

# Rapid Bayesian Learning in Mammalian Olfactory System

Naoki Hiratani and Peter Latham, 2020

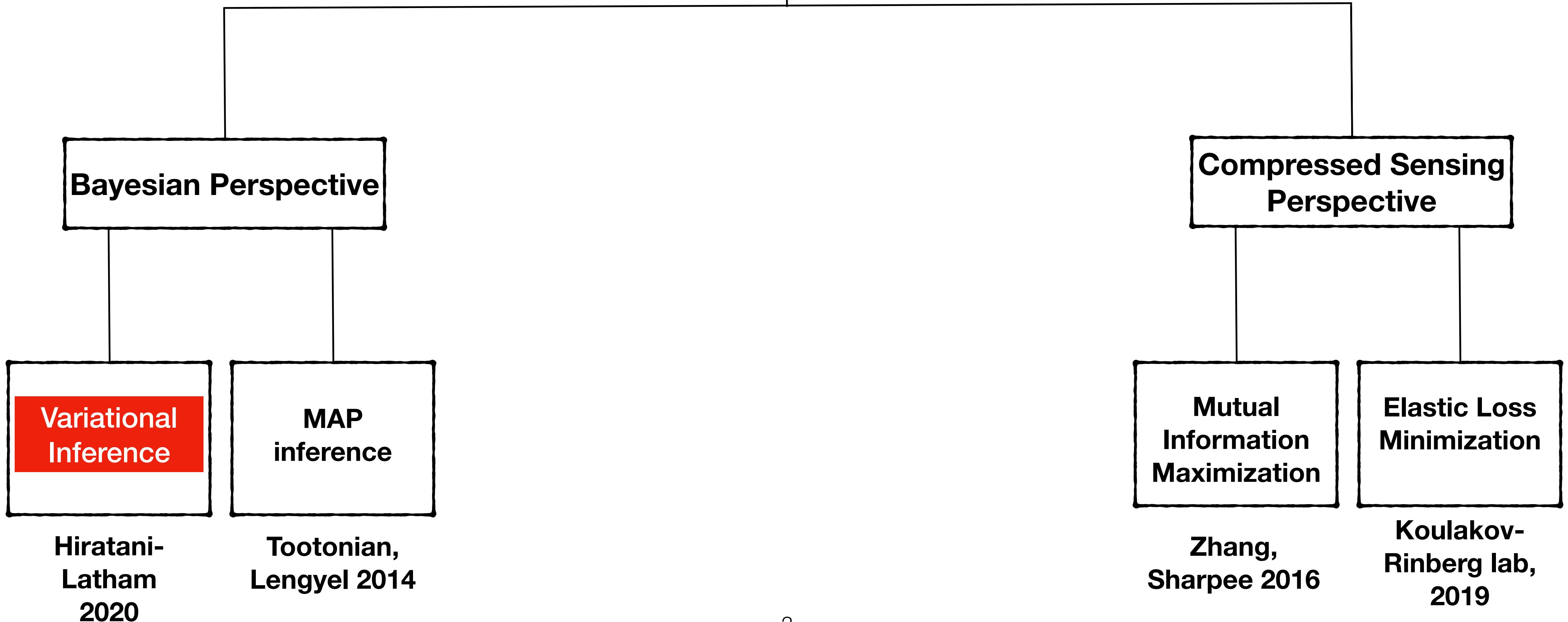
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# Central Question

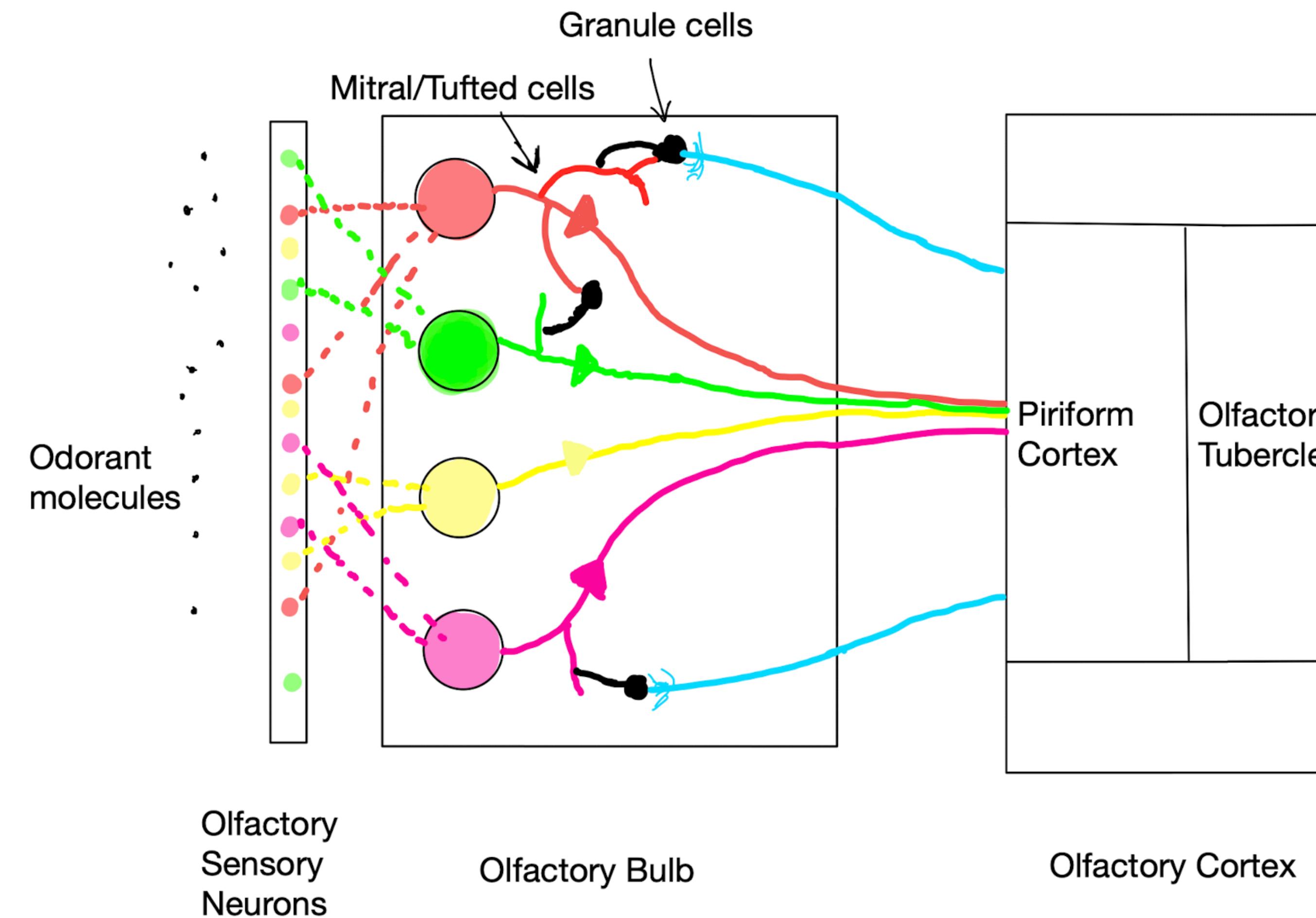
- How olfactory system learns odor identity?
- How olfactory system performs odor-reward association?



