## **SOLUTIONS CUBED**

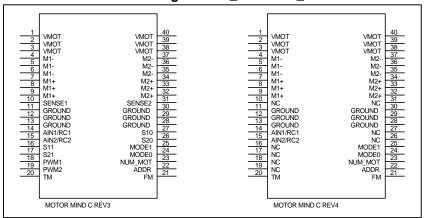
Electronics Prototyping, Custom Design, Product Development

## MMC\_REV3 versus MMC\_REV4 Differences

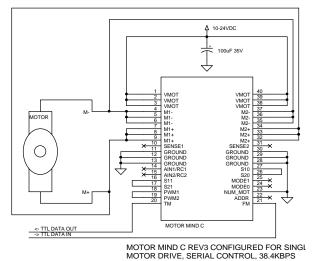
Due to a discontinued component the Motor Mind C (MMC) has been modified with replacement components. There are a variety of changes; some minor and some not so minor that may be of importance to previous users of the product. As of April 2003 all new MMC units will be of the REV4 variety. These parts are physically distinguishable in that the MMC\_REV3 has a silver heat sink, while the MMC\_REV4 has no heat sink.

| Subject of Change                          | MMC_REV3  | MMC_REV4   |
|--|---|--|
| Single Motor Mode                          | Motors leads paralleled (M2+ tied to M1+, etc) and many other pins are tied together                                  | Only M1+ and M1- are used to connect to the motor (motor leads cannot be paralleled) |
| Motor Supply Voltage                       | 10-24V  | 6-24V  |
| Continuous Current                         | 4.0A (4.0A single motor)  | 4.5A (2.25A single motor)  |
| Over-temperature fault                     | 165°C   | 150°C  |
| PWM Frequency                              | 19.2KHZ   | 1.2KHZ (19.2KHZ with Change Frequency command and a serious loss of resolution)      |
| PCB Size (both fit 40 pin 0.6" DIP socket) | 2.35"L x 0.74"W x 0.5"H   | 2.4"L x 0.74"W x 0.36"H  |
| Clearing faults in serial mode             | Done by sending SetDC command   | Done by sending Clear Fault command  |
| AMPS1 / AMPS2 registers                    | Stores approximate motor current  | No current measurements made or available to user                                    |
| BRAKE_MODE register                        | Dynamic or free-spinning brake modes when<br>under serial control, free spinning brake under<br>analog or R/C control | Dynamic or free-spinning brake modes when under all modes of control                 |

## Pinout Changes MMC\_3 to MMC\_4



## Changes in Single Motor Connections (REV4 Drives Cannot be Paralleled)



MOTOR M. 40

1 VMOT VMOT 33

4 VMOT VMOT 33

4 VMOT VMOT 33

4 VMOT VMOT 33

5 M1- M2

6 M1- M2

7 M3

7

MOTOR MIND C CONFIGURED FOR SINGLE MOTOR DRIVE, SERIAL CONTROL, 38.4KBPS

Δ 6-24VDC

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