

Econ 675: HW 2

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1 Kernel Density Estimation

1.1

First we consider the kernel density derivative estimator. $\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^N k\left(\frac{X_i - x}{h}\right)$

The expectation of the estimator is:

$$\mathbb{E}[\hat{f}^{(s)}(x)] = \mathbb{E}[\hat{f}^{(s)}(x, h_n)] = \int_{-\infty}^{\infty} \frac{(-1)^s}{h^{1+s}} k^{(s)}\left(\frac{z-x}{h}\right) f(z) dz$$

where $k^{(s)}$ is the s^{th} derivative of the kernel function Now integrate by parts

$$\begin{aligned} & \int_{-\infty}^{\infty} \frac{(-1)^s}{h^{1+s}} k^{(s)}\left(\frac{z-x}{h}\right) f(z) dz = \\ & (-h) k^{(s-1)}\left(\frac{z-x}{h}\right) f^{(1)}(z) \Big|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \frac{(-1)^{s-1}}{h^{1+s-1}} k^{(s)}\left(\frac{z-x}{h}\right) f^{(1)}(z) dz \end{aligned}$$

As $k(\cdot)$ is a P^{th} order kernel function and $s - 1 < P$, the first term on the RHS of the equation above is equal to zero. Integrating by parts $s-1$ more times and changing the base, we get the following expression

$$\int_{-\infty}^{\infty} k(u) f^{(s)}(uh + x) du$$

So now we take a P^{th} order Taylor expansion of $f^{(s)}(uh + x)$ around x , which gives us

$$\begin{aligned} f^{(s)}(x) + \frac{1}{P!} \int_{-\infty}^{\infty} k(u) f^{(s+P)}(uh + x)(uh + x - x)^P du + o(h_n^P) \\ = f^{(s)}(x) + \frac{1}{P!} \int_{-\infty}^{\infty} k(u) f^{(s+P)}(uh + x)(uh)^P du + o(h_n^P) \\ = f^{(s)}(x) + \frac{f^{(s+P)}(x)}{P!} \mu_P(K) h_n^P + o(h_n^P) \end{aligned}$$

where $\mu_P(K) = \int_{\mathbb{R}} u^P K(u) du$ - which gives the result. (Note: the second term is the bias of the estimator)

Now consider the variance of the estimator

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \frac{1}{nh^{2+2s}} \mathbb{V} \left[k^{(s)} \left(\frac{z - x}{h} \right) \right] = \frac{1}{nh^{2+2s}} \mathbb{E} \left[k^{(s)} \left(\frac{z - x}{h} \right) \right]^2 - \frac{1}{n} \mathbb{E} \left[\frac{1}{nh^{1+s}} k^{(s)} \left(\frac{z - x}{h} \right) \right]^2$$

Now using our derivation of the expected value of our estimator we can rewrite the expression above as:

$$\frac{1}{nh^{2+2s}} \mathbb{E} \left[k^{(s)} \left(\frac{z - x}{h} \right) \right]^2 - \frac{1}{n} f^{(s)}(x)^2 + O \left(\frac{1}{n} \right)$$

(This comes from $\left\{ \frac{f^{(s+P)}(x)}{P!} \mu_P(K) h_n^P + o(h_n^P) \right\}$ being bounded)
So continuing on, we just expand the first term a bit

$$\begin{aligned}
\mathbb{V}[\hat{f}^{(s)}(x)] &= \frac{1}{nh^{2+2s}} \int_{-\infty}^{\infty} k^{(s)} \left(\frac{z-x}{h} \right)^2 f(z) dz - \frac{1}{n} f^{(s)}(x)^2 + O\left(\frac{1}{n}\right) \\
&= \frac{1}{nh^{1+2s}} \int_{-\infty}^{\infty} k^{(s)}(u) f(uh+x) du - \frac{1}{n} f^{(s)}(x)^2 + O\left(\frac{1}{n}\right) \\
&= \frac{f(x)}{nh^{1+2s}} \int_{-\infty}^{\infty} k^{(s)}(u) du - \frac{1}{n} f^{(s)}(x)^2 + O\left(\frac{1}{n}\right) \\
&= \frac{f(x)\nu_s(k)}{nh^{1+2s}} - \frac{1}{n} f^{(s)}(x)^2 + O\left(\frac{1}{n}\right)
\end{aligned}$$

where $\nu_s(k) = \int_{\mathbb{R}} k^{(s)}(u)^2 du$ is the roughness of the s^{th} derivative of a given function k - which gives the result.

