

# Quadtree/Octree Distribution of Data using p4est

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In this project we see the advantages of using mesh refinement to process massive amounts of data. When there are a large number of data points that a computer needs to process, it can be problematic when the computer does not have enough memory to load and process all data points at the same time. In this project I simulate a large number of data points and use quadtrees or octrees to partition the data and have different processors working with different parts of the data. In particular, I use the package p4est in the C programming language to do the mesh refinement and load data into different processors.

## 1 Data

I simulated the data using a file of the NYU logo as seen in Figure ?? . I will cover the 2-dimensional case in detail and then extend the explanations to the 3-dimensional case. Inside of the torch, many points are generated and outside just a few. The  $x$ -coordinates of the figure are stored in one vector and the  $y$ -coordinates in another. At each image point, we repeat the storing of the row ( $x$ -coordinate) and column ( $y$ -coordinate) location of that data point but with random noise added each time. This is that for image row  $i$  we loop for  $0 \leq j < m_i$  such that

$$x_{i,j} = r_i + u_{i,j}$$

where  $u_{i,j}$  is a uniform random variable between 0 and 1 and  $m_i$  is the number of repetitions for that image point. If we are at an inside point we repeat more times so  $m_i$  will be larger than if we are at an outside point.

Figure 1: Image for Data Simulation

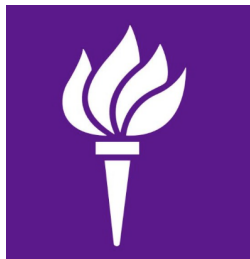


Table 1: Data

Min row:	0.000008
Max row:	397.999939
Min col:	0.000289
Max col:	406.000000
Total points:	8001102

## 2 p4est

The package p4est does all the handling of the splitting of the quadtrees and octrees for us. I took the example file p4est\_step1.c and modified it for my purposes. In particular, it has a function that defines the condition for splitting. This function is a boolean that, if we have more than a certain number of points in a quadrant, will return 1.

## 3 Quadtree

I first implemented the 2-dimensional case. In table ?? we can see the minimum and maximum row and column values as well as the total number of points generated for a single run. Since positive noise was added to the row and column values, we can see that the values go a little over zero or the number of rows and columns corresponding to the minimums and maximums respectively.

I ran the code using 5 processors with MPI and it took about 35 seconds. Figure ?? shows the levels of partitioning. The red in the middle shows small areas and the blue outside shows large quadtrees. Figure ?? shows the points that are being processed by the different processors. Each color represents a different processor, an MPI rank.

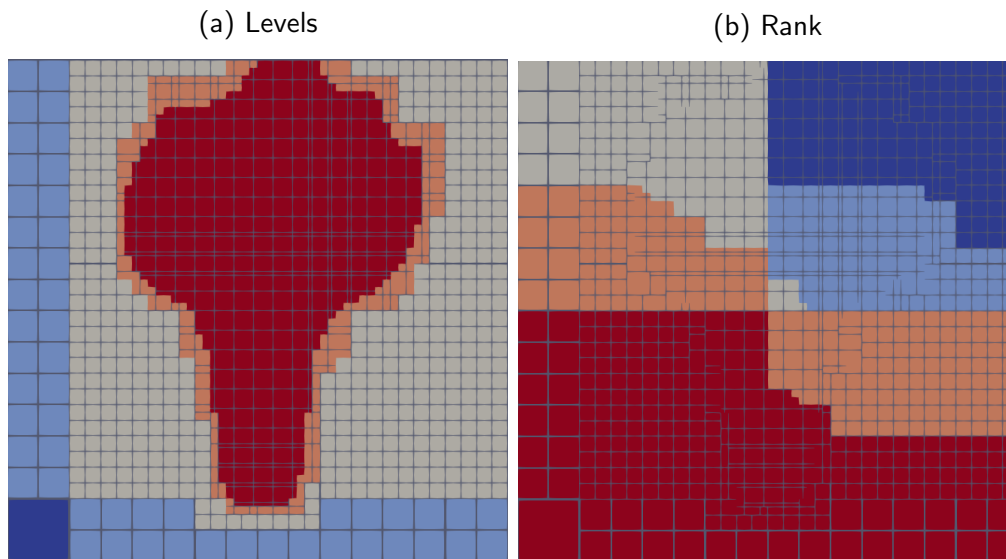
```
mpirun -np 5 p4est_data
```

## 4 Octree

Octrees are 3-dimensional representation of the quadtrees. In my case, I repeated the data in the  $z$ -direction  $5/8$  of the way up and  $5/8$  down. I repeated the above run with 5 MPI ranks for this 3-dimensional case. Now Figure ?? shows the data points themselves to be able to view the shape of the volume. We can see in Figure ?? the levels of refinement by color. The red in the center is fine grid and the blue in the outside is coarse. In Figure ?? the colors represent a different rank, where we can see each processor got about the same number of points.

```
mpirun -np 5 p8est_data
```