# Odor Identity Recognition



# Olfactory System in a Nutshell



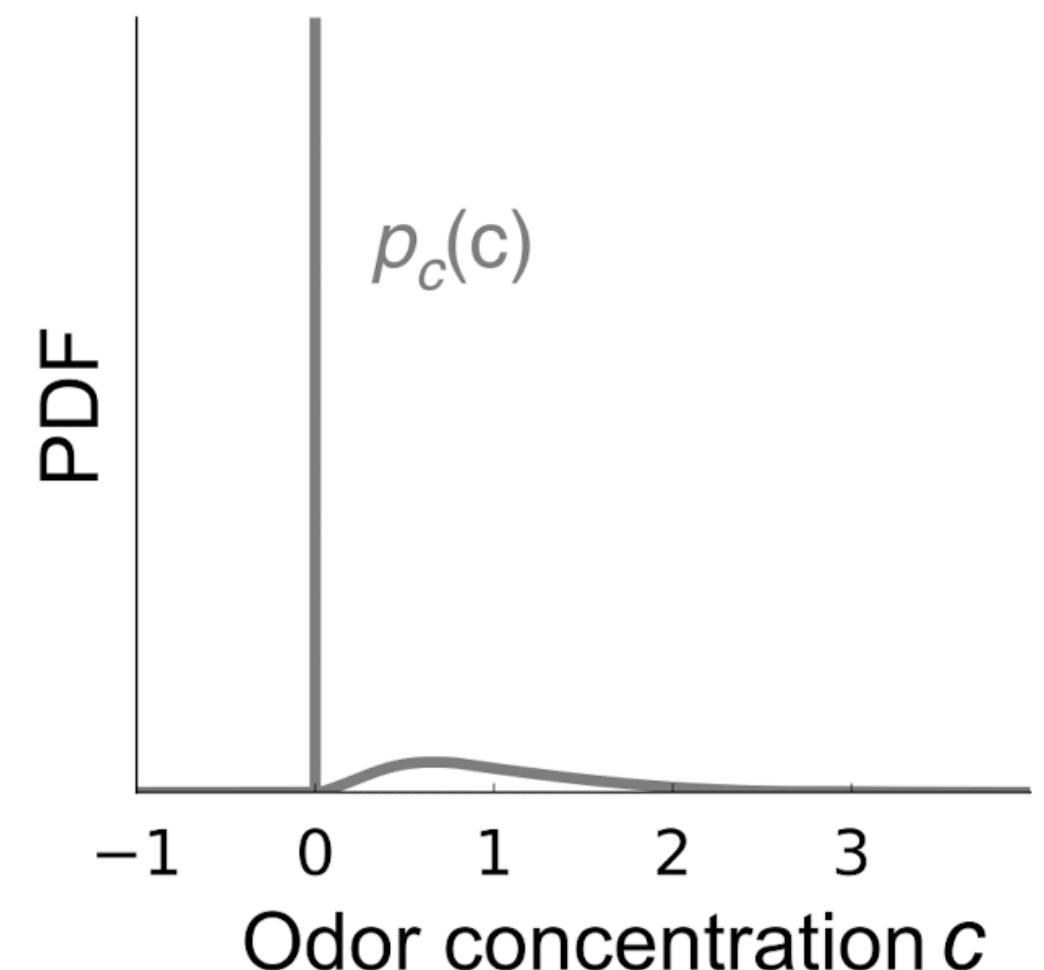
# Problem Setting

$$p(c_j) = (1 - c_0)\delta(c_j) + \text{Gamma}(\alpha, \alpha)$$

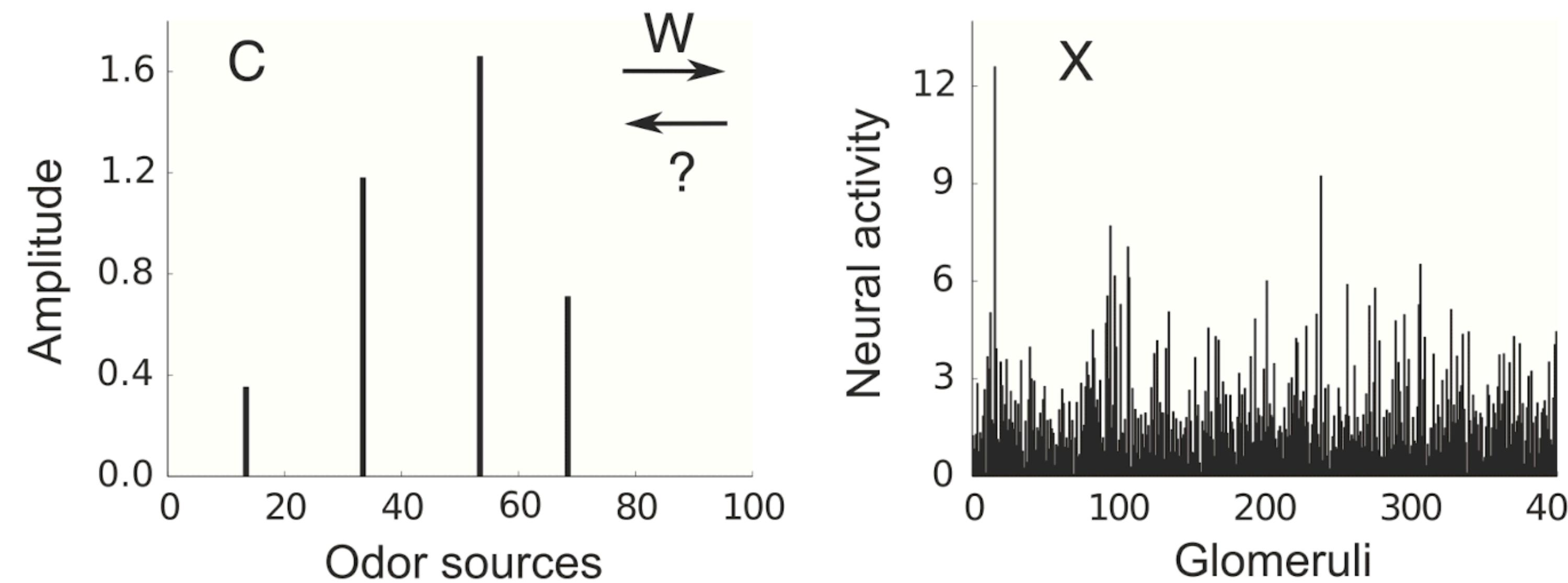
- Let  $\mathbf{c}$  represent a  $M \times 1$  vector of odor concentration
- Let  $\mathbf{x}$  represent a  $N \times 1$  vector of glomerular activity

$$x_i = \sum_{j=1}^M w_{ij} c_j + \xi_i$$

- Goal: Given  $\mathbf{x}$ , find  $\mathbf{c}$



# Goal: Find $p(c|x)$



# Olfactory Learning as Bayesian Inference

Prelude: Why we need Variational Approximation?

Step 1: Use Variational Approximation to get variational odor and weight distributions

Step 2: Minimize KL divergence between variational distributions and the true distribution to get iterative relations for the variational distributions

Step 3: Solve the iterative relations to get expression for the variational distributions

Step 4: Show that the parameters of the variational distributions can be learnt by neural network dynamics and synaptic plasticity rules

# Prelude: Why variational approximation?

$$\begin{aligned} p(\mathbf{c}_t | \mathbf{x}_{1:t}) &= \int d\mathbf{w} p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) & p(A|B) &= \frac{p(A, B)}{p(B)} \\ &= \int d\mathbf{w} p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t-1}, \mathbf{x}_t) & p(A|B) &= \frac{p(B|A)p(A)}{p(B)} \\ &= \int d\mathbf{w} \frac{p(\mathbf{x}_t | \mathbf{c}_t, \mathbf{w}, \mathbf{x}_{1:t-1})p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t-1})}{p(\mathbf{x}_t)} \\ &\propto \int d\mathbf{w} p(\mathbf{x}_t | \mathbf{c}_t, \mathbf{w})p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t-1}) \\ &= \int d\mathbf{w} p(\mathbf{x}_t | \mathbf{c}_t, \mathbf{w})p(\mathbf{c}_t)p(\mathbf{w} | \mathbf{x}_{1:t-1}) \end{aligned}$$

The goal is to evaluate the above integral. The first term in the integrand is Gaussian distribution, i.e.  $p(\mathbf{x}_t | \mathbf{c}_t, \mathbf{w}) \sim \mathcal{N}(W\mathbf{c}_t + \mathbf{w}, 1)$  and we also know the expression for  $p(\mathbf{c}_t)$ . It is the third term which makes it intractable to evaluate the integral.