1.2

The optimal bandwidth estimator solves the following problem

$$\min_h AIMSE[h] = \min_h \int_{-\infty}^{\infty} \left[\left(h_n^p \mu_p(k) \frac{f^{(P+s)}(x)}{P!} \right)^2 + \frac{\nu_s(k)f(x)}{nh_n^{1+2s}} \right] dx$$

Take first order conditions

$$0 = 2Ph^{2P-1} \int_{-\infty}^{\infty} \left[\left(\mu_p(k) \frac{f^{(P+s)}(x)}{P!} \right)^2 - \frac{(1+2s)\nu_s(k)f(x)}{nh^{2s}} \right] dx$$

$$\begin{aligned}
\frac{2Pnh^{1-2P-2s}}{(1+2s)\nu_s(k)} &= \left(\frac{P!}{\mu_p(k)\nu_{(P+s)}(f)} \right)^2 \\
h_{AIMSE,s} &= \left(\frac{(1+2s)\nu_s(k)(P!)^2}{2Pn\mu_p(k)^2\nu_{(P+s)}(f)} \right)^{\frac{1}{1-2P-2s}} \\
h_{AIMSE,s} &= \left(\frac{(1+2s)(P!)^2}{2Pn} \frac{\nu_s(k)}{\mu_p(k)^2\nu_{(P+s)}(f)} \right)^{\frac{1}{1-2P-2s}}
\end{aligned}$$

Now for a consistent bandwidth estimator we use cross validation procedure from the lecture notes. Cross-Validation minimizes the estimated mean-squared error through a choice of bandwidth.

$$h^* = \operatorname{argmin}_{h \in \mathbb{R}^{++}} CV(h) = \frac{1}{n^2 h} \sum_{i=1}^n \sum_{j=1}^n K\left(\frac{X_i - X_j}{h}\right) K\left(\frac{X_i - X_j}{h}\right) - \frac{2}{n} \sum_{i=1}^n \hat{f}_{-i}(X_i)$$

where $\hat{f}_{-i}(X_i)$ is the estimated density w/o x_i in the sample.

1.3

1.3.1

PUT GRAPHS HERE

1.3.2

Talk about convergence here!!!!

1.3.3 C

onsidering a rule-of-thumbs estimate of the bandwidth, we assume the DGP is gaussian, so

$$\bar{h}_{AIMSE} = M^{-1} \sum_{m=1}^M \hat{h}_{AIMSE,m} =$$

2 Linear Smoothing, Cross-Validation and Series

2.1

Local polynomial regression solves the following problem:

$$\hat{\beta}_{LPR} = \operatorname{argmin}_{\beta \in \mathbb{R}^{p+1}} \frac{1}{n} \sum_{i=1}^N (Y_i - r_p(x-x)\beta)^2 K\left(\frac{x_i - x}{h}\right)$$

where $r_p(u) = (1, u, u^2, \dots, u^p)'$ The true regression function $e(x_i)$ is estimated by $\hat{e}(x) = \hat{\beta}_{LPR}$, which can be rewritten as a weighted least-squares problem where $\hat{\beta}_{LPR}(x) = (\mathbf{R}_p' \mathbf{W} \mathbf{R}_p)^{-1} \mathbf{R}_p' \mathbf{W} \mathbf{Y}$ where the weighting matrix is a diagonal matrix with the kernel functions of the x_i .
where

$$\mathbf{R}_p = \begin{bmatrix} 1 & (x_1 - x) & (x_1 - x)^2 & \cdots & (x_1 - x)^p \\ \vdots & \cdots & \ddots & \ddots & \vdots \\ 1 & (x_n - x) & \cdots & \cdots & (x_n - x)^p \end{bmatrix}$$

and \mathbf{W} is a matrix with kernel weights of x_i s on the diagonal

$$\mathbf{W} = \begin{bmatrix} K\left(\frac{x_1 - x}{h}\right) & 0 & 0 & 0 \\ 0 & K\left(\frac{x_2 - x}{h}\right) & 0 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & K\left(\frac{x_n - x}{h}\right) \end{bmatrix}$$

So we can rewrite the estimator of our regression equation as

$$\hat{e}(x) = \mathbf{e}_1' \hat{\beta}_{LPR} = \mathbf{R}_p' \mathbf{W} \mathbf{R}_p)^{-1} \mathbf{R}_p' \mathbf{W} \mathbf{Y}$$

where \mathbf{e}_1 is a basis vector of length $1 + p$.