Figure 2: Quadtree



## 5 C Code

```

/*
Datatree
Ana C. Perez-Gea
Code adapted from p4est example file p4est_step1.c
*/
#ifdef P4_T0_P8
#include <p4est_vtk.h>
#else
#include <p8est_vtk.h>
#endif

#ifdef P4_T0_P8
static const p4est_qcoord_t eighth = P4EST_QUADRANT_LEN (3);
#endif

/* Parameters to adjust */
#define max_pow0 6 // no deeper than this level (power of 2)
int max_size; // keep splitting if we have more than this many data points
int max_data = 10000000; //max points to simulate, adjust so it covers all your points

/* Parameters not to touch */
float *array, *cols, *rows, max_col, min_col, max_row, min_row;
int count = 0; // actual number read from file
#define max_quad0 (1<<max_pow0)
static const int max_pow = max_pow0;
static const int max_quad = max_quad0;

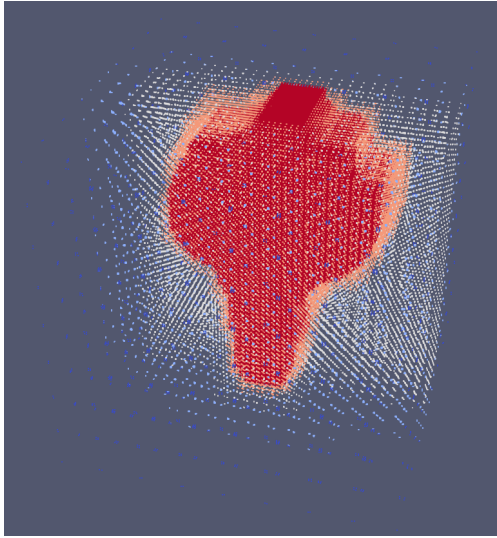
/** Callback function to decide on refinement. */
static int refine_fn (p4est_t * p4est, p4est_topidx_t which_tree, p4est_quadrant_t *
    quadrant){
    int tilelen, inside, ql;
    int i, j, offsi, offsj;
    float dx, dy, qx, qy;

    /* We do not want to refine deeper than a given maximum level. */
    if (quadrant->level > max_pow) {
        return 0;
    }
}

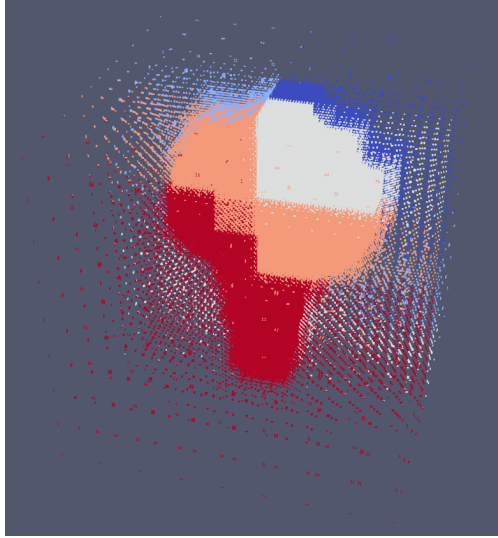
```

Figure 3: Octree

(a) Levels



(b) Rank



```

#ifdef P4_T0_P8
/* In 3D we extrude the 2D image in the z direction between [3/8, 5/8]. */
if (quadrant->level >= 3 && (quadrant->z < 3 * eighth || quadrant->z >= 5 * eighth)) {
    return 0;
}
#endif

inside = 0;
qx = quadrant->x;
qy = quadrant->y;
ql = quadrant->level;
offsi = quadrant->x / P4EST_QUADRANT_LEN (max_pow);
offsj = quadrant->y / P4EST_QUADRANT_LEN (max_pow);
qx = (float)offsi / (float)max_quad;
qy = (float)offsj / (float)max_quad;
for(i=0; i<count; i++){
    dx = (rows[i]-min_row) / (max_row-min_row);
    dy = (cols[i]-min_col) / (max_col-min_col);
    //printf("dx in rows[%d]=%f\n", i, dx);
    //printf("dy in cols[%d]=%f\n", i, dy);
    if(qx<dx && dx<(qx+1.0/(float)(ql+1))){
        //printf("condition in rows < %f + %f\n", qx,1.0/(float)(ql+1));
        if(qy<dy && dy<(qy+1.0/(float)(ql+1))){
            //printf("condition in cols < %f + %f\n", qy,1.0/(float)(ql+1));
            inside++;
            if(inside > max_size){
                //printf("WIN rows[%d]=%f\n", i, rows[i]);
                //printf("WIN cols[%d]=%f\n", i, cols[i]);
                return 1;
            }
        }
    }
}
return 0;
}

/* Main function creates a connectivity and forest, refines it, and writes a VTK file. */
int main (int argc, char **argv) {
    int mpiRET, i;
    int recursive, partforcoarsen, balance;

