches**



- Reranking: 2 pass approach
  - first pass: run decoder to generate set of candidate translations
  - second pass:
    - \* add features
    - \* rescore translations
- Tuning
  - integrate all features into the decoder
  - learn feature weights that lead decoder to best translation
- Large scale discriminative training (next lecture)
  - thousands or millions of features
  - optimization of the entire training corpus
  - requires different training methods



# finding candidate translations

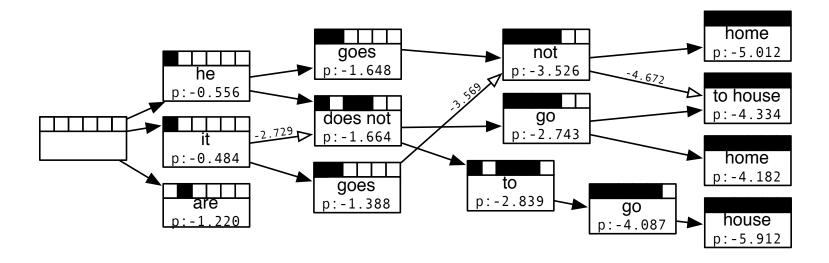
### **Finding Candidate Translations**



- Number of possible translations exponential with sentence length
- But: we are mainly interested in the most likely ones
- Recall: decoding
  - do not list all possible translation
  - beam search for best one
  - dynamic programming and pruning
- How can we find **set** of best translations?

### Search Graph

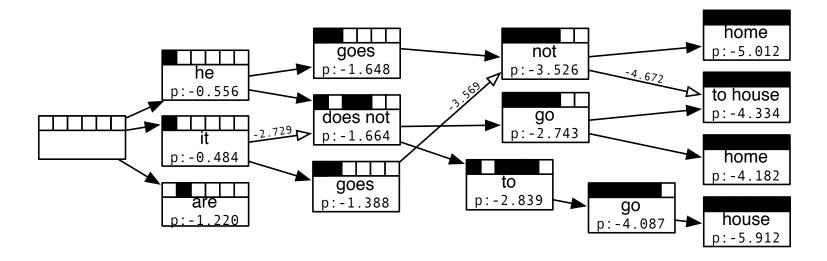




- Decoding explores space of possible translations by expanding the most promising partial translations
- $\Rightarrow$  Search graph

### Search Graph

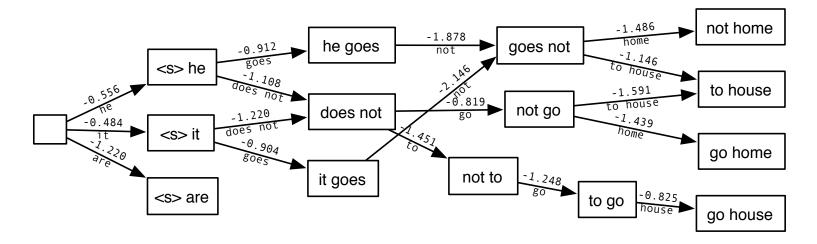




- Keep transitions from recombinations
  - without: total number of paths = number of full translation hypotheses
  - with: combinatorial expansion
- Example
  - without: 4 full translation hypotheses
  - with: 10 different full paths
- Typically many more paths due to recombination

#### **Word Lattice**





- Search graph as finite state machine
  - states: partial translations
  - transitions: applications of phrase translations
  - weights: added scores by phrase translation

### **Finite State Machine**



- Formally, a finite state machine, is a q quintuple  $(\Sigma, S, s_0, \delta, F)$ , where
  - $\Sigma$  is the alphabet of output symbols (in our case, the emitted phrases)
  - S is a finite set of states
  - $s_0$  is an initial state ( $s_0 \in S$ ), (in our case the initial hypothesis)
  - $\delta$  is the state transition function  $\delta: S \times \Sigma \to S$
  - F is the set of final states (in our case representing hypotheses that have covered all input words).
- Weighted finite state machine
  - scores for emissions from each transition  $\pi: S \times \Sigma \times S \to \mathbf{R}$

