

# GRACE HOPPER CELEBRATION



ANITA  
B.ORG

How we built a  
successful  
product they  
didn't even know  
they wanted

This is a story of how a ragtag team of developers designed and built an educational raspberry-pi robot and brought it from a hackathon to our community.

# Take aways

Some neat stuff we learned along the way  
...while doing good for the community.

○ ITERATION

○ EMPOWERMENT

○ COMMUNITY

# The Team

Terry Tan | Software Developer

Smita Ghosh | Configuration Analyst

Rebecca Thayil | AI Engineer

Natan Organick | AI Engineer



**Vanguard**

#GHC19

# A HopperBot History

A hackathon gave us the opportunity to begin building HopperBot, an interactive learning platform.

'17

'17 - '19

In the following 2 years we improved HopperBot far beyond the prototype we began with until it was ready to bring to schools.

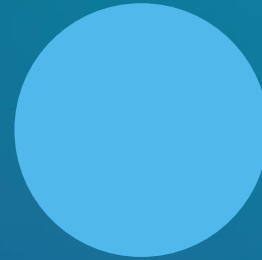
We took HopperBot to a STEAM Expo called GETT – Girl's Exploring Tomorrow's Technology – and got to teach girls how to code through our platform.

'18, '19

# The Beginning



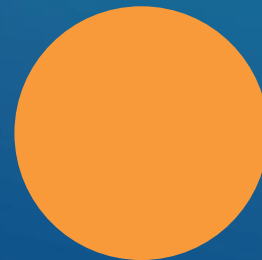
Ideation Session



First Generation Robot



Experiences at the Start



MVP Momentum

# MVP Robot



## Hardware

- Raspberry Pi 3 running raspbian
- 2 wheel chassis kit
- DC motors
- Duct tape



## Architecture

- Ran webapp and web server on the Pi
- Opened ngrok tunnel on Pi
- website sends user commands via REST request to web service
- Commands are executed on Pi

