

Supporting personnel in warehouses with the inertial measurement unit

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October 10, 2018

Abstract

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List of Acronyms and Abbreviations

This document requires readers to be familiar with terms and concepts described in RFC 1235 [1]. For clarity we summarize some of these terms and give a short description of them before presenting them in next sections.

IPv4	Internet Protocol version 4 (RFC 791 [2])
IPv6	Internet Protocol version 6 (RFC 2460 [3])

1 Introduction

It was conjectured in [1] that multicasting could provide gains by

See also [4], the paper [5], and the book [6].

1.1 Theoretical framework/literature study

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1.2 Research questions, hypotheses

We saw that several solutions exist for displacement tracking using ultrasonic sensors. We would like to experiment with an IMU and find out if it is capable of executing similar measurements.

Our hypothesis is that we can correctly decide whether an item had been placed inside the correct container or not. In this scenario we assume that the containers are around the size of 50-100 cm wide and long.

2 Method(s)

We implement our own software for Android operating system[7]. We use Android Studio [8] to implement our application and to deploy it to the mobile device. We decided to use Java programming language [9] for the implementation. Our test device is a Xiaomi Redmi Note 4 mobile phone [10] and its inbuilt measurement units.

We implement an application according for the mentioned system. For this, we use already existing libraries on GitHub to avoid implementing complex algorithms such as a Kalman filter[11]. In our application we use two GitHub projects. After collecting the sensor data, we use FSensor [12] to filter the data. This helps us filter out the noise and keep the useful data. This step is an important step as the raw data is very noisy. —————citation here if we can find something—————. Then the acceleration data is integrated twice to get position and at this point another GitHub repository is used. It is the GraphView [13]. This provides a simple way to plot data on the phone screen. Using this method, the X and Y position data is displayed and the results can be seen. After starting the app, the tracking starts and automatically stops after a few seconds, concluding the results. This time is enough to perform the movement of placing the item from one container to another but short enough not to accumulate too much error increasing the accuracy of the final position.

3 Results and Analysis

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4 Discussion

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A Insensible Approximation

Note that the Appendix or Appendices are Optional.