

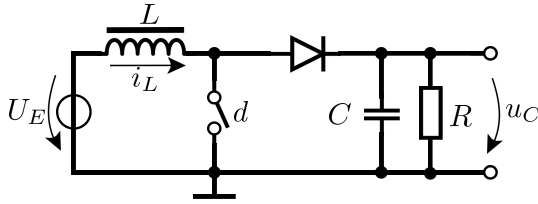
# Model Documentation of the Boost Converter

## 1 Nomenclature

### 1.1 Nomenclature for Model Equations

|       |                              |
|-------|------------------------------|
| $L$   | inductivity of the inductor  |
| $C$   | capacity of the capacitor    |
| $R$   | resistance of the load       |
| $U_E$ | input voltage                |
| $i_L$ | current through the inductor |
| $u_C$ | voltage over the capacitor   |
| $d$   | duty ratio of the switch     |

### 1.2 Circuit Diagram



## 2 Model Equations

State Vector and Input Vector:

$$\underline{x} = (x_1 \ x_2)^T = (i_L \ u_C)^T$$
$$\underline{u} = d$$

System Equations:

$$\dot{x}_1 = -(1 - u) \frac{1}{L} x_2 + \frac{U_E}{L} \quad (1a)$$

$$\dot{x}_2 = (1 - u) \frac{1}{C} x_1 - \frac{1}{RC} x_2 \quad (1b)$$

Parameters:  $L, C, R, U_E$

Outputs:  $x_2 = u_C$

### 2.1 Assumptions

1. The switching frequency is high enough, to prevent the inductor from fully discharging between charging stages.

## 2.2 Exemplary parameter values

|               |       | Symbol              | Value    |
|---------------|-------|---------------------|----------|
| Inductivity   | $L$   | 0.00018             | H        |
| Capacity      | $C$   | $2.0 \cdot 10^{-5}$ | F        |
| Resistance    | $R$   | 10                  | $\Omega$ |
| Input Voltage | $U_E$ | 24                  | V        |

## 3 Derivation and Explanation

Using PWM (puls width modulation), instead of only discrete values  $d \in \{0, 1\}$  representing an *open* or *closed* switch, any value of the interval  $[0, 1]$  can be modeled. This is done by using the averaged values for states and inputs:

$$\bar{d} = \frac{1}{T} \int_t^{t+T} d(\tau) d\tau$$

$$\bar{x}_i = \frac{1}{T} \int_t^{t+T} x_i(\tau) d\tau \quad i = 1, 2$$

with the switching period  $T$ . For  $T \rightarrow 0$ , which is achieved by a high enough switching frequency, an averaged model can be obtained.

## 4 Simulation

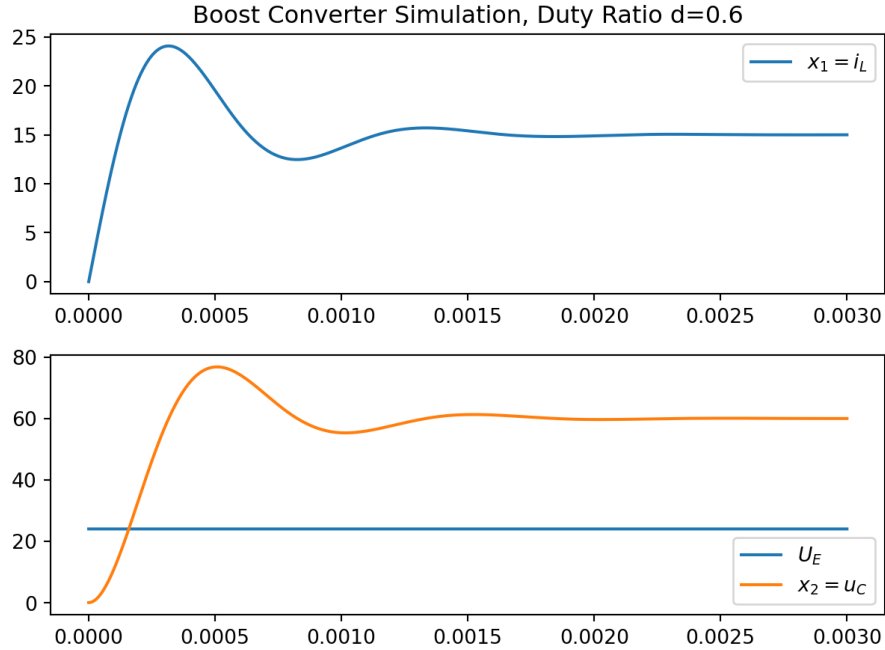


Figure 1: Simulation of the boost converter.

## References

- [1] K. Röbenack, Nichtlineare Regelungssysteme: Theorie und Anwendung der exakten Linearisierung. Berlin, Heidelberg: Springer Berlin Heidelberg, 2017. doi: 10.1007/978-3-662-44091-9.
- [2] Sira-Ramirez, H.: A geometric approach to pulse-width modulated control in nonlinear dynamical systems. IEEE Trans. on Automatic Control, 34(2):184–187, Februar 1989.
- [3] R. H. G. Tan and L. Y. H. Hoo, DC-DC converter modeling and simulation using state space approach, in 2015 IEEE Conference on Energy Conversion (CENCON), Oct. 2015, pp. 42–47. doi: 10.1109/CENCON.2015.7409511.