



FIG. 1 – ROBOT PRRRRP

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Paramètres de Denavit-Hartenberg :

	1	2	3	4	5	6
$\sigma_i$						
$\alpha_{i-1}$						
$a_{i-1}$						
$\theta_i$						
$r_i$						
$q_i(\text{figure})$						

$$T_{01} = \begin{pmatrix} & & & \\ & & & \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{pmatrix}$$

$$T_{12} = \begin{pmatrix} & & & \\ & & & \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{pmatrix}$$

$$T_{23} = \begin{pmatrix} & & & \\ & & & \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{pmatrix}$$

$$T_{34} = \begin{pmatrix} & & & \\ & & & \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{pmatrix}$$

$$T_{45} = \begin{pmatrix} & & & \\ & & & \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{pmatrix}$$

$$T_{56} = \begin{pmatrix} & & & \\ & & & \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{pmatrix}$$