



**END SEMESTER ASSESSMENT (ESA) B.TECH. (CSE)  
IV SEMESTER**

**UE18CS256 – MICROPROCESSOR AND COMPUTER ARCHITECTURE  
LABORATORY**

**PROJECT REPORT**

**ON**

**BUILDING SECURITY SYSTEM USING ARDUINO**

**SUBMITTED BY**

NAME	SRN
1) Achyut Jagini	PES2UG19CS013
2) Amar S Sajjanshetty	PES2UG19CS032
3) Akshay B K	PES2UG19CS030
4) Amit	PES2UG19CS033

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**DEPARTMENT OF COMPUTER SCIENCE & ENGINEERING**

**ELECTRONIC CITY CAMPUS,**

**BENGALURU – 560100, KARNATAKA, INDIA**

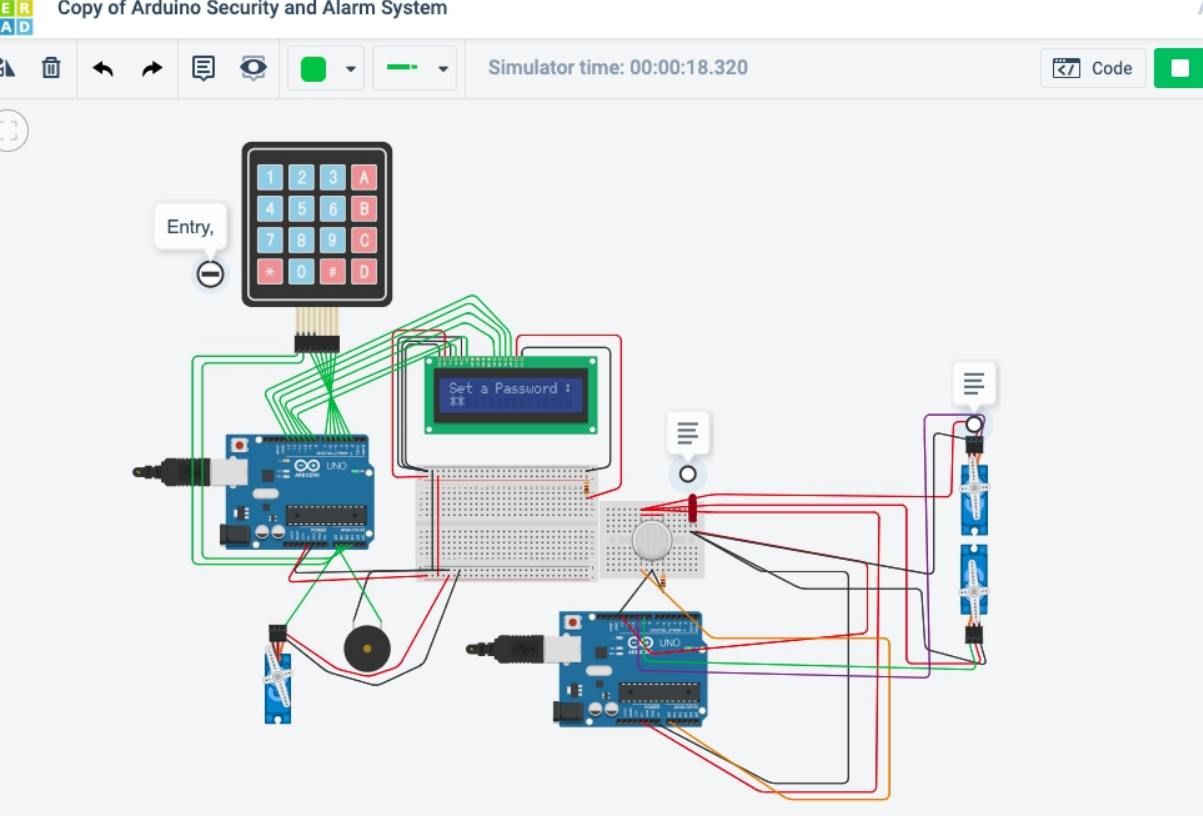
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## **ABSTRACT OF THE PROJECT:**