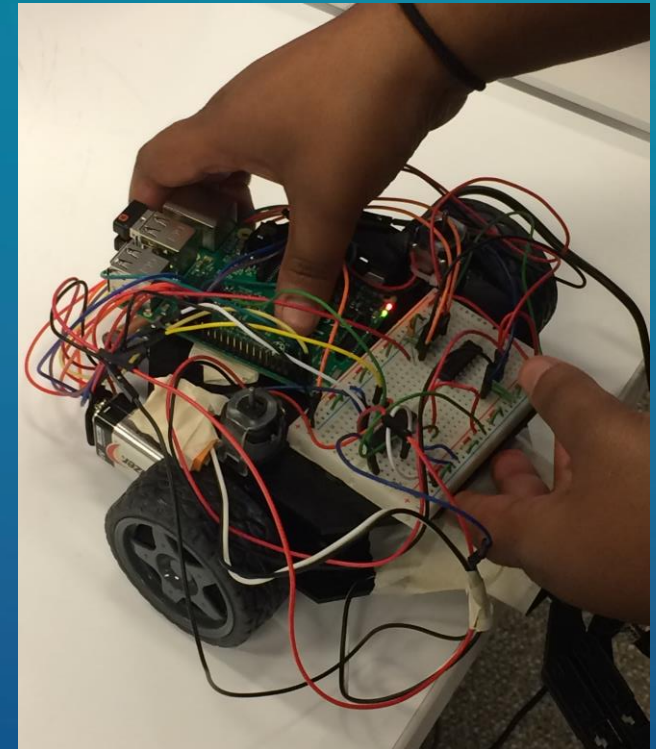
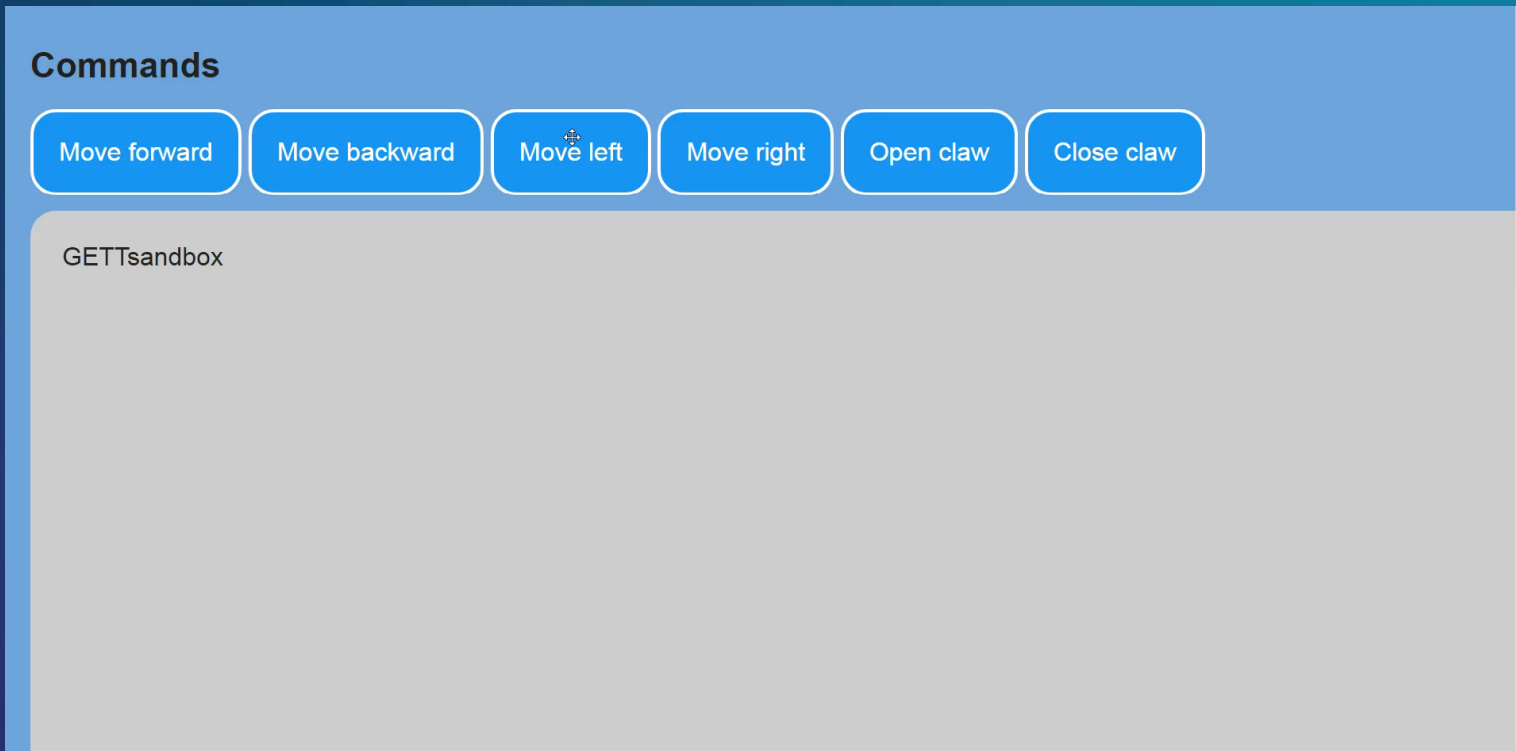


## Webapp

- HTML/CSS/JS
- Drag and Drop UI
- Supports only one move at a time



# First Generation Robot

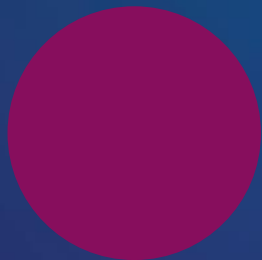




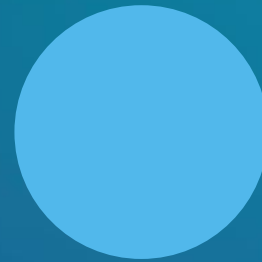
# The Middle



Feedback and  
Learning



Tech Iteration



GETT

# Technical Improvements



## Hardware

- Raspberry Pi 3 running raspbian
- 4 wheel chassis kit
- Case
- Cleaned up wires



## Architecture

- Publish subscribe communication model
- Host on platform



## Webapp

- Hosted on Heroku
- Google's Blockly API
- Replaced Flask with node

# Second Generation Robot

Vanguard - GETT Coding!

