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#include "Proj_1E_header_file.h"

volatile int m;
volatile char overflow;
unsigned int PORT_1;

int main (void){
    unsigned long counter_squared, counter=1;
    m=1;
    PORT_1=1;
    overflow=0;
    setup_HW;
    sei();
    T1_65ms_clock_tick();

    while(1){
        counter_squared = counter*counter;
        if((!(counter%33))&& (switch_2_down)){
            Num_to_PC_U(10, counter); Char_to_PC('\t');
            Num_to_PC_U(10, counter*counter); newline();
            counter = (counter + 1)%0x10000;
            Timer_T2_sub(T2_delay_2ms);}
    }

ISR(TIMER1_OVF_vect) {
    I2C_Tx_2_integers(PORT_1, ~PORT_1);
    if (m<=5){PORT_1 |= (PORT_1 << 1);m += 1;}
    else PORT_1 = PORT_1 << 1;
    if(overflow)PORT_1 |= 1;
    if (PORT_1 & 0x8000) overflow=1;
    else overflow = 0;
}

//Used in ISR but apparently does not need to be volatile?
//overflow is set to 1 when the most left hand leds are illuminated

//32 bits are reserved for each of these variables

//This subroutine starts HW clock Timer 1 that generates an interrupt every 65ms
//Interrupts enable several process to take place simultaneously
//In this case squares are calculated some of which are printed out
//"counter%33" is only zero when counter is 33, 66, 99 etc.
//Only print out results if Switch_2 has been pressed
//code in this while-loop could be interrupted at any point
//limits the value of counter to avoid overflow and garbage out.

//m += 1; is shorthand for m = m+1;
//once "m" is 6 simply shift the display left
//if overflow is 1 execute "PORT_1 |= 1;".
//0x8000 = binary 1000000000000000

```