

Model Documentation of the Hysteresis System

1 Nomenclature

1.1 Nomenclature for Model Equations

s_1	switching treshold down
s_2	switching treshold up
y_i	output values of the hysteresis system for $i = 1, 2$
$T_{storage}$	time constant of the internal linear first order system (PT1)
w	input signal
x_1	state signal
a_i	auxiliary signals for $i = 1, 2, 3, 4, 5$

2 Model Equations

Input Vector:

$$u = w$$

Equations:

$$a_1 = \begin{cases} -1, & \text{for } w < 4 \\ 0, & \text{for } w \geq 4 \end{cases} \quad (1a)$$

$$a_2 = \begin{cases} 0, & \text{for } w < 8 \\ 1, & \text{for } w \geq 8 \end{cases} \quad (1b)$$

$$a_3 = a_1 + a_2 + x_1 \quad (1c)$$

$$a_4 = \begin{cases} 0, & \text{for } w < 4 \\ & \text{or } w < 8 \text{ in case w decreased under 4} \\ & \text{and did not rise over 8 since then} \\ 1, & \text{for } w > 8 \\ & \text{or } w > 4 \text{ in case w increased over 8} \\ & \text{and did not sink under 4 since then} \end{cases} \quad (1d)$$

$$x_1 = [0, 1] \quad (1e)$$

$$a_5 = [2, 11] \quad (1f)$$

Parameters: $s_1, s_2, y_1, y_2, T_{storage}$

Outputs: y

2.1 Exemplary parameter values

Symbol	Value
s_1	4
s_2	8
y_1	2
y_2	11
$T_{storage}$	0.0001

3 Derivation and Explanation

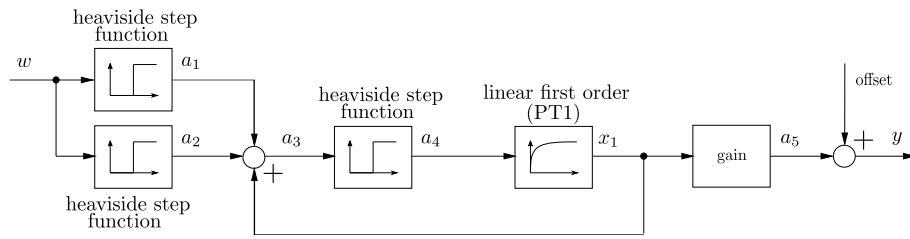


Figure 1: Block Diagram

4 Simulation

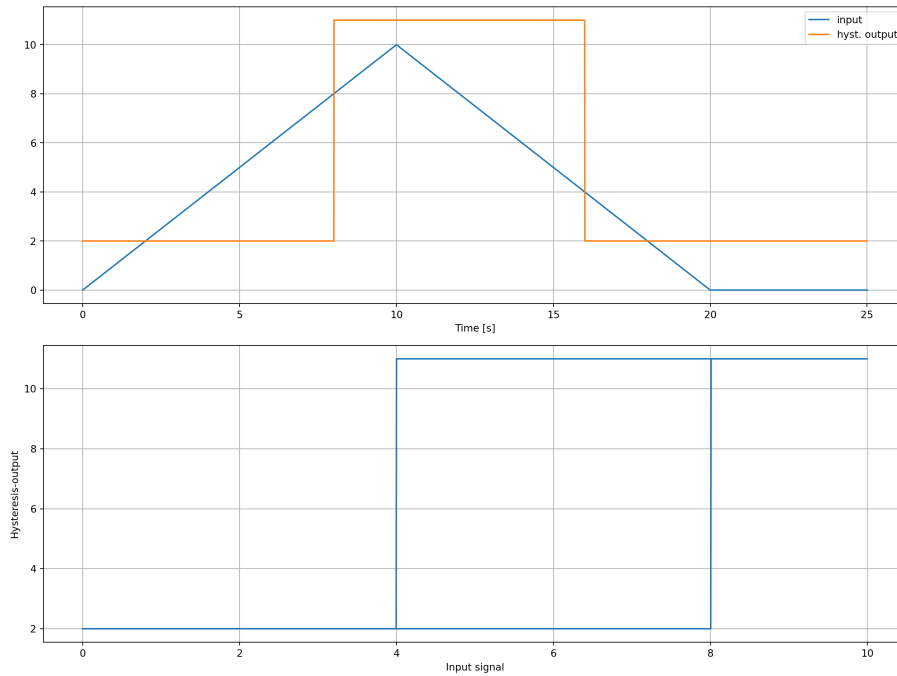


Figure 2: Simulation of the hysteresis system.

References

- [1] Knoll, Carsten: *Approximation of a simple hysteresis system.*, Python script published 2021.
<https://github.com/TUD-RST/pyblocksim/blob/master/examples/example-hysteresis.py>