#### **N-Best List**

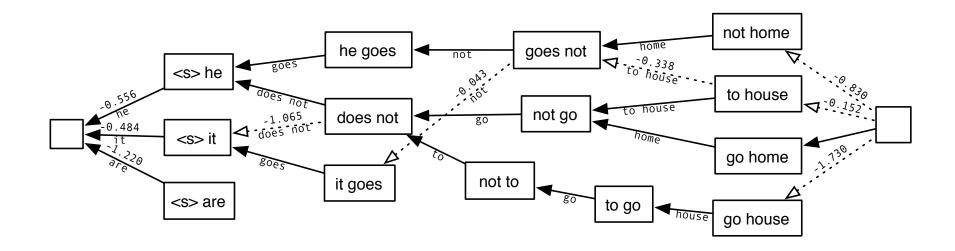


rank	score	sentence
1	-4.182	he does not go home
2	-4.334	he does not go to house
3	-4.672	he goes not to house
4	-4.715	it goes not to house
5	-5.012	he goes not home
6	<i>-</i> 5.055	it goes not home
7	-5.247	it does not go home
8	-5.399	it does not go to house
9	-5.912	he does not to go house
10	-6.977	it does not to go house

- Word graph may be too complex for some methods
- $\Rightarrow$  Extract *n* best translations

### **Computing N-Best Lists**

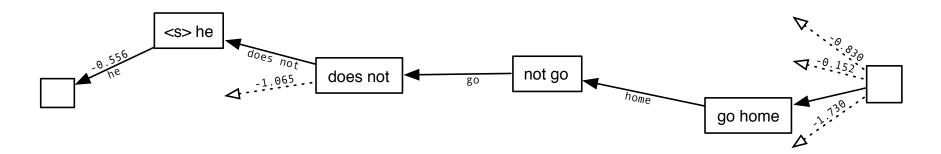




- Representing the graph with back transitions
- Include "detours" with cost

#### Path 1



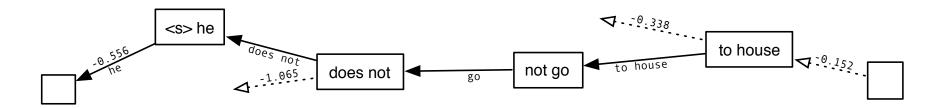


- Follow back transitions
- ⇒ Best path: he does not go home
  - Keep note of detours from this path

Base path	Base cost	<b>Detour cost</b>	<b>Detour state</b>
final	-0	-0.152	to house
final	-0	-0.830	not home
final	-0	-1.065	does not
final	-0	-1.730	go house

#### Path 2



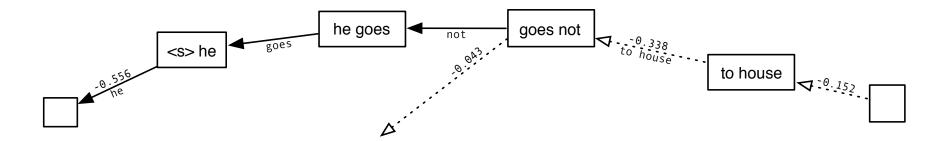


- Take cheapest detour
- Afterwards, follow back transitions
- Second best path: he does not go to house
- Add its detours to priority queue

Base path	Base cost	<b>Detour cost</b>	<b>Detour state</b>
to house	-0.152	-0.338	goes not
final	-0	-0.830	not home
final	-0	-1.065	does not
to house	-0.152	-1.065	it
final	-0	-1.730	go house

### Path 3





- Third best path: he goes not to house
- Add its detours to priority queue

Base path	Base cost	<b>Detour cost</b>	<b>Detour state</b>		
to house / goes not	-0.490	-0.043	it goes		
final	-0	-0.830	not home		
final	-0	-1.065	does not		
to house	-0.152	-1.065	it		
final	-0	-1.730	go house		

## **Scoring N-Best List**



- Two opinions about items in the n-best list
  - model score: what the machine translation system thinks is good
  - error score: what is actually a good translation
- Error score can be computed with reference translation
  - recall: lecture on evaluation
  - canonical metric: BLEU score
- Some methods require sentence-level scores
  - commonly used: BLEU+1
  - adjusted precision:  $\frac{\text{correct matches}+1}{total+1}$

