```
clear all;
final19_q7_data;
cvx_begin
    variables x(n) B0
    minimize(P'*x+B0)
    subject to
        -x <= 0
        -B0 <= 0
        B(1) = (1+rp)*B0
        for t=1:T-1
            B(t+1) = min((1+rp)*(B(t)+A(t,:)*x-E(t)),
(1+rn)*(B(t)+A(t,:)*x-E(t)))
        E(T)-B(T)-A(T,:)*x <= 0
cvx end
% Compare to investment if no bonds were purchased
cvx_begin
    variable D0
    minimize(D0)
    subject to
        -D0 <= 0
        D(1) = (1+rp)*D0
        for t=1:T-1
            D(t+1)=min((1+rp)*(D(t)-E(t)),(1+rn)*(D(t)-E(t)));
        end
        E(T)-D(T) <= 0
cvx_end
disp("Optimal values of x:")
disp(x)
disp("Optimal value of B0:")
disp(B0)
disp("Optimal total initial investment:")
disp(P'*x+B0)
disp("Optimal investment without bonds:")
disp(D0)
figure(1)
plot(1:T,B)
title('Optimal Cash Balance with Investments')
xlabel('Period')
ylabel('Cash Balance')
figure(2)
plot(1:T,D)
title('Optimal Cash Balance without Investments')
xlabel('Period')
ylabel('Cash Balance')
```

```
B =
    cvx real affine expression (scalar)
B =
    cvx mixed concave/real affine expression (1x2 vector)
B =
    cvx mixed concave/real affine expression (1x3 vector)
B =
   cvx mixed concave/real affine expression (1x4 vector)
B =
    cvx mixed concave/real affine expression (1x5 vector)
B =
    cvx mixed concave/real affine expression (1x6 vector)
B =
   cvx mixed concave/real affine expression (1x7 vector)
B =
    cvx mixed concave/real affine expression (1x8 vector)
B =
    cvx mixed concave/real affine expression (1x9 vector)
B =
    cvx mixed concave/real affine expression (1x10 vector)
B =
    cvx mixed concave/real affine expression (1x11 vector)
```

```
B =
```

cvx mixed concave/real affine expression (1x12 vector) Calling SDPT3 4.0: 30 variables, 18 equality constraints For improved efficiency, SDPT3 is solving the dual problem. _____ num. of constraints = 18 dim. of linear var = 30******************** SDPT3: Infeasible path-following algorithms version predcorr gam expon scale_data NT 1 0.000 1 0 prim-obj dual-obi it pstep dstep pinfeas dinfeas gap cputime 0/0.000/0.000/2.2e+01/6.2e+00/7.4e+03/-8.638509e+02 0.000000e+00/ 0:0:00 | chol 1 1 1/0.978/1.000/4.9e-01/2.2e-02/4.5e+02/-5.247813e+01 -3.011420e+02/ 0:0:00/ chol 1 1 2|1.000|1.000|3.5e-07|2.2e-03|4.6e+01|-3.279908e+01 -7.859801e+01| 0:0:00 | chol 1 1 3/1.000/0.929/7.7e-08/3.6e-04/3.1e+00/-3.876965e+01 -4.181308e+01/0:0:00/ chol 1 1 4|0.908|0.918|3.9e-07|5.0e-05|3.3e-01|-4.063267e+01 -4.095806e+01| 0:0:00 | chol 1 1 5/0.598/1.000/5.2e-07/2.2e-06/1.7e-01/-4.068372e+01 -4.085830e+01/ 0:0:01/ chol 1 1 6 | 0.930 | 0.772 | 1.4e-07 | 7.1e-07 | 4.4e-02 | -4.073543e+01 -4.077891e+01 | 0:0:01 chol 1 1 7/0.951/1.000/3.6e-08/5.1e-08/1.9e-02/-4.074352e+01 -4.076239e+01/ 0:0:01 chol 1 1 8|0.937|0.963|1.1e-08|1.1e-08|9.3e-04|-4.074909e+01 -4.075002e+01| 0:0:01 chol 2 2 9|0.981|0.955|1.4e-07|2.6e-09|5.2e-05|-4.074949e+01 -4.074954e+01| 0:0:01/ chol 2 2 10/0.988/0.988/1.7e-09/1.2e-09/6.8e-07/-4.074950e+01 -4.074950e+01/ 0:0:01 stop: max(relative gap, infeasibilities) < 1.49e-08</pre> number of iterations = 10 primal objective value = -4.07495028e+01 dual objective value = -4.07495034e+01gap := trace(XZ) = 6.78e-07 relative gap = 8.22e-09 actual relative gap = 7.03e-09 rel. primal infeas (scaled problem) = 1.71e-09

rel. dual " " = 1.23e-09 rel. primal infeas (unscaled problem) = 0.00e+00

```
rel. dual
                                   = 0.00e+00
norm(X), norm(y), norm(Z) = 3.2e+00, 2.9e+01, 2.5e+01
norm(A), norm(b), norm(C) = 9.0e+00, 3.6e+00, 2.5e+01
Total CPU time (secs) = 0.59
CPU time per iteration = 0.06
termination code = 0
DIMACS: 3.1e-09 0.0e+00 3.1e-09 0.0e+00 7.0e-09 8.2e-09
Status: Solved
Optimal value (cvx_optval): +40.7495
D =
   cvx real affine expression (scalar)
Calling SDPT3 4.0: 24 variables, 12 equality constraints
  For improved efficiency, SDPT3 is solving the dual problem.