- ❖ This project is implemented using Arduino circuit board.
- ❖ In this project we made “ BUILDING SECURITY SYSTEM ” using following sensors.
  - 1) Arduino boards
  - 2) LCD screen
  - 3) Buzzer
  - 4) Servo motors.
  - 5) Number Keypad
  - 6) Gas sensor
  - 7) Led lights
  - 8) Bread boards.
- ❖ Our project helps to maintain security of the building.
- ❖ We have used 2 Arduino boards to implement the security system. First arduino board is connected with number keypad, servo motor (Main door), buzzer. The second Arduino board is connected with leds (indicator), pair of servo motors (emergency exit doors), gas sensors etc
- ❖ We have installed keypad with LCD screen to prompt the user to type his password to enter into the building.  
If the user fails to enter the correct password multiple times, the system will lock and the door remains closed.
- ❖ If any intruder tries to enter into the building and types incorrect password multiple times, then the system buzzer starts to make a emergency sound.
- ❖ If the building catches fire accidentally or by terrorists (manually) the gas sensor will sense the smoke from the building and this will automatically opens the exit door,

so that the people who were residing inside the building can escape out from the building and save there lives.

## CIRCUIT DIAGRAM:



## ARDUINO CODE:

```

#include <LiquidCrystal.h>
#include <Keypad.h>
#include <Servo.h>

LiquidCrystal LCD( 8, 9, 10, 11, 12, 13 );

Servo servo ;

const int buzzerPin = 14 ;
const int servoPin = 15 ;

const byte ROWS = 4, COLS = 4 ;

char keys[ROWS][COLS] = {{'1','2','3','A'},
  {'4','5','6','B'},
  {'7','8','9','C'},
  {'*','0','#','D'}
};

byte rowPins[ROWS] = { 16, 17, 2, 3 } ;

byte colPins[COLS] = { 4, 5, 6, 7 } ;

Keypad kpd = Keypad( makeKeymap(keys), rowPins, colPins, ROWS, COLS ) ;

char password[16], string[16] ;
int flag_h_setpassword = 1, flag_inputpassword = 0, flag_inputstring = 0, flag_opendoor = 1,
flag_state = 0, flag_remoteopen = 0, flag_lockdown = 0 ;
int count = 0, trial_count=0, pos = 0, state = 0 ;

void setup() {
  for(int k=8 ; k<14 ; k++) {
    pinMode(k,OUTPUT) ;
  }

  LCD.begin(16, 2) ;

  pinMode(buzzerPin, OUTPUT) ;
  servo.attach(servoPin) ;

  LCD.setCursor(0,0) ;
  LCD.print("  WELCOME !!") ;
  LCD.setCursor(0,1) ;
  LCD.print("Set a Password :)") ;

```

```

InitializePassword(), InitializeString() ;
CloseDoor() ;
}

void loop() {
    if( Serial.available() > 0 ) {
        state = Serial.read() ;
        flag_state = 0 ;
    }

    if( trial_count < 3 ) {

        char key = kpd.getKey() ;

        if( key != NO_KEY ) {

            if( flag_h_setpassword == 1 ) {
                H_SetPassword() ;
            }
            if( key == '*' ) {
                if( flag_inputpassword == 1 ) {
                    InitializePassword(), H_SetPassword() ;
                }
                else if( flag_inputstring == 1 ) {
                    InitializeString(), H_EnterPassword() ;
                }
            }
            else if( key == '#' ) {
                if( flag_inputpassword == 1 && count > 0 ) {
                    flag_inputpassword = 0 ;
                    password[count] = '\0' ;
                    H_EnterPassword() ;
                }
                else if( flag_inputstring == 1 && count > 0 ) {
                    flag_inputstring = 0 ;
                    string[count] = '\0' ;
                    if( Compare_Password_and_String() == 1 ) {
                        LCD.clear() ;
                        LCD.print("***VERIFIED!!***") ;
                        Serial.println("UNLOCKED !!") ;
                        trial_count = 0 ;
                        for( int i=0 ; i<3 ; ++i ) {
                            tone(buzzerPin, 500, 200) ;
                            delay(230) ;
                            tone(buzzerPin, 100, 200) ;
                            delay(300) ;
                            OpenDoor() ;
                        }
                    }
                }
            }
        }
    }
}