#### **Scored N-Best List**



- Reference translation: he does not go home
- N-best list

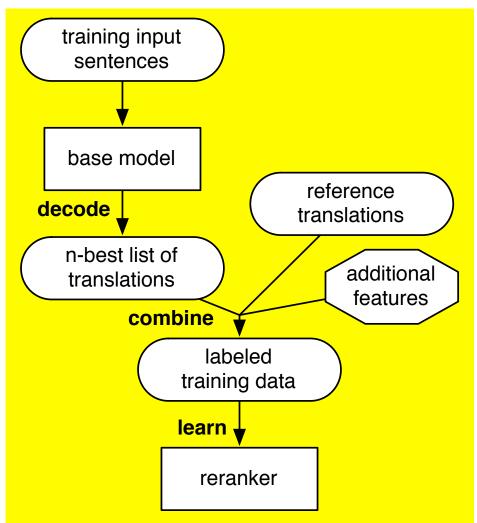
Translation	Feature values				BLEU+1		
it is not under house	-32.22	-9.93	-19.00	-5.08	-8.22	<b>-</b> 5	27.3%
he is not under house	-34.50	-7.40	-16.33	-5.01	-8.15	<i>-</i> 5	30.2%
it is not a home	-28.49	-12.74	-19.29	-3.74	-8.42	<i>-</i> 5	30.2%
it is not to go home	-32.53	-10.34	-20.87	-4.38	-13.11	-6	31.2%
it is not for house	-31.75	-17.25	-20.43	-4.90	-6.90	<i>-</i> 5	27.3%
he is not to go home	-35.79	-10.95	-18.20	-4.85	-13.04	-6	31.2%
he does not home	-32.64	-11.84	-16.98	-3.67	-8.76	-4	36.2%
it is not packing	-32.26	-10.63	-17.65	-5.08	-9.89	-4	21.8%
he is not packing	-34.55	-8.10	-14.98	-5.01	-9.82	-4	24.2%
he is not for home	-36.70	-13.52	-17.09	-6.22	-7.82	<i>-</i> 5	32.5%

• What feature weights push up the correct translation?

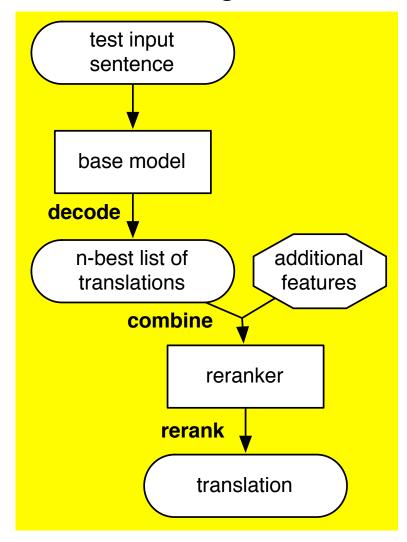
### Rerank Approach



#### **Training**



#### **Testing**





# parameter tuning

### **Parameter Tuning**



• Recall log-linear model

$$p(x) = \exp \sum_{i=1}^{n} \lambda_i h_i(x)$$

- Overall translation score p(x) is combination of components  $h_i(x)$ , weighted by parameters  $\lambda_i$
- Setting parameters as supervised learning problem
- Two methods
  - Powell search
  - Simplex algorithm

## **Experimental Setup**



- Training data for translation model: 10s to 100s of millions of words
- Training data for language model: billions of words
- Parameter tuning
  - set a few weights (say, 10–15)
  - tuning set of 1000s of sentence pairs sufficient
- Finally, test set needed

## **Minimum Error Rate Training**



- Optimize metric: e.g., BLEU
- Tuning set of 1000s of sentences, for each we have n-best list of translations
- Different weight setting
  - → different translations come out on top
  - $\rightarrow$  BLEU score
- Even with 10-15 features: high dimensional space, intractable

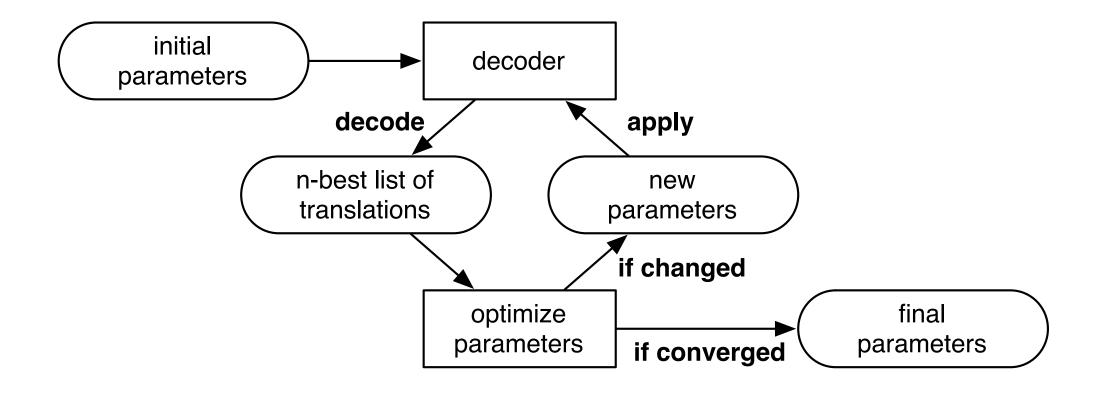
#### **Bad N-Best Lists?**



- N-Best list produced with initial weight setting
- Decoding with optimized weight settings
  - → may produce completely different translations
- ⇒ Iterate optimization, accumulate n-best lists

