

# Contents of the shipping box

Nortek order no:

44237-1-627

Type of system:

SIGNATURE 100



Vangskroken 2  
N-1351 RUD  
Norway  
Tel: +47 6717 4500  
Fax: +47 6713 6770  
inquiry@nortek-as.com  
www.nortek.no

## Instrument type:

- |   |                                  |  |  |  |
|---|----------------------------------|--|--|--|
| <input type="checkbox"/> Aquadopp               | <input type="checkbox"/> AWAC    | <input type="checkbox"/> Vectrino          | <input checked="" type="checkbox"/> Signature100 | <input type="checkbox"/> Signature1000 |
| <input type="checkbox"/> Aquadopp profiler      | <input type="checkbox"/> VM AWAC | <input type="checkbox"/> Vectrino profiler | <input type="checkbox"/> Signature250            | <input type="checkbox"/> NortekDVL     |
| <input type="checkbox"/> Aquadopp DW 3000/6000m | <input type="checkbox"/> Vector  | <input type="checkbox"/> Signature55       | <input type="checkbox"/> Signature500            | <input type="checkbox"/> NLR DVL       |

Software version:

SIGNATURE  
DEPLOYMENT

Firmware version:

1.45422.2272-11/169

Other:

## Cable:

☒ 10m length

☐ Other:

## Connector:

☐ 8-pin Inline

☐ 12-pin UW

☒ 6-pin Inline

☐ 7-pin Souriau

☐ Other:

## Communication:

☐ RS232

☒ Ethernet

☐ RS422

☐ Other:

## Options:

☐ Analog input

☐ Synch

☐ Analog output

☐ Other:

## Battery cannister:

☐ Paradopp battery cannister

☐ Single battery aluminium cannister

☐ Double battery aluminium cannister

## Battery cables:

☐ 2pin Inline-2pin

☐ 8pin Inline-2pin

☐ 8pin rectangular-2pin

## Accessories:

☒ Toolkit

☒ Quick guide

☒ Final test checklist

☐ Seeding material

☐ USB to serial converter RS232

☐ Altronix AL310 USB driver

☐ Recorder kit/ProLog

☐ Battery harness for 2 batteries

## Batteries:

- |   |                    |                          |
|---|--------------------|--------------------------|
| <input type="checkbox"/> Alkaline 50Wh  | 13.5V              | <input type="checkbox"/> |
| <input type="checkbox"/> Alkaline 100Wh | 13.5V              | <input type="checkbox"/> |
| <input type="checkbox"/> Alkaline 540Wh | 13.5V              | <input type="checkbox"/> |
| <input type="checkbox"/> Alkaline 540Wh | 18V                | <input type="checkbox"/> |
| <input type="checkbox"/> Alkaline 90Wh  | 15V(Signature1000) | <input type="checkbox"/> |
| <input type="checkbox"/> Alkaline 180Wh | 18V(Signature500)  | <input type="checkbox"/> |

## Extra set:

## AC/DC Power supply

☐ 15V standard

☐ 48V Signature55

Online

☐ 24V Vectrino

## Plug

☒ 24V DC/DC &  
Signature

☐ EU

☐ UK

☒ US

Other:

Date:

29/6-20

Responsible:

Olav Hauch

# Final test checklist AD2CP



Order number:  
**44237-1-621**

Name: **Signature 100**  
Instrument serial number: **101650**  
Frequency: **100 KHz** Main board: **AD2CP-2352**  
Firmware versions: **1.4.5422.2212-11/169**

Label checked ☒ OK  
Dock test ☒ OK  
Baudrate 115200 ☒ OK

Comments:

**Tilt check**  
☒ Pitch up  
☒ Roll up  
☒ Status bit  
☒ Pitch down  
☒ Roll down  
pitch & roll within +/- 0.2 °

**Clock**  
☒ Set clock  
**Heading**  
☒ Up  
☒ Down  
tolerance: +/- 2 °

**Pressure**  
Psensortemp ☒ OK  
tolerance: +/- 0.1 % of  
**1500** m

**Temperature**  
☒ OK  
tolerance: +/- 0.1 °

**Beam check**

Correct order	Beam Imp	Noise floor	Amplitude in tank	Range
Beam 1 <input checked="" type="checkbox"/> OK	<b>85</b> Ω	<b>25</b> dB	<b>&gt;80</b> dB	<input checked="" type="checkbox"/> OK
Beam 2 <input checked="" type="checkbox"/> OK	<b>82</b> Ω	<b>25</b> dB	<b>&gt;80</b> dB	<input checked="" type="checkbox"/> OK
Beam 3 <input checked="" type="checkbox"/> OK	<b>82</b> Ω	<b>25</b> dB	<b>&gt;80</b> dB	<input checked="" type="checkbox"/> OK
Beam 4 <input checked="" type="checkbox"/> OK	<b>83</b> Ω	<b>25</b> dB	<b>&gt;80</b> dB	<input checked="" type="checkbox"/> OK
Beam 5 <input checked="" type="checkbox"/> OK	<b>574</b> Ω	<b>25</b> dB	<b>&gt;80</b> dB	<input checked="" type="checkbox"/> OK

**Velocity direction**

XYZ coordinate system	ENU coordinate system
X <input checked="" type="checkbox"/> OK	E <input checked="" type="checkbox"/> OK
Y <input checked="" type="checkbox"/> OK	N <input checked="" type="checkbox"/> OK
Z <input checked="" type="checkbox"/> OK	U <input checked="" type="checkbox"/> OK
Z <sub>2</sub> <input checked="" type="checkbox"/> OK	U <sub>2</sub> <input checked="" type="checkbox"/> OK

**Head file**  
☒ Headfile checked  
☒ Saved as read only

**Serial communication**  
☐ RS422 **NA**  
☐ RS232

**Trigger**  
☐ TTL **NA**  
☐ RS485

**Recorder erased**  
☒ OK  
Rec size: **256 GB**

**Ethernet**  
MAC address: **8C:68:78:00:09:30** DHCP enabled ☒  
Static IP address:  FTP OK ☒  
Set host name: **101650**

**Licenses**

Averaging mode <input checked="" type="checkbox"/>	Wave mode <input type="checkbox"/>	Vertical velocity <input type="checkbox"/>	64GB recorder <input type="checkbox"/>	Calibration license erased <input checked="" type="checkbox"/>
Burst Five beams <input type="checkbox"/>	Echo Sounder <input checked="" type="checkbox"/>	Dual frequency low <input type="checkbox"/>	128GB recorder <input type="checkbox"/>	Production license erased <input checked="" type="checkbox"/>
Bottom track <input type="checkbox"/>	Ice Measurement <input type="checkbox"/>	Dual frequency high <input type="checkbox"/>	256GB recorder <input checked="" type="checkbox"/>	Default configuration set <input checked="" type="checkbox"/>
High Resolution <input type="checkbox"/>	Altimeter <input type="checkbox"/>	16GB recorder <input type="checkbox"/>		

**Cable/Harness**  
Communication ☒ Cable ☒ Harness  
Battery ☒ Battery ☒

**Electrical isolation test**  
50V OK ☒

**External sensors**

**Power down**  
☒ OK

**Date**  
Day **29** Month **06** Year **20**  
Signature: **[Signature]**



# Tilt and Compass Report

Page 3 of 3

## Details

Instrument Type	Signature100
Instrument S/N	101650
Date	June 11, 2020
Operator	Kim Dunserudhagen
Location	Nortek Factory Norway
Result	Passed

## Description

Calibration and verification is performed in a two axis automated jig. Continuous and fixed-point measurements are collected to calibrate and verify the sensor.

Criteria of acceptance for tilt sensor is  $\pm 0.2^\circ$ .

Criteria of acceptance for compass sensor is  $\pm 2^\circ$ .

Reference: Digital Protractor Series 950 Pro 3600. Accuracy  $\pm 0.05^\circ$ .

## Tilt Verification Results

Reference ( $^\circ$ )	Diff. Up		Diff. Down	
	Pitch ( $^\circ$ )	Roll ( $^\circ$ )	Pitch ( $^\circ$ )	Roll ( $^\circ$ )
-30.00	-0.13	-0.06	-0.11	-0.14
-15.00	0.03	0.15	0.13	0.06
0.00	0.11	-0.08	0.11	0.14
15.00	-0.15	-0.04	-0.12	-0.12
30.00	0.13	0.13	-0.04	-0.07

## Compass Verification Results

Reference ( $^\circ$ )	Heading Diff. Up ( $^\circ$ )	Heading Diff. Down ( $^\circ$ )
0.00	-0.31	0.24
45.00	-0.18	-0.08
90.00	-0.21	-0.40
135.00	-0.33	-0.39
180.00	-0.06	0.04
225.00	-0.04	0.14
270.00	0.03	0.41
315.00	-0.19	0.45