

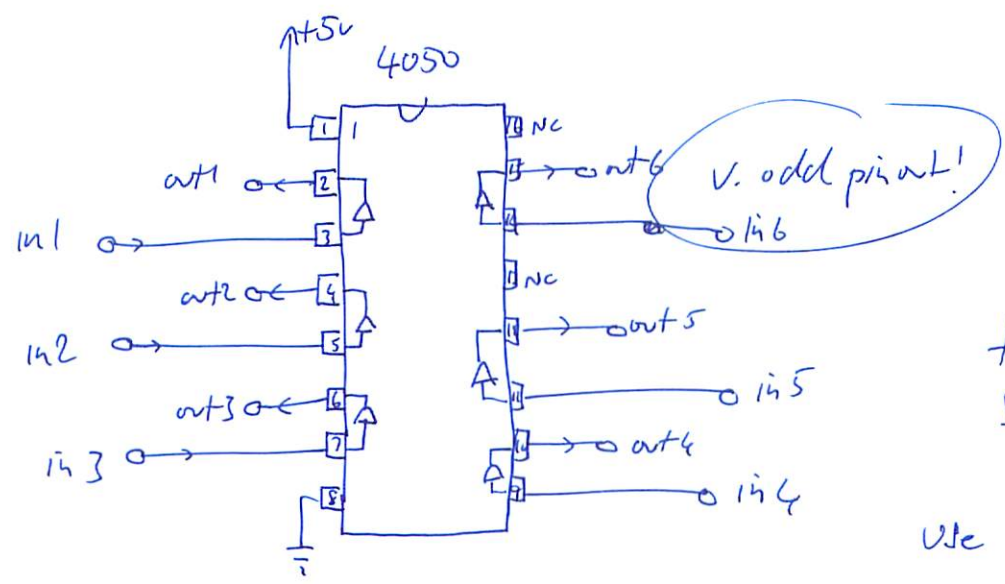
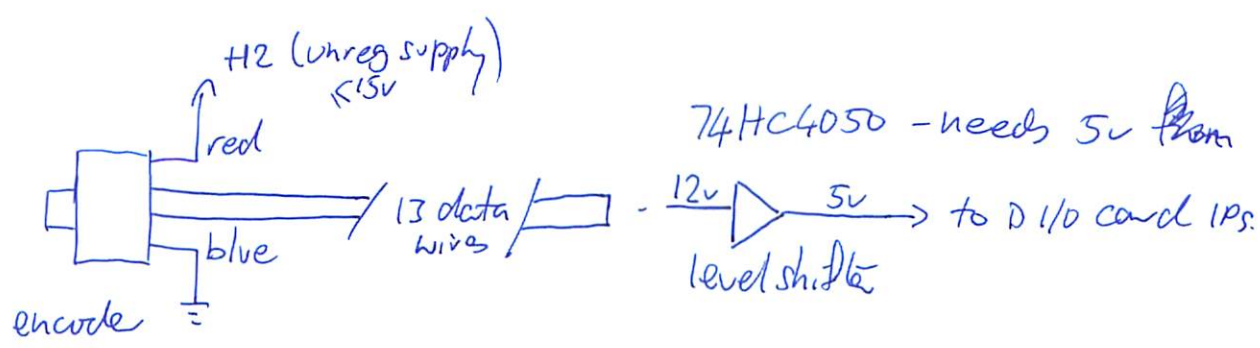
Encoder interface 9/7/09

" ①

- Voltage 6 10..32V. We will use 12v.
- current drain ~ 90mA
- ~~2¹³~~ 2¹³ = 8192 step encoder in a Gray code

Wire	Gray	color
1	G ₀	violet
2	G ₁	white/brown
3	G ₂	white/green
4	G ₃	white/yellow
5	G ₄	white/gray
6	G ₅	white/pink
7	G ₆	white/blue
8	G ₇	white/red
9	G ₈	white/black
10	G ₉	brown/green
11	G ₁₀	brown/yellow
12	G ₁₁	brown/gray
13	G ₁₂	brown/pink
17	Store	pink - low = freeze data bits hi = free run (default)
18	yellow enable	yellow - hi = tristate outputs - low = outputs active (default)
19	CU/CW	brown - hi = clockwise increase (default) * 7s. low = counter clockwise
20	GND	blue - ground
21	V+	red - + voltage (12v) Do not exceed 15v.

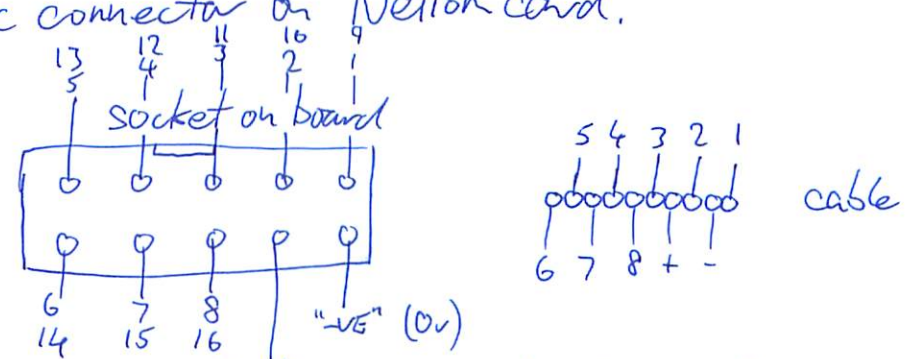
(gray = set line. Could use TS, but better to use the button on the encoder itself).



there are 13 bits,
so we need 3 chips
use staggered veropins.

power from IDC connector on Netion card.

IDC connector:



"VE" (12V) - 12 on the q/p connector,
5V on the l/p connectors

4050's are powered from the l/p IDC connector (5V)
DAC is powered from the q/p IDC connector (12V)
- this is necessary as the DAC supply must
be > the voltage it produces (10V here, max)

Maxon Servo Amp

LSC 30/2
12-30V 2A

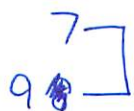
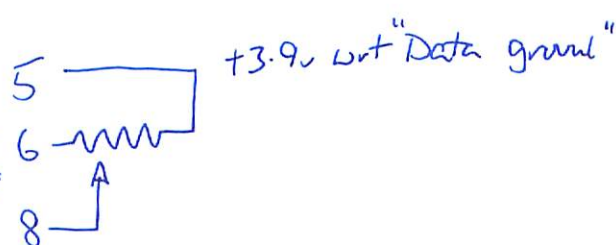
(3)

pin



3 - V_{CC} (12V)

4 - GND (0V)



10 → to output 9 of Motion card - this is the 'motor disable' signal (1 = enable, 0 = disable)
11 → 4.7k

There are also switches to set - look at device for these.

(voltage ref mode)

This is the control stage with a pot. We use the op of the DAC. Wrt to pure ground, the two reference voltages are actually 10V and 2.4V. (rather than $\pm 3.9V$)

7524 DAC

- using 'voltage reference mode'
(so some of the pin labels are backwards, and 'inputs' are used as 'outputs')