### **Parameter Tuning**







# powell search

## Och's minimum error rate training (MERT) 29

• Line search for best feature weights

### Find Best Feature Weight



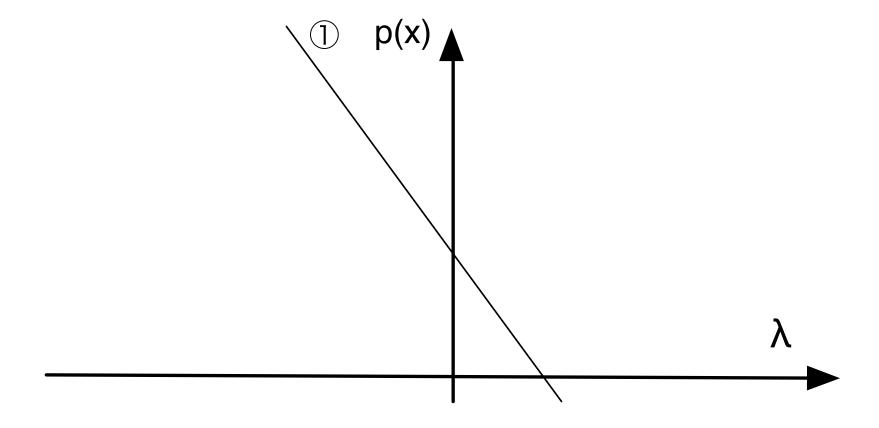
- Core task:
  - find optimal value for one parameter weight  $\lambda$
  - ... while leaving all other weights constant
- Score of translation i for a sentence f:

$$p(\mathbf{e}_i|\mathbf{f}) = \lambda a_i + b_i$$

- Recall that:
  - we deal with 100s of translations  $e_i$  per sentence f
  - we deal with 100s or 1000s of sentences f
  - we are trying to find the value  $\lambda$  so that over all sentences, the error score is optimized

### **One Translations for One Sentence**



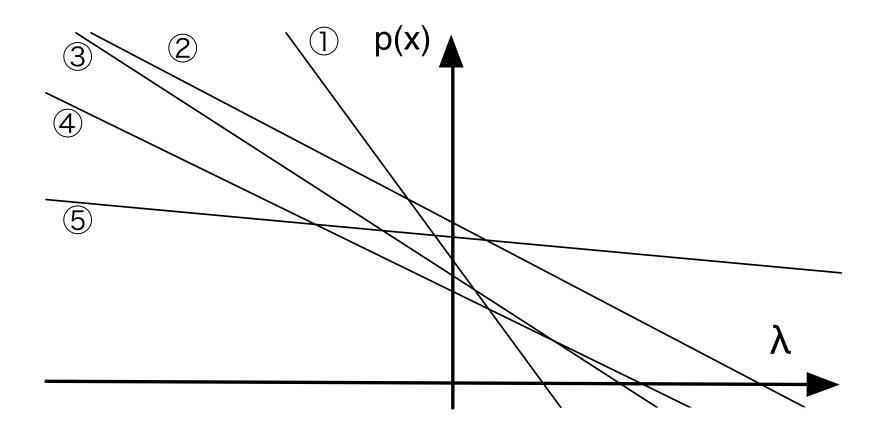


• Probability of one translation  $p(\mathbf{e}_i|\mathbf{f})$  is a function of  $\lambda$ 