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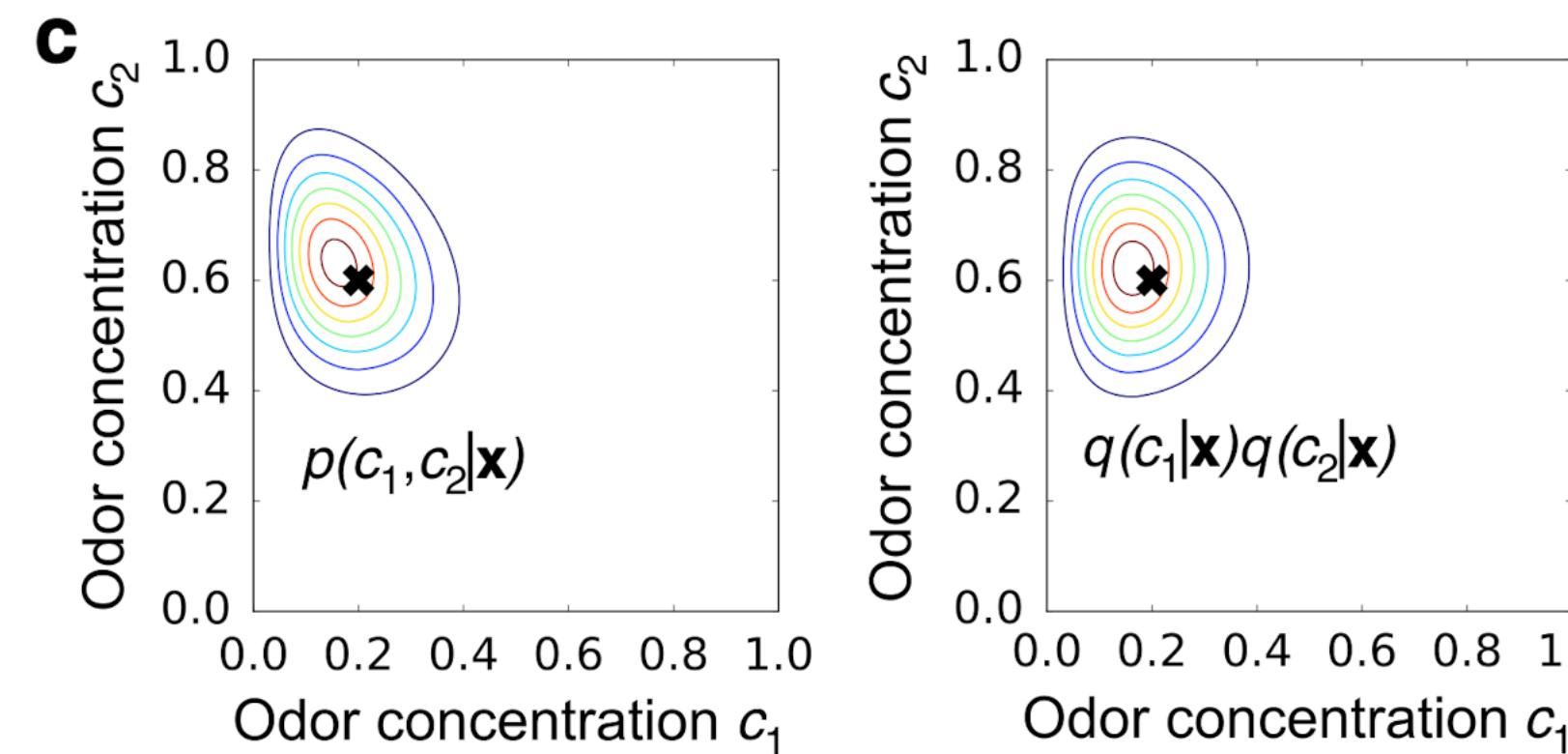
Step 4: Show that the parameters of the variational distributions can be learnt by neural network dynamics and synaptic plasticity rules

# Step 1: Using Variational Approximation

We make the following assumption:

$$p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) \approx q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) \equiv \prod_{ij} q_{ij}^{w,t}(w_{ij} | \mathbf{x}_{1:t}) \times \prod_j q_j^c(c_j | \mathbf{x}_{1:t})$$

We are basically assuming each element of  $w_{ij}$  and  $c_j$  are independent. While this assumption for  $c_j$  is always true but  $w_{ij}$  independence is only true at the beginning of trials and this approximation become progressively worse as the number of trials increases.



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# Step 2: Minimizing KL divergence

$$p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) \approx q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) \equiv \prod_{ij} q_{ij}^{w,t}(w_{ij} | \mathbf{x}_{1:t}) \times \prod_j q_j^c(c_j | \mathbf{x}_{1:t})$$

We minimize the KL divergence between:  $p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})$  and  $q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})$

$$D_{KL}[q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) || p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})] = \int d\mathbf{c} d\mathbf{w} q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) \log \frac{q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})}{p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})}$$

Taking functional derivative with respect to  $q_{ij}^{w,t}(w_{ij} | \mathbf{x}_{1:t})$  and equating to zero gives,

$$\begin{aligned} 0 &= \int d\mathbf{c} \frac{\partial}{\partial q_{ij}^{w,t}} \int d\mathbf{w} q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t}) (\log[q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})] - \log[p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})]) \\ &= - \int d\mathbf{c} d\mathbf{w}_{\setminus w_{ij}} \log[p(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})] + \int d\mathbf{c} d\mathbf{w}_{\setminus w_{ij}} \log[q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})] \\ &\quad + \int d\mathbf{c} d\mathbf{w}_{\setminus w_{ij}} [q^t(\mathbf{c}_t, \mathbf{w} | \mathbf{x}_{1:t})] \end{aligned}$$

Next, we take functional derivative with respect to  $q_j^c(c_j | \mathbf{x}_{1:t})$ . We are left with these two relations:

$$\begin{aligned} \log q_{ij}^{w,t} &\sim \langle \log p(\mathbf{x} | \mathbf{c}, \mathbf{w}) \rangle_{\setminus w_{ij}} + \langle \log p(\mathbf{w} | \mathbf{x}_{1:t-1}) \rangle_{\setminus w_{ij}} \\ \log q_j^c &\sim \langle \log p(\mathbf{x} | \mathbf{c}, \mathbf{w}) \rangle_{\setminus c_j} + \log p(c_j) \end{aligned}$$

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# Step 3: Solving for variational odor distribution

$$q_j^c(c_j) \propto p_c(c_j) \exp \left[ \langle \log p(\mathbf{x}|\mathbf{c}, \mathbf{w}) \rangle_{\setminus c_j} \right]$$

$$q_j^c(c_j) \propto p_c(c_j) \exp \left[ -\frac{\lambda_j^t}{2} \left( c_j - \mu_j^t \right)^2 \right]$$

$$\mu_j^t \equiv \frac{1}{\sum_i \langle w_{ij}^{t-1 2} \rangle} \sum_i \langle w_{ij}^{t-1} \rangle \left[ m_i^t + \langle w_{ij}^{t-1} \rangle \langle c_j \rangle \right] \quad \lambda_j^t \equiv \sum_i \langle w_{ij}^{t-1 2} \rangle$$

$$m_i^t \equiv x_i^t - \sum_{j=1}^M \langle w_{ij}^{t-1} \rangle \langle c_j \rangle$$

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# Step 4: Inferring the neural dynamics and learning rule

- From the variational odor distribution:

$$\tau_r \frac{dm_i}{d\tau} = -m_i - \sum_{j=1}^M w_{ij}^L \bar{c}_j + x_i$$

$$\tau_r \frac{d\bar{c}_j}{d\tau} = -\bar{c}_j + F_j \left( \sum_{i=1}^N w_{ji}^F m_i \right)$$