Therefore we can rewrite the estimator above as a sum.

$$\hat{e}(x) = \mathbf{e}_1' \left(\sum_{i=1}^n r_p(x_i - x) r_p(x_i - x)' K\left(\frac{x_i - x}{h}\right) \right)^{-1} \left(\sum_{i=1}^n r_p(x_i - x) r_p(x_i - x) y_i K\left(\frac{x_i - x}{h}\right) \right)$$

Now we consider the series estimator, which solves the following problem

$$\hat{\beta}_s = \operatorname{argmin}_{\beta \in \mathbb{R}^{k_n}} \frac{1}{n} \sum_{i=1}^N (Y_i - r_{k_n}(x)\beta)^2 K\left(\frac{x_i - x}{h}\right)$$

where $r_{k_n}(x)$ is the basis of some series defined on x , so that

$$\hat{e}(x) = \mathbf{r}_{k_n}(\mathbf{x})' \hat{\beta}$$

where

$$\hat{\mathbf{beta}}_s = (\mathbf{R}_p' \mathbf{R}_p)^{-1} \mathbf{R}_p \mathbf{Y}$$

and

$$\mathbf{R}_p = \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^p \\ \vdots & \cdots & \ddots & \ddots & \vdots \\ 1 & x_n & \cdots & \cdots & x_n^p \end{bmatrix}$$

So we can rewrite the estimated regression function as

$$\hat{e}(x) = \mathbf{r}_p(\mathbf{x})' (\mathbf{R}_p' \mathbf{R}_p)^{-1} \mathbf{R}_p \mathbf{Y}$$

and

$$\hat{e}(x) = \mathbf{r}_p(\mathbf{x})' \left(\sum_{i=1}^n r_p(x_i) r_p(x_i)' \right)^{-1} \left(\sum_{i=1}^n r_p(x_i) y_i \right)$$

2.2

Next, we need to show the following simplified cross-validation formula holds for local polynomial regression and series estimation:

$$CV(c) = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{e}(x_i))^2 = \frac{1}{n} \sum_{i=1}^n \left(\frac{y_i - \hat{e}_{(i)}(x_i)}{1 - w_{n,1}(x_i)} \right)^2$$

where c is a tuning parameter (h_n for LPR or a truncation K for series estimators)

3 Semiparametric Semi-Linear Model

3.1

The following question concerns this moment condition:

$$\mathbb{E}[(t_i - h_0(x_i))(y_i - t_i\theta)] = 0, \text{ where } h_0(x_i) = \mathbb{E}[t_i|x_i]$$

As long as t_i is not collinear with x_i then θ_0 will be identifiable. Assuming that θ_0 is identifiable, it satisfies the moment condition above:

$$\begin{aligned} \mathbb{E}[t_i y_i] + \mathbb{E}[h_0(x_i) t_i \theta] - \mathbb{E}[h_0(x_i) y_i] - \mathbb{E}[t_i t_i \theta] &= 0 \\ \mathbb{E}[\mathbb{E}[t_i y_i | t_i, x_i]] + \mathbb{E}[\mathbb{E}[h_0(x_i) t_i \theta | t_i, x_i]] - \mathbb{E}[\mathbb{E}[h_0(x_i) y_i | t_i, x_i]] + \mathbb{E}[\mathbb{E}[t_i t_i \theta | t_i, x_i]] &= 0 \\ \mathbb{E}[h_0(x_i) \mathbb{E}[y_i | t_i, x_i]] + \mathbb{E}[h_0(x_i) h_0(x_i) \theta] - \mathbb{E}[h_0(x_i) \mathbb{E}[y_i | t_i, x_i]] + \mathbb{E}[h_0(x_i) h_0(x_i) \theta] &= 0 \\ 0 &= 0 \end{aligned}$$