num. of constraints = 12
dim. of linear\ var\ = 24
*******************
  SDPT3: Infeasible path-following algorithms
******************
version predcorr gam expon scale_data
               0.000 1 0
         1
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj
cputime
 0/0.000/0.000/1.5e+01/5.6e+00/7.0e+03/-8.630333e+02 0.000000e+00/
 0:0:00/ chol 1 1
 1/0.364/1.000/9.8e+00/1.7e-02/3.3e+03/-7.994290e+02 -2.122809e+02/
 0:0:00 | chol 1 1
 2|1.000|1.000|4.3e-06|1.7e-03|1.6e+02|-4.021972e+01 -1.954105e+02|
 0:0:00/ chol 1 1
 3/1.000/0.978/7.2e-07/2.0e-04/3.4e+00/-4.065878e+01-4.402331e+01/
 0:0:00/ chol 1 1
 4|0.974|0.925|2.4e-07|3.1e-05|4.2e-01|-4.153863e+01 -4.195341e+01|
 0:0:00 | chol 1 1
 5/0.955/0.944/2.9e-08/3.3e-06/5.0e-02/-4.176869e+01 -4.181810e+01/
 0:0:00/ chol 1 1
 6|0.986|0.884|5.3e-09|5.4e-07|5.6e-03|-4.178863e+01 -4.179415e+01|
 0:0:00/ chol 1 1
 7|0.976|0.981|1.7e-09|1.1e-08|1.7e-04|-4.179018e+01 -4.179035e+01|
 0:0:00 | chol 1 1
 8/0.989/0.989/2.9e-10/4.8e-10/2.0e-06/-4.179024e+01 -4.179024e+01/
 0:0:00/ chol 1 1
 9|0.996|0.996|2.6e-12|4.3e-11|3.2e-08|-4.179024e+01 -4.179024e+01|
 0:0:00/
 stop: max(relative gap, infeasibilities) < 1.49e-08</pre>
```

```
number of iterations = 9
primal objective value = -4.17902433e+01
dual objective value = -4.17902434e+01
gap := trace(XZ)
                     = 3.20e-08
relative gap
                     = 3.79e-10
actual relative gap = 3.46e-10
rel. primal infeas (scaled problem) = 2.63e-12
rel. dual " " = 4.35e-11
rel. primal infeas (unscaled problem) = 0.00e+00
rel. dual " " = 0.00e+00
norm(X), norm(y), norm(Z) = 3.4e+00, 7.1e+01, 4.2e+01
norm(A), norm(b), norm(C) = 7.8e+00, 2.0e+00, 2.9e+01
Total CPU time (secs) = 0.14
CPU time per iteration = 0.02
termination code = 0
DIMACS: 2.6e-12 0.0e+00 9.1e-11 0.0e+00 3.5e-10 3.8e-10
Status: Solved
Optimal value (cvx_optval): +41.7902
Optimal values of x:
   0.0000
  18.9324
   0.0000
   0.0000
  13.8495
   8.9228
Optimal value of B0:
  1.7792e-06
Optimal total initial investment:
  40.7495
Optimal investment without bonds:
  41.7902
```