- From the variational weight distribution:

$$\Delta w_{ji}^{F,t} = \frac{m_i c_j}{t \rho_j}$$

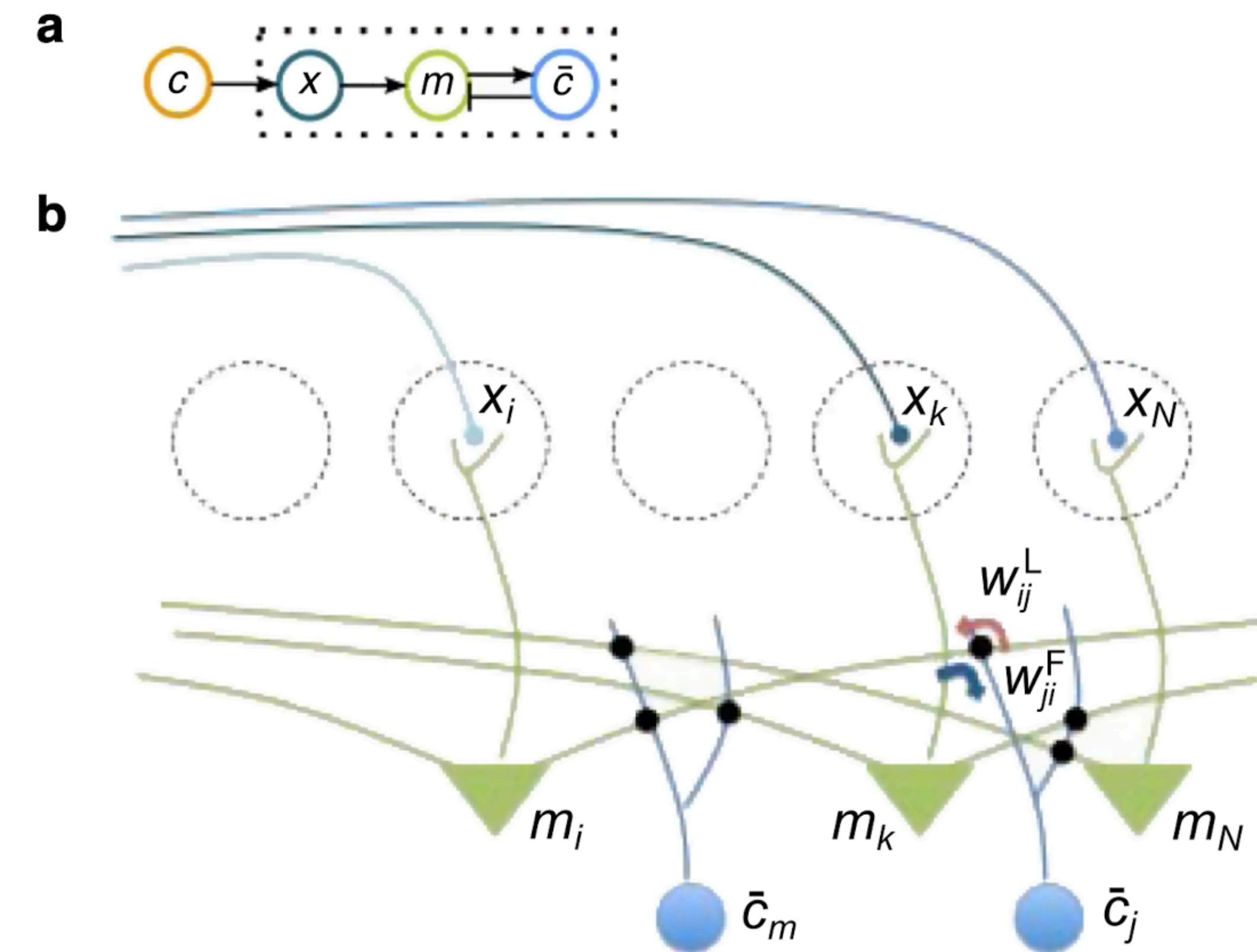
$$\Delta w_{ji}^{L,t} = \frac{m_i c_j}{t \rho_j}$$

# Neural Implementation of Bayesian Learning

$$\tau_r \frac{dm_i}{d\tau} = -m_i - \sum_{j=1}^M w_{ij}^L \bar{c}_j + x_i$$

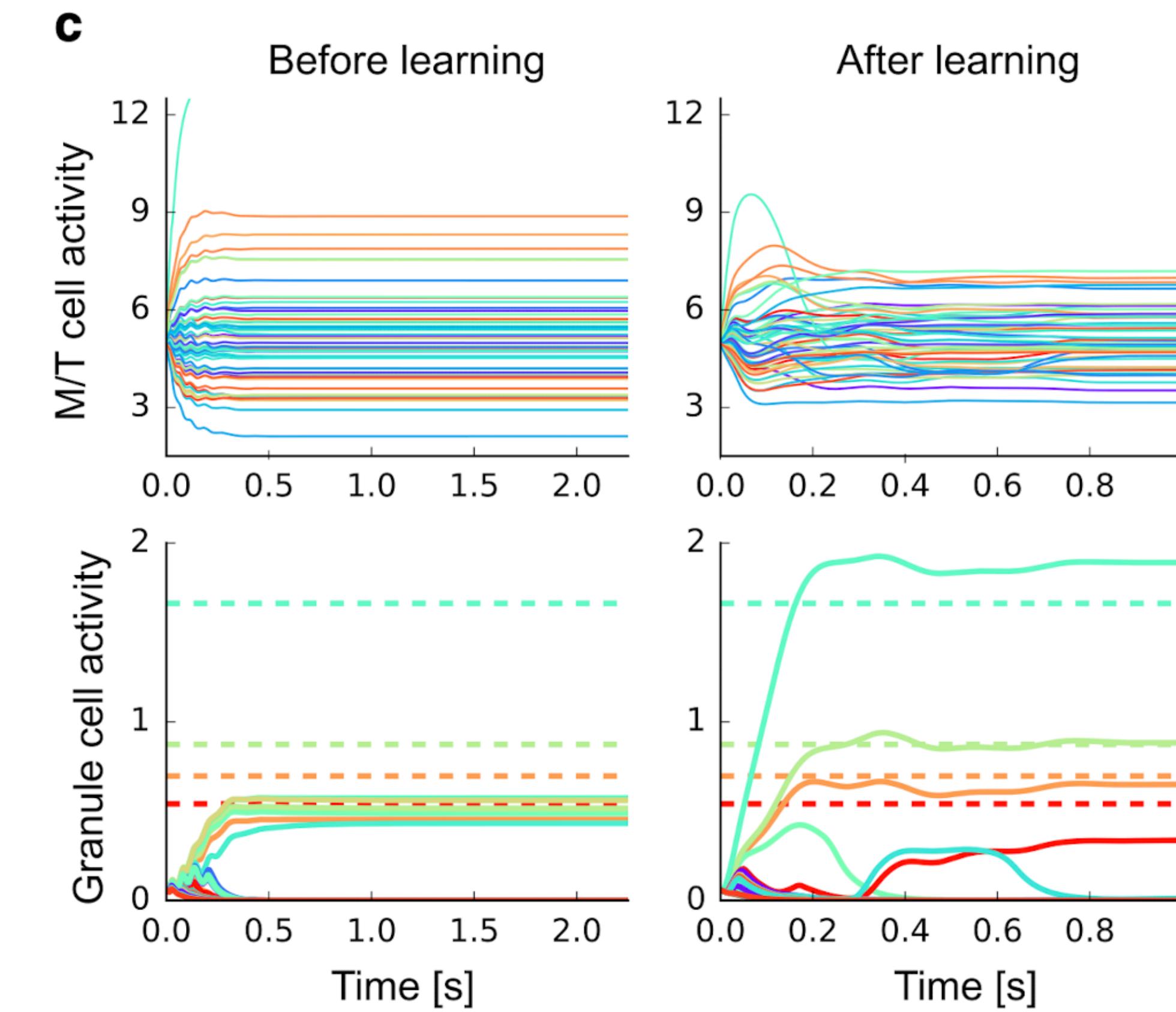
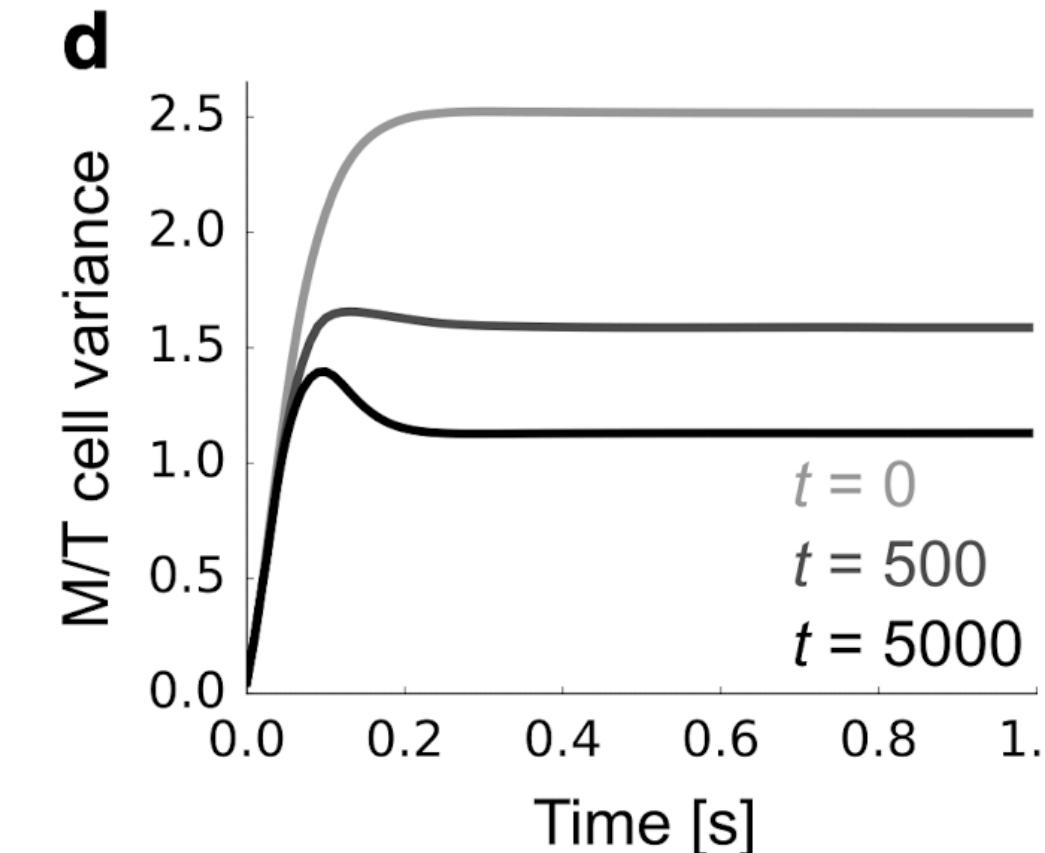
$$\tau_r \frac{d\bar{c}_j}{d\tau} = -\bar{c}_j + F_j \left( \sum_{i=1}^N w_{ji}^F m_i \right)$$

