Model Documentation of the Buck-Boost Converter

1 Nomenclature

1.1 Nomenclature for Model Equations

L inductivity of the inductor

C capacity of the capacitor

R resistance of the load

 U_E input voltage

 i_L current through the inductor

 u_C voltage over the capatitor

d duty ratio of the switch

1.2 Circuit Diagram

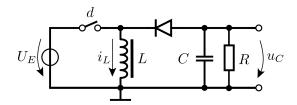


Figure 1: Circuit

2 Model Equations

State Vector and Input Vector:

$$\underline{x} = (x_1 \ x_2)^T = (i_L \ u_C)^T$$
$$u = d$$

System Equations:

$$\dot{x}_1 = (1 - u)\frac{1}{L}x_2 + \frac{U_E}{L}u\tag{1a}$$

$$\dot{x}_2 = -(1-u)\frac{1}{C}x_1 - \frac{1}{RC}x_2 \tag{1b}$$

Parameters: $L \ C \ R \ U_E$ Outputs: $x_2 = u_C$

2.1 Exemplary parameter values

| | | Symbol | Value |
|---------------|-------|---------------------|--------------|
| Inductiviy | L | 0.00018 | H |
| Capacity | C | $2.0 \cdot 10^{-5}$ | \mathbf{F} |
| Resistence | R | 10 | Ω |
| Input Voltage | U_E | 24 | V |

3 Derivation and Explanation

See boost converter.

4 Simulation

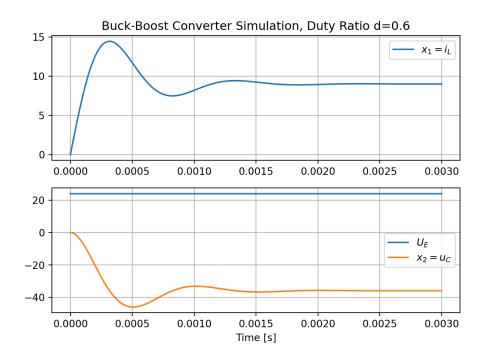


Figure 2: Simulation of the buck-boost converter.

References

- [1] R. H. G. Tan and L. Y. H. Hoo, DC-DC converter modeling and simulation using state space approach, in 2015 IEEE Conference on Energy Conversion (CENCON), Oct. 2015, pp. 42–47. doi: 10.1109/CENCON.2015.7409511.
- [2] K. Röbenack, Nichtlineare Regelungssysteme: Theorie und Anwendung der exakten Linearisierung. Berlin, Heidelberg: Springer Berlin Heidelberg, 2017. doi: 10.1007/978-3-662-44091-9.