```

```

    else {
        LCD.clear() ;
        LCD.print("Wrong Password !") ;
        Serial.println("Someone unsuccessfully attempted to open the lock !") ;
        ++trial_count ;
        tone(buzzerPin, 100, 1000) ;
        delay(1000) ;
        H_EnterPassword() ;
    }
}
}
else if( flag_inputpassword == 1 || flag_inputstring == 1 ) {
    LCD.print(key) ;
    delay(100) ;
    LCD.setCursor(count,1) ;
    LCD.print('*') ;
    if( flag_inputpassword == 1 ) password[count] = key ;
    else if( flag_inputstring == 1 ) string[count] = key ;
    ++count ;
}
}
}
else {
    LCD.clear() ;
    LCD.setCursor(0,0) ;
    LCD.print("SYSTEM LOCKDOWN!") ;
    tone(buzzerPin, 1000, 1000) ;
    delay(1500) ;
    flag_lockdown = 1 ;
}
}

void InitializePassword() {
    for( int i=0 ; i<16 ; ++i )
        password[i] = 0 ;
}

void InitializeString() {
    for( int i=0 ; i<16 ; ++i )
        string[i] = 1 ;
}

void H_SetPassword() {
    LCD.clear() ;
    LCD.setCursor(0,0) ;
    LCD.print("Set a Password :)") ;
    LCD.setCursor(0,1) ;
    flag_h_setpassword = 0 ;
    flag_inputpassword = 1, count = 0 ;
}

```



```

void H_EnterPassword() {
    CloseDoor() ;
    LCD.clear() ;
    LCD.setCursor(0,0) ;
    LCD.print("Enter Password :") ;
    LCD.setCursor(0,1) ;
    flag_inputstring = 1, count = 0 ;
}

int Compare_Password_and_String() {
    int i ;
    for( i=0 ; password[i]!='\0' && string[i]!='\0' ; ++i ) {
        if( password[i] != string[i] )
            return 0 ;
    }
    if( password[i] == '\0' && string[i] == '\0' )
        return 1 ;
    else return 0 ;
}

void OpenDoor() {
    if( flag_opendoor == 1 )
        return;
    for( pos=15 ; pos<=100 ; ++pos ) {
        servo.write(pos) ;
        delay(15) ;
    }
    flag_opendoor = 1 ;
}

void CloseDoor() {
    if( flag_opendoor == 0 )
        return;
    for( pos=100 ; pos>=15 ; --pos ) {
        servo.write(pos) ;
        delay(15) ;
    }
    flag_opendoor = 0 ;
}

```

## 2 Aurdino

```

#include<Servo.h>
int sensor=0;

```

```

Servo m1;