Bayesian Learning model maps perfectly onto the circuitry of the Olfactory Bulb



# Firing Rate Dynamics before and after learning

- M/T cells show both positive and negative responses relative to baseline
- Granule cells show very selective responses with activity levels roughly matching the concentration of the corresponding odors
- M/T cells response range decreases with learning



# Transfer Function

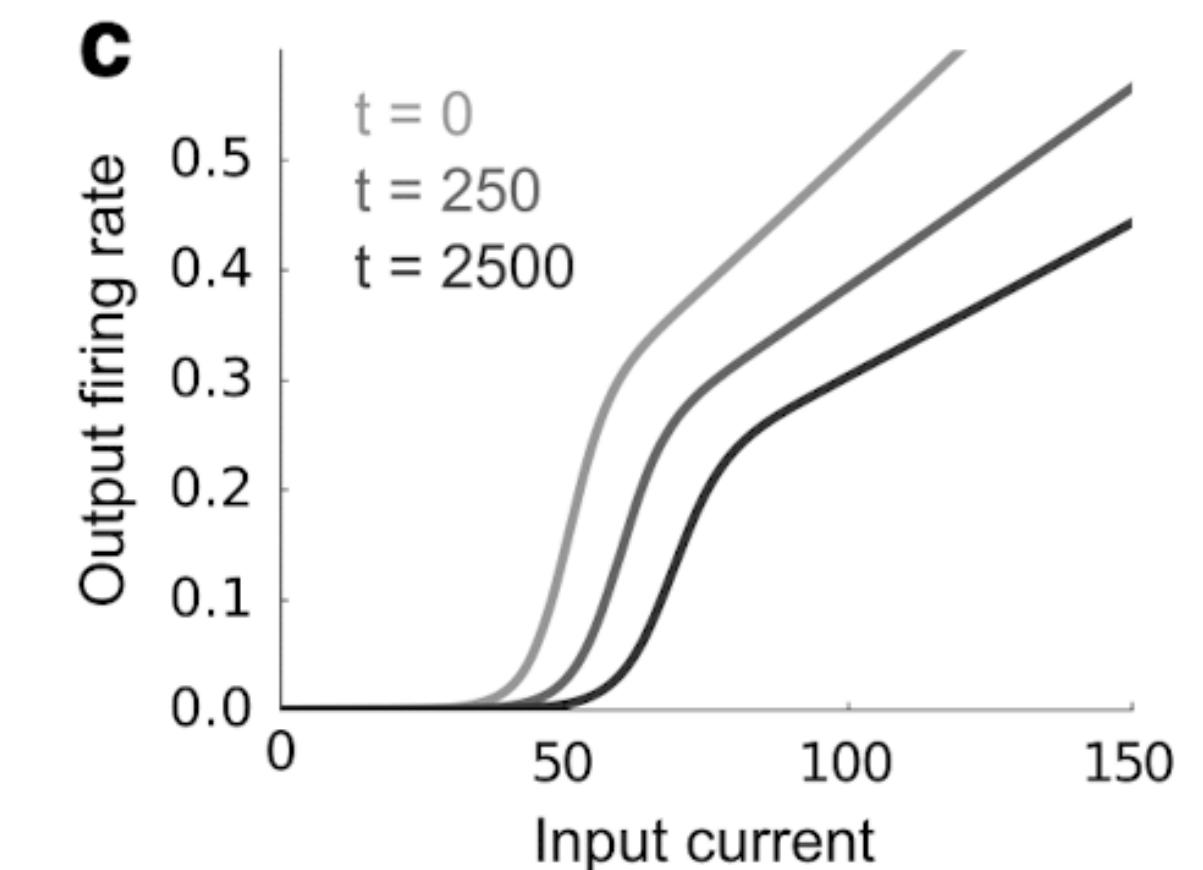
