

Christopher Walczak

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OBJECTIVE

Dynamic Computer Science and Robotics double major with hands-on experience in robotics, computer vision, software development, and embedded systems, seeking experience in innovative drone research.

EDUCATION

Worcester Polytechnic Institute (WPI), Worcester MA

B.S. Robotics & B.S. Computer Science, GPA: 3.87/4.0

M.S. Robotics & Computer Science (planned)

August 2021 - present

Completed: May 2025

Expected Graduation: May 2027

SKILLS

Languages: MATLAB, C, C++, Python, Java, JavaScript, HTML

Libraries: ROS, SLAM, OpenCV, SQL, WebGL

Software: Ardupilot Mission Planner, QtCreator, Blender, Zbrush, SOLIDWORKS, Final Cut Pro X, Prusa Slicer, UltiMaker Cura

Links: <http://www.youtube.com/@polandsfinest4594> | <https://github.com/cwalczak66>

WORK EXPERIENCE

NRIP SOFTWARE ENGINEERING INTERNSHIP, Naval Undersea Warfare Center, Newport, RH

June 2025 - August 2025

- Developed and documented a custom software recording system using a blend of MATLAB and C for model munition simulations, significantly improving post-test analysis capabilities for the software and analysis team.
- Streamlined previously manual data capture processes, enhancing team efficiency and accelerating test results.
- Designed and documented automated testing programs in C to simulate a wide range of recording environments and data scenarios, ensuring tool robustness and ability to handle large data inputs.
- Collaborated closely with software engineers to ensure seamless system integration and full compliance with all critical performance and reliability requirements.

COMBUSTION ENGINEERING RESEARCH LAB MQP, Shibaura Institute of Technology, Tokyo, Japan September 2024 - December 2024

- Co-developed IgniteCV, a modular computer vision tool built in C++ using OpenCV, Qt, and CMake. The software automates the analysis of combustion experiments by identifying flame speed, angle of attack, burned area, and rocket propulsion patterns from high-speed video data.
- Designed and implemented a real-time flame tracking UI for visualizing processed data and exporting analytical results to CSV, streamlining experimental workflows for researchers.
- Proactively gathered software requirements through direct collaboration with Japanese researchers, overcoming language and communication barriers to deliver a solution aligned with the lab's technical and research needs.

PROJECTS

MORPHING FUSELAGE VTOL UAV (SOARV2) MQP, WPI

January 2024 - present

- Spearheaded flight testing research for a morphing VTOL UAV, leveraging personal expertise and enthusiasm for drone systems and piloting; served as the primary test pilot for all flight experiments
- Designed a UAV integrating soft robotics with drone maneuverability, using ArduPilot for precise flight control and data collection, and conducting experiments on flight performance and energy efficiency.
- Modified C++ ArduPilot firmware to evaluate control surface behavior during flight mode transitions; documented findings and collaborated with faculty and peers to present results effectively.

BRIGHAM WOMEN'S HOSPITAL SOFTWARE PROJECT, WPI

January 2023 - February 2023

- Worked in a team of ten students to create a software template for Brigham Women's Hospital's multi service platform in Java, which included a pathfinder, map editor, csv file management, and handling of medical service requests.
- Developed team working skills, large scale object oriented design, agile scrum workflow, Git, used collaborative software like Jira to manage tasks, and leadership experience being the lead front end engineer.
- Collaborated in the creation of detailed user stories and software requirements with the team, ensuring clear communication and alignment to promote seamless software development and maintain a unified project vision.

HONORS AND AWARDS

Rho Beta Epsilon (Robotics Engineering Honor Society)(2024)

MQP finalist award (SOARV2) (2025)

Best MQP video presentation award (SOARV2) (2025)

Deans List (all semesters) (2021-2025)

NSLS (National Society of Leaders and Success) (2024)