$$p(\mathbf{e}_i|\mathbf{f}) = \lambda a_i + b_i$$

### **N-Best Translations for One Sentence**

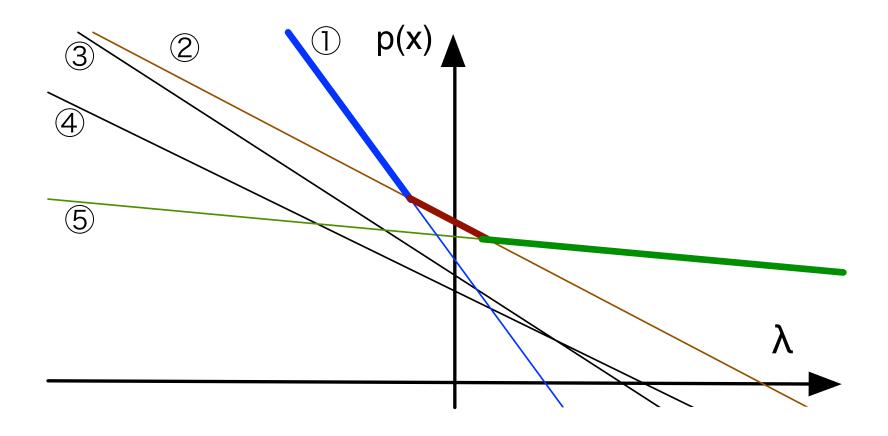




• Each translation is a different line

## **Upper Envelope**

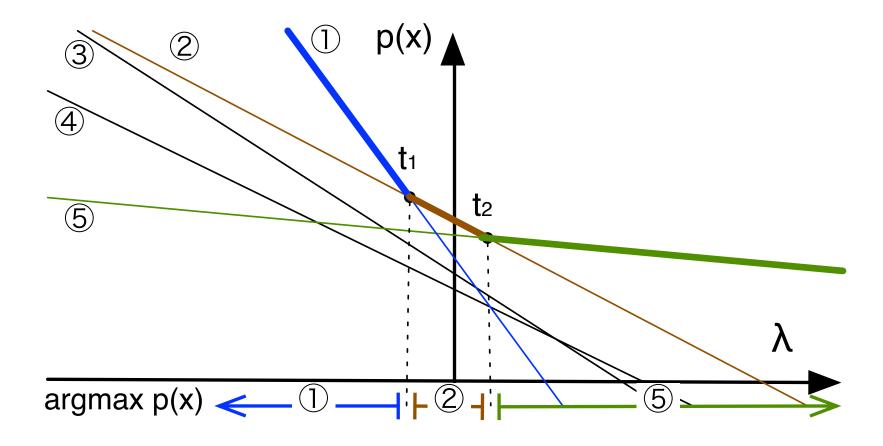




ullet Highest probability translation depends on  $\lambda$ 

#### **Threshold Points**





• There are one a few threshold points  $t_j$  where the model-best line changes

### Finding the Optimal Value for $\lambda$



- Real-valued  $\lambda$  can have infinite number of values
- But only on threshold points, one of the model-best translation changes

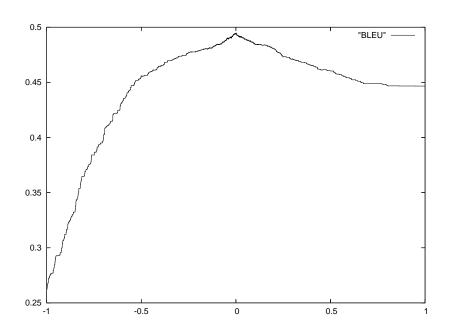
#### $\Rightarrow$ Algorithm:

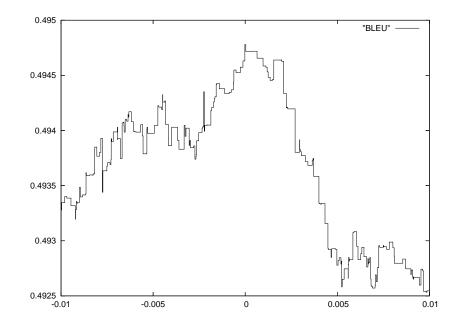
- find the threshold points
- for each interval between threshold points
  - \* find best translations
  - \* compute error-score
- pick interval with best error-score

#### **BLEU Error Surface**



• Varying one parameter: a rugged line with many local optima





full range

peak

#### **Pseudo Code**



**Input:** sentences with n-best list of translations, initial parameter values

```
1: repeat
       for all parameter do
           set of threshold points T = \{\}
          for all sentence do
              for all translation do
                 compute line l: parameter value \rightarrow score
 6:
              end for
              find line l with steepest descent
              while find line l_2 that intersects with l first do
                  add parameter value at intersection to set of threshold points T
10:
11:
                 l = l_2
12:
              end while
           end for
13:
           sort set of threshold points T by parameter value
14:
           compute score for value before first threshold point
15:
16:
           for all threshold point t \in T do
              compute score for value after threshold point \boldsymbol{t}
17:
              if highest do record max score and threshold point t
18:
           end for
19:
20:
           if max score is higher than current do update parameter value
21:
       end for
22: until no changes to parameter values applied
```