To derive a closed form equation for θ_0 we follow the steps outlined in Hansen's notes on nonparametrics (chapter 7), which describes Robinson (Econometrica, 1988).

$$y_i = t_i \theta_0 + g(x_i) + \epsilon_i$$

First we take the conditional expectation with respect to the treatment and other covariates. (We assume the treatment is not collinear with the other covariates.)

$$\mathbb{E}[y_i | t_i, x_i] = \mathbb{E}[t_i | t_i, x_i] \theta_0 + \mathbb{E}[g(x_i) | t_i, x_i] + 0 \mathbb{E}[\epsilon_i | t_i, x_i] = h_0(x_i) \theta_0 + g(x_i) + 0$$

Next, let's define $g_{y,x} := \mathbb{E}[y_i | t_i, x_i]$, and subtract the equation above from the original regression.

$$y_i - g_{y,x} = (t_i - h_0(x_i)) \theta_0 + g(x_i) - g(x_i) + \epsilon_i$$

Now, we can rewrite the regression as a residual regression:

$$\begin{aligned} \epsilon_{yi} &= \epsilon_{ti} \theta_0 + \epsilon_i \\ y_i &= g_{y,x} + \epsilon_{yi} \\ t_i &= h_0(x_i) + \epsilon_{ti} \end{aligned}$$

Which produces the infeasible estimator:

$$\beta = \left(\sum_{i=1}^n \epsilon_{ti} \epsilon'_{ti} \right)^{-1} \left(\sum_{i=1}^n \epsilon_{ti} \epsilon'_{yi} \right)$$

Note that we can rewrite the residual regression as :

$$M_{yx}y_i = M_{tx}t_i\theta_0 + \epsilon_i$$

Which is the second stage of an IV regression that partials out the effects of X_i on y_i and t_i using anihilation matrixes.

3.2

3.2.1

If the treatment is undetermined by the power series of the covariates, θ_0 is simply

$$\theta_0 = (T'T)^{-1}(T'Y)$$

which has a feasible estimator of

$$\hat{\theta}(K) = \left(\sum_{i=1}^n t_i t_i\right)^{-1} \left(\sum_{i=1}^n t_i y_i\right)$$

3.2.2

If the treatment is correlated to the other covariates, in order to estimate a feasible estimator, one must run Nadaraya - Watson kernel regressions of the outcome and treatment variables onto the power series.

$$\begin{aligned}\hat{y}_i &= \frac{\sum_{i=1}^n k \left(\frac{p^{K_n}(x_i) - p^{K_n}(x)}{h} \right) y_i}{\sum_{i=1}^n k \left(\frac{p^{K_n}(x_i) - p^{K_n}(x)}{h} \right)} \\ h_0(x_i) &= \frac{\sum_{i=1}^n k \left(\frac{p^{K_n}(x_i) - p^{K_n}(x)}{h} \right) t_i}{\sum_{i=1}^n k \left(\frac{p^{K_n}(x_i) - p^{K_n}(x)}{h} \right)}\end{aligned}$$

Now, construct residualize

$$\begin{aligned}\hat{\epsilon}_{yi} &= y_i - \hat{y}_i = M_{yx}y_i \\ \hat{\epsilon}_{ti} &= t_i - h_0(x_i) = M_{tx}t_i\end{aligned}$$

Which produces the feasible estimator

$$\hat{\theta}(K) = \left(\sum_{i=1}^n \hat{\epsilon}_{ti} \hat{\epsilon}_{ti}'\right)^{-1} \left(\sum_{i=1}^n \hat{\epsilon}_{ti} \hat{\epsilon}_{yi}'\right)$$

3.3

3.3.1

Fixing K , the reason this approach is called a "flexible parametric" estimation because you are estimating θ_0 , while letting

If $K \rightarrow \infty$ does not invalidate the "fixed K " assumption as long as the ratio between the observations and covariates is fixed $\left(\frac{K_n}{n} = \frac{\bar{K}}{\bar{n}}\right)$

3.3.2

Using the results above the confidence interval is

$$CI_{95} = \left[\hat{\theta}(K) - 1.96\sqrt{\hat{V}_{HCO}/n}; \hat{\theta}(K) + 1.96\sqrt{\hat{V}_{HCO}/n} \right]$$

3.4