ACHU WILSON

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Research Interests

Robot Manipulation, Tactile Sensing, Grasping, In-hand Manipulation, Computer Vision, Reinforcement Learning for Robot Control, Design of Robot Actuators, Controllers and Mechanisms

EDUCATION

Government Engineering College

Sreekrishnapuram, India

aff. University of Calicut, India; B. Tech in Electronics and Communication Engineering

August 2008 - May 2012

EXPERIENCE

Robert Bosch Centre for Cyber Physical Systems, Indian Institute of Science

Bangalore, India

Technical Associate

September 2020 Onwards

- Developed a two finger robot hand which has tactile sensing on the inner and outer surfaces, provided by GelSight and a proximity sensor array respectively.
- Working on reinforcement learning algorithms to explore and pick up objects in vision denied environments, especial, inside granular media.

Perceptual Science Group, CSAIL, MIT

Cambridge, MA, USA

Research Assistant

Oct 2018 - Oct 2019

- Designed a fully actuated robot hand with multiple GelSight tactile sensors. It involved design of the mechanical system, electronics and software for simultaneous capture of multiple high resolution optical tactile sensors.
- Developed point cloud processing software for fusion and registration of multiple point cloud data streams from the GelSight sensors on the robot hand.

Sastra Robotics

Cochin, India

Co-Founder & Chief Technology Officer

Aug 2013 - Sept 2018

- As the technical guy of the founding team, designed and built the drive systems, kinematics, motion controllers and user software for the SCARA and 6 axis robots for device testing applications. Later built and managed a technical team of 20 engineers, designed product road-maps and oversaw the R&D.
- Developed force control capabilities for robots to ensure that the devices are tested without even any cosmetic damage.
- Developed a sensorized finger to analyze the haptic feedback generated on touchscreens.
- Created image processing and machine learning systems to read and analyze state of devices for LCD screens, dials
 and status of switches of the devices.

Asimov Robotics (Energid Technologies)

Cochin, India

Robotics Software Engineer

June 2012 - July 2013

- Developed ROS & LabVIEW interfaces for Cyton Gamma 7DOF manipulator through Energid Actin framework.
- o Designed electrical subsystems, motor controllers and sensor interfaces for a humanoid social robot.
- Implemented kinematics and motion planning systems for a bi-manual anthropomorphic manipulator system using ROS.

Publications

Papers

- Radhen Patel, Rui Ouyang, Branden Romero, Achu Wilson, Edward Adelson, **Digger Finger: GelSight for Granular Media**, Accepted *International Symposium of Experimental Robotics (ISER) 2020 Malta*
- Achu Wilson, Design and Development of a Magneto-Rheological Linear Clutch for Force controlled Human Safe Robots, IEEE International Conference on Robotics and Automation (ICRA) 2017, Singapore

Posters

- Achu Wilson, Shaoxiong Wang, Branden Romero, Edward Adelson, **Design of a Fully Actuated Robotic Hand**With Multiple Gelsight Tactile Sensors, RoboTac Workshop, International Conference on Intelligent Robotics and
 Systems (IROS)2019 Macau.
- Daniel Fernandes Gomes, Achu Wilson, Shan Luo, **GelSight Simulation for Sim2Real Learning**, ViTac: Integrating Vision & Touch Workshop, IEEE International Conference on Robotics & Automation (ICRA) 2019, Montreal.
- Achu Wilson, Modular, Whole Finger Tactile Sensing Gripper, Active Touch Workshop, IEEE International Conference on Robotics & Automation (ICRA) 2018, Brisbane.

SKILLS

- Programming Languages: Python, C/C++
- Technologies and Frameworks: OpenCV, Open3D, ROS, Drake, Numpy, TensorFlow, Keras, Matlab, LabVIEW
- Embedded Systems: AVR, ARM Cortex-M0 & Cortex-M4, FreeRTOS
- Electronics: Schematic Design, PCB development, Eagle, KiCad, NI MultiSim, Ansys Maxwell
- Design & Fabrication: Solidworks/FreeCAD, 3D Printing, Laser & Waterjet cutting, CNC Lathe & Mill, Molding Soft Robots

PATENTS

• Robot Arm for Testing of Touchscreen Applications Pub. No.: WO/2017/051263, International Application No.: PCT/IB2016/053292

ACCOMPLISHMENTS

- Finalist, Kuka Innovation Award 2021: Artificial Intelligence, Team: Blindgrasp, Role: Team Leader (finals ongoing).
- Winner, IEEE ICRA 2016 Humanitarian Robotics Challenge (HRATC), Team: Autobots, Role: Team Leader
- Best Project Award: MIT Class 2.12 (Introduction to Robotics) Spring 2019.
- Funding for side project by MIT Innovation Initiative under ProjX-2019 (Project: PulleyDrive).
- Best Undergraduate Project Award : High Altitude Platform based Communication System, 2011-2012, Government Engineering College, Sreekrishnapuram.
- Received TEQUIP funding from Government of India for Undergraduate Project.
- Winner of India Innovation Growth Program (IIGP) 2018 organized by Department of Science and Technology-India, MIT TATA Center and Lockheed Martin.
- Best First Line Entrepreneur Award 2017 from Kerala (State) Chief Minister.
- TiE Silicon Valley Top 50 Tech startups in world award 2017.
- First Prize, Circuit design competition at DHRUVA 2kX,2010 a national level tech festival.

LEADERSHIP EXPERIENCE

- Reviewer and Program Committee Member Advances in Robotics (AIR-2019) an International biennial conference organized by Robotics Society of India, Indian Institute of Technology, Chennai.
- Voting Member, Bureau of Indian Standards: Production Automation Systems & Robotics Sectional Committee.
- Industry Member in drafting the Robotics & Automation Roadmap for India, IEEE-SA Industry Connections Workshop, Indian Institute of Technology (IIT)-Delhi, June 2017.
- Elected as Student Representative in College Union for 2011-2012.
- Coordinated Robotics Exhibition for INVENTO 2012, an intercollegiate tech festival.
- ECE Department Exhibition Convener, GHATECH-2011, an intercollegiate tech festival.
- Exhibited a self-navigating robot to showcase OpenCV at FOSS.in 2009, one of the largest FOSS events in Asia.
- Conducted workshops for undergraduate students in various colleges on Robotics, ROS, simulation using NI Multisim, Embedded Systems Programming.