```
 1  # This work is licensed by James Town and ACOE Core Learning under a
 2  # Creative Commons Attribution—NonCommercial—ShareAlike 4.0
 3  # International License: http://creativecommons.org/licenses/by—nc—sa/4.0/
 4
 5  import linkbot   # loads library for the Linkbots
 6
 7  robotID = input('Enter Linkbot ID: ')   # prompts user for the ID for their Li
 8                                           # and saves the result in a variable c
 9                                           # "robotID" — fyi: case doesn't matter
10
11  robot = linkbot.Linkbot(robotID)   # Assigns the name 'robot' to the given ro
12
13  robot.move(some number of degrees, 0, —some number of degrees) #moves the rob
14                                                                 #number of deg
15
```