# simplex algorithm



- Similar to Powell search
- Less calculations of the current error
  - recall: error is computed over the entire tuning set
  - brute force method requires reranking of 1000s of n-best lists
- Similar to gradient descent methods
  - try to find direction in which the optimum lies
  - here: we cannot compute derivative



- Randomly generate three points in the high dimensional space
  - high dimensional space = each dimension is one of the  $\lambda_i$  parameters
  - a point in the space = each parameter set to a value



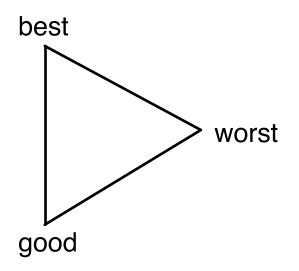
best

worst

good

- We can score each of these points
  - use parameter settings to rerank all the n-best lists
  - compute overall tuning set score (BLEU)
- Rank the 3 points into best, good, worst

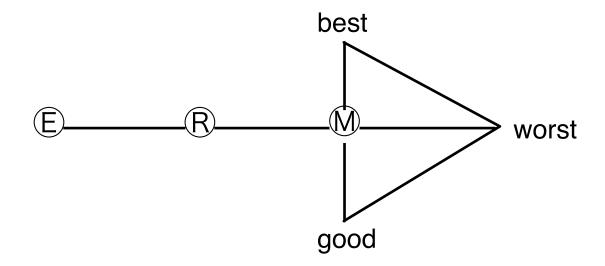




• The 3 points form a triangle

## First Idea: Move Away from the Bad Point

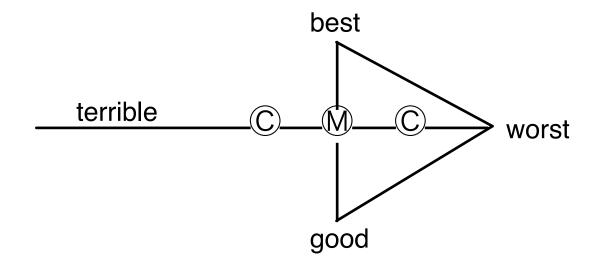




- Compute 3 additional points
  - mid point:  $M = \frac{1}{2}(best + good)$
  - reflection point: R = M + (M worst)
  - extension: R = M + 2(M worst)
- Three cases
  - 1. if error(E) < error(R) < error(worst), replace worst with E.
  - 2. else if error(R) < error(worst), replace worst with R.
  - 3. else try something else

## Second Idea: Well, Not Too Far Away

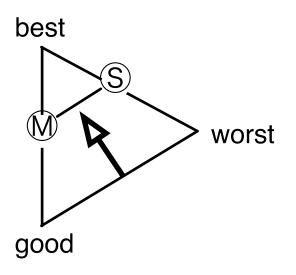




- Compute 2 additional points
  - $C_1$  point between worst and M:  $C_1 = M + \frac{1}{2}(M worst)$
  - $C_2$  point between M and R:  $C_2 = M + \frac{3}{2}(\tilde{M} worst)$ .
- Three cases
  - 1. if  $error(C_1) < error(worst)$  and  $error(C_1) < error(C_2)$ , replace worst with  $C_1$ .
  - 2. if  $error(C_2) < error(worst)$  and  $error(C_2) < error(C_1)$ , replace worst with  $C_2$ .
  - 3. else continue

#### Third Idea: Move Closer to Best Point





- Compute 1 additional point
  - S point between worst and best:  $S = \frac{1}{2}(best + worst)$ .
- Shrink triangle

## **Simplex in High Dimensions**



- Process of updates is iterated until the points converge
- Typically very quick
- More dimensions: more points
  - n + 1 points for n parameters
  - midpoint M is the center of all points except worst
  - in final case, all *good* points moved towards midpoints closer to *best*
- Once optimum is found
  - generate n-best list
  - iterate

# **Summary**



- Reframing probabilistic model as log-linear model with weights
- Discriminative training task: set weights
- Generate n-best candidate translations from search graph
- Reranking
- Powell search (Och's MERT)
- Simplex algorithm