```

```

sc_MPI_Comm  mpicomm;
p4est_t *p4est;
p4est_connectivity_t *conn;
double t1, t2;

/* Open file we will use to simulate data points */
FILE *fp;
int row,col,inc;
float data, u1, u2;
char ch;
//array = (float*)malloc(sizeof(float)*ple*ple);
cols = (float*)malloc(sizeof(float)*max_data);
rows = (float*)malloc(sizeof(float)*max_data);
fp = fopen("example/steps/NYUlogo.txt","r");
row = col = 0;
while(EOF!=(inc=fscanf(fp,"%f%c", &data, &ch)) && inc == 2){
    //array[count] = data;
    for(i=0;i<(int)data;i++){
        u1 = (float)rand() / (float)RAND_MAX ;
        rows[count] = row+u1;
        if(rows[count]<min_row || 0==count){
            min_row = rows[count];
        }
        if(rows[count]>max_row || 0==count){
            max_row = rows[count];
        }
        u2 = (float)rand() / (float)RAND_MAX ;
        cols[count] = col+u2;
        if(cols[count]<min_col || 0==count){
            min_col = cols[count];
        }
        if(cols[count]>max_col || 0==count){
            max_col = cols[count];
        }
        ++count;
        if(count==max_data){
            printf("Maximum data reached.\n");
            goto exit;
        }
    }
    ++col;
    if(ch == '\n'){
        ++row;
        col = 0;
    } else if(ch != ','){
        fprintf(stderr, "Different separator (%c) of row at %d\n", ch, row);
        goto exit;
    }
}
exit:
    fclose(fp);

printf("Min row: %f\n", min_row);
printf("Max row: %f\n", max_row);
printf("Min col: %f\n", min_col);
printf("Max col: %f\n", max_col);
printf("Total points: %d with %d^2 maximum quadrants\n", count, max_quad);
max_size = (int) (count/max_quad);

/* Initialize MPI */
mpiret = sc_MPI_Init (&argc, &argv);
SC_CHECK_MPI (mpiret);
mpicomm = sc_MPI_COMM_WORLD;
// Get the rank of the process
int world_rank;
sc_MPI_Comm_rank(MPI_COMM_WORLD, &world_rank);
t1 = sc_MPI_Wtime();

```

```

/* Store the MPI rank as a static variable so subsequent global p4est log messages are
   only issued from processor zero. */
sc_init (mpicomm, 1, 1, NULL, SC_LP_ESSENTIAL);
p4est_init (NULL, SC_LP_PRODUCTION);
P4EST_GLOBAL_PRODUCTIONF
    ("This is the p4est %dD data\n", P4EST_DIM);

/* Create a forest that consists of just one quadtree/octree. */
#ifdef P4_T0_P8
    conn = p4est_connectivity_new_unitsquare ();
#else
    conn = p8est_connectivity_new_unitcube ();
#endif

/* Create a forest that is not refined; it consists of the root octant. */
p4est = p4est_new (mpicomm, conn, 0, NULL, NULL);

/* Refine the forest recursively in parallel. */
recursive = 1;
p4est_refine (p4est, recursive, refine_fn, NULL);

/* Partition: The quadrants are redistributed for equal element count. */
partforcoarsen = 1;
p4est_partition (p4est, partforcoarsen, NULL);

/* If we call the 2:1 balance we ensure that neighbors do not differ in size by more than
   a factor of 2. */
balance = 1;
if (balance) {
    p4est_balance (p4est, P4EST_CONNECT_FACE, NULL);
    p4est_partition (p4est, partforcoarsen, NULL);
}
printf("Hi this is processor %d\n", world_rank);
/* Write the forest to disk for visualization, one file per processor. */
p4est_vtk_write_file (p4est, NULL, P4EST_STRING "_data");

/* Destroy the p4est and the connectivity structure. */
p4est_destroy (p4est);
p4est_connectivity_destroy (conn);

/* Verify that allocations internal to p4est and sc do not leak memory. */
sc_finalize ();

t2 = sc_MPI_Wtime();
printf( "Elapsed time is %f\n", t2 - t1 );

/* This is standard MPI programs. Without --enable-mpi, this is a dummy. */
mpiret = sc_MPI_Finalize ();
SC_CHECK_MPI (mpiret);
return 0;
}

```