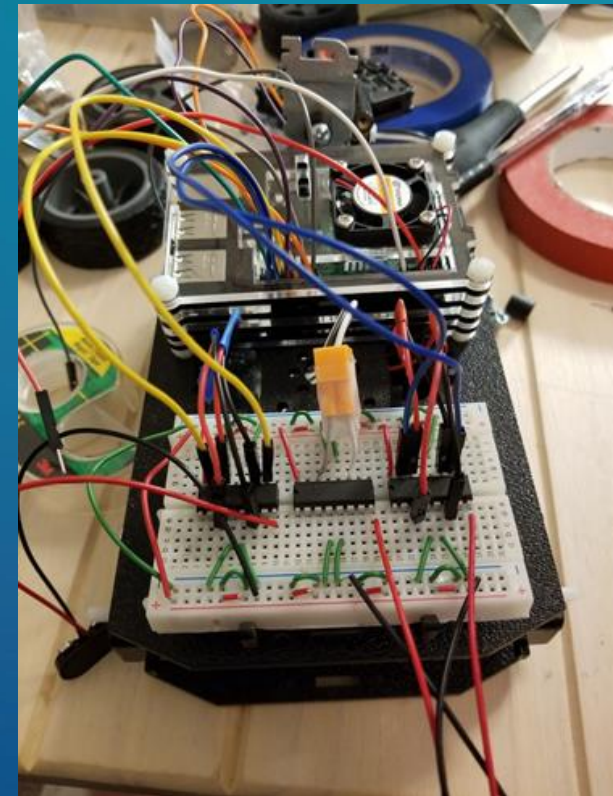
Logic  
Lists  
Loops  
Math  
Text  
Variables  
Functions  
Library  
Controller Mode  
Motor Mode  
Pin Mode

setup RaspberryPi  
for each item i in list create list with 19, 26, 20, 21, 5, 0, 12, 1, 6, 16, 14  
turn on pin #  
turn off pin #  
set pin # to OUTPUT mode  
sleep for 0.5 seconds  
clean up RaspberryPi  
do set pin # to OUTPUT mode

100%

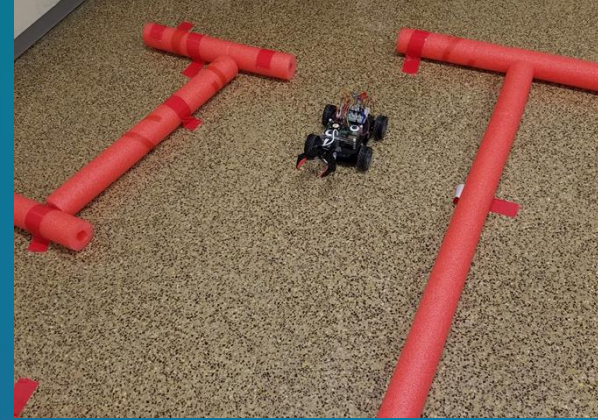
Run Code

```
i = None  
  
import RPi.GPIO as GPIO  
import time  
import bot  
  
GPIO.setmode(GPIO.BCM)  
for i in [19, 26, 20, 21, 5, 0, 12, 1, 6, 16, 14]:  
    GPIO.setup(i, GPIO.OUT)
```





# GETT – A Successful Day



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# Lessons Learned

○ Outcome-driven product design

○ Things go wrong and that's OK

○ Promoting STEAM in communities

# Thank You!



Check out Vanguard's  
Tech (1862) and  
Career (1922) Booth!