

From Human-Human Joint Action to Human-Robot Joint Action

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1.1 Joint Action Theory

What is Joint Action: sebanz06

1.1.1 What do we need to perform a Joint Action?

1.1.2 Commitment

1.1.3 Perception and prediction

1.1.4 Coordination

1.2 How to endow a robot with Joint Action abilities

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1.2.2 Perspective taking and human mental states

1.2.3

1.3 A three level architecture

1.3.1 The three levels of Pacherie

1.3.2 A three level robotics architecture

+ related work on others robotics architecture

Cited while no other citation: [?]