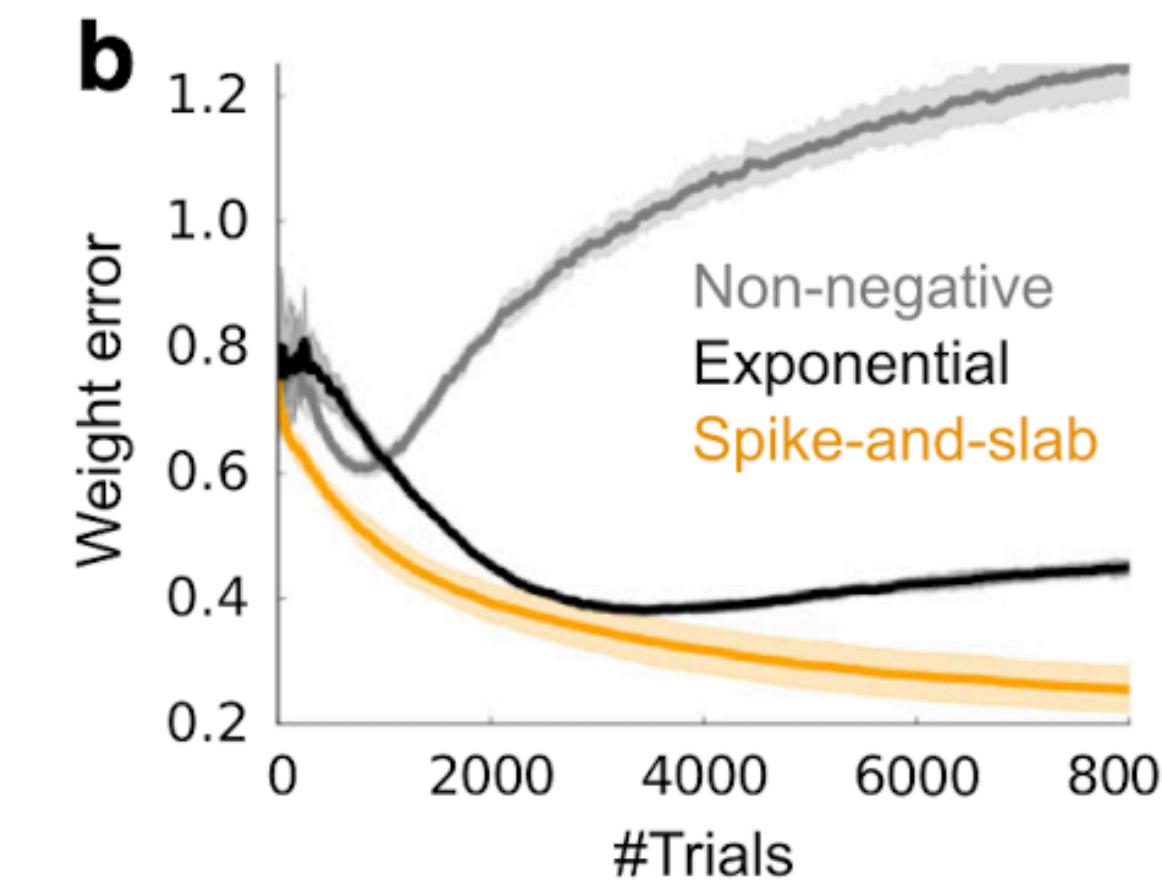
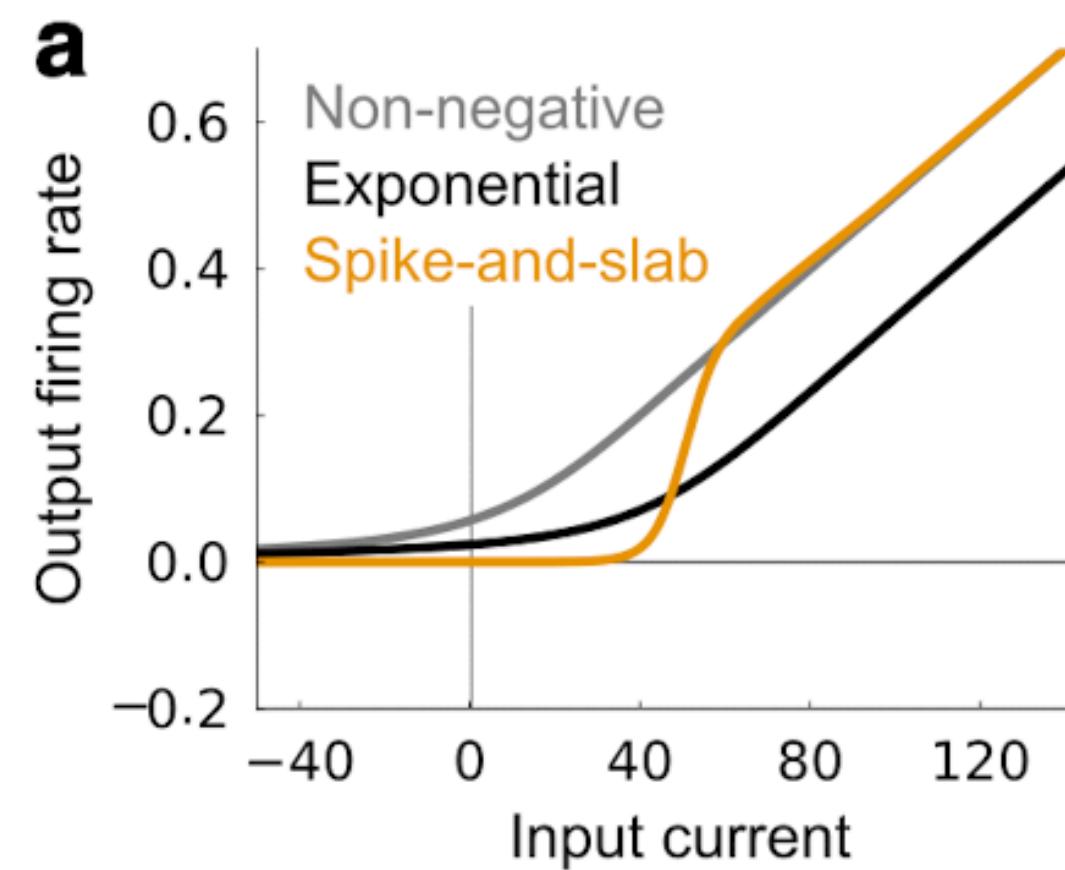
$$\tau_r \frac{dm_i}{d\tau} = -m_i - \sum_{j=1}^M w_{ij}^L \bar{c}_j + x_i$$

$$\tau_r \frac{d\bar{c}_j}{d\tau} = -\bar{c}_j + F_j \left( \sum_{i=1}^N w_{ji}^F m_i \right)$$

$$p_c(c) \propto \Theta(c)$$

$$p_c(c) = \frac{1}{c_0} \exp(-c/c_0)$$

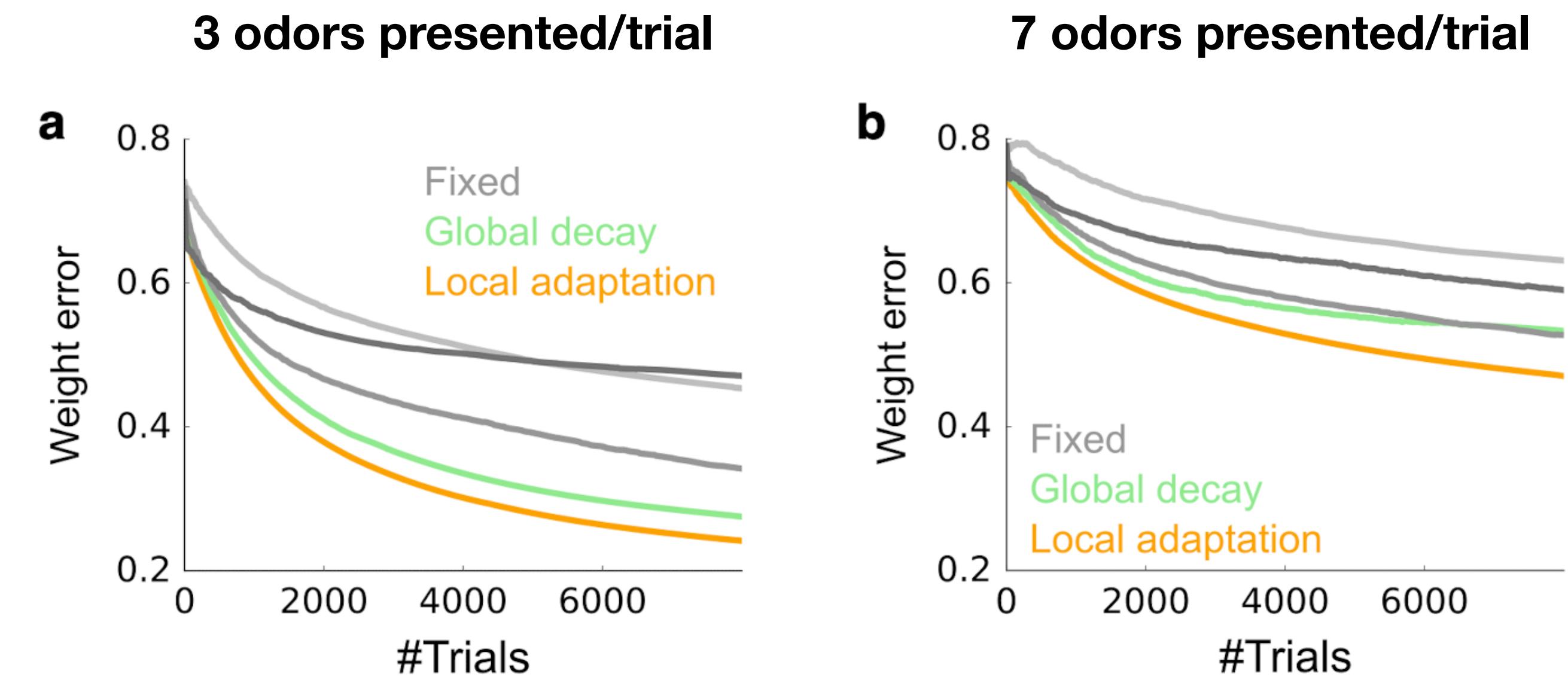
$$p(c_j) = (1 - c_0) \delta(c_j) + \text{Gamma}(\alpha, \alpha)$$



