# Model Documentation of the Boost Converter

## 1 Nomenclature

## 1.1 Nomenclature for Model Equations

L inductivity of the inductor

C capacity of the capacitor

R resistance of the load

 $U_E$  input voltage

 $i_L$  current through the inductor

 $u_C$  voltage over the capatitor

d duty ratio of the switch

#### 1.2 Circuit Diagram

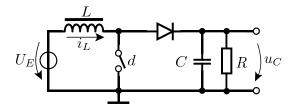


Figure 1: Circuit

# 2 Model Equations

State Vector and Input Vector:

$$\underline{x} = (x_1 \ x_2)^T = (i_L \ u_C)^T$$
$$\underline{u} = d$$

System Equations:

$$\dot{x}_1 = -(1-u)\frac{1}{L}x_2 + \frac{U_E}{L} \tag{1a}$$

$$\dot{x}_2 = (1 - u)\frac{1}{C}x_1 - \frac{1}{RC}x_2 \tag{1b}$$

Parameters:  $L, C, R, U_E$ 

Outputs:  $x_2 = u_C$ 

## 2.1 Assumptions

1. The switching frequency is high enough, to prevent the inductor from fully discharging beween charging stages.

## 2.2 Exemplary parameter values

|               |       | Symbol              | Value    |
|---------------|-------|---------------------|----------|
| Inductiviy    | L     | 0.00018             | Н        |
| Capacity      | C     | $2.0 \cdot 10^{-5}$ | F        |
| Resistence    | R     | 10                  | $\Omega$ |
| Input Voltage | $U_E$ | 24                  | V        |

# 3 Derivation and Explanation

Using PWM (puls width modulation), instead of only discrete values  $d \in \{0, 1\}$  representing an *open* or *closed* switch, any value of the interval [0, 1] can be modeled. This is done by using the averaged values for states and inputs:

$$\begin{split} \bar{d} &= \frac{1}{T} \int_t^{t+T} d(\tau) d\tau \\ \bar{x}_i &= \frac{1}{T} \int_t^{t+T} x_i(\tau) d\tau \quad i = 1, 2 \end{split}$$

with the switching period T. For  $T \to 0$ , which is achieved by a high enough switching frequency, an averaged model can be obtained.

## 4 Simulation

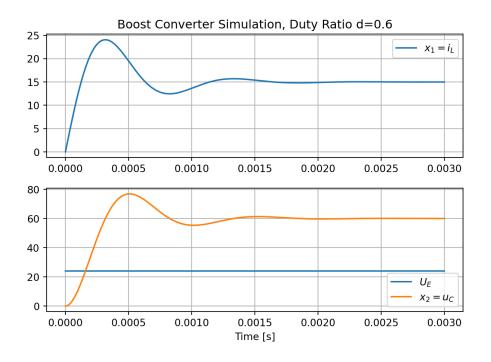


Figure 2: Simulation of the boost converter.

# References

- [1] K. Röbenack, Nichtlineare Regelungssysteme: Theorie und Anwendung der exakten Linearisierung. Berlin, Heidelberg: Springer Berlin Heidelberg, 2017. doi: 10.1007/978-3-662-44091-9.
- [2] Sira-Ramirez, H.: A geometric approach to pulse-width modulated control in nonlinear dynamical systems. IEEE Trans. on Automatic Control, 34(2):184–187, Februar 1989.
- [3] R. H. G. Tan and L. Y. H. Hoo, DC-DC converter modeling and simulation using state space approach, in 2015 IEEE Conference on Energy Conversion (CENCON), Oct. 2015, pp. 42–47. doi: 10.1109/CENCON.2015.7409511.