```

```
Servo m2;

int pos1 = 0;
int pos2 = 0;

int flago1=0;
int flago2=0;

void setup() {
  m1.attach(9);
  m2.attach(10);
  pinMode(13, OUTPUT);
  Serial.begin(9600);
}

void loop() {
  sensor = analogRead(A0);

  if (sensor > 250)
  {
    digitalWrite(13, HIGH);
    Serial.println(sensor);
    open1();
    Serial.print("FIRE !! Please Exit ");
  }

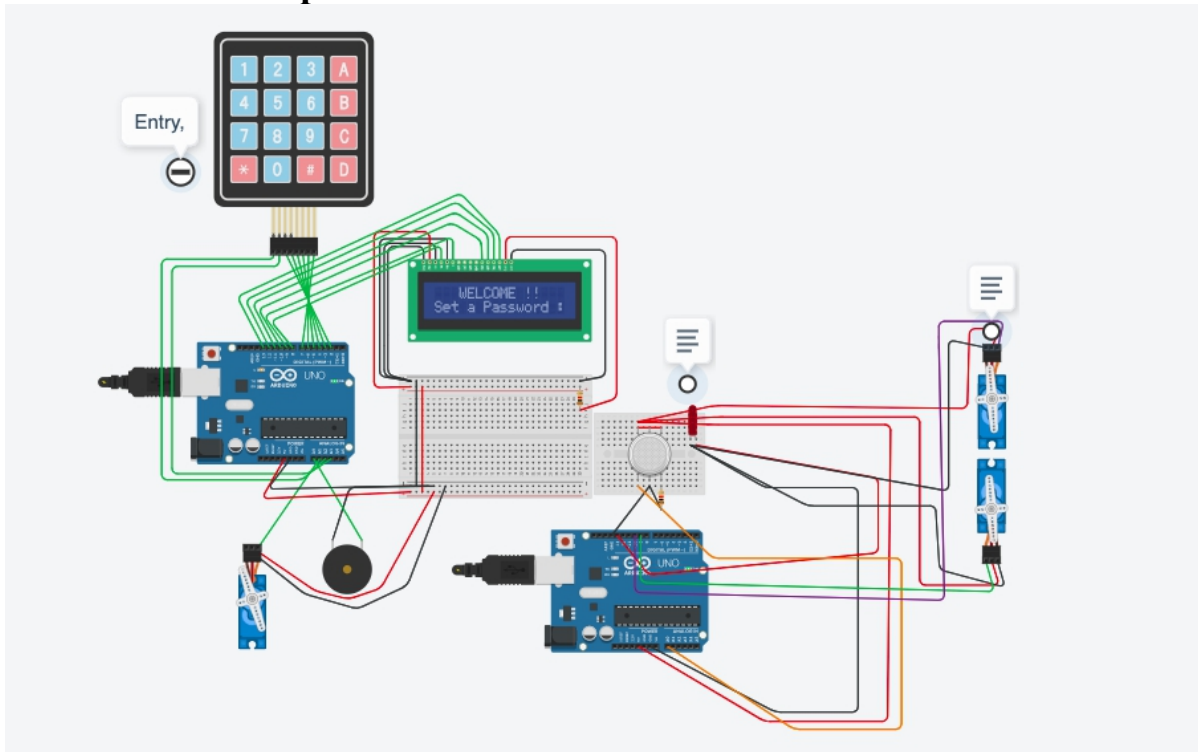
  else {
    digitalWrite(13, LOW);
    close1();
  }
}

void open1()
{
  m1.write(90);
  m2.write(90);
}

void close1()
{
  m1.write(0);
  m2.write(0);
}
```

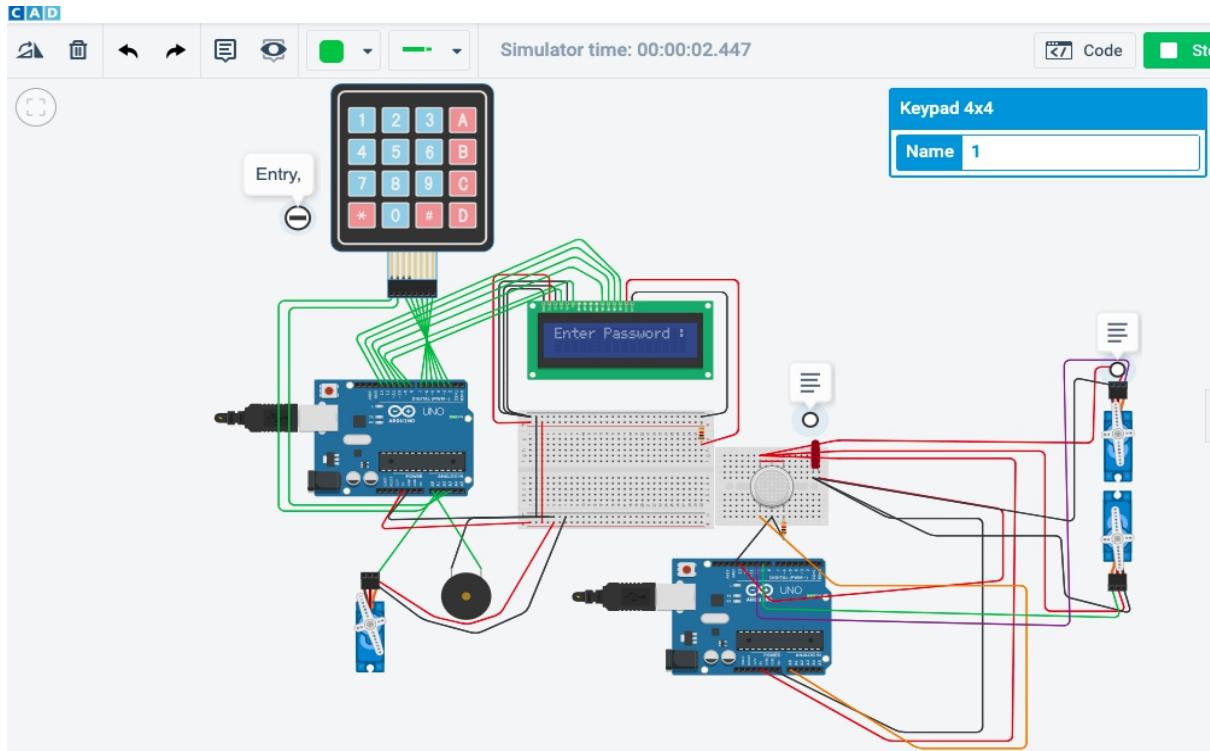
## SCREEN SHOTS OF THE OUTPUT:

welcome and set password

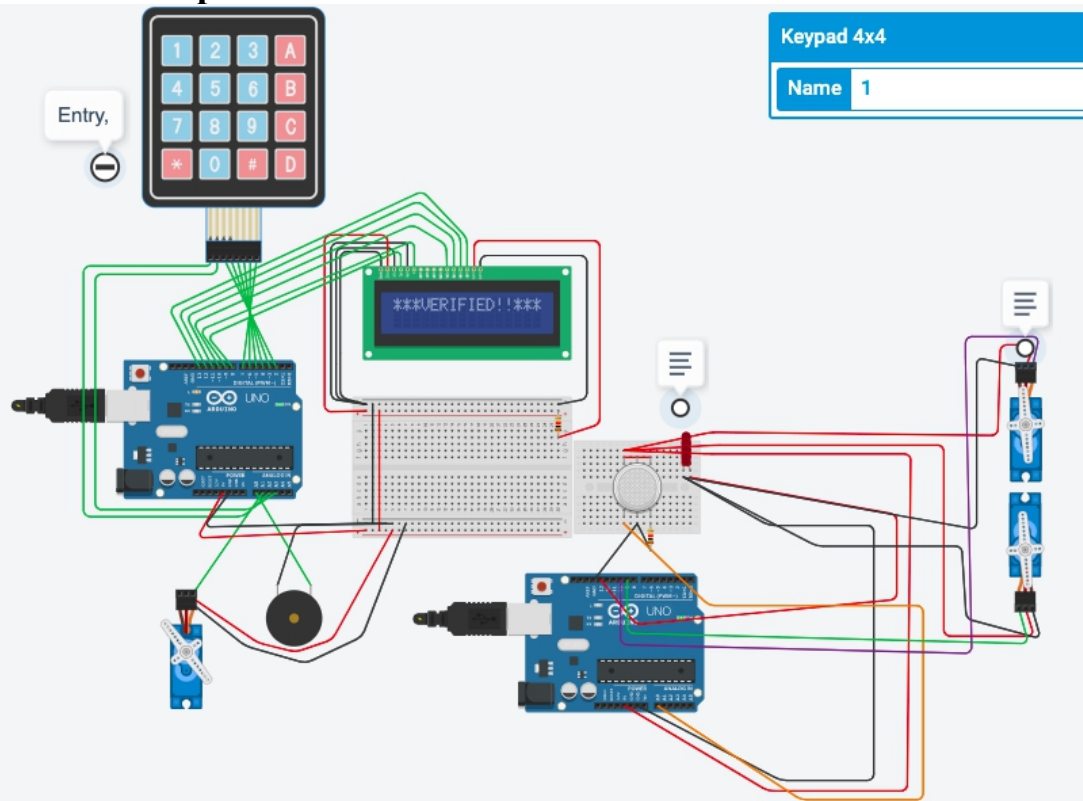


# Set password

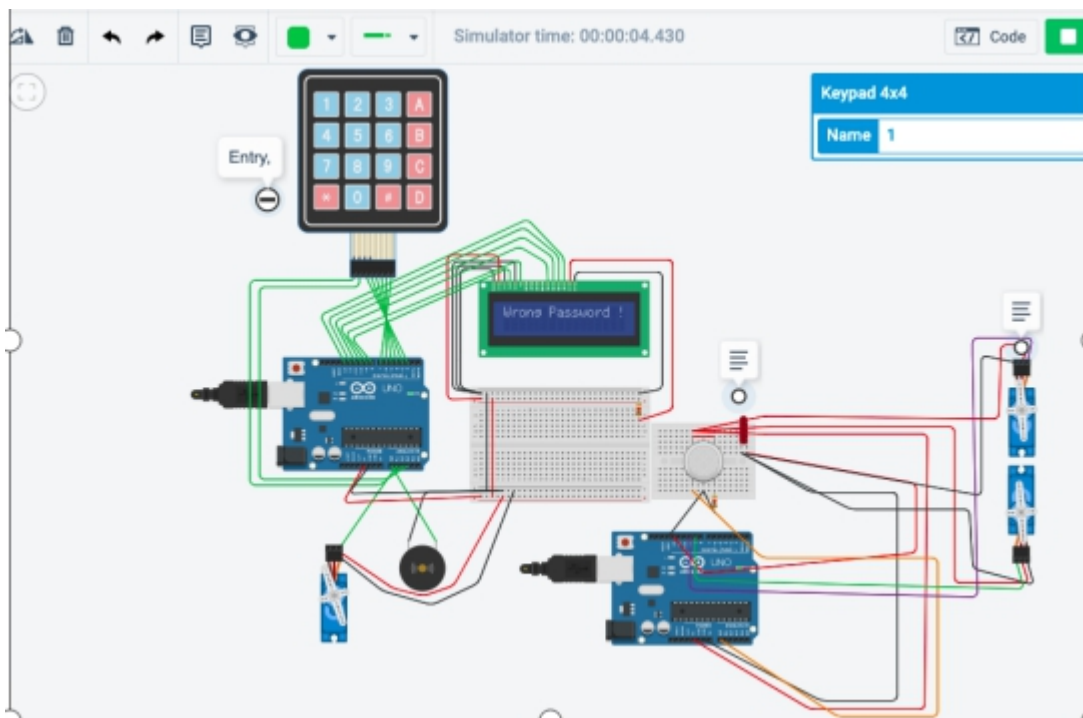
enter password



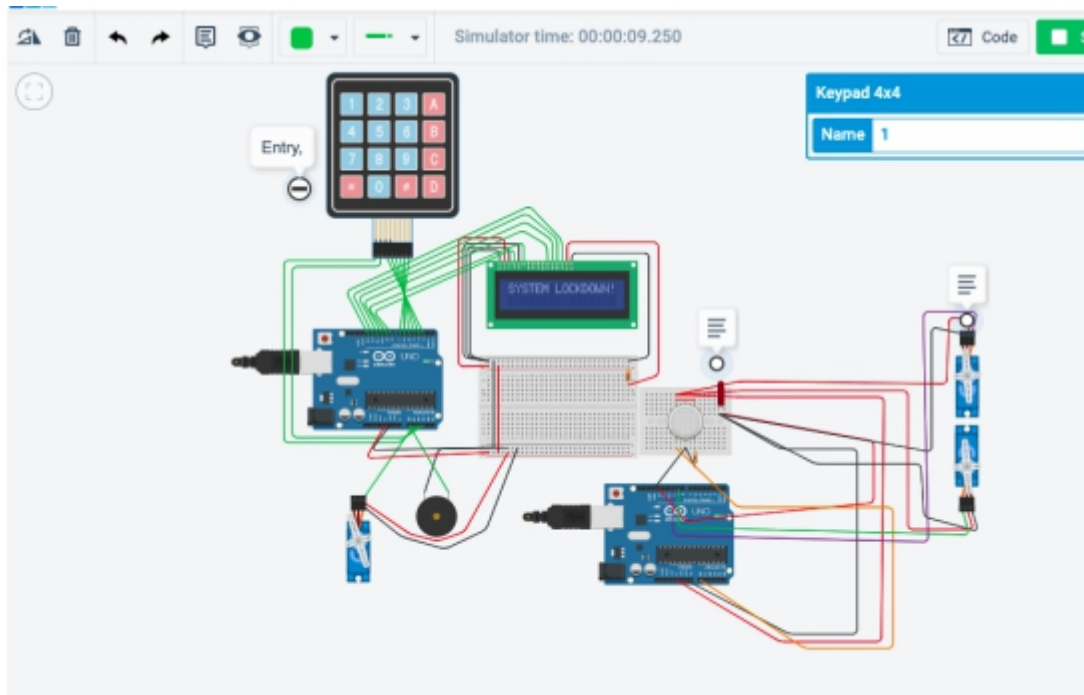