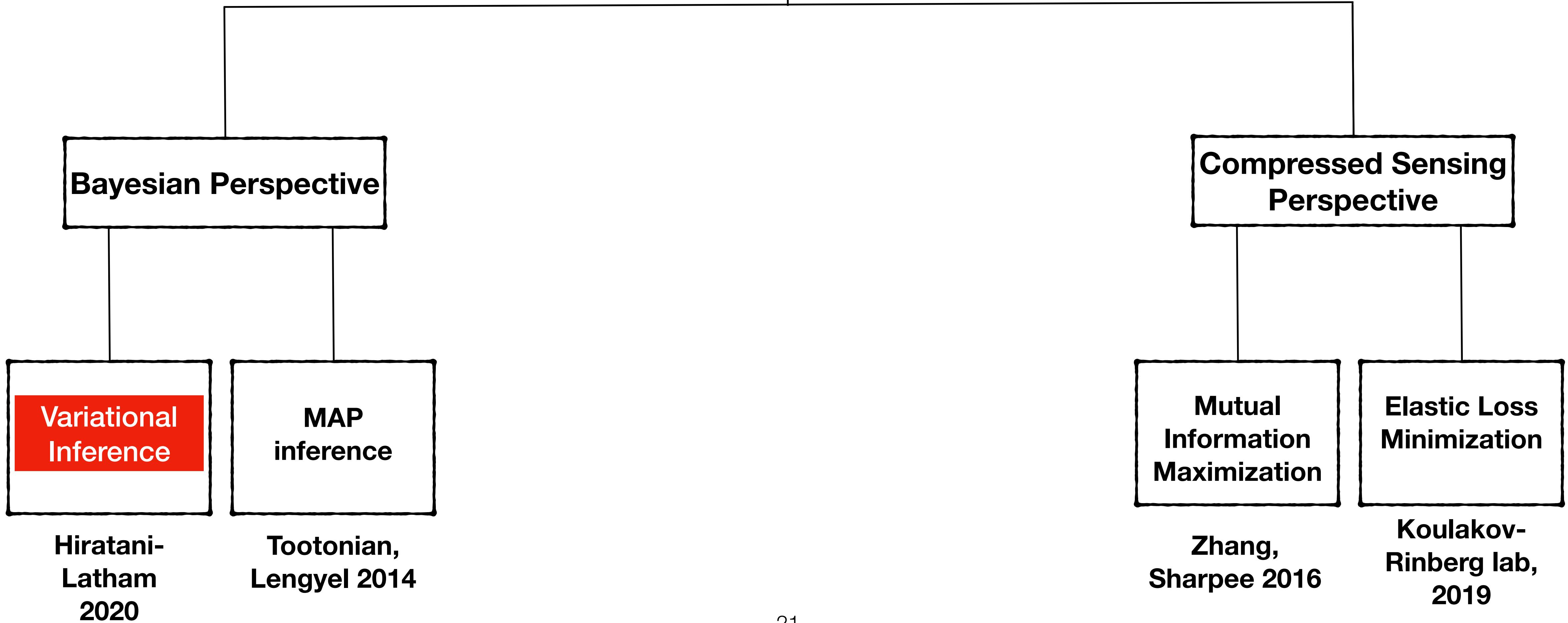
# Synaptic Plasticity rule

- Learning rate is product of two terms:  $1/(t\rho)$
- $1/\rho_j \propto S_j$  (lifetime sparseness)
- Fixed:  $1/(t\rho) = \text{constant}$
- Global Decay:  $1/\rho = \text{constant}$

$$\Delta w_{ji}^{F,t} = \frac{m_i c_j}{t \rho_j}$$
$$\Delta w_{ji}^{L,t} = \frac{m_i c_j}{t \rho_j}$$



# Odor Identity Recognition



# MAP inference: Quick Introduction

By Bayes rule,

$$p(\mathbf{c}_t | \mathbf{x}_t) \propto p(\mathbf{x}_t | \mathbf{c}_t) p(\mathbf{c}_t)$$

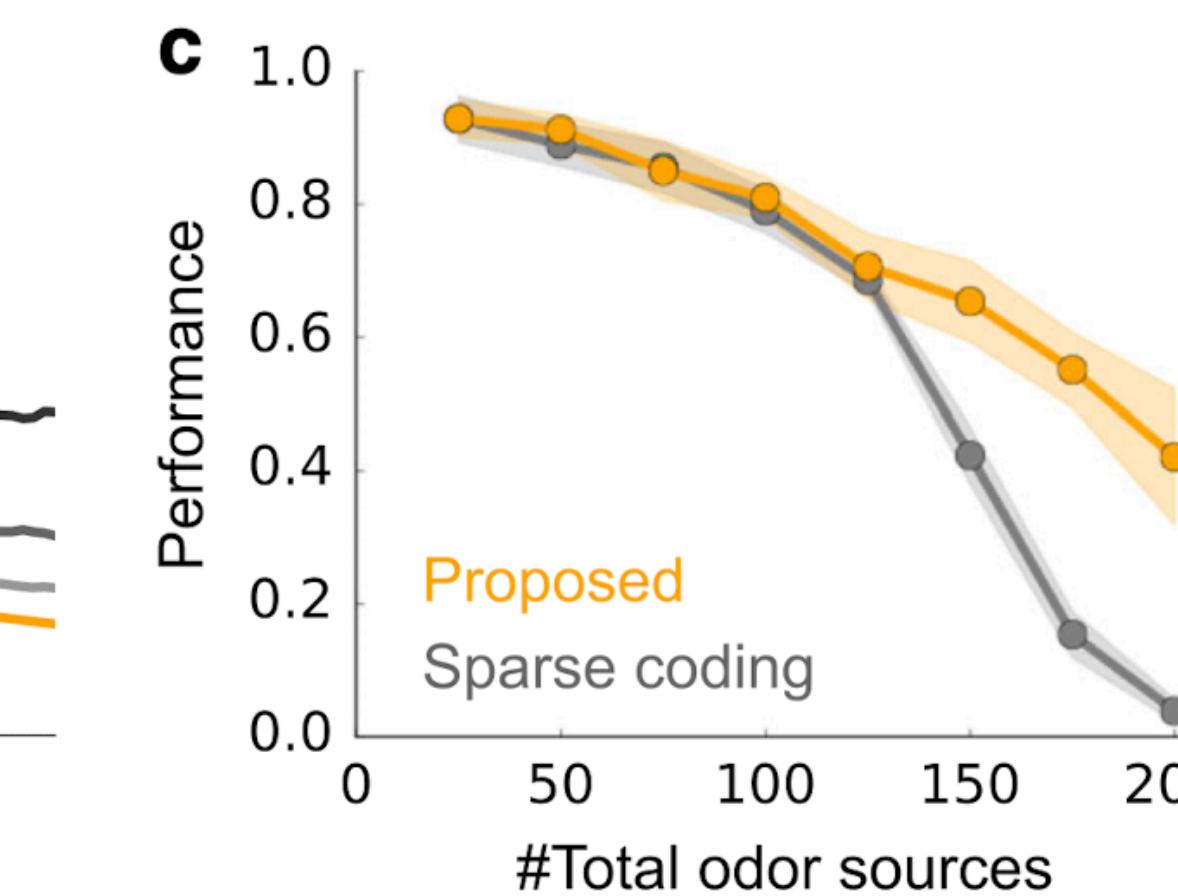
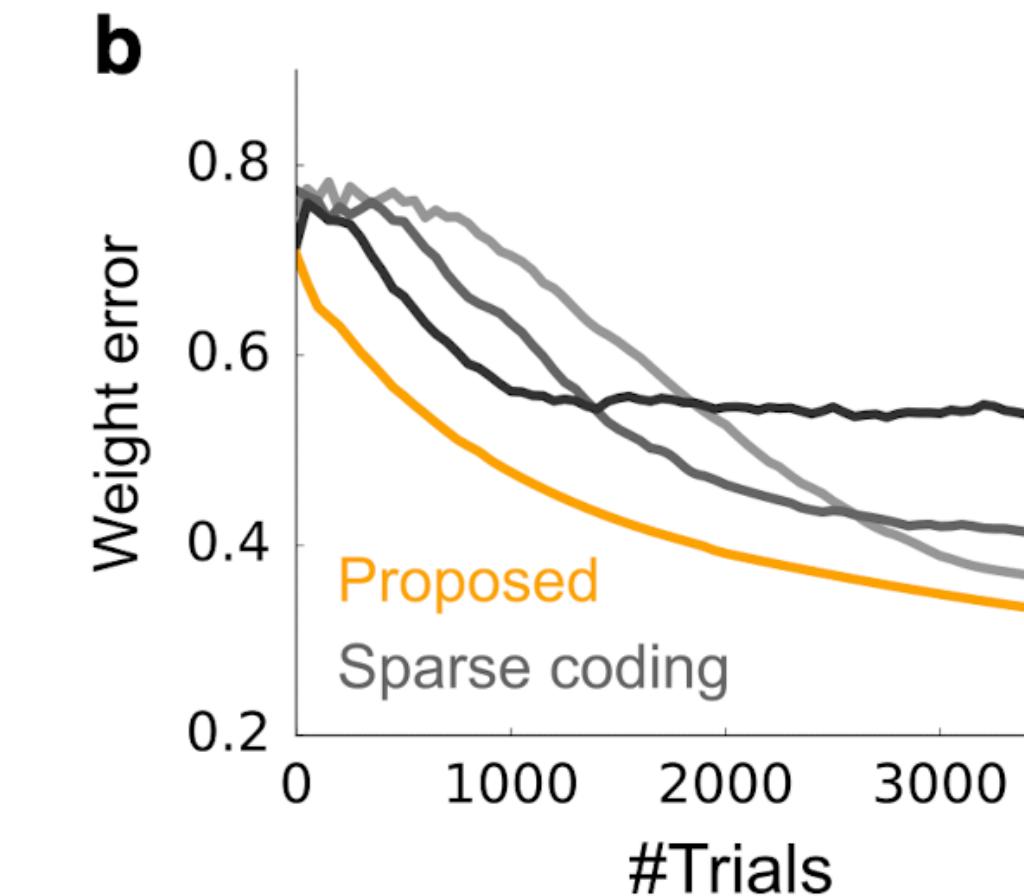
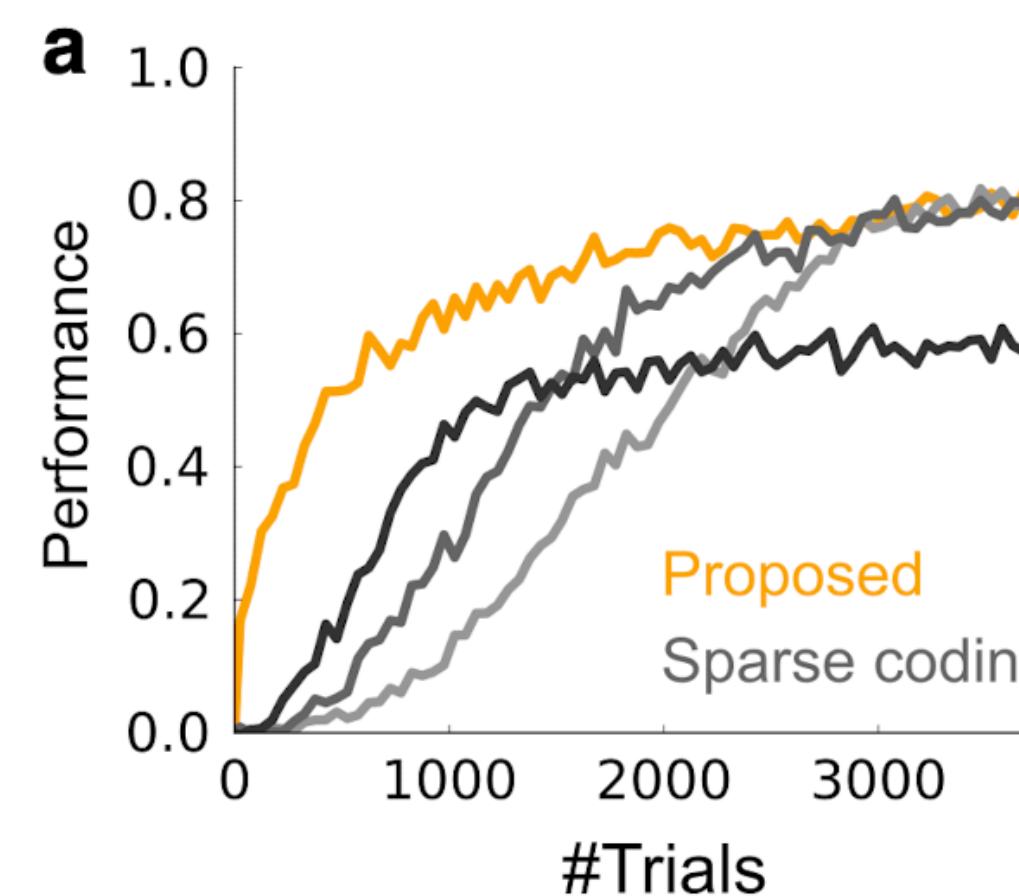
So, the Maximum a posteriori estimate is given by:

$$\hat{\mathbf{c}}_t = \arg \max_{\mathbf{c}} p(\mathbf{x}_t | \mathbf{c}, \hat{\mathbf{w}}) p(\mathbf{c})$$

We define an objective function:  $E_t \equiv \log p(\mathbf{x}_t | \hat{\mathbf{c}}_t, \hat{\mathbf{w}}) + \log p(\hat{\mathbf{c}}_t)$  and maximize with respect to  $c_j$  and  $w_{ij}$

# Comparison between Variational and MAP inference

- Variational approach doesn't require fine tuning and learns much faster (see a)
- Variational approach leads to lower error in weights (see b)
- Variational approach performs better when there are large number of odor sources (see c)



# Conclusion

- Variational Bayesian inference leads to a biologically plausible learning rules
- Some predictions are consistent with experiments, others can tested by future experiments
- Future work could involve, including periglomerular cells which have been implicated in whitening of OB, a natural prediction of circuitry in PCx