**Verified as correct password**



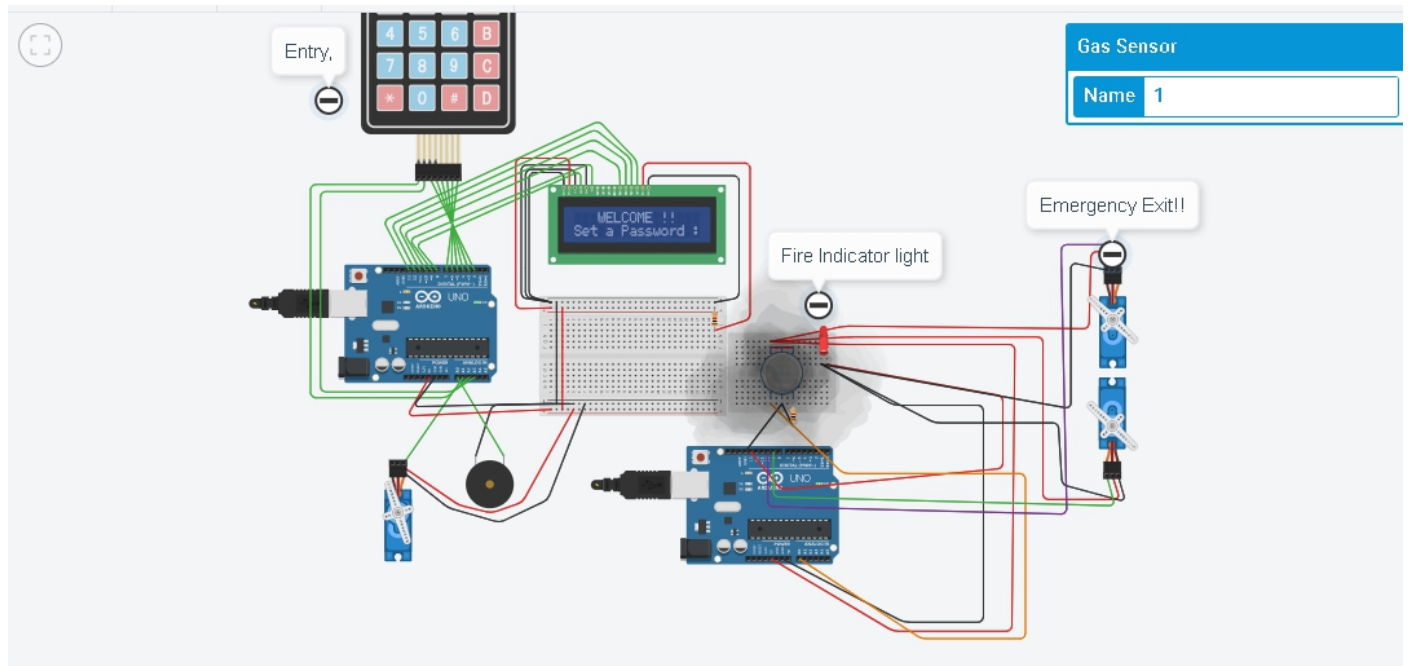
## Wrong password



## System lockdown if wrong password entered 3 times



**Fire alarm system. When the building catches fire. The emergency doors will open automatically**





